Trend Prediction

IoT Time Series Forecasting

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Agenda

- 1. Motivation
- 2. Dataset
- 3. Objective & Scope
- 4. Available Forecasting Techniques
- 5. Our Model
- 6. Deployment
- 7. Live Demo



Motivation

Time Series Forecasting has always been a very important area of research in many domains.

For example:

- → Manufacturing
- → Medicine
- → Energy
- → Weather
- → Smart Cities

Motivation: Manufacturing



Motivation: Medicine



Motivation: Energy

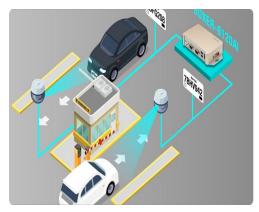


Motivation: Weather



Motivation: Smart Cities





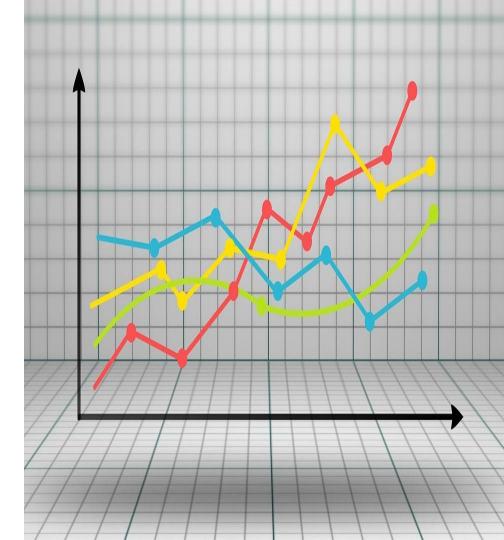




In mathematics, a series of data points indexed (or listed or graphed) in time order.

Most commonly, it is a sequence taken at equally spaced points in time. That's:

Time Series



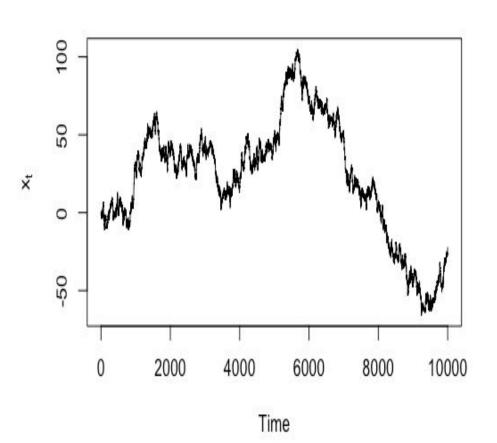
Time Series: Types

- → Non-Stationary
 - Random Walk
 - White Noise
 - **♦** Trend Stationary

→ Strict Stationary

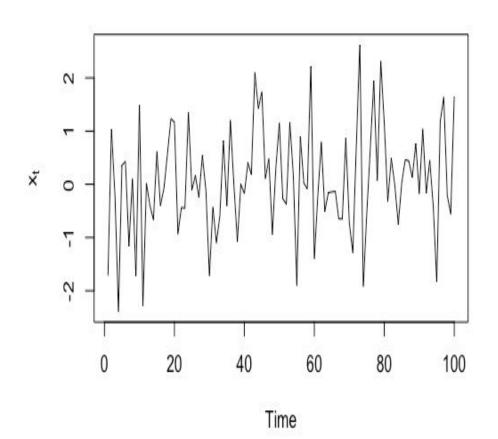
Random Walk

Time Series: Types Random Walk



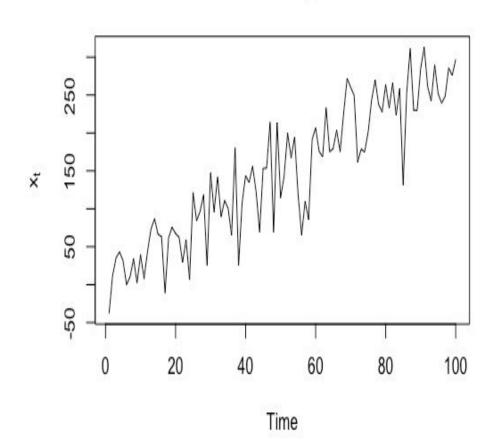
White Noise Process

Time Series: Types White Noise

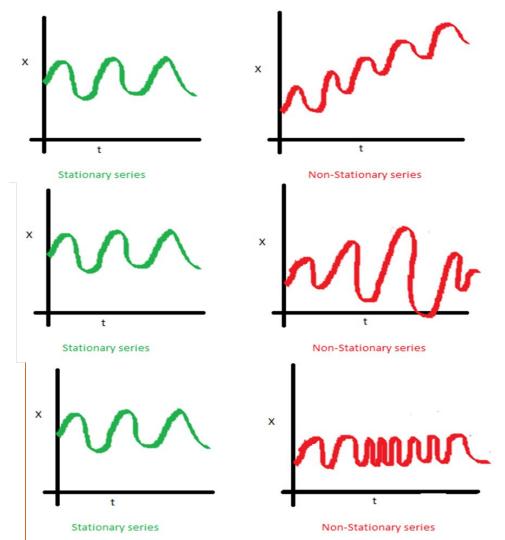


Trend Stationary Process

Time Series: Types Trend Stationary



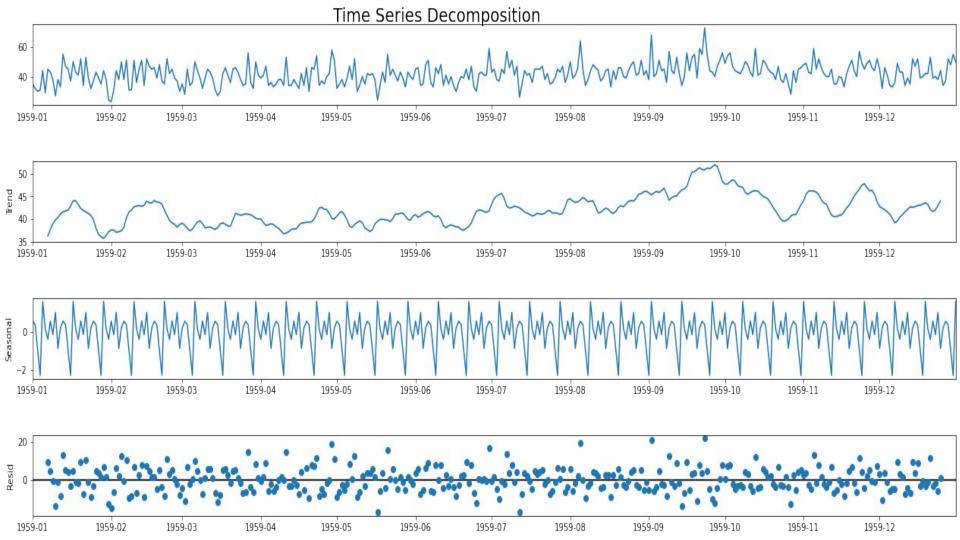
Time Series: Types Stationary



Time Series: Decomposition

- → Long Term Trend
 - Up Trend
 - Downtrend

- → Seasonality
 - Based on frequency
 - Annually, Monthly, Daily, etc...
- → Noise (Residuals)





Objective & Scope

→ Main Objective:

- Building a stable Time Series Predictor works for IoT sensor readings in order to forecast the upcoming readings of that sensor.
- Deployment on Master of Things (MoT).
- Running of any script in time frame less than 2 seconds.

→ Scope:

- Univariate Predictor.
- Predictor doesn't forecast long sequence.

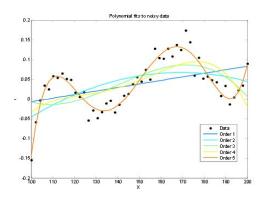


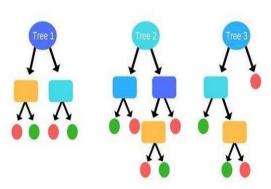
Forecasting: Traditional Methods

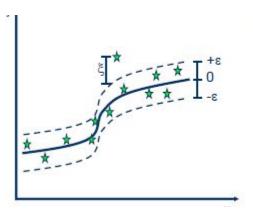
- → Naive Method
- → Simple Average
- → Moving Average
- → Weighted Moving Average
- → Exponential Smoothing

Forecasting: Classic ML

- → Polynomial Regression
- → Random Forests
- → Support Vector Machine

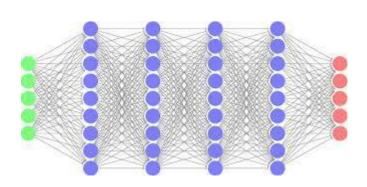


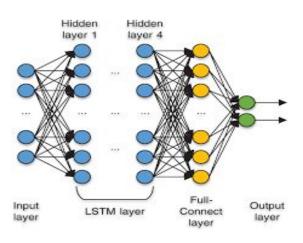




Forecasting: Deep Learning

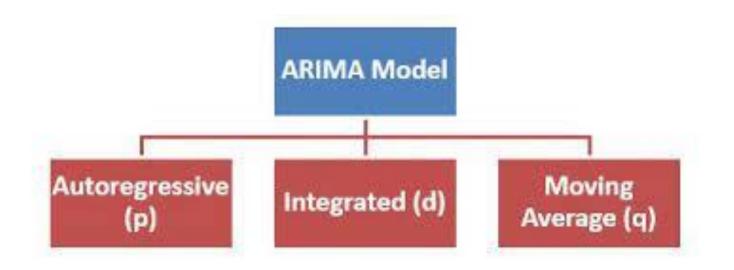
- → Deep Neural Networks
- → Recurrent Neural Networks (RNNs)





Forecasting: ARIMA

AutoRegressive Moving Average



Forecasting: ARIMA

→ ARMA

→ ARIMA

→ SARIMA

→ Auto ARIMA



Our ARIMA Model

- → Overview
- → Mathematically
- → In Code
- → Training Approach
- → Evaluation

Our ARIMA Model: Overview

ARIMA(p, d, q)

Demo Sheet

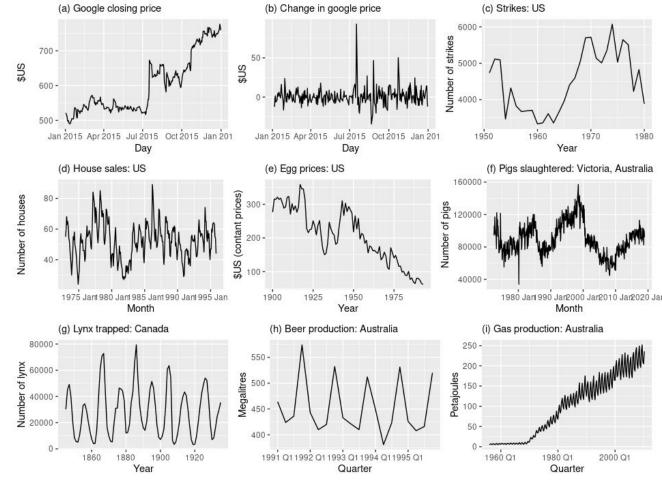
- → AR (p): refers to a model that shows a changing variable that regresses on its own lagged, or prior, values.
- → I (d): represents the differencing of raw observations to allow for the time series to become stationary.
- → MA (q): incorporates the dependency between an observation and a residual error.

→ Stationarisation Techniques

→ Autoregressive

→ Integration

→ Moving Average



$$y_t'=y_t-y_{t-1}$$
 $y_t-y_{t-1}=arepsilon_t o y_t=y_{t-1}+arepsilon_t$: random walk $y_t=c+y_{t-1}+arepsilon_t$: random walk w/ drift $y_t''=y_t'-y_{t-1}'=y_t-2y_{t-1}+y_{t-2}$ $By_t=y_{t-1}; B^2y_t=y_{t-2} o B^dy_t=y_{t-d}$ $y_t'=y_t-y_{t-1}=(1-B)y_t$ $y_t''=y_t'-y_{t-1}'=y_t-2y_{t-1}+y_{t-2}=(1-2B+B^2)y_t=(1-B)^2y_t$ $(1-B)^dy_t$: d-th order difference

$$\hat{y_t} = c + \phi_1 y_{t-1} + \phi_2 y_{t-2} + ... + \phi_p y_{t-p} + arepsilon_t$$
 $\hat{y_t} = c + arepsilon_t + heta_1 arepsilon_{t-1} + heta_2 arepsilon_{t-2} + ... + heta_q arepsilon_{t-q}$

$$\begin{split} \hat{y_t'} &= c + \phi_1 y_{t-1} + ... + \phi_p y_{t-p} + \theta_1 \varepsilon_{t-1} + ... + \theta_q \varepsilon_{t-q} + \varepsilon_t \\ &(1 - B\phi_1 - ... - B^p \phi_p)(1 - B)^d y_t = c + (1 + B\theta_1 + ... + B^q \theta_q) \varepsilon_t \\ &\Phi(B)(y_t' - \mu) = \Theta(B); c = \mu(1 - \phi_1 - ... - \phi_p) \varepsilon_t; \mu = \frac{1}{T} \sum_{t=0}^T y_t' \\ \end{split}$$

Our ARIMA Model: In Code

- → Pure JS Implementation
 - Pros: has no dependency on any other frameworks.
 - Cons: in absence of any low level optimisation, combined with time limit requirement; data records are kept under 128 & results could be significantly inaccurate.

Our ARIMA Model: In Code

```
module.exports = {
826
827
          array, empty, diff, dot, ndim, reshape, shape, sum, transpose, diag, ones,
          zeros, eye, arange, vstack, hstack, NDArray, linalg, linspace, random,
828
          cumsum, mean, std, prod
829
830
      class AutoRegressionIntegratedMovingAverage extends GradientDescent {
        constructor(order = [1, 0, 0], KWArgs = { learningRate: 1e-3 }) {
          super(KWArgs.learningRate || 1e-3, KWArgs);
          [this._p, this._d, this._q] = order;
          this._update = function (gradient, m, vt1 = 0) {
            this. W = this. W.add(this.vt(gradient, m, vt1));
          };
```

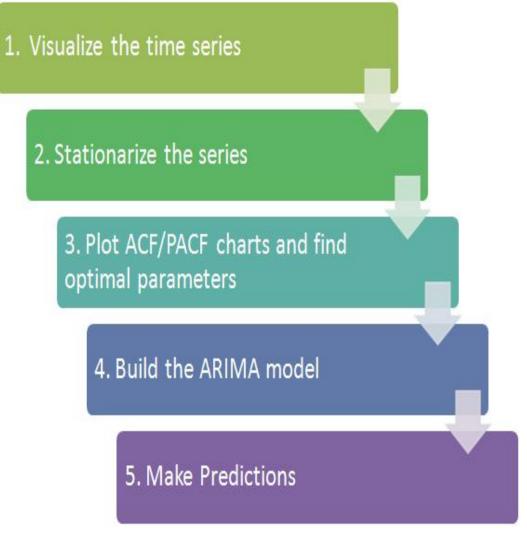
Our ARIMA Model: In Code

- → TensorFlow JS Implementation
 - ◆ Pros: Problem could be implemented as a neural network; Optimisations allow for faster processing (up to x20); which in turn encourages usage of more data records, plus allows for training on several loss functions.
 - ◆ Cons: Still not fully deployed yet, Miss the integration part

Our ARIMA Model: In Code

```
function buildModel(inputShape, optimizer, loss, metrics) {
    // Define input, which has a size of inputShape
    const inputLayer = tf.input({ shape: inputShape });
    // Output dense layer uses linear activation.
    const denseLayer1 = tf.layers.dense({ units: 1 });
    // Obtain the output symbolic tensor by applying the layers on the inputLayer.
    const output = denseLayer1.apply(inputLayer);
    // Create the model based on the inputs.
    const model = tf.model({ inputs: inputLayer, outputs: output });
    model.compile({
        optimizer: optimizer,
       loss: loss,
       metrics: metrics,
```

Framework Of **Time Series** ARIMA Modeling (Box-Jenkins)



Our ARIMA Model: Training Approach

We need to tune some hyperparameters to help the model adapt the data in an appropriate way, So how to choose correct value for:

- → Epochs
- → Learning Rate
- **→** p
- **→** d
- \rightarrow \circ

Our ARIMA Model: Training Approach

For tuning (p, d, q) there are some visual and statistical methods such as:

- → Augmented Dickey-Fuller test (ADF)
- → Kwiatkowski-Phillips-Schmidt-Shin test (KPSS)
- → Autocorrelation Function (ACF)
- → Partial Autocorrelation Function (PACF)

Our ARIMA Model: Evaluation Metrics

- → Mean Squared Error (MSE)
- → Root Mean Squared Error (RMSE)
- → Log Likelihood
- → Akaike's Information Criteria (AIC)
- → Bayesian Information Criteria (BIC)

Our ARIMA Model: Evaluation Metrics

Metrics in mathematical forms

Log Likelihood

$$LL = -rac{n}{2}ln(2\pi\sigma^2) - rac{1}{2n\sigma^2}\sum_{i=0}^narepsilon^2$$

Akaike's Information Criteria

$$AIC=2(p+q+k+1)-2LL); k=1$$
 if $c
eq 0, k=0$ if $c=0$

Corrected AIC

$$AICc = AIC + rac{2(p+q+k+2)(p+q+k+1)}{T-p-q-k-2}$$

Bayesian Information Criteria

$$BIC = AIC + (p+q+k+1)(ln(T)-2)$$

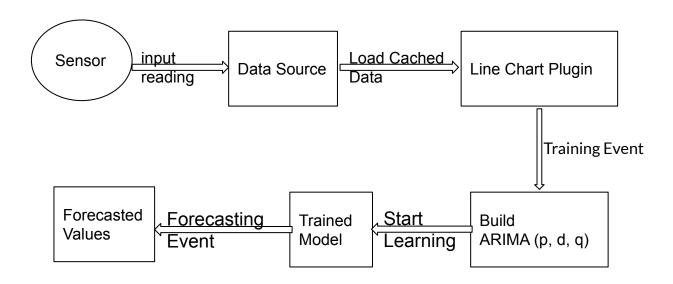


Deployment: Master of Things (MoT)

→ It's an Internet of Things (IoT) platform enables you to create IoT & Machine-to-machine (M2M) applications to serve you in few hours.

→ It'a product of SpimeSenseLabs.

Deployment: Architecture



- → On Click Events
 - Training
 - **♦** Forecasting
 - Evaluation

→ Custom Events

→ Timer Tick Event

→ Onclick Training Event:

- Read sensor data.
- Build the model with required hyperparameters from UI.
- ♦ Start fitting the data.
- Save the trained model after finishing fitting into JSON object containing all the learned params.

→ Onclick Forecasting Event:

- Read the number of needed prediction steps.
- Load the saved trained model.
- Call forecast method.
- Show the predictions in UI list.

→ Onclick Evaluate Event:

- ◆ Train on 90% of sensor data.
- Forecast number of steps equals to 10% of sensor data
- Call an evaluation matrix, such as: MSE.

Deployment: Performance

- → Training Action:
 - ◆ Less than 2,000 ms

- → Forecasting Action:
 - ◆ Less than 2,000 ms

Deployment: Retraining Schedule

Based on readings frequency:

The higher the frequency of coming readings, the more retraining must be done, And vice versa...



Live Demo

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Mouse X,Y Position: 29,308

Thank You