

Name: Muhammed Essam

ID: 20190462

Name: Fatema Hesham

ID: 20190373

Mnist dataset:

The MNIST dataset is an acronym that stands for the Modified National Institute of Standards and Technology dataset. It is a dataset of 60,000 small square 28×28 pixel grayscale images of handwritten single digits between 0 and 9.

Features Extraction:

- 1- At first divide the image to 16 blocks each block has 7x7 pixels so I reshaped the image from 28x28 to 16x7x7
- 2- Then I have to calculate the centroid of each block using this formula for x and y

$$X = \frac{\sum f(x,y) * x}{\sum f(x,y)}, y = \frac{\sum f(x,y) * y}{\sum f(x,y)}.$$

Normalization on Features:

1. Normalization on features because the use of sigmoid in activation function of layers
2. Min_Max normalization is used:

$$x^{new} = \frac{x^{old} - min}{max - min}$$

Neural Network Structure:

1. Neural Network divided into two main parts:

i) Layers: Each layer has number of neural and each neural has its own weights, input and output.

- (1) Input layer
- (2) Hidden layers
- (3) Output layer

ii) Activation function: Output is a function of the output of neural

2. The output is calculated by (WeightxInput) and pass the result to the activation function which is the input of the second layer.

➤ At neural first take input and give a random value to weights at calculates output forward **** (Forward_Function)**

➤ Calculate partial of the error at output layer **** (Backward_Function)**

i) $\frac{\partial E}{\partial Y} = \text{predicted} - \text{target}$ (output layer only)

Then calculate **delta** = $\frac{\partial E}{\partial Y} * \text{predicted}(\text{output}) * (1 - \text{predicted})$

//will use to update the delta of the previous layer (the concept of the chain rule)//

ii) Each layer is affected by the error of the output layer so go backward to update weights and delta of the layer.

$$W^{new} = W^{old} - \eta \frac{\partial E}{\partial w}$$

$$\frac{\partial E}{\partial w} = \text{delta}^{next_layer} * \text{Output}^{current_layer}$$

$$\text{delta}^{current_layer} = \text{predicted}(\text{Output}^{current_layer}) * (1 - \text{predicted}) * \text{weights}^{current_layer} * \text{delta}^{next_layer}$$

Repeat till reach input layer and update its weights

Accuracy:

- Increasing number of neurals and layers accuracy decreases
Best at num_neurals of hidden layer = 60
One hidden layer only.
- Increasing learning rate accuracy decreasing best at 0.01
- Accuracy = 75.8

END