

# APIS DOCUMENTATION

[Document subtitle]



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Task: Task1\_APIs Documentation

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## 1-Dio Module:

Function name	Dio_Init()	
	Input	void
Arguments	Output	void
	Input/Output	void
Return	E_OK 0	
	E_NOK	1
Description	Initialize Dio Peripheral Registers according to configuration file.	

Function name	Dio_Write()		
		Pin number	U8
Arguments	Input	Show the number of pin to write it.	
		value	U8
		It's the va	alue written to
		pin.	
	Output	void	
	Input/Output	void	
Return	E_OK	0	
	E_NOK	1	
Description	Set Pin Mode and write value on the pin		

Function name	Dio_Read()		
		Pin number	U8
Arguments	Input	Show the to read it	number of pin 's value.
	Output	Value	Pointer to u8
	Input/Output	void	void
Return	E_OK	0	
	E_NOK	1	
Description	Read the pin value.		

## 2-Timer Module:

Function name	timer_Init()	
	Input	void
Arguments	Output	void
	Input/Output	void
Return	E_OK	0
	E_NOK	1
Description	Initialize Timer Peripheral Registers To Work As Timer	
	According To The Configuration file.	

Function name	timer_Stop()	
	Input	void
Arguments	Output	void
	Input/Output	void
Return	E_OK	0
	E_NOK	1
Description	Stop The Timer Peripheral To Stop Counting.	

Function name	timer_Start()		
		Value	U16
Arguments	Input		e the number of nds elapsed to ner flag.
	Output	void	
	Input/Output	void	
Return	E_OK	0	
	E_NOK	1	
Description	Start Timer To Count Value.		

#### 3-Pwm Module:

Function name	pwm_Init()		
		Pin number	U8
	Input	Show the	number of pin
Arguments		to use it f	or pwm.
		Initializat	U8
		ion value	
		It's the va	alue written to
		pin.	
	Output	void	
	Input/Output	void	
Return	E_OK	0	
	E_NOK	1	
Description	Initialize pin.		

Function name	pwm_Stop()		
		Pin	U8
		Number	
	Input	Show the number of pin	
Arguments		to disconnect it from pwn	
		channel.	_
	Output	void	
	Input/Output	void	
Return	E_OK	0	
	E_NOK	1	
Description	Stop PWM Channel To Disconnect Pin.		

Function name	pwm_Start()		
		Pin number	U8
Arguments		Show the number of pin to write value on it.	
		value	U8
		It's the vapin.	alue written to
	Output	void	
	Input/Output	void	
Return	E_OK	0	
	E_NOK	1	
Description	Write value on the pin.		

## 4-Motor Module:

Function name	Motor_Init()		
	Input	Array of U8 * Pin numbers	
Arguments		Show the number of pin for H bridge interface.	ıs
		Array of U8 * Pin numbers	
		Show the number of pin for pwm.	ıS
	Output	void	
	Input/Output	void	
Return	E_OK	0	
	E_NOK	1	
Description	Initialize H bridge p	Initialize H bridge pins and pwm pins.	

Function name	Motor_Start()		
		Period	U16
	Input	Number of	of milliseconds,
	Прис	the timer	counts and sets
Arguments		the flag.	
	Output	void	
	Input/Output	void	
Return	E_OK	0	
	E_NOK	1	
Description	Determining direction and speed based on state machine and time elapsed.		

Function name	Motor_Stop()		
	Input	Array of U8 * Pin numbers	
Arguments		Show the number of pins for H bridge interface.	
		Array of U8 * Pin numbers	
		Show the number of pins for pwm.	
	Output	void	
	Input/Output	void	
Return	E_OK	0	
	E_NOK	1	
Description	Clear pwm pins an	Clear pwm pins and reset H bridge pins.	

## 5-Robot Module:

Function name	Robot_Init()		
	Inout	void	
	Output	void	
	Input/Output	void	
Return	E_OK	0	
	E_NOK	1	
Description	Use Motor_Init() to Initialize Robot Motors, Pins		
	defined in configuration file.		

Function name	Robot_Update()		
Arguments	Input	Period	U16
		Number of milliseconds, the timer counts and sets the flag.	
	Output	void	
	Input/Output	void	
Return	E_OK	0	
	E_NOK	1	
Description	Use Motor_Start() to Clear pwm pins and reset H bridge pins.		

Function name	Robot_Start()	Robot_Start()		
	Inout	void		
	Output	void		
	Input/Output	void		
Return	E_OK	0		
	E_NOK	1		
Description		Put Robot in initial value, Pins defined in configuration file.		

Function name	Robot_Stop()	Robot_Stop()		
	Inout	void		
	Output	void		
	Input/Output	void		
Return	E_OK	0		
	E_NOK	1		
Description	<u>-</u>	Use Motor_Stop() to Initialize Robot Motors, Pins defined in configuration file.		

## 6-Lcd Module:

Function name	Lcd_Init()		
Arguments	Input		U8 by lcd to with Dio.
	Output	void	
	Input/Output	void	
Return	E_OK	0	
	E_NOK	1	
Description	Initialize the pins.	•	

Function name	Lcd_Display()		
Arguments	Input	Array of pins	U8
		Pins used by 1cd to interface with Dio.	
		string	U8 *
		It's the string written on	
		lcd.	
	Output	void	
	Input/Output	void	
Return	E_OK	0	
	E_NOK	1	
Description	Display string on lcd		