## 1. Bayesian Inference from Noisy Observation

(a) Finding w such that [X = x, Y = y] is equivalent to [X = x, W = w]

We are given:

$$Y = X^2 + W$$
,  $W \sim \mathcal{N}(0, 1)$ 

We want to find the value of w such that the event [X = x, Y = y] is equivalent to [X = x, W = w].

**Step 1:** Substitute X = x into the equation:

$$Y = x^2 + W \Rightarrow W = Y - x^2$$

**Step 2:** Now substitute Y = y:

$$W = y - x^2$$

**Conclusion:** The event [X = x, Y = y] is equivalent to  $[X = x, W = y - x^2]$ .

$$w = y - x^2$$

## (b) Deriving the unnormalized posterior $\pi_{X|Y=y}(x)$

We are to derive the unnormalized posterior using Bayes' Theorem:

$$\pi_{X\mid Y=y}(x) \propto \pi_X(x) \cdot p_{Y\mid X}(y\mid x)$$

**Step 1:** Prior of X: Since  $X \sim \mathcal{N}(1,1)$ ,

$$\pi_X(x) = \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{(x-1)^2}{2}\right)$$

Step 2: Likelihood  $p_{Y|X}(y\mid x)$ : Given  $Y=X^2+W$  and  $W\sim\mathcal{N}(0,1),$  then conditional on X=x,

$$Y \sim \mathcal{N}(x^2, 1) \Rightarrow p_{Y|X}(y \mid x) = \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{(y - x^2)^2}{2}\right)$$

**Step 3:** Combine prior and likelihood:

$$\pi_{X|Y=y}(x) \propto \exp\left(-\frac{(x-1)^2}{2}\right) \cdot \exp\left(-\frac{(y-x^2)^2}{2}\right)$$

$$\Rightarrow \boxed{\pi_{X|Y=y}(x) \propto \exp\left(-\frac{(x-1)^2 + (y-x^2)^2}{2}\right)}$$