# Global Features

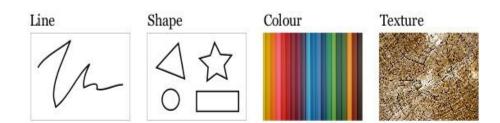
An Example:

Content-Based Image Retrieval Using Global Features



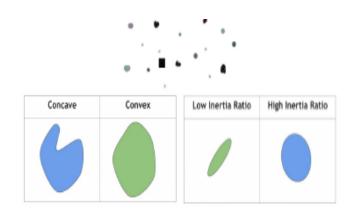
#### **Global Features**

General features that can be extracted from the whole image. Examples: color, texture and shape.

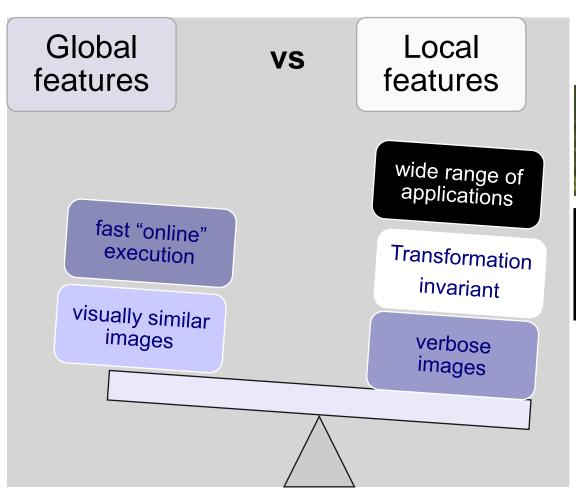


#### **Local Features**

The features extracted from localized regions within images. For examples: Blobs, edges, and corners

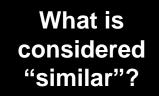








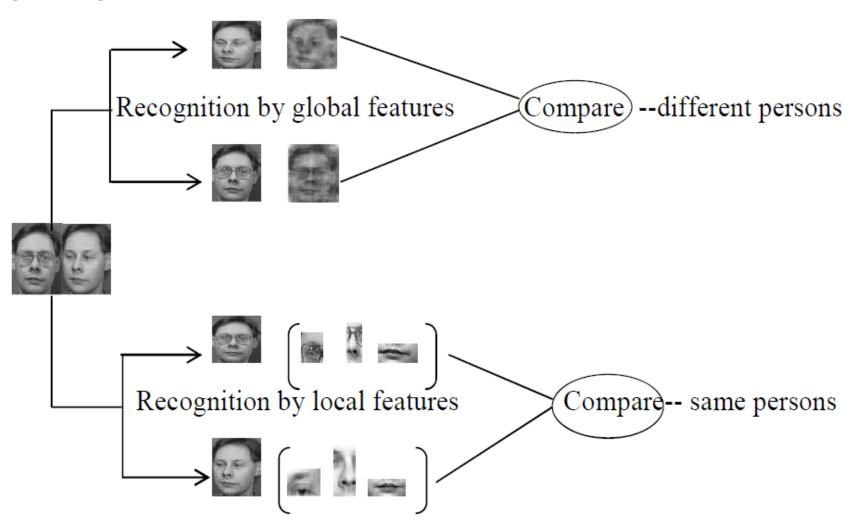






- What does the user rate as effective image retrieval?
- Local or global features?
   Depending on the application

# Different roles of global and local features in face perception





# **Content-Based Image Retrieval (CBIR)**

#### What is CBIR?

Retrieving desired images from a large collection on the basis of features (such as color, texture and shape) that can be automatically extracted from the images themselves.

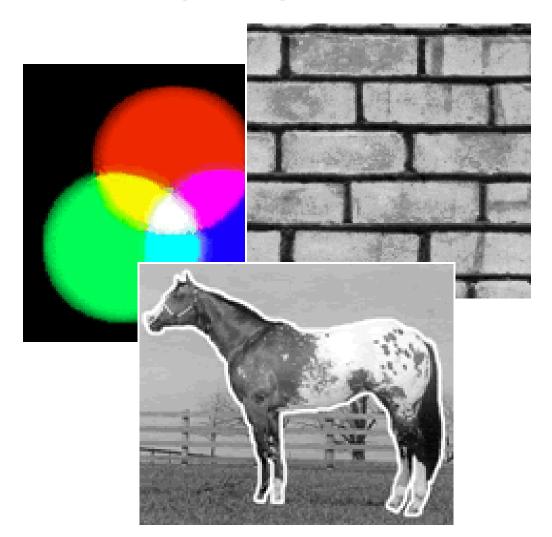
## Why we need CBIR?

- The limits of the keywords approach.
- Large amount of pictures.
- Human perception.

(Every person may have a different description to the same picture )



- □ Color
- **□** Texture
- □ Shape
- Other primitive features include
- □ Spatial location
- ☐ Pixel intensity





# **Applications of CBIR**

- □ Several application areas in which to apply contentbased image retrieval have been proposed over the years like:
  - Medical applications
  - □ Geographic information system
  - □ Criminal database
  - Picture archiving and communication systems
  - □ Fabric and fashion design
  - □ Face recognition.
  - □ Home Entertainment



# **CBIR Systems**

- ☐ There are many commercial and research CBIR systems that are available for:
  - Accessing huge image databases
  - Creating image databases
  - Applying image processing operations on images
- ☐ They Support one or more of the following options:
  - Search by example
  - Search by sketch
  - Random browsing
  - Search using keywords or text.

	EVRW	VISE	QBIC	VSEK	MARS
Interface	Excellent	Excellent	Excellent	Excellent	Good
Initial Query	Choose one, randomize	Choose one, randomize	Choose one, randomize	Choose one, sketch one, randomize	Choose one, randomize
Feature Extractions	Color,Shape, Texture, Structure	Histogram, Composition , Structure	Color, Texture, Sketch	Histogram, Composition , Texture	Color, Texture, Shape
Relevance Feedback (RF)	No	No	No	YES (3 levels)	YES (5-level weight)
Improvement from RF	N\A	N\A	N\A	A little	Not clear
Performance Without RF	Good		Good	Good	Ok



# **Problem Description**

CBIR has advantages and disadvantages with regard to the nature of image analysis and retrieval.

## **Advantages of CBIR include:**

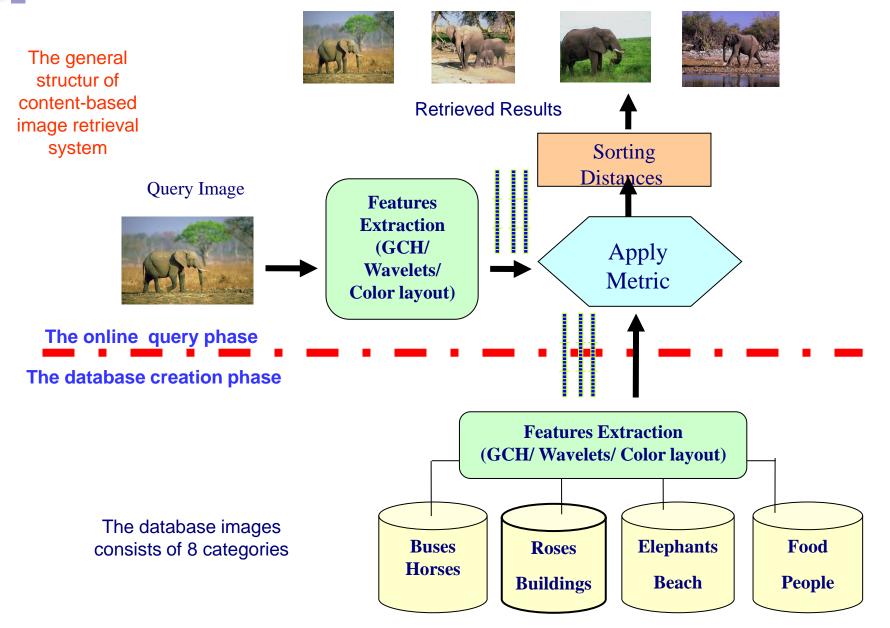
- 1) Easy to extract features from images
- 2) Able to change extracted features to other forms such as histograms
- 3) Easy to build an automatic process



## Main problems of CBIR approach include:

- 1) Hard to determine effectiveness.
- 2) Difficult to choose features for extraction and also which extraction algorithms to use.
- 3) Hard to get the semantic meaning of image from low level features (Semantic Gap).
- 4) Difficult to process a specific region in the image.
- 5) Limited markets of profit for CBIR
- 6) No standard dataset for testing and evaluating CBIR Systems

- м
  - ☐ In content-based image retrieval, image data representation and the similarity measurement are two important tasks. In addition , the use of simple features like color, shape or texture is not sufficient
  - Natural images contain both color and texture, so for better performance they should be considered together in the retrieval process
  - ☐ Using more than one representation of the images in a collection can improve the results presented to a user without changing the underlying feature extraction or search technologies.



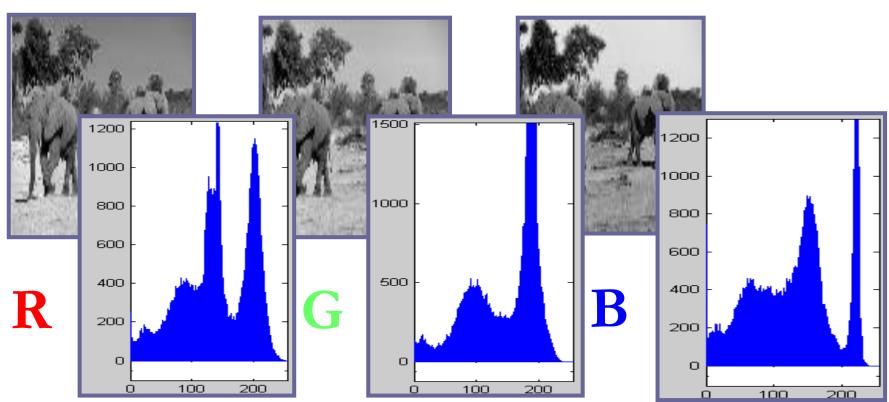
#### **Color Feature**

# **Global Color Histogram (GCH)**

**Original image** 



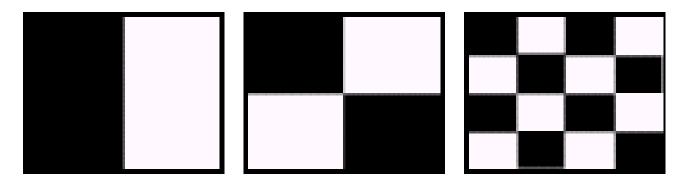
256x3





## **Color Layout Feature**

☐ Color histogram does not include any spatial information about an image and we may find images that have the same color histogram although they have different color distributions



Three images with similar color histograms but different color distributions



# **Color Layout Feature vector**

- □ The steps for creating the color layout feature vector from an image are:
  16x16x3
- 1. Divide the image into 16x16 sub-blocks.
- 2. Extract the color feature components for each sub-block (Identifying the three components *R*, *G*, and *B* for each block).
- 3. Calculate the average for each of the three components in each sub-block.
- 4. Then construct the color layout feature vector (16x16x3) that will represent the color layout feature.



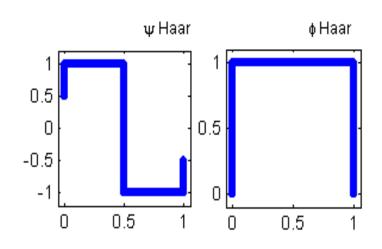
#### **Haar and Daubechies Wavelets**

Daubechies family includes the **Haar wavelet**, written as 'DB1, the simplest wavelet imaginable and certainly the earliest.

$$\phi := x \to \{ \begin{array}{cc} 0 \leq x \text{ and } x < 1 & 1 \\ otherwise & 0 \end{array}$$

$$\psi := x \rightarrow \begin{cases} 0 \le x \text{ and } x < \frac{1}{2} & 1 \\ \frac{1}{2} \le x \text{ and } x < 1 & -1 \\ otherwise & 0 \end{cases}$$

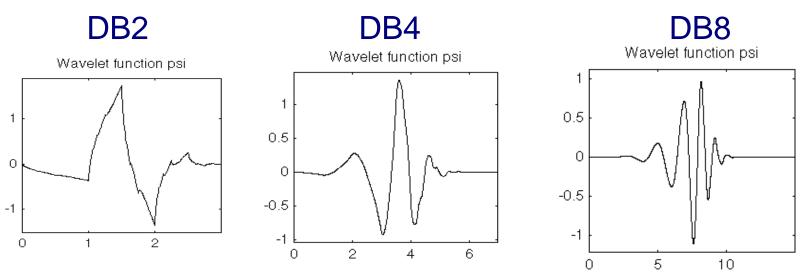
Where  $\phi$  is called the scale of the Haar wavelet and  $\psi$  is the actual wavelet



The Haar wavelet  $\psi$  and its scale function  $\Phi$ 

#### **Texture feature**

## **Haar and Daubechies Wavelets**



From left to right: the mother wavelets Daubechies DB2, DB4, and DB8

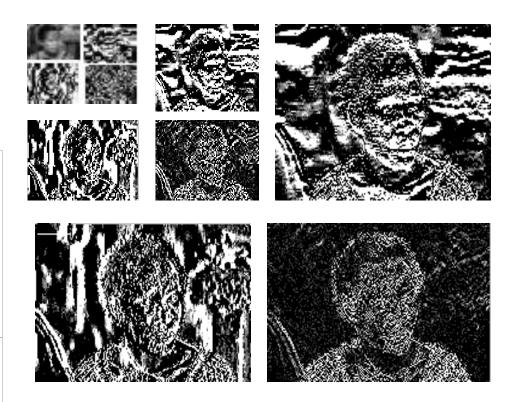
The wavelet analysis of an image gives four outputs at each level of analysis *I* (we used 3-levels), one approximation and three details: the approximation A<sub>I</sub>, horizontal details H<sub>I</sub>, vertical details V<sub>I</sub>, and diagonal details D<sub>I</sub>

#### **Texture feature**

## **Haar and Daubechies Wavelets**



<b>V</b> <sub>3</sub>	H <sub>3</sub>	H <sub>2</sub>	Horizontal Details H <sub>1</sub>
V	2	$D_2$	
Vertical Details V <sub>1</sub>			Diagonal Details D <sub>1</sub>



3 levels wavelet analysis



#### **Haar and Daubechies Wavelets**

#### ☐ Texture feature vector:

The energy of each sub-band image is calculated using the following relation:

$$E = \frac{1}{MN} \sum_{i=1}^{m} \sum_{j=1}^{n} \left| X(i,j) \right|$$
 3 sub bands

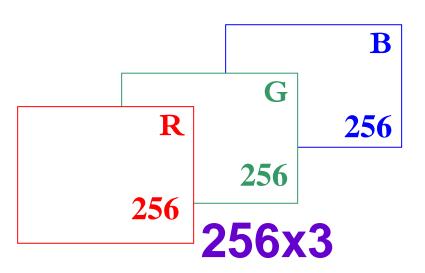
Where:

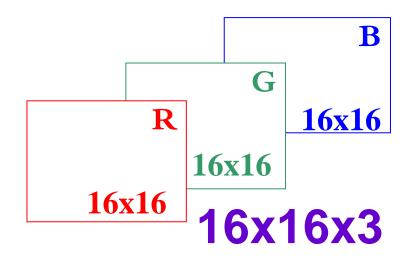
M and N: are the dimensions of the image,

X is the intensity of the pixel located at row i and column j.

### Color feature vector

## Color layout feature vector





Texture feature vector (consists of energies)

Wavelets analysis levels								
Level 1			Level 2			Level 3		
H1	V1	<b>D1</b>	H2	V2	D2	Н3	V3	D3

#### Similarity distance Measuring

## ■ Manhattan or L1 Distance

$$D_{i,k} = \sum_{j=1}^{G} \left| \frac{H_i(j)}{M_i * N_i} - \frac{H_k(j)}{M_k * N_k} \right| \qquad \begin{array}{c} \text{Distance} \\ \text{between two} \\ \text{histograms} \end{array}$$

Distance

#### Where:

 $H_i(j)$  denote the histogram value for the  $i^{th}$  image, j is one of the G possible gray levels,

 $M_i * N_i$  is the number of pixels in an image i,

 $M_k * N_k$  is the number of pixels in image k, and M is the number of rows and N is the number of columns.

$$D^{C} = 0.299*D^{C}(R) + 0.587*D^{C}(G) + 0.114*D^{C}(B)$$



#### ☐ Euclidean Distance

■ Euclidean Distance measure:

$$D_i^{CL} = \sqrt{\sum_{s=1}^{S} (M_s - N_{s,i})^2}$$
 Texture & Color layout

Where:

 $D_i^{CL}$  is the length of the color layout feature vector.

In the Euclidean distance between the query image feature vector M and M is the feature vector of the ith database image.

 $N_i$  is the feature vector of the  $i^{th}$  database image.

$$D^{CL} = 0.299 * D^{CL}(R) + 0.587 * D^{CL}(G) + 0.114 * D^{CL}(B)$$





**Animals** 





**Beach** 





Food







**Buses** 





**Horses** 





**Roses** 





People

**Buildings** 

The test database downloaded from: http://wang.ist.psu.edu/~jwang/test1.tar



## **Performance Evaluation**

The Methods used to measure the performance of content-based image retrieval systems include:

- Precision and Recall

$$\Pr ecision = \frac{r}{N} \qquad \qquad \operatorname{Re} call = \frac{r}{R}$$

Where  ${\bf r}$  is the no. of relevant retrieved images,  ${\bf N}$  total number of retrieved images, and  ${\bf R}$  is the no. of relevant images in the database

- Before after comparison
- Rank of the best match
- Retrieval Accuracy and Noise Graphs



## **Performance Evaluation**

☐ Retrieval Accuracy:

The ratio between the number of relevant (belongs to the same category) retrieved images and the total number of retrieved image

Retrieval Accuracy =  $\frac{\text{No. of relevant retrieved images}}{\text{Total No. of retrieved images}}$ 

Sometimes known as a single precision

☐ Retrieval Accuracy and Noise Graphs

### **GCH** alone



#### The combination of GCH and Haar wavelet



# The combination of GCH and Haar wavelet when adding the color layout

