Utilizing SCADA-Log Data to Improve Normal Behavior Models for Wind Turbine Condition Monitoring

Vorgelegt von

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Eidesstattliche Versicherung

Hiermit erkläre ich, dass ich die vorliegende Arbeit selbstständig und eigenhändig sowie ohne unerlaubte fremde Hilfe und ausschließlich unter Verwendung der aufgeführten Quellen und Hilfsmittel angefertigt habe.

Berlin, den 01. Mai 2023   ....

Mohamed Samy ELSISI

Abstract

English version of the German "Zusammenfassung".

Zusammenfassung

Deutsche Version des Englischen "Abstracts".

Contents

Introduction

Contents

1.1   Background

In 2020, renewable energy represented 22.1% of energy consumed in the EU [European Commission 2023a]. This percentage is expected to increase drastically in the upcoming years with the target, set by the European Commission, of at least 32% by the year 2030 [European Commission 2023b]. With the increasing number of renewable energy assets being deployed every year, automated condition monitoring solutions are needed for operators to be able to scale up. This need gets more relevant in the case of operating offshore wind farms, where the cost of maintenance relative to the levelized cost of energy (LCOE) is significantly higher compared with onshore [Tautz-Weinert 2017]. Several approaches for condition monitoring were developed in the recent years that use SCADA1 data given its low cost (normally requiring no additional sensors). One of the methods used for condition monitoring using SCADA data is Normal Behavior Modelling (NBM). NBM uses the idea of detecting anomalies from normal operation by empirically modelling a measured parameter, used to reflect the condition of a specific part of the turbine, based on a training phase (usually during a healthy state of the turbine). During operation, the difference between the measured and the modelled/predicted signal is used as indicator for a possible fault. A difference of 0, with some tolerance, reflects normal conditions, whereas a difference greater or less than 0 reflects changed conditions or failures [Tautz-Weinert 2017].

1.2   Motivation

While NBMs using SCADA data were proven capable of predicting failures [Tautz-Weinert 2017], they are treated as black box by the operators since they don't provide any insights regarding the root cause of the failure. Incorporating SCADA log data2 to NBM could help tackle this problem by providing some insights to an anomaly detected by the model in case a relevant warning or failure

message was logged by the SCADA system around the same time. It was also shown that incorporating SCADA logs containing information about operation conditions or control events could help improve the accuracy of the model in case of events unexplainable by the input signals [Letzgus 2020].//

Logs were "Never" treated as input feature in NBMs

State of the art

Contents

NBM// What was done in the topic of logs?

2.1 Standalone Chapter or better as part of the introduction?

Methods

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3.1 Dataset

In this section, we will describe the dataset used in this work to train, test and validate the models.

We used open-source data published on the [EDP 2018] *OpenData* web platform and made available for research purposes. The data was collected from the SCADA systems of five different Vestas wind turbines (Turbine 01, 06, 07, 09 and 11) in the same wind park between the years 2016 and 2017 and is made up of the following four subsets: *Signals, Logs, Failures and Metmast*. We will, however, only describe three sets since *Metmast* was not used in this work.

Type of signal	Signals
Average temperature (°C)	Generator, Generator bearings, Hydraulic group oil, Gearbox oil, Gearbox bearing on the high-speed shaft, Nacelle, HV transformer, Ambient temperature,..
Average production value	Active power (Wh), Reactive power (VArh), Power according to grid (kW),..

Table 3.1: Sample signals found in the Signals dataset

Type of log event	Sample log event
Alarm log	*"High temperature brake disc"* *"High pres offlin:____RPM/ ___°C"*
Warning log	*"Yaw Position is changed: __°"* *"Low Battery Nacelle"*
Operation and System log	*"External power ref.:_____kW"* *"GearoilCooler _ , gear: ___°C"*

Table 3.2: Sample log events found in the Logs dataset

3.1.1 Signals

The *Signals* dataset contains 10-min-averaged data collected from the wind turbines' sensors installed at the major components (e.g., gearbox, generator, transformer,..) and power meters to measure temperatures, angles, wind and rotational speeds, power production,... This dataset was the most crucial for this work since it provides information that reflects the status of the turbine operation which is needed to perform automated condition monitoring and predictive maintenance.
Table 3.1 shows a sample of the 81 signals included in this dataset.

3.1.2 Logs

In this dataset, events logged by the SCADA system are collected in non-fixed intervals. The events recorded by the system are divided into three categories: Alarm log, Warning log and Operation and System log. According to the VestasOnline Enterprise user manual [Vestas 2016], alarms are system notifications that alert operators to an error scenario that has forced a wind turbine to cease normal operation and transition to one of three operational states: Pause, Stop, or Emergency (one of the following three acknowledgments is needed to resume operation: Local acknowledgment from the controller unit of the turbine, Remote acknowledgment from VestasOnline®, or Automatic acknowledgment), whereas warnings are system messages that indicate an irregularity that requires attention but does not cause the turbine to immediately cease normal operation and exit the Run state.

3.1.3 Failures

The Failures dataset contains the history of failures, inspections, or maintenance that occurred in the turbines and was manually recorded by technicians. Each record reports the time of the event, component (e.g., Generator, Hydraulic group,..), and a text description of the failure or event (e.g., "Generator replaced", "Oil leakage in Hub",..).

This dataset was used in backtesting to validate the models' capability of detecting failures early.

3.2 Machine learning models

In this section, we will demonstrate the architecture of the machine learning models used in our experiments.

3.2.1 Linear regression

Sir Francis Galton proposed the idea of linear regression in 1894 [Galton 1894]. Linear regression is used for analyzing the linear relationship between one or more independent variables (X) and a dependent variable (Y). The dependent variable Y must be continuous, whereas the independent variables can be continuous or categorical.

When the relationship between the dependent variable and the independent variables is assumed to be linear and there are a small number of independent variables, linear regression is usually used. Linear regression is easy to use and understand, and it can be used to make predictions or find relationships between variables.

In the example of normal behavior modeling for a wind turbine component, the dependent variable can be defined as the component's temperature and the independent variables as a set of weather and turbine conditions measures (e.g., wind speed, ambient temperature, production value, other components' temperatures,..) that have either a direct or indirect effect on the target component.

The way the independent variables are chosen is usually done by measuring the correlation coefficients between available features in a dataset and the target feature and then selecting the features having a high correlation coefficient. Depending on the problem setting, other features can be also considered based on domain knowledge, especially when dealing with a mechanical system as in the case of this work. A good example of this would be the incorporation of the ambient temperature measurement as an input feature—even if it does not highly correlate with the target feature—to make sure that your model generalizes when trying to predict a component's temperature throughout the year, by considering the effect of seasonality (temperatures are expected to be higher in summer than in winter).

In this work, we selected input features based on both domain knowledge and correlation coefficients. We used Kendall's method to measure the rank correlation [Kendall 1938]. In contrast to Pearson's correlation coefficient, Kendall's rank cor-
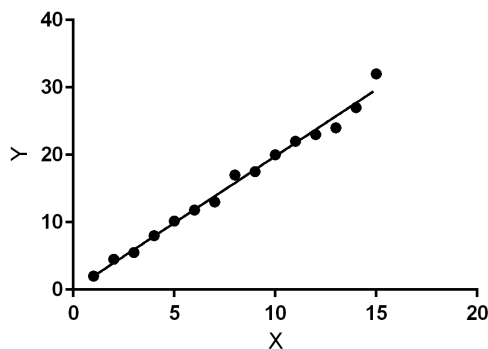
Figure 3.1: Example linear regression

relation can capture both linear and non-linear dependency between two variables by measuring the monotonic relationship. In addition to that, variables don't have to be normally distributed when using Kendall's method.

3.2.2   Deep learning

Although multiple linear regression models are capable of fitting the data with high accuracy in many applications (e.g., [Wang 2019]), they are, by definition, not capable of capturing more complex non-linear dependencies. In addition to that, linear regression may not be appropriate when there are a significant number of independent variables. Deep learning may be a better approach in these situations. After obtaining better results with it (see Experiment 4.1), we decided to train the normal behavior models on a feed-forward neural network (for a comprehensive review of deep learning and neural networks, see [Schmidhuber 2014]) having the architecture shown in Fig. 3.2.
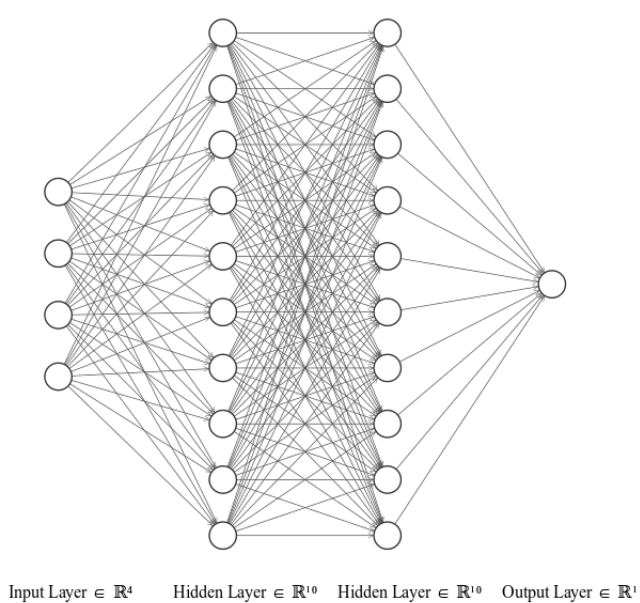
Figure 3.2: Architecture of normal behavior neural network model used in this work. *P.S.: The input layer shape will vary based on the experiment and the number of input features.*

3.3   Log analysis

In this section, we will describe the different approaches we propose to utilize SCADA log messages and incorporate them into normal behavior models. In summary, we introduce three different ways for utilizing SCADA log messages: Extracting input features for normal behavior models, Data filtering, and Visualization of warnings. We will explain each approach in depth.

3.3.1   Extracting input features

Most machine-learning architectures can only work with vector-shaped numerical inputs. Given that there are limited resources in the research field on how to generate numerical vectors from wind turbine SCADA system logs (see chapter 2), we came up with two methods that were proven capable of not only generating input features for machine-learning normal behavior models but also improving their accuracy (see chapter 4): 1. our Novel method based on domain knowledge and 2. Utilizing an open-source framework for analyzing log data called LogPAI. We will discuss each method in detail.

3.3.1.1   Novel method

Background:
We scanned through the different log messages available in the dataset looking for information that reflects the turbine state and might help the normal behavior model fit the data more accurately. Since normal behavior models monitor the state of a component by monitoring its temperature, we narrowed the search down to operation and system logs that reflect events causing a change of temperature in major components. We, then, ended up with a category of logs that shows the states of internal or external ventilators of some components (see table 3.3). Being parts of the cooling systems of major components, fans or ventilators must affect the component's temperature.

Log text template	Log text sample
Gen. ext. vent. _, temp:___°C	Gen. ext. vent. 2, temp:65°C
Gen. int. vent. _, temp:___°C	Gen. int. vent. 1, temp:50°C
HV Trafo. vent. _, temp:___°C	HV Trafo. vent. 0, temp:2°C
Nac.vent._, nac/gear:___/___°C	Nac.vent.3, nac/gear:43/ 54°C

Table 3.3: Example log text templates with sample texts

Indeed, our analysis showed a clear relationship between the state of a ventilator and the temperature of its turbine component. As shown in Fig. 3.3, at low temperatures of the generator bearings, the internal ventilator will switch off. The bearings will then heat up which, in turn, causes the ventilator to turn on which cools the bearings down, and so on. . .
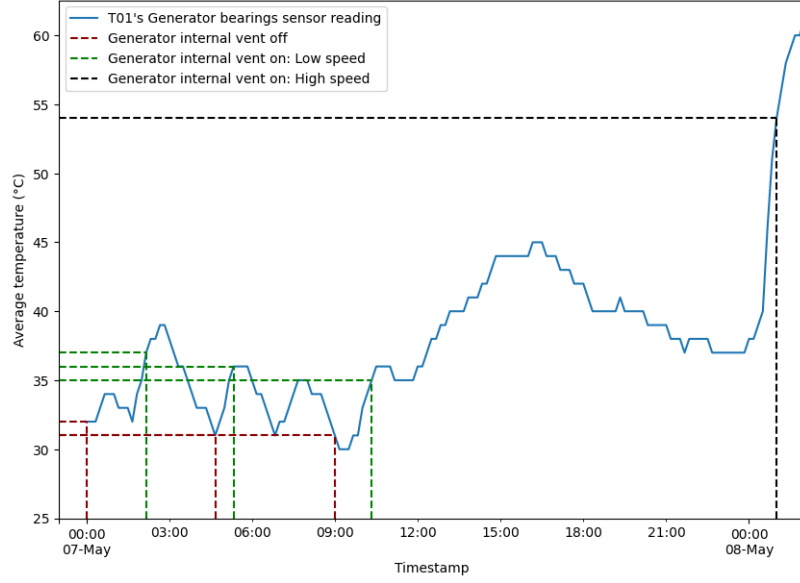
Figure 3.3: Generator internal vent control signals and their effect on the generator bearings temperature

Method:
Analyzing the log texts of interest (e.g., *Gen. ext. vent. 2, temp:65°C*), we deduce that they provide three pieces of information: 1. Description of the ventilator (e.g., *Gen. ext. vent.*), 2. State of the ventilator (*0, 1, 2 or 3*), 3. Temperature of the turbine component the ventilator is installed in (e.g., *65°C*).

Since the component temperature is regularly provided as a SCADA signal, we decided to focus on the other two parts of the log messages. Our method simply filters log messages containing the word "vent." and creates a new feature for every ventilator (1.) found in the data having its state (2.) as a value.
In contrast to the signals data fixed rate of occurrence (10 min), the generated log feature has an inconsistent frequency (the SCADA system creates a new log entry only when a ventilator changes states). We join both datasets by taking the value of the last occurrence in the log feature vector within a 10-min window relative to a signal reading. Gaps in the log feature columns in the resulting dataset are then filled by propagating the last valid observation forward to the next valid (a ventilator has the same state as long as it hasn't changed).
Measuring the Kendall correlation factor between the generated log features and all the signals of the turbines, we found that for every temperature signal, there is at least one log feature that, on average, highly correlates ($Rank > 0.5$) with it.
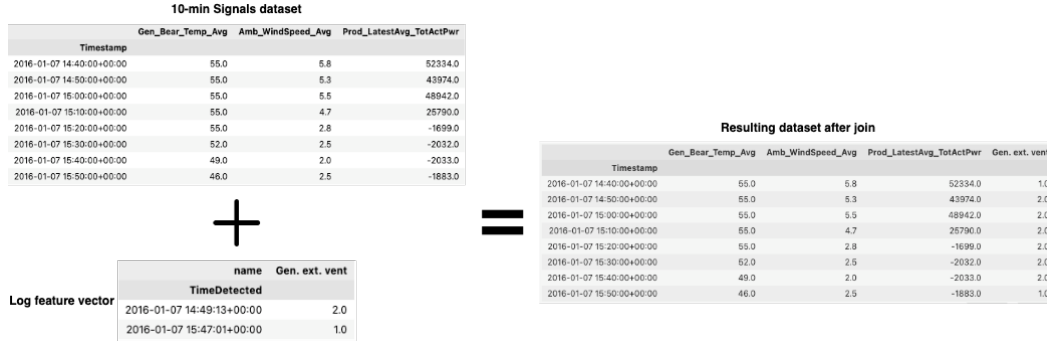
Figure 3.4: Demonstration of the join operation between the signals 10-min dataset and a log feature vector

3.3.1.2   Utilizing LogPAI

LogPAI (Log Analysis and Intelligence) is a study project and open-source platform for analyzing and managing log data [Lyu 2019]. Tsinghua University researchers started the project, which focuses on developing efficient algorithms and tools for log analysis, anomaly detection, and log data visualization. LogPAI includes a complete suite of log analysis and processing tools such as Logparser, Loglizer, and Logreduce. These applications can assist users in preprocessing and parsing raw log data, detecting anomalies and patterns, and summarizing log data concisely and understandably. We decided to utilize LogPAI's Logparser ([Zhu 2018], [He 2016a]) and Loglizer ([He 2016b]) to respectively parse and create numerical features from SCADA logs in a more generic and automated way.

Preprocessing using Logparser:
From the list of parsers available in the toolkit, we decided to use Drain [He 2017] given that it is an online parser, which means it can process the SCADA logs in real-time as they are generated. The Drain algorithm groups similar log messages together and extracts structured events from them using a clustering-based approach. The research demonstrates that Drain is very good at dealing with enormous amounts of log data and extracting meaningful events from noisy and diverse log data. Several phases are involved in the Drain algorithm, including log parsing, log message clustering, and event extraction. Drain employs a fixed-depth tree to parse log messages into a set of log keys and their related values during the log parsing stage. The log keys are unique identifiers for each type of log message, whereas the log values are the specific information connected with each log message. Drain uses a similarity measure to compare the log keys and values of each log message and allocates them to the best appropriate cluster based on their similarity scores during the log message clustering stage. Drain creates a template for each cluster that summarizes the relevant information contained in the log

messages once the log messages have been clustered. Overall, the Drain algorithm makes an important contribution to log data analysis and management by providing a scalable and effective approach for extracting structured events from unstructured log data. Applying Drain on the SCADA log data in hand by specifying its log format "$<TimeDetected>,<TimeReset>,<UnitTitle>,<Content>,<UnitTitleDestination>$", we get output structured log data (see Fig. 3.5 for an example) that the Loglizer can process to generate numerical features.

Figure 3.5: Sample raw logs and their corresponding structured logs after being parsed by Drain

Creating numerical features using Loglizer:

Loglizer's *Feature Extraction* component supports various feature extraction techniques, such as Bag-of-Words, TF-IDF, and Word2Vec, to capture the essential information contained in log data. We utilized the Loglizer feature extractor, using TF-IDF [Sparck Jones 1972] for term weighting, to generate numerical features from the parsed logs' *Event IDs*.

3.3.2 Data labeling and filtering

In this approach, we developed a method to improve SCADA-data-driven wind turbine power curve models (for a comprehensive review of the various modeling techniques used to predict the power output of wind turbines and their applications in wind-based energy systems, see [Sohoni 2016]). We start by extracting the log messages that report the current state of operation; namely logs containing one of the following expressions:

- *"Run"*,

- *"(Stop|Pause).*kW.*RPM"*, or

- *"new SERVICE state"*

The SCADA signals are then merged with the extracted log messages, using the same join strategy described in 3.3.1.1, and labeled based on the following logic:

- Turbine's state of operation = *"Run"*, if the log feature contains the expression *"Run"* or *"new SERVICE state: 1"*

- Turbine's state of operation = *"Stop"*, if the log feature contains the expression *"(Stop|Pause).*kW.*RPM"* or *"new SERVICE state: 0"*
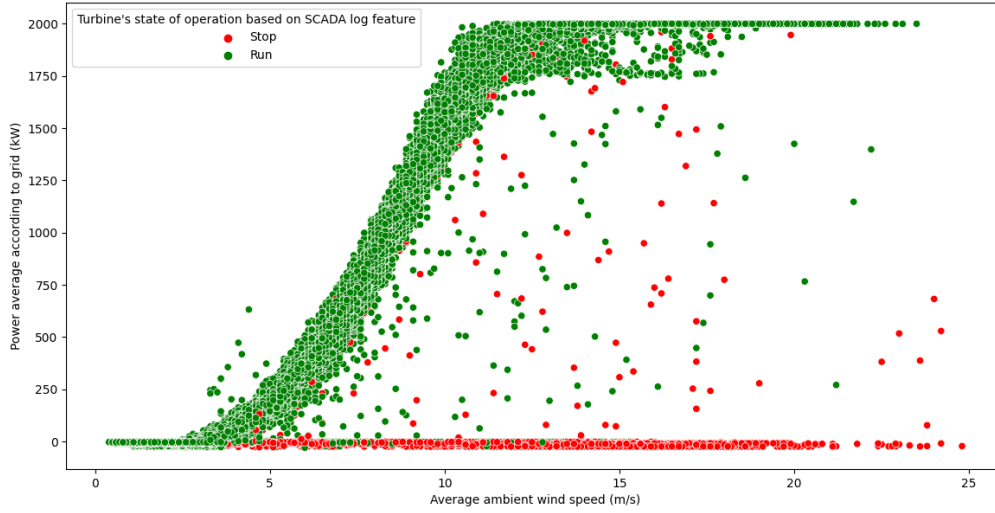

Figure 3.6: T01 power curve with log-feature-based labels

The log-based feature we introduced showed a clear improvement in the accuracy of power curve models (see experiment..TODO) when used to filter the data being input to the normal behavior model (using data points having *"Run"* as the state of operation exclusively).

3.3.3   Visualization of warnings

Here, we introduced a straightforward yet effective way of visualizing (e.g., on an operation dashboard) messages from the Alarm and Warning logs that are relevant to faults detected or predicted by normal behavior models and that are worth being reported to the operators.

When the normal behavior model detects a fault in a certain turbine component, the SCADA logs are queried for messages reporting high temperatures in this component during the same time window (e.g., last hour, last 12 hours, current day,. . .). If found, these messages could be included in the system reports that get sent to the operators to inform them of the detected failure. This gives more visibility and credibility to the detected/predicted failure by the system.

(TODO add graph showing an example)

3.4   Anomaly detection

3.4.1   Background

The main idea behind training and improving normal behavior models is to allow our models to detect anomalies more accurately. An anomaly is defined as an occurrence or observation that differs from what is expected, usual, or typical. An anomaly is commonly referred to as an outlier or an uncommon trend in data in numerous domains such as statistics, data analysis, and security. By comparing the observed data to a reference set, such as historical data or a pre-defined model, anomalies can be found. Positive and negative anomalies are also possible. Depending on the context, positive anomalies could suggest that something is performing better than predicted and negative anomalies indicate that something is underperforming (e.g., in the context of a company's sales figures), or the other way around. In the context of wind turbine condition monitoring and when mainly monitoring temperatures of the system, we focus on positive anomalies because a component that is overheating—due to wear and tear, oil leakage, faulty fan,... —is likely to fail. There is, however, no unified method in the research field to identify a data point as an anomaly. Brandao et al. ([Brandao 2010], [Brandao 2015]) used a fixed value of the mean absolute error as an anomaly threshold in their gearbox and generator fault detection model, even though this number was particular and no longer valid following maintenance procedures. Schlechtingen and Santos [Schlechtingen 2011] used daily average prediction errors in generator bearings temperature to trigger alarms. Zhang and Wang [Zhang 2014] used a hard threshold of 1.5°C for the residual to identify anomalies in the main shaft rear bearing temperature. Bangalore and Tjernberg ([Bangalore 2015], [Bangalore 2013b], [Bangalore 2013a]) used a Mahalanobis distance to compare residual and target distributions from the training period to find anomalies in gearbox bearings temperatures. The Mahalanobis distance was averaged over three days and compared to a training result-defined threshold.

3.4.2   Method

As there is no standard way to identify anomalies in temperatures in the context of condition monitoring for wind turbines using normal behavior models, we experimented with several methods to do that and, finally, decided to set the anomaly threshold to the maximum prediction error seen in the training period. This way it is guaranteed that the normal behavior models will not label any data point in the training dataset as an anomaly (complying with the assumption that the turbine was operating in a healthy state during the training phase of the model) while having the threshold dynamically set based on the setup (e.g., input and output features, training period, condition of the turbine during the training phase,...) without having to incorporate any domain knowledge related to the specific component to-be-monitored. This also helped better compare different architectures of normal behavior models and the effect of incorporating the proposed log features, not only in terms of prediction accuracy but also in terms of the quality and frequency of

anomalies identified (a model that better fits the training data will have a tighter anomaly threshold).

3.4.3   Alarms

In our approach, we differentiate between *Anomalies* and *Alarms*. An anomaly is a data point that deviates from "normal", whereas an alarm is a proactive way of communication that gets triggered when the operator's attention is urgently needed. The reason why we propose not to send an alarm every time an anomaly is found by the system is that we want our system to limit the number of false alarms as they are costly and counterproductive.

As opposed to anomalies, which are tracked on a 10-min basis, we base alarms on daily events. If the number of anomalies found from the start of a day up until a given point in time exceeds a certain threshold, an alarm is triggered. We set the *alarm threshold* to the 99th percentile of the distribution of the number of anomalies that occurred per day during the training period when using an *anomaly threshold* set as the 99th percentile of the distribution of the training prediction errors. To summarize, an alarm can be defined as an anomaly in the number of system anomalies found per day.

(TODO: Maybe soma visualization is needed here?)

3.5   Summary

TODO: PUSH TO THE TOP// Diagram of all methods put together: ML model + log feature + Anomaly detection + Alarms,...

Experiments

Contents

4.1 Experiment I: Benchmark

4.1.1 Research question

The aim of this experiment is to test the ability of NBM, as defined in the literature, to early-detect failures of a faulty turbine using the ERP dataset. The final model architecture that we pick after running this experiment will serve as a baseline model used as a benchmark in the later experiments.

4.1.2 Setup

The following elements were used in this experiment:

- **Machine learning models:** Linear regression (baseline) and feed-forward neural network

- **Target wind turbine:** T09

- **Dataset:** Training/healthy period: 01/01/2016 - 15/02/2016, Testing/faulty period: 16/02/2016 - 18/10/2016

- **Input features:** Nac_Temp_Avg, Amb_Temp_Avg, Gen_RPM_Avg, Prod_LatestAvg_TotActPwr (or use verbose names of signals: the average temperature in the nacelle, average ambient temperature, average generator rpm, total active power)

- **Target feature:** Gen_Bear_Temp_Avg (Average temperature in generator bearing 1 (Non-Drive End))

- **Recorded failure:** *"Generator bearings replaced on October 17, 2016, 9:19 AM"*

- **Logs used:** None

4.1.3   Results

According to the results documented in 4.2, we conclude that both NBMs are capable of predicting the failure in the monitored part. We will, however, use only the feed-forward network model as a benchmark since it outperformed the linear regression model.

Comparison metric	Measure for linear regression	Measure for feed-forward network
RMSE		
First-detected anomaly timestamp		
Number of anomalies detected		

Table 4.1: Experiment I results: Metrics used to compare between the benchmark models

4.2   Experiment II: Incorporating log features into NBM applied on healthy turbine

4.2.1   Research question

The aim of this experiment is to quantitatively (RMSE) and qualitatively (number of false alarms) measure the effect of incorporating SCADA-log-based features into the benchmark NBM.

4.2.2   Setup

The following elements were used in this experiment:

- **Machine learning models:** Feed-forward neural network with single target features and Feed-forward neural network with multiple target features

- **Target wind turbine:** T01

- **Dataset:** Training/healthy period: 01/09/2016 - 31/12/2016, Testing period: 01/01/2017 - 31/12/2017

- **Input features (SCADA signals):** Nac_Temp_Avg, Amb_Temp_Avg, Gen_RPM_Avg, Prod_LatestAvg_TotActPwr (or use verbose names of signals: the average temperature in the nacelle, average ambient temperature, average generator rpm, total active power)

- **SCADA-log-based input features:** Operation and System log messages containing the word "vent", which resulted in four different features extracted from the following components: Generator external vent, Generator internal vent, High-voltage transformer vent, and Nacelle vent

- **Target feature for single-output model:** Gen_Bear_Temp_Avg (Average temperature in generator bearing 1 (Non-Drive End))

- **Target features for multiple-output model:** All signals whose names contain the keywords "Gen" and "Temp": 'Gen_Bear_Temp_Avg', 'Gen_Phase1_Temp_Avg', 'Gen_Phase2_Temp_Avg', 'Gen_Phase3_Temp_Avg', 'Gen_SlipRing_Temp_Avg', 'Gen_Bear2_Temp_Avg'

- **Recorded failure:** No generator-related recorded failures (hence the assumption that the turbine is healthy)

4.2.3 Results

According to the results documented in 4.2, we conclude that both NBMs are capable of predicting the failure in the monitored part. We will, however, use only the feed-forward network model as a benchmark since it outperformed the linear regression model.

Comparison metric	Measure for linear regression	Measure for feed-forward network
RMSE		
First-detected anomaly timestamp		
Number of anomalies detected		

Table 4.2: Experiment I results: Metrics used to compare between the benchmark models

Conclusions

Appendix I

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