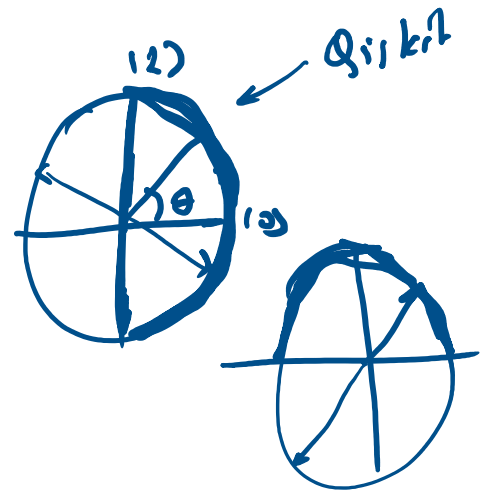


$$\begin{pmatrix} a \\ b \end{pmatrix} \in \mathbb{R}^2$$

$|0\rangle$

$\frac{\theta}{T} |0\rangle$
global phase

$$(a|b) \quad a^2 + b^2 = 1 \quad \frac{\theta}{T} \rightarrow \begin{pmatrix} \cos \theta \\ \sin \theta \end{pmatrix} \in \mathbb{R}^2$$



$$\begin{pmatrix} c_1 \\ c_2 \end{pmatrix} \in \mathbb{C}^2$$

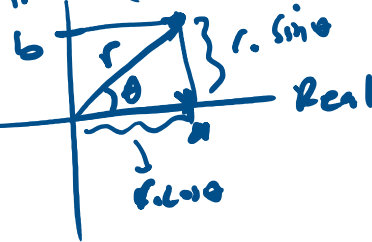
$$\underline{\underline{|c_1|^2 + |c_2|^2 = 1}}$$

$$\begin{pmatrix} a+bi \\ c+di \end{pmatrix} \in \mathbb{C}^2$$

$$\Rightarrow \text{imag} (a+bi)|0\rangle + (c+di)|1\rangle$$

$$(a, b, c, d)$$

$$(a, b) \rightarrow (r, \theta) \Rightarrow r \cdot e^{i\theta}$$



$$\begin{aligned} a+bi &= r \cos \theta + r \sin \theta i \\ &= r (\cos \theta + i \sin \theta) \end{aligned}$$

Euler form
 $\leftarrow r \cdot e^{i\theta}$

$$(a+bi)|0\rangle + (c+di)|1\rangle$$

$$\begin{pmatrix} a+bi \\ c+di \end{pmatrix}$$

$$r_1 \cdot \cancel{e^{i\theta_1}} |0\rangle + r_2 e^{i\theta_2} |1\rangle$$

$$|e^{i\theta}|^2 = 1,$$

↓

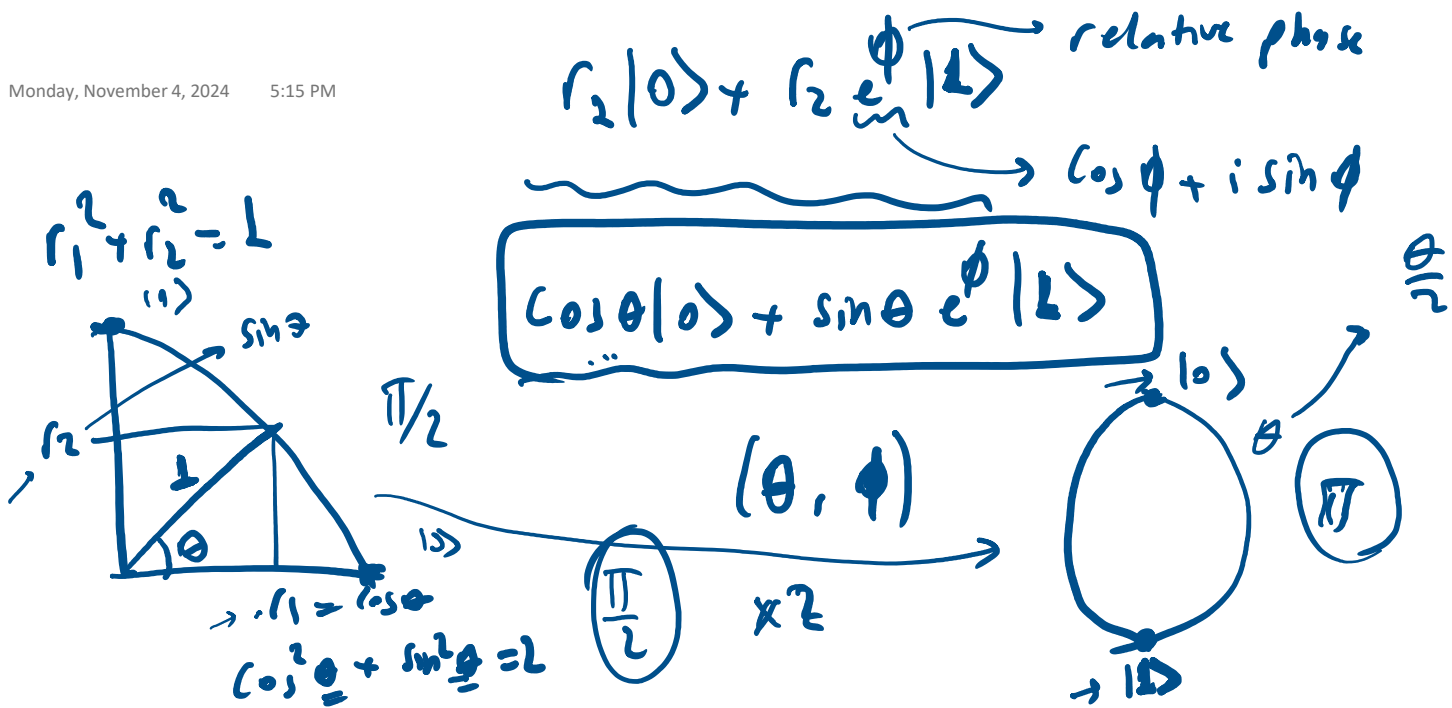
$$r_1^2 + r_2^2 = 1$$

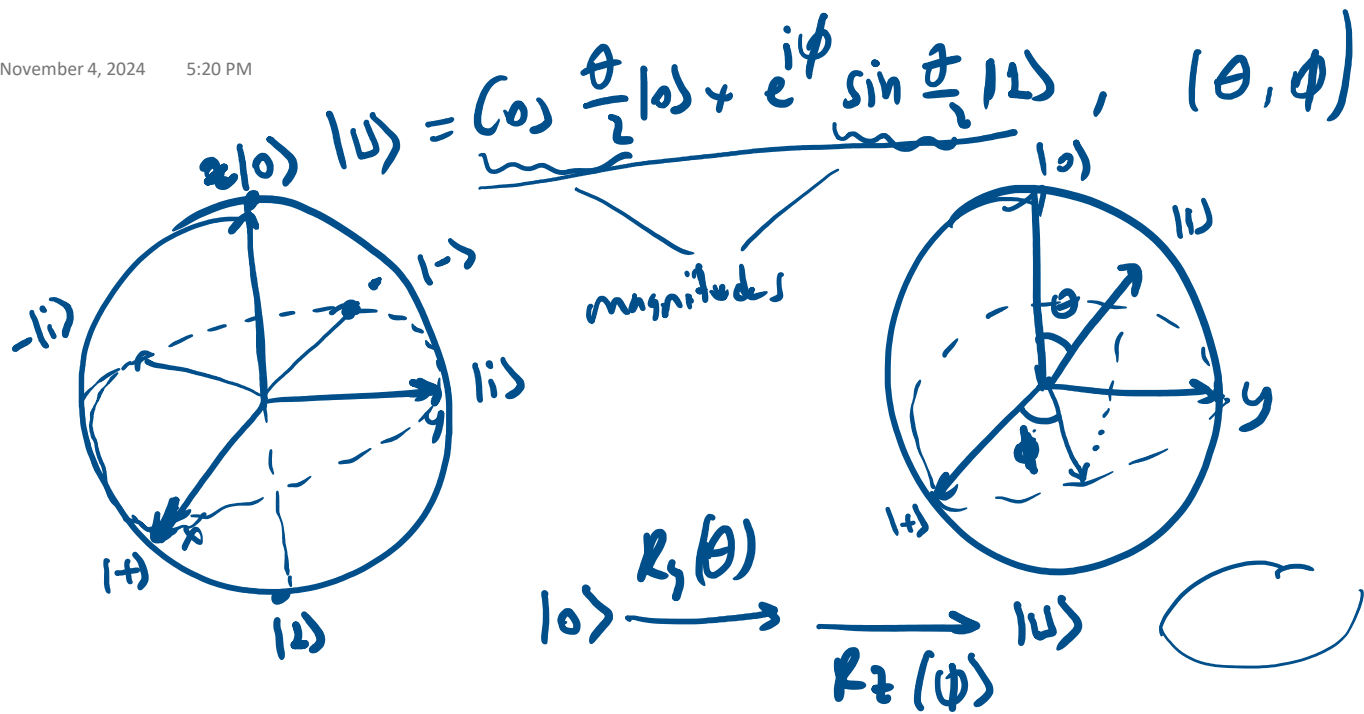
$$0 \leq r_1, r_2 \leq 1$$

Keep the amplitude of $|0\rangle$ always only real (remove imaginary part).

$$\cancel{e^{i\theta_1}} \left(r_1 |0\rangle + r_2 \frac{e^{i\theta_2}}{\cancel{e^{i\theta_1}}} |1\rangle \right)$$

$\underbrace{e^{i(\theta_2 - \theta_1)}}_{\text{relative phase}} = e^{i\phi}$







Pauli matrices = $\{X, Y, Z, I\}$

$R_Y(\theta)$
 $R_X(\theta)$
 $R_Z(\theta)$

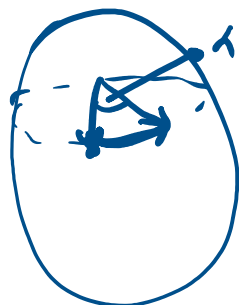
rotations with angle θ

$$X = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

$$Y = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}$$

$$Z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$R_z(\alpha) = \begin{pmatrix} e^{i\frac{\alpha}{2}} & 0 \\ 0 & e^{-i\frac{\alpha}{2}} \end{pmatrix} = e^{-i\frac{\alpha}{2}} \begin{pmatrix} 1 & 0 \\ 0 & e^{i\alpha} \end{pmatrix} \cdot \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} \quad (b)$$



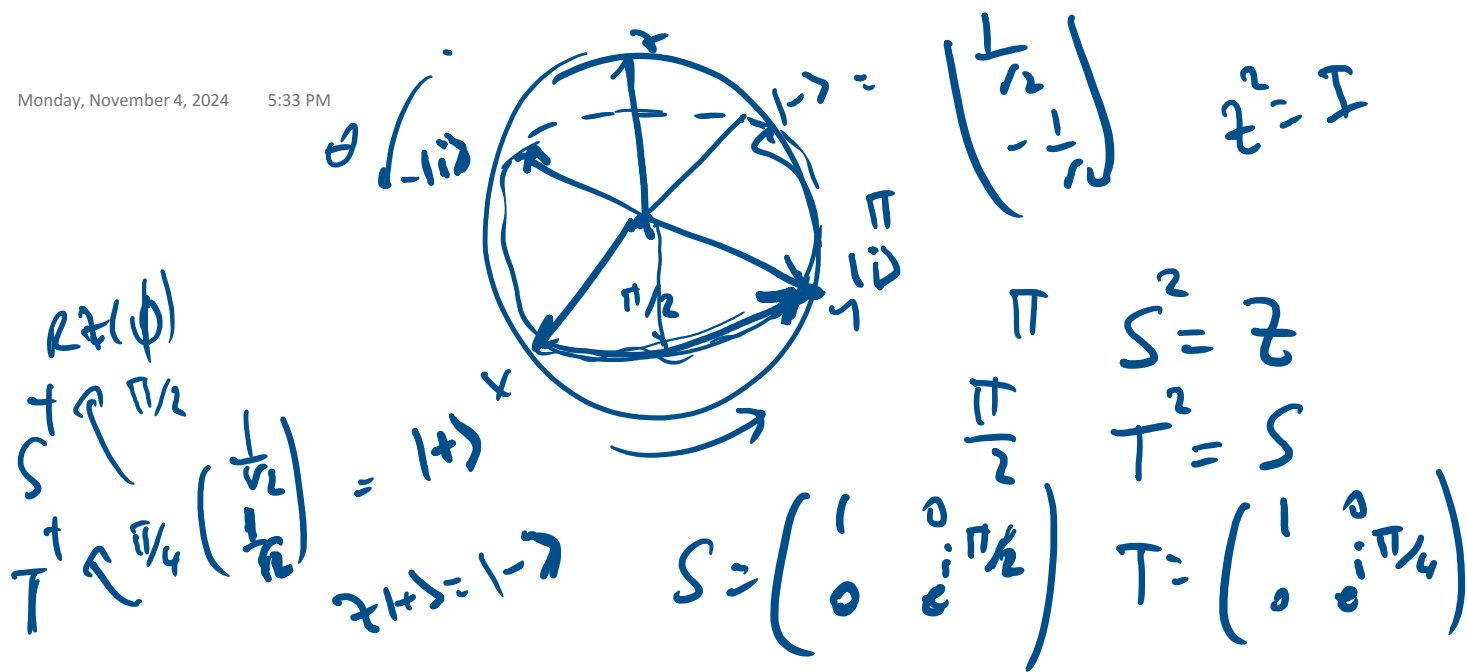
$$z = R_z(\pi)$$

$$= \begin{pmatrix} 1 & 0 \\ 0 & e^{i\pi} \end{pmatrix}$$

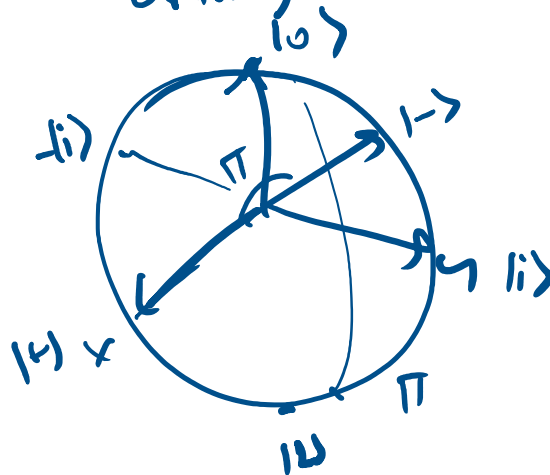
$$\begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$\cos \theta + i \sin \theta$$



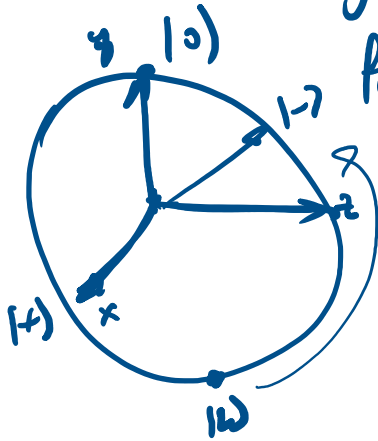
Orthogonality on the Bloch sphere



$$\text{Hadamard} \equiv H$$

90° rotation around y -axis

followed by a 180° rotation around the x -axis



$$U_3(\theta, \phi, \lambda) = \begin{pmatrix} \cos \frac{\theta}{2} & -e^{i\lambda} \sin \frac{\theta}{2} \\ e^{i\phi} \sin \frac{\theta}{2} & e^{i\lambda+i\phi} \cos \frac{\theta}{2} \end{pmatrix}$$

SWAP

$$\begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$\begin{aligned} |\vec{00}\rangle &\rightarrow |00\rangle \\ |\vec{01}\rangle &\rightarrow |10\rangle \\ |\vec{10}\rangle &\rightarrow |01\rangle \\ |\vec{11}\rangle &\rightarrow |11\rangle \end{aligned}$$

