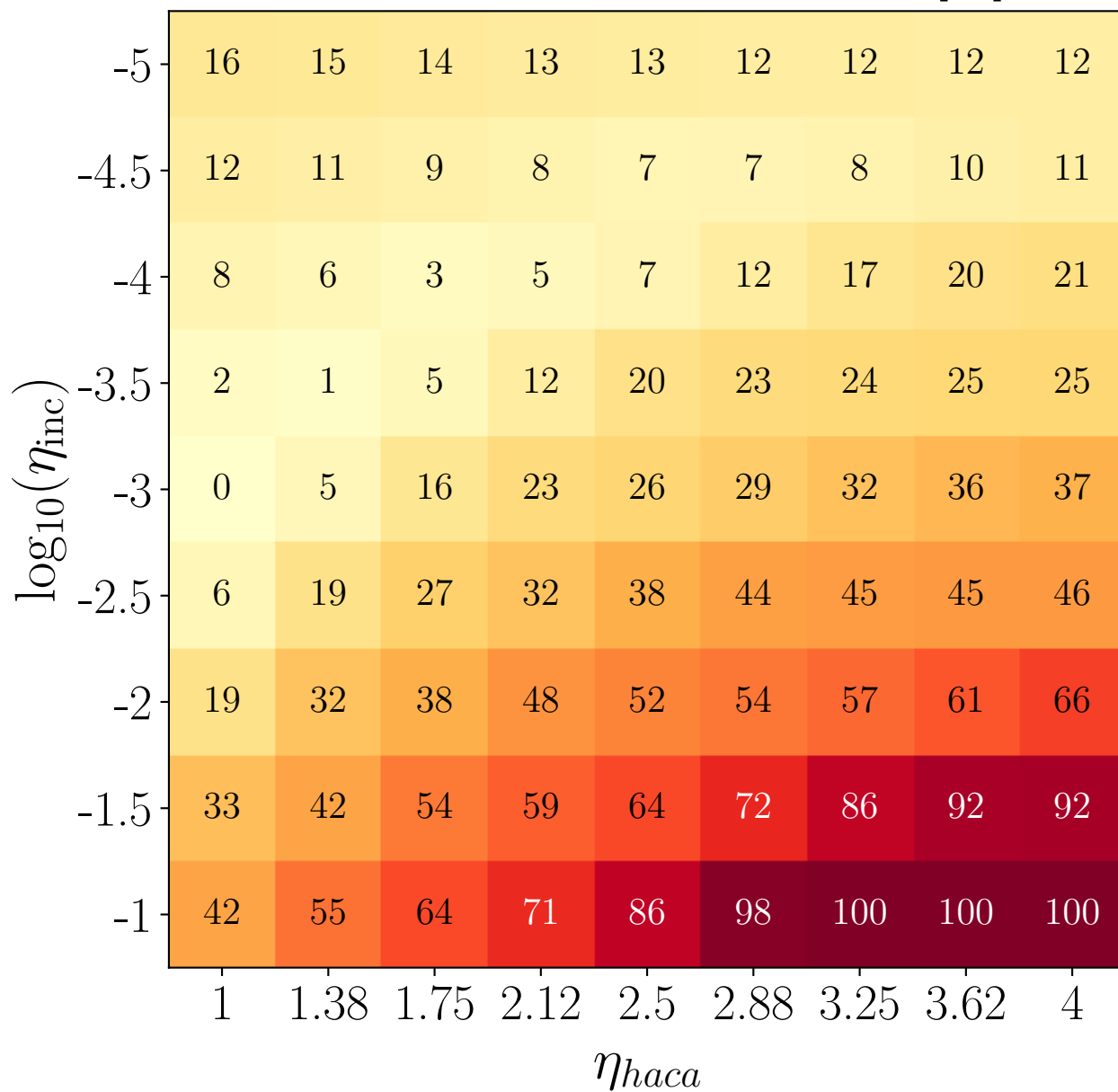


f_v normalized relative error [%] d_p normalized relative error [%]