

VinMax = 4.2V Vout = 10.0V Iout = 2.8A

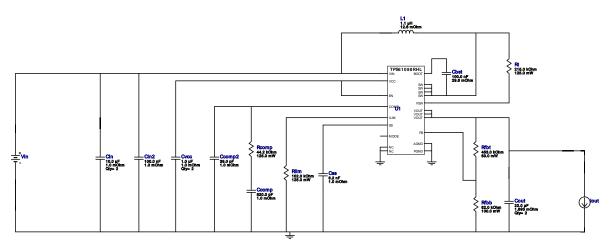
VinMin = 3.6V

Device = TPS61088RHLR Topology = Boost Created = 2019-07-23 07:09:14.061 BOM Cost = \$5.08

BOM Cost = \$5.08BOM Count = 18Total Pd = 2.78W

# WEBENCH® Design Report

Design: 4 TPS61088RHLR TPS61088RHLR 3.6V-4.2V to 10.00V @ 2.8A



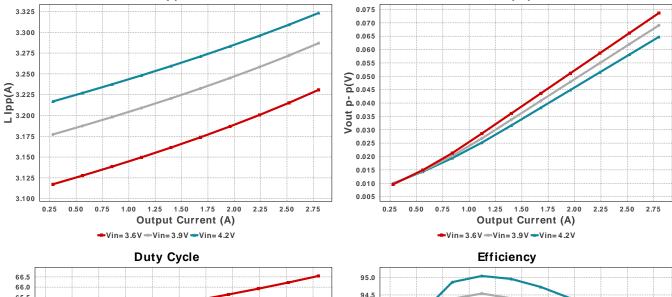
### **Electrical BOM**

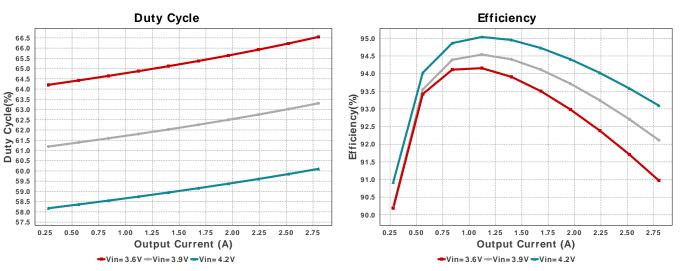
Name	Manufacturer	Part Number	Properties	Qty	Price	Footprint
Cbst	TDK	CGA3E2X7R1H104K080AA Series= X7R	Cap= 100.0 nF ESR= 29.6 mOhm VDC= 50.0 V IRMS= 971.99 mA	1	\$0.01	0603 5 mm <sup>2</sup>
Ccomp	MuRata	GRM155R71H821KA01D Series= X7R	Cap= 820.0 pF ESR= 1.0 mOhm VDC= 50.0 V IRMS= 0.0 A	1	\$0.01	0402 3 mm <sup>2</sup>
Ccomp2	MuRata	GRM1555C1E390JA01D Series= C0G/NP0	Cap= 39.0 pF ESR= 1.0 mOhm VDC= 25.0 V IRMS= 0.0 A	1	\$0.01	0402 3 mm <sup>2</sup>
Cin	TDK	C3216X5R1H106K160AB Series= X5R	Cap= 10.0 uF ESR= 1.0 mOhm VDC= 50.0 V IRMS= 4.9 A	2	\$0.30	1206_180 11 mm <sup>2</sup>
Cin2	MuRata	GRM155R71A104KA01D Series= X7R	Cap= 100.0 nF ESR= 1.0 mOhm VDC= 10.0 V IRMS= 0.0 A	1	\$0.01	0402 3 mm <sup>2</sup>
Cout	TDK	CGA9P2X7R1E226M250KA Series= X7R	Cap= 22.0 uF ESR= 1.893 mOhm VDC= 25.0 V IRMS= 6.635 A	2	\$0.99	2220_280 54 mm <sup>2</sup>
Css	MuRata	GRM155R71C822KA01D Series= X7R	Cap= 8.2 nF ESR= 1.0 mOhm VDC= 16.0 V IRMS= 0.0 A	1	\$0.01	0402 3 mm <sup>2</sup>
Cvcc	Taiyo Yuden	EMK107B7105KA-T Series= X7R	Cap= 1.0 uF ESR= 1.0 mOhm VDC= 16.0 V IRMS= 0.0 A	2	\$0.02	0603 5 mm <sup>2</sup>
L1	Coilcraft	XAL6020-112MEB	L= 1.1 μH 12.6 mOhm	1	\$0.76	

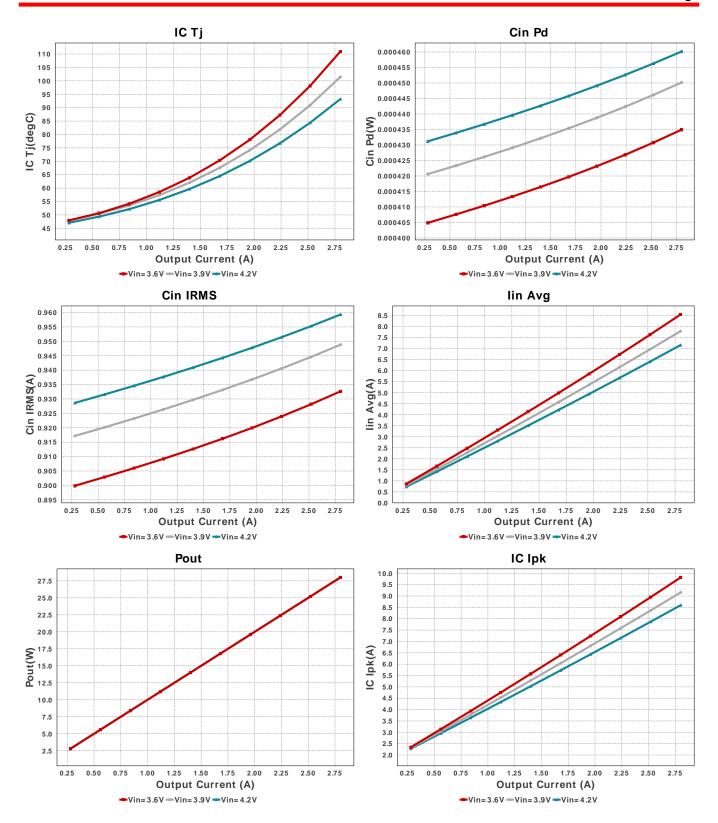
XAL6020 75 mm<sup>2</sup>

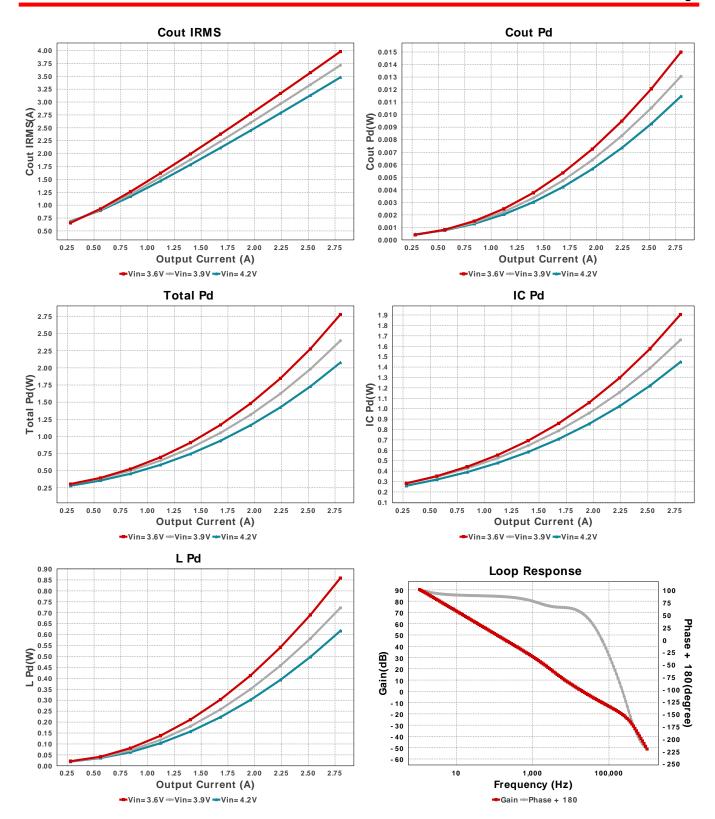
Name	Manufacturer	Part Number	Properties	Qty	Price	Footprint
Rcomp	Vishay-Dale	CRCW080544K2FKEA Series= CRCWe3	Res= 44.2 kOhm Power= 125.0 mW Tolerance= 1.0%	1	\$0.01	0805 7 mm <sup>2</sup>
Rfbb	Yageo	RC0603FR-0762KL Series= ?	Res= 62.0 kOhm Power= 100.0 mW Tolerance= 1.0%	1	\$0.01	0603 5 mm <sup>2</sup>
Rfbt	Vishay-Dale	CRCW0402453KFKED Series= CRCWe3	Res= 453.0 kOhm Power= 63.0 mW Tolerance= 1.0%	1	\$0.01	0402 3 mm <sup>2</sup>
Rlim	Vishay-Dale	CRCW0805102KFKEA Series= CRCWe3	Res= 102.0 kOhm Power= 125.0 mW Tolerance= 1.0%	1	\$0.01	■ 0805 7 mm <sup>2</sup>
Rt	Panasonic	ERJ-6ENF2153V Series= ERJ-6E	Res= 215.0 kOhm Power= 125.0 mW Tolerance= 1.0%	1	\$0.01	■ 0805 7 mm <sup>2</sup>
U1	Texas Instruments	TPS61088RHLR	Switcher	1	\$1.60	

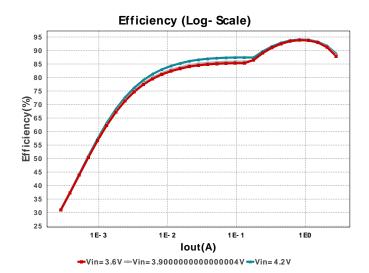












### **Operating Values**

#	Name	Value	Category	Description
1.	BOM Count	18		Total Design BOM count
2.	Total BOM	\$5.08		Total BOM Cost
3.	Cin IRMS	932.654 mA	Capacitor	Input capacitor RMS ripple current
4.	Cin Pd	434.92 μW	Capacitor	Input capacitor power dissipation
5.	Cout IRMS	3.979 A	Capacitor	Output capacitor RMS ripple current
6.	Cout Pd	14.989 mW	Capacitor	Output capacitor power dissipation
7.	IC lpk	9.818 A	IC	Peak switch current in IC
8.	IC Pd	1.905 W	IC	IC power dissipation
9.	IC Tj	110.911 degC	IC	IC junction temperature
10.	ICThetaJA	38.8 degC/W	IC	IC junction-to-ambient thermal resistance
11.	lin Avg	8.55 A	IC	Average input current
12.	L lpp	3.231 A	Inductor	Peak-to-peak inductor ripple current
13.	L Pd	858.67 mW	Inductor	Inductor power dissipation
14.	Cin Pd	434.92 μW	Power	Input capacitor power dissipation
15.	Cout Pd	14.989 mW	Power	Output capacitor power dissipation
16.	IC Pd	1.905 W	Power	IC power dissipation
17.	L Pd	858.67 mW	Power	Inductor power dissipation
18.	Total Pd	2.779 W	Power	Total Power Dissipation
19.	Cross Freq	20.238 kHz	System	Bode plot crossover frequency
	•		Information	
20.	Duty Cycle	66.546 %	System	Duty cycle
	, ,		Information	, ,
21.	Efficiency	90.97 %	System	Steady state efficiency
	,		Information	,,
22.	FootPrint	283.0 mm <sup>2</sup>	System	Total Foot Print Area of BOM components
		203.0 111111	Information	
23.	Frequency	674.094 kHz	System	Switching frequency
_0.	1 roquonoy	07 1.00 T KI IZ	Information	Cintorning requestoy
24.	Gain Marg	-9.873 dB	System	Bode Plot Gain Margin
	Can marg	0.070 45	Information	2000 Flot Gain Margin
25.	lout	2.8 A	System	lout operating point
20.	lout	2.071	Information	lout operating point
26.	Low Freq Gain	89.732 dB	System	Gain at 1Hz
20.	Low Froq Cam	00.702 dB	Information	Can at 1112
27.	Mode	BOOST CCM	System	PWM/PFM Mode
۷١.	Wiode	DOOST CCIVI	Information	1 WIW/I I W Wode
28.	Phase Marg	54.124 deg	System	Bode Plot Phase Margin
20.	Filase Mary	34.124 deg	Information	bode Flot Fliase Margill
29.	Pout	28.0 W	System	Total autaut navar
29.	Poul	20.U VV	•	Total output power
30.	\/in	261/	Information	Vin an arating point
30.	Vin	3.6 V	System	Vin operating point
	Mand Astro-1	40.004.1/	Information	Most Astrological state has a decreased surface of State as 25 the second
31.	Vout Actual	10.001 V	System	Vout Actual calculated based on selected voltage divider resistors
			Information	
32.	Vout Tolerance	4.44 %	System	Vout Tolerance based on IC Tolerance (no load) and voltage divide
			Information	resistors if applicable
33.	Vout p-p	73.673 mV	System	Peak-to-peak output ripple voltage
			Information	

## **Design Inputs**

Name	Value	Description	
lout	2.8	Maximum Output Current	
SoftStart	1.97 ms	Soft Start Time (ms)	
VinMax	4.2	Maximum input voltage	
VinMin	3.6	Minimum input voltage	
Vout	10.0	Output Voltage	
base_pn	TPS61088	Base Product Number	
source	DC	Input Source Type	
Та	37.0	Ambient temperature	
UserFsw	687.0 k	Customer Selected Frequency	

### WEBENCH® Assembly

#### Component Testing

Some published data on components in datasheets such as Capacitor ESR and Inductor DC resistance is based on conservative values that will guarantee that the components always exceed the specification. For design purposes it is usually better to work with typical values. Since this data is not always available it is a good practice to measure the Capacitance and ESR values of Cin and Cout, and the inductance and DC resistance of L1 before assembly of the board. Any large discrepancies in values should be electrically simulated in WEBENCH to check for instabilities and thermally simulated in WebTHERM to make sure critical temperatures are not exceeded.

#### Soldering Component to Board

If board assembly is done in house it is best to tack down one terminal of a component on the board then solder the other terminal. For surface mount parts with large tabs, such as the DPAK, the tab on the back of the package should be pre-tinned with solder, then tacked into place by one of the pins. To solder the tab town to the board place the iron down on the board while resting against the tab, heating both surfaces simultaneously. Apply light pressure to the top of the plastic case until the solder flows around the part and the part is flush with the PCB. If the solder is not flowing around the board you may need a higher wattage iron (generally 25W to 30W is enough).

#### Initial Startup of Circuit

It is best to initially power up the board by setting the input supply voltage to the lowest operating input voltage 3.6V and set the input supply's current limit to zero. With the input supply off connect up the input supply to Vin and GND. Connect a digital volt meter and a load if needed to set the minimum lout of the design from Vout and GND. Turn on the input supply and slowly turn up the current limit on the input supply. If the voltage starts to rise on the input supply continue increasing the input supply current limit while watching the output voltage. If the current increases on the input supply, but the voltage remains near zero, then there may be a short or a component misplaced on the board. Power down the board and visually inspect for solder bridges and recheck the diode and capacitor polarities. Once the power supply circuit is operational then more extensive testing may include full load testing, transient load and line tests to compare with simulation results.

#### Load Testing

The setup is the same as the initial startup, except that an additional digital voltmeter is connected between Vin and GND, a load is connected between Vout and GND and a current meter is connected in series between Vout and the load. The load must be able to handle at least rated output power + 50% (7.5 watts for this design). Ideally the load is supplied in the form of a variable load test unit. It can also be done in the form of suitably large power resistors. When using an oscilloscope to measure waveforms on the prototype board, the ground leads of the oscilloscope probes should be as short as possible and the area of the loop formed by the ground lead should be kept to a minimum. This will help reduce ground lead inductance and eliminate EMI noise that is not actually present in the circuit.



#### **Design Assistance**

- 1. Master key: 84F8F281898B6F10[v1]
- 2. TPS61088 Product Folder: http://www.ti.com/product/TPS61088: contains the data sheet and other resources.

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