

Introduction to Mathematica

#CA1

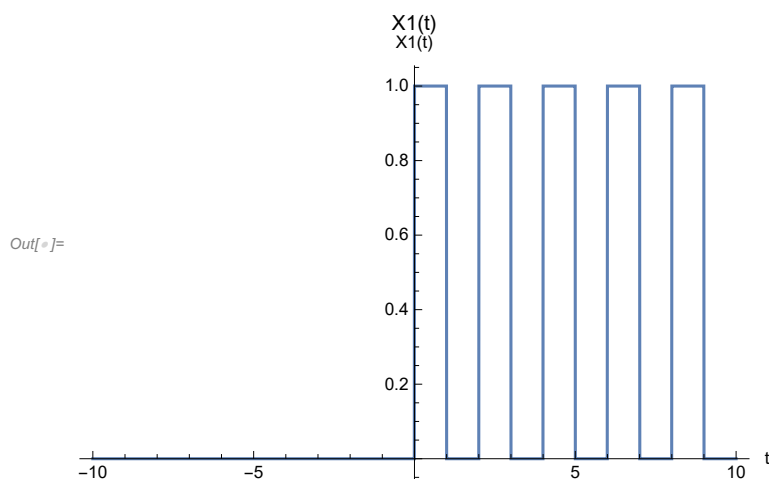
#Q3

Signals & Systems

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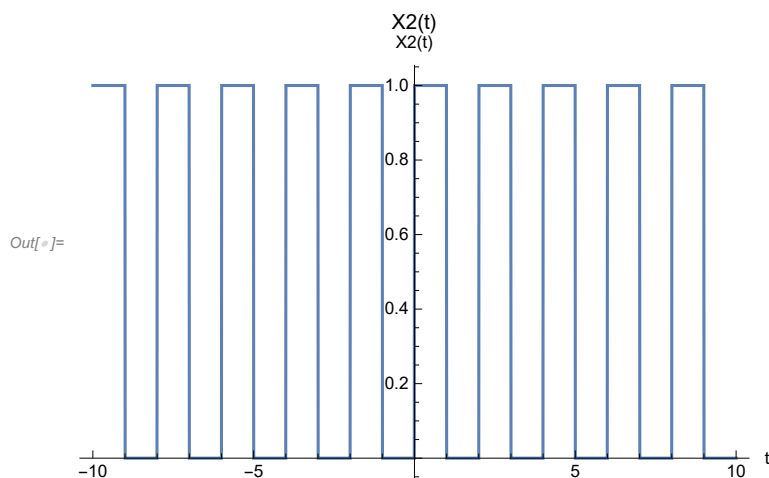
`In[]:= X1[t_] := $\sum_{n=0}^{\text{Infinity}}$ (UnitStep[t - 2 n]) * (UnitStep[1 + 2 * n - t])`

`Plot[X1[t], {t, -10, 10}, PlotLabel -> "X1(t)", AxesLabel -> {"t", "X1(t)"}]`



`In[]:= X2[t_] := $\sum_{n=-\text{Infinity}}^{\text{Infinity}}$ (UnitStep[t - 2 n]) * (UnitStep[1 + 2 * n - t])`

`Plot[X2[t], {t, -10, 10}, PlotLabel -> "X2(t)", AxesLabel -> {"t", "X2(t)"}]`

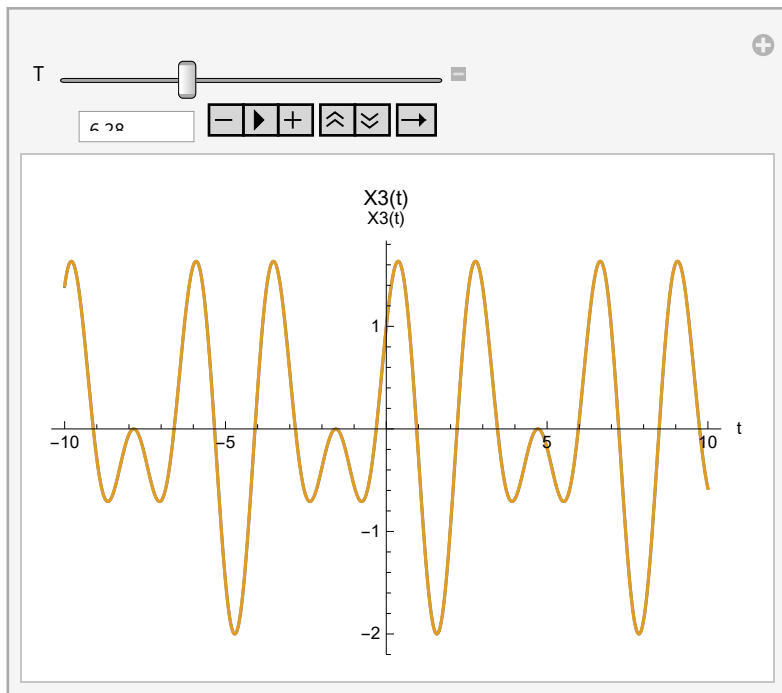


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In[1]:= X3[t_] := Cos[2 * t] + Sin[3 * t]
Manipulate[Plot[{X3[t + T], X3[t]}, {t, -10, 10},
  PlotLabel -> "X3(t)", AxesLabel -> {"t", "X3(t)"}], {T, 0, 20}]

```

Out[2]=

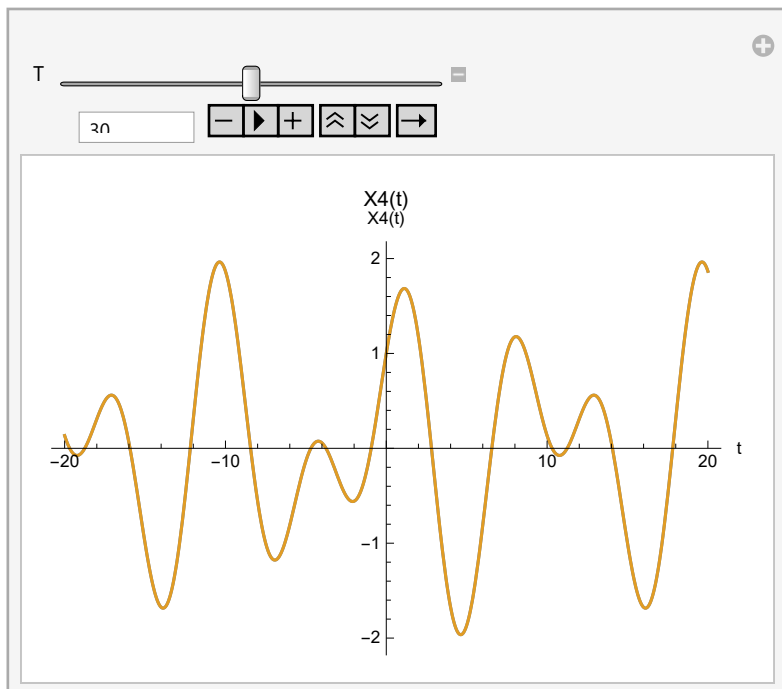


```

In[3]:= X4[t_] := Cos[(Pi * t) / 5] + Sin[(Pi * t) / 3]
Manipulate[Plot[{X4[t + T], X4[t]}, {t, -20, 20},
  PlotLabel -> "X4(t)", AxesLabel -> {"t", "X4(t)"}], {T, 0, 60}]

```

Out[4]=

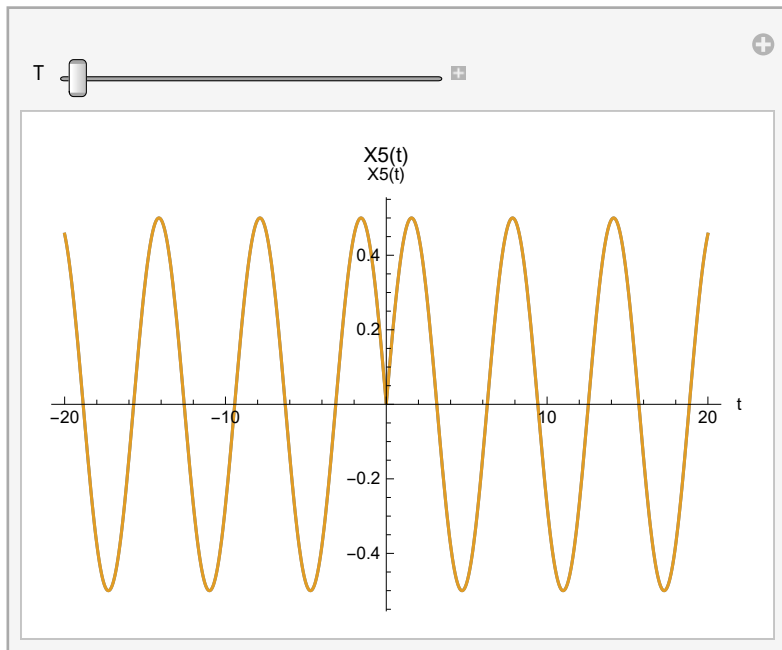


```

In[5]:= X5[t_] := Sin[t] * UnitStep[t]
Manipulate[Plot[{(X5[t + T] + X5[-(t + T)]) / 2, (X5[t] + X5[-t]) / 2},
  {t, -20, 20}, PlotLabel -> "X5(t)", AxesLabel -> {"t", "X5(t)"}], {T, 0, 100}]

```

Out[6]=

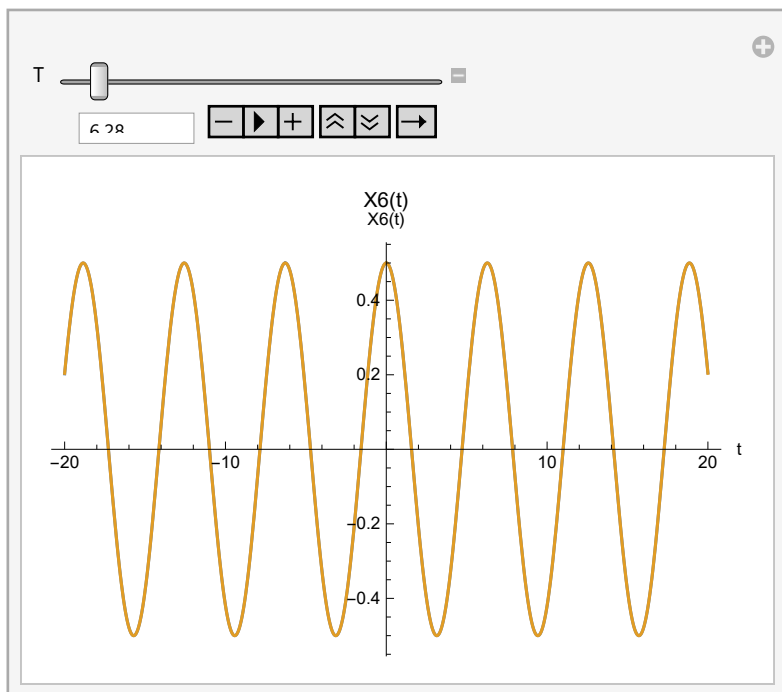


```

In[7]:= X6[t_] := Cos[t] * UnitStep[t]
Manipulate[Plot[{(X6[t + T] + X6[-(t + T)]) / 2, (X6[t] + X6[-t]) / 2},
  {t, -20, 20}, PlotLabel -> "X6(t)", AxesLabel -> {"t", "X6(t)"}], {T, 0, 100}]

```

Out[8]=



```

In[9]:= X7[t_] := Sum[Ramp[t - 0.3 * k] + 1 - 2 Ramp[t - 0.3 * k] + Ramp[t - 0.3 * k - 1], {k, -100, 100}]
Plot[X7[t], {t, -1, 1}, PlotLabel -> "X7(t)", AxesLabel -> {"t", "X7(t)"}]

```

