opency

August 26, 2024

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[11]: !pip install opency-python
      import cv2
      # Read the image from fig
      img = cv2.imread('C:
       →\\Users\\moham\\OneDrive\\Desktop\\Documents\\Pictures\\sana1.jpg')
      # Display the image in a window
      cv2.imshow('Image', img)
      # Wait for a key press and close the image window
      cv2.waitKey(0)
      cv2.destroyAllWindows()
     Requirement already satisfied: opency-python in
     c:\users\moham\anaconda3\lib\site-packages (4.10.0.84)
     Requirement already satisfied: numpy>=1.21.2 in
     c:\users\moham\anaconda3\lib\site-packages (from opencv-python) (1.24.3)
 [2]: # Resize the image to a specific width and height
      resized_img = cv2.resize(img, (400, 400))
      # Display the resized image
      cv2.imshow('Resized Image', resized_img)
      cv2.waitKey(0)
      cv2.destroyAllWindows()
 [3]: # Convert the image to grayscale
      gray_img = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)
      # Display the grayscale image
      cv2.imshow('Grayscale Image', gray_img)
      cv2.waitKey(0)
      cv2.destroyAllWindows()
 [4]: # Apply Gaussian blur to the image
      blurred_img = cv2.GaussianBlur(img, (15, 15), 0)
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# Display the blurred image
     cv2.imshow('Blurred Image', blurred_img)
     cv2.waitKey(0)
     cv2.destroyAllWindows()
[5]: # Perform Canny edge detection
     edges = cv2.Canny(img, 100, 200)
     # Display the edges
     cv2.imshow('Edges', edges)
     cv2.waitKey(0)
     cv2.destroyAllWindows()
[6]: # Apply binary thresholding
     _, thresholded_img = cv2.threshold(gray_img, 127, 255, cv2.THRESH_BINARY)
     # Display the thresholded image
     cv2.imshow('Thresholded Image', thresholded_img)
     cv2.waitKey(0)
     cv2.destroyAllWindows()
[7]: # Draw a rectangle on the image
     rect_img = img.copy()
     cv2.rectangle(rect_img, (50, 50), (200, 200), (0, 255, 0), 3)
     # Draw a circle on the image
     cv2.circle(rect_img, (300, 300), 50, (255, 0, 0), -1)
     # Display the image with shapes
     cv2.imshow('Image with Shapes', rect_img)
     cv2.waitKey(0)
     cv2.destroyAllWindows()
[8]: # Load the Haar Cascade for face detection
     face_cascade = cv2.CascadeClassifier(cv2.data.haarcascades +__
      ⇔'haarcascade_frontalface_default.xml')
     # Convert the image to grayscale (Haar Cascade works on grayscale images)
     gray img = cv2.cvtColor(img, cv2.COLOR BGR2GRAY)
     # Detect faces in the image
     faces = face_cascade.detectMultiScale(gray_img, scaleFactor=1.1,__
      →minNeighbors=5, minSize=(30, 30))
     # Draw rectangles around the detected faces
     for (x, y, w, h) in faces:
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cv2.rectangle(img, (x, y), (x+w, y+h), (255, 0, 0), 2)
      # Display the image with faces detected
      cv2.imshow('Faces Detected', img)
      cv2.waitKey(0)
      cv2.destroyAllWindows()
 [9]: # Split the image into its blue, green, and red channels
      b, g, r = cv2.split(img)
      # Display the individual channels
      cv2.imshow('Blue Channel', b)
      cv2.imshow('Green Channel', g)
      cv2.imshow('Red Channel', r)
      cv2.waitKey(0)
      cv2.destroyAllWindows()
[10]: # Get the image dimensions
      (h, w) = img.shape[:2]
      # Calculate the center of the image
      center = (w // 2, h // 2)
      # Define the rotation matrix
      M = cv2.getRotationMatrix2D(center, 45, 1.0)
      # Rotate the image
      rotated_img = cv2.warpAffine(img, M, (w, h))
      # Display the rotated image
      cv2.imshow('Rotated Image', rotated_img)
      cv2.waitKey(0)
      cv2.destroyAllWindows()
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