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Project Team

ABSTRACT

In this project, we develop a complete platform for coordination and control of multi-agent robotic system composed of a set of mobile robots that can be used to transport objects with different weights in an indoor environment. The main objective of the system is to use low-cost robots with limited capabilities and make them cooperate to perform complex tasks such as transportation of heavy objects that can't be transported by single robot. As a proof of concept, the platform is applied to three omnidirectional mobile robots connected to a main server that assign tasks to them and coordinate their work to meet client requirements. A web-based interface is developed for clients to interact with the system.

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