Mohammed Ali Cheddad

github.com/mohammedAcheddad

SKILLS SUMMARY

- Core Skills: Linux, Embedded Systems, Control Engineering, Test Automation, Security & Compliance
- Programming: C/C++, Python (advanced), Bash, NodeJs, Java
- Technologies: PX4 Autopilot, ROS2, Gazebo, Docker, Podman, Git, Ansible, Virtualization
- AI & Robotics: Deep Reinforcement Learning, Computer Vision (OpenCV), UAV Dynamics Modeling
- Other: LLMs (RAG, MCP), Test Orchestration, Automation Pipelines

EXPERIENCE

Oracle

Casablanca, Morocco

Email: mohammedalicheddad@gmail.com

Aug 2024 - Present

System Engineer (Linux QA)

- Reduced destructive test time from **3 days to 7 hours**, with launch setup cut from hours to minutes, by automating OLAM deployments and test pipelines.
- Optimized resource usage by replacing week-long persistent clusters with on-demand automation.
- Refactored QA test suites (shunit2, modularization, clearer logs) for maintainability and faster triage.
- Embedded AI into QA workflows by designing preprocessing pipelines and developing RAG/MCP-based prompts in Oracle Explain to triage logs, classify failures, and correlate issues with code changes and bug reports.

Oracle

Casablanca, Morocco

System Engineer Intern (Linux QA)

Feb 2024 - Aug 2024

- \circ Applied OpenSCAP compliance scanning across Oracle Linux and UEK systems, improving baseline security validation across the OS stack.
- Automated CVE detection workflows, catching vulnerabilities earlier in the QA cycle.
- Built early log-analysis scripts that reduced debugging time for QA engineers.

Intelcia IT Solutions

Casablanca, Morocco

Internship (SD-WAN POC)

2023

Deployed and managed SD-WAN network using Fortinet, enhancing network resilience and security.

EDUCATION & RESEARCH

Euro-Mediterranean University of Fez, EIDIA

Fez, Morocco

Diploma in Software & Security Engineering 17/20 (GPA: 3.7/4.0 equivalent)

2021 - 2024

• PhD in Control Engineering (in progress): AI-based UAV control using nonlinear backstepping, Lyapunov stability, and dynamic reference generation (PX4, ROS2, Gazebo, C++, Eigen).

SELECTED TECHNICAL PROJECTS

- Autonomous UAV Controller: Designed and implemented a nonlinear backstepping controller on SE(3) for UAV thrust/torque control. Validated performance using PX4 SITL and ROS2.
- Oracle Explain AI Log Triage: Built a full pipeline integrating log preprocessing, chunking, and LLM-based classification (RAG/MCP) for automated issue triage and bug correlation in Oracle Linux QA.
- Autonomous Car with Raspberry Pi: Developed a computer vision-based navigation system using OpenCV and deep learning for competition.

ACHIEVEMENTS & CERTIFICATIONS

- Paper in preparation: "Geometric Backstepping Control of quadrotos" (target: IFAC 2025)
- Founder & President, DigiClub (2020–2024): Launched university's first robotics club; led 100+ members.
- Oracle: Oracle Cloud Infrastructure Associate & Oracle Linux 8: System Administration