

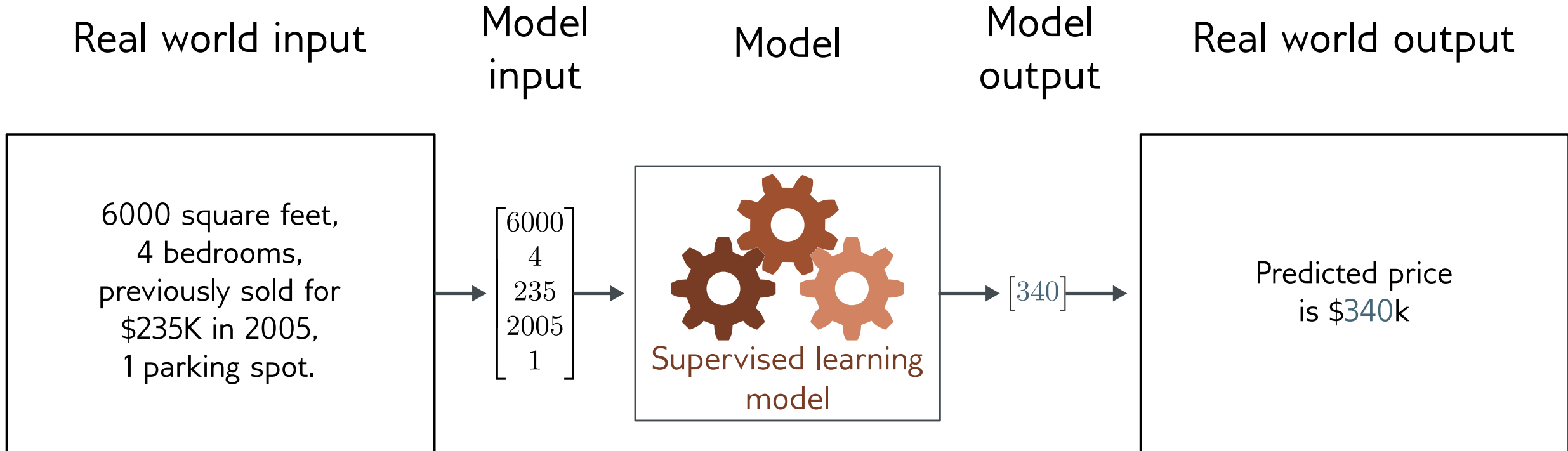
CM20315 - Machine Learning

Prof. Simon Prince

3. Shallow Neural Networks

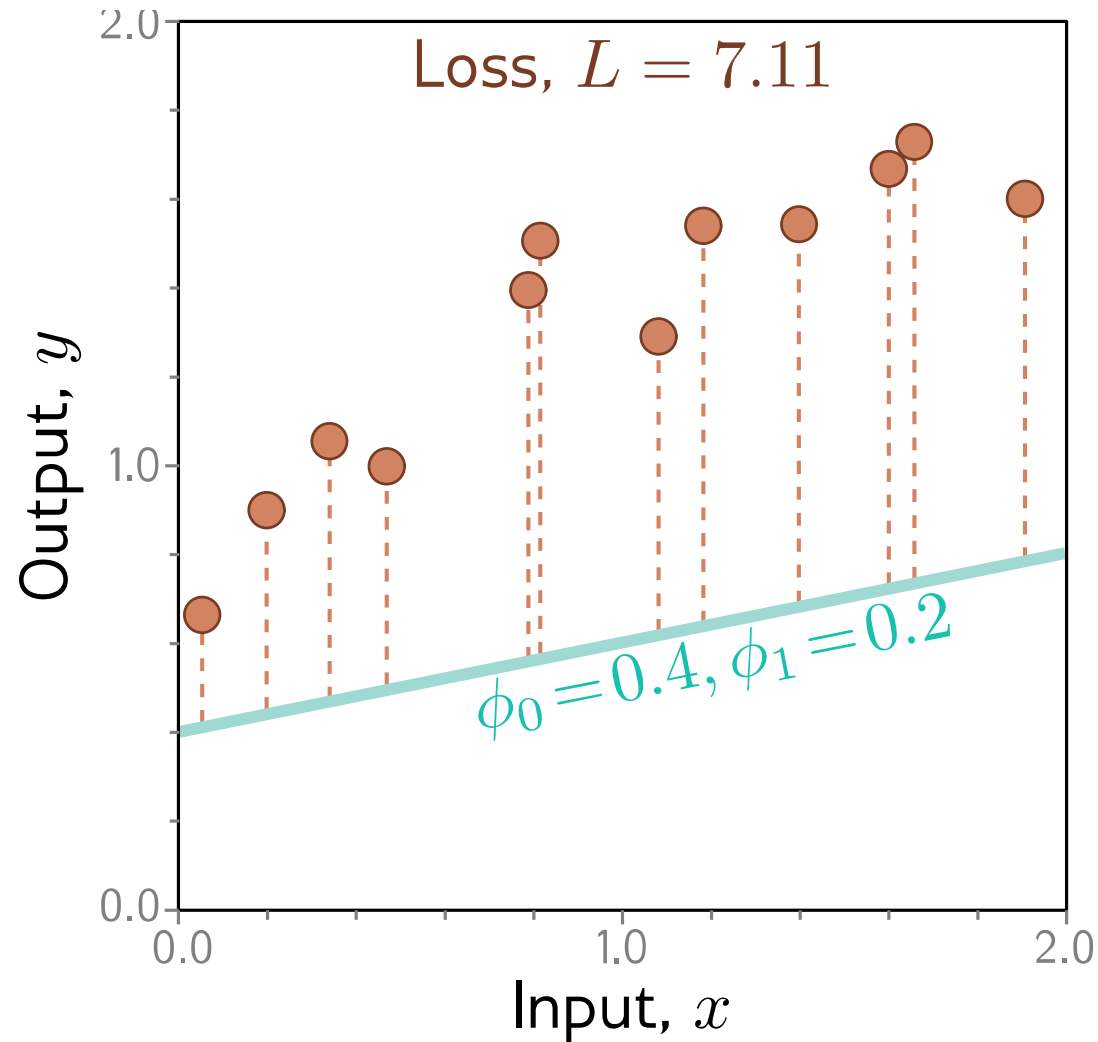


Regression



- Univariate regression problem (one output, real value)
- Fully connected network

Example: 1D Linear regression loss function

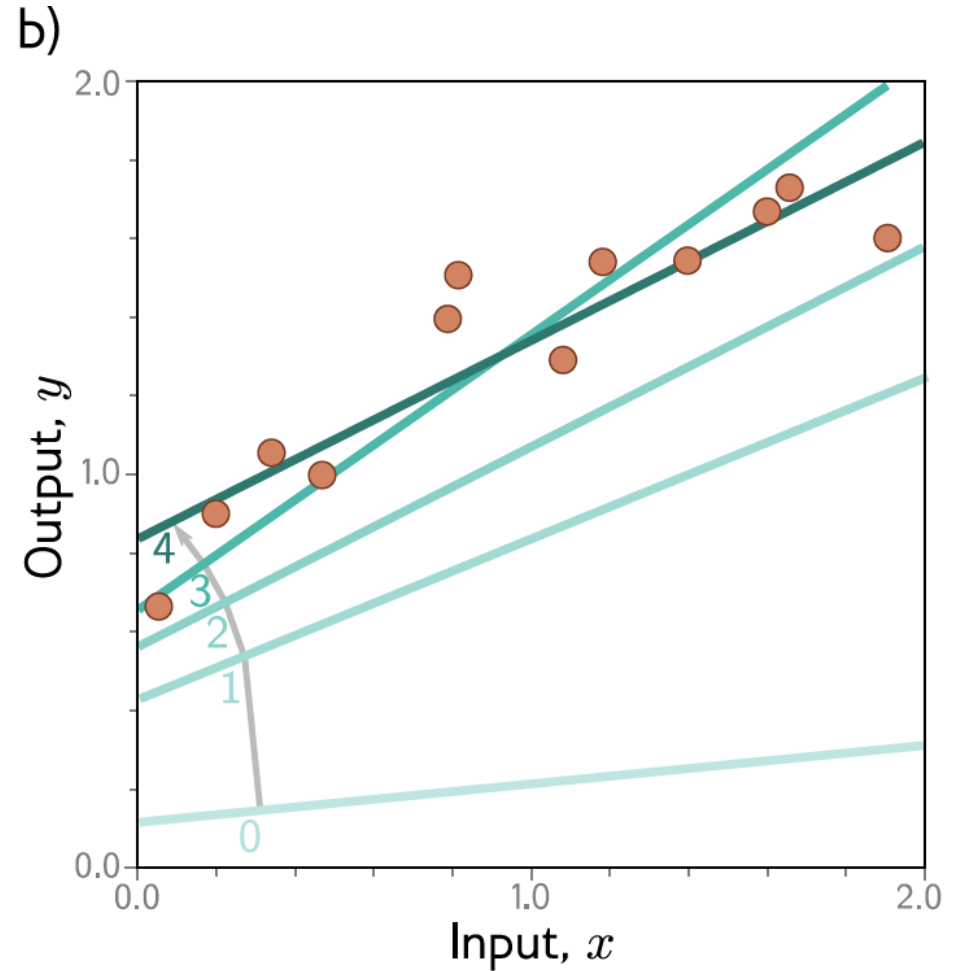
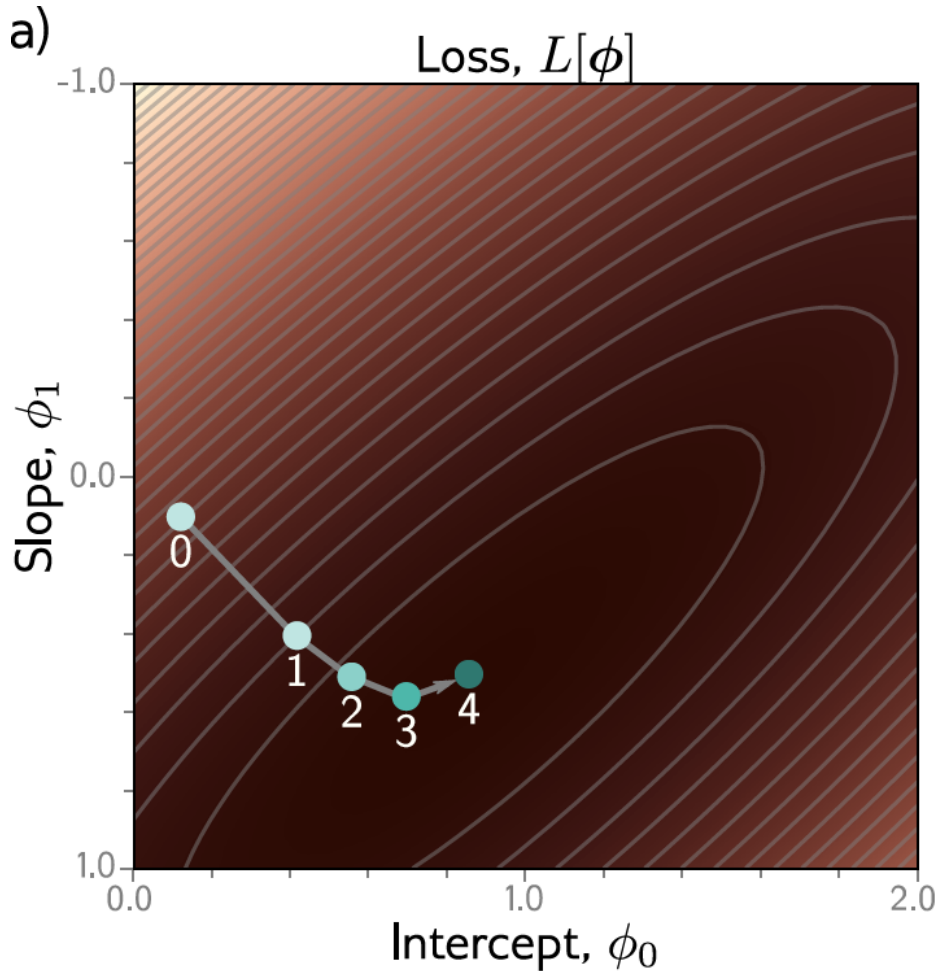


Loss function:

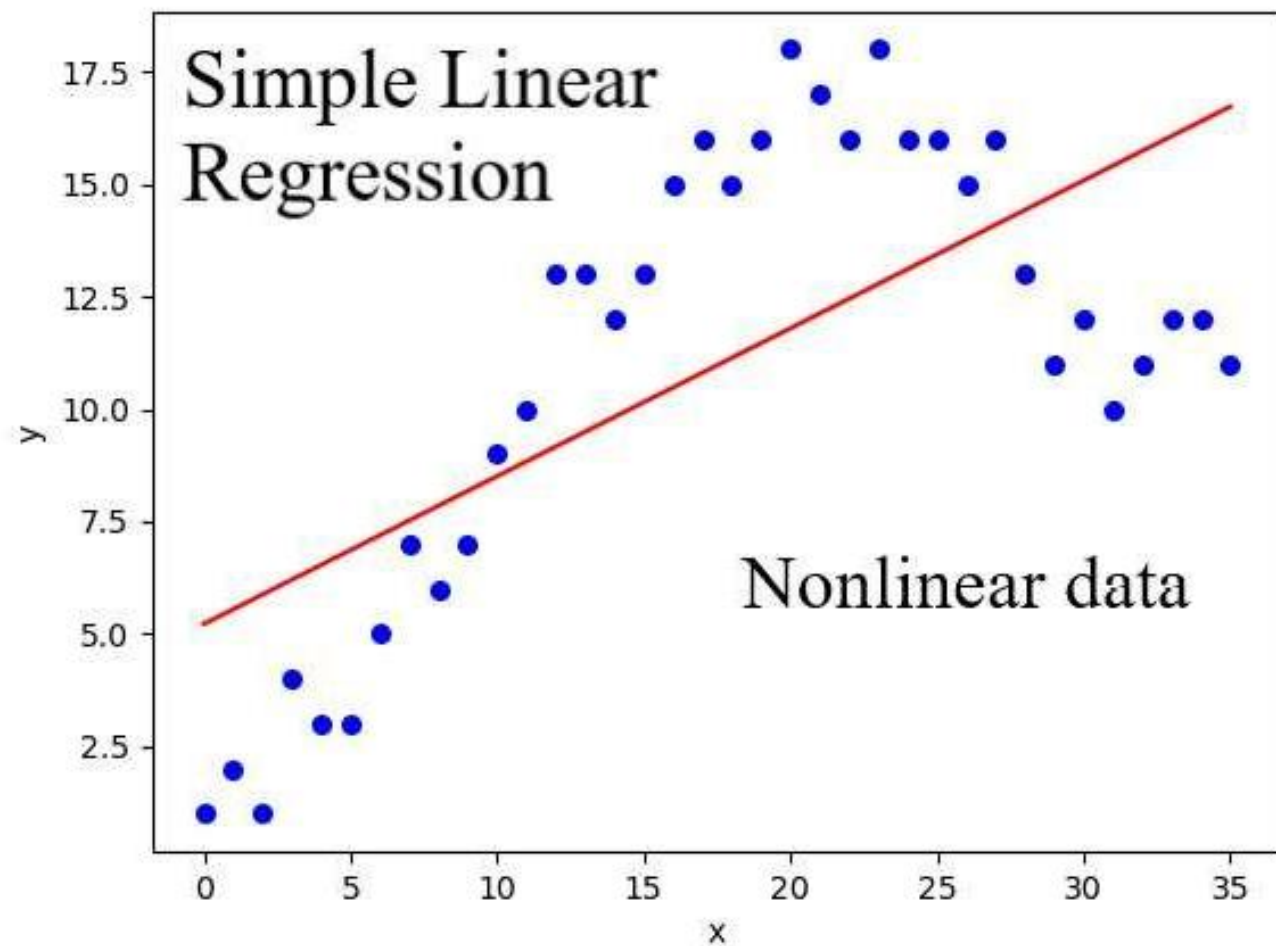
$$L[\phi] = \sum_{i=1}^I (f[x_i, \phi] - y_i)^2$$
$$= \sum_{i=1}^I (\phi_0 + \phi_1 x_i - y_i)^2$$

“Least squares loss function”

Example: 1D Linear regression training



This technique is known as **gradient descent**



What about non- linear data?

We need non-linear
model

Shallow neural networks

- 1D regression model is obviously limited
 - Want to be able to describe input/output that are not lines
 - Want multiple inputs
 - Want multiple outputs
- Shallow neural networks
 - Flexible enough to describe arbitrarily complex input/output mappings
 - Can have as many inputs as we want
 - Can have as many outputs as we want

Shallow neural networks

Example network, 1 input, 1 output

Universal approximation theorem

More than one output

More than one input

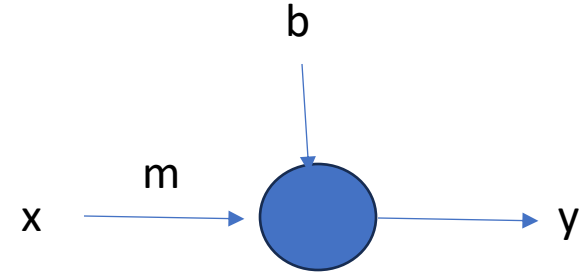
General case

Number of regions

Terminology

1D Linear Regression

$$\begin{aligned} y &= f[x, \phi] \\ &= \phi_0 + \phi_1 x \end{aligned}$$



Example shallow network

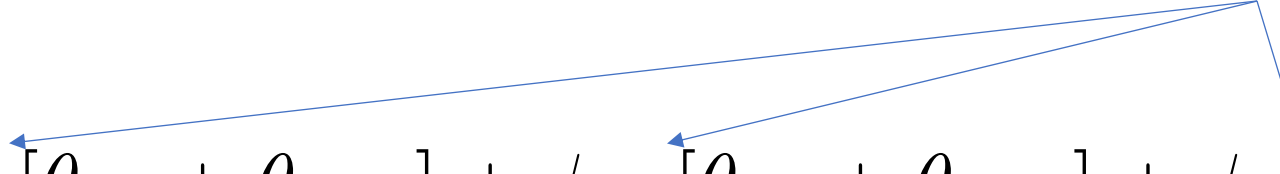
$$\begin{aligned} y &= f[x, \phi] \\ &= \phi_0 + \phi_1 a[\theta_{10} + \theta_{11}x] + \phi_2 a[\theta_{20} + \theta_{21}x] + \phi_3 a[\theta_{30} + \theta_{31}x] \end{aligned}$$

Example shallow network

$$\begin{aligned} y &= f[x, \phi] \\ &= \phi_0 + \phi_1 a[\theta_{10} + \theta_{11}x] + \phi_2 a[\theta_{20} + \theta_{21}x] + \phi_3 a[\theta_{30} + \theta_{31}x] \end{aligned}$$

Example shallow network

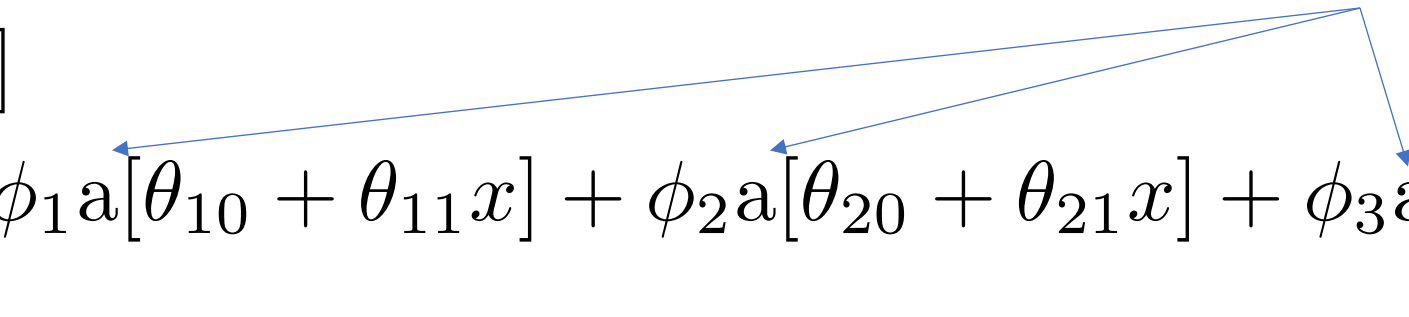
Activation function

$$\begin{aligned} y &= f[x, \phi] \\ &= \phi_0 + \phi_1 a[\theta_{10} + \theta_{11}x] + \phi_2 a[\theta_{20} + \theta_{21}x] + \phi_3 a[\theta_{30} + \theta_{31}x] \end{aligned}$$


The diagram shows three blue arrows originating from the text 'Activation function' and pointing to the 'a' functions in the equation: $a[\theta_{10} + \theta_{11}x]$, $a[\theta_{20} + \theta_{21}x]$, and $a[\theta_{30} + \theta_{31}x]$. A horizontal blue line is positioned below the equation.

Example shallow network

Activation function

$$\begin{aligned} y &= f[x, \phi] \\ &= \phi_0 + \phi_1 a[\theta_{10} + \theta_{11}x] + \phi_2 a[\theta_{20} + \theta_{21}x] + \phi_3 a[\theta_{30} + \theta_{31}x] \end{aligned}$$


$$a[z] = \text{ReLU}[z] = \begin{cases} 0 & z < 0 \\ z & z \geq 0 \end{cases}.$$

Rectified Linear Unit

(particular kind of activation function)

Example shallow network

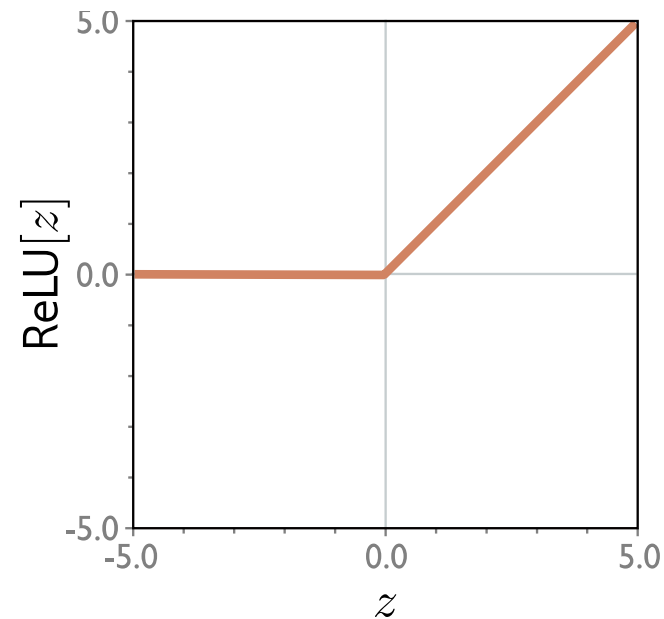
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Rectified Linear Unit

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Example shallow network

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This model has 10 parameters:

$$\phi = \{\phi_0, \phi_1, \phi_2, \phi_3, \theta_{10}, \theta_{11}, \theta_{20}, \theta_{21}, \theta_{30}, \theta_{31}\}$$

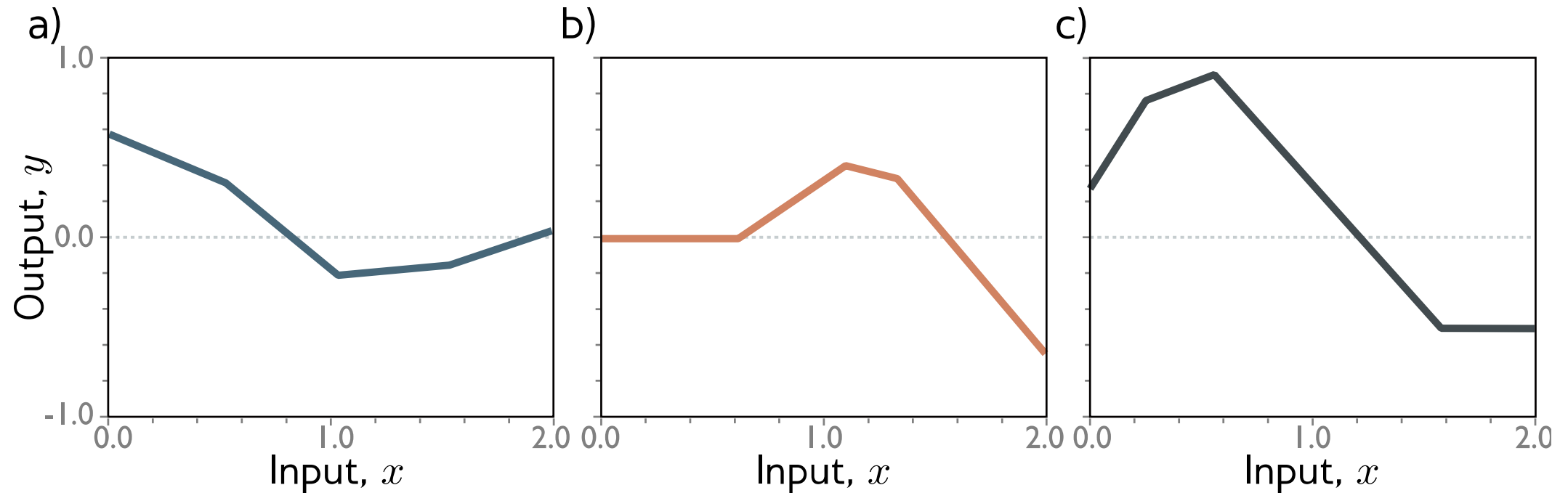
- Represents a family of functions
- Parameters determine particular function
- Given parameters can perform inference (run equation)
- Given training dataset $\{\mathbf{x}_i, \mathbf{y}_i\}_{i=1}^I$
- Define loss function $L[\phi]$ (least squares)
- Change parameters to minimize loss function

Example shallow network

$$y = \phi_0 + \phi_1 a[\theta_{10} + \theta_{11}x] + \phi_2 a[\theta_{20} + \theta_{21}x] + \phi_3 a[\theta_{30} + \theta_{31}x].$$

Example shallow network

$$y = \phi_0 + \phi_1 a[\theta_{10} + \theta_{11}x] + \phi_2 a[\theta_{20} + \theta_{21}x] + \phi_3 a[\theta_{30} + \theta_{31}x].$$



Piecewise linear functions with three joints

Hidden units

$$y = \phi_0 + \phi_1 a[\theta_{10} + \theta_{11}x] + \phi_2 a[\theta_{20} + \theta_{21}x] + \phi_3 a[\theta_{30} + \theta_{31}x].$$

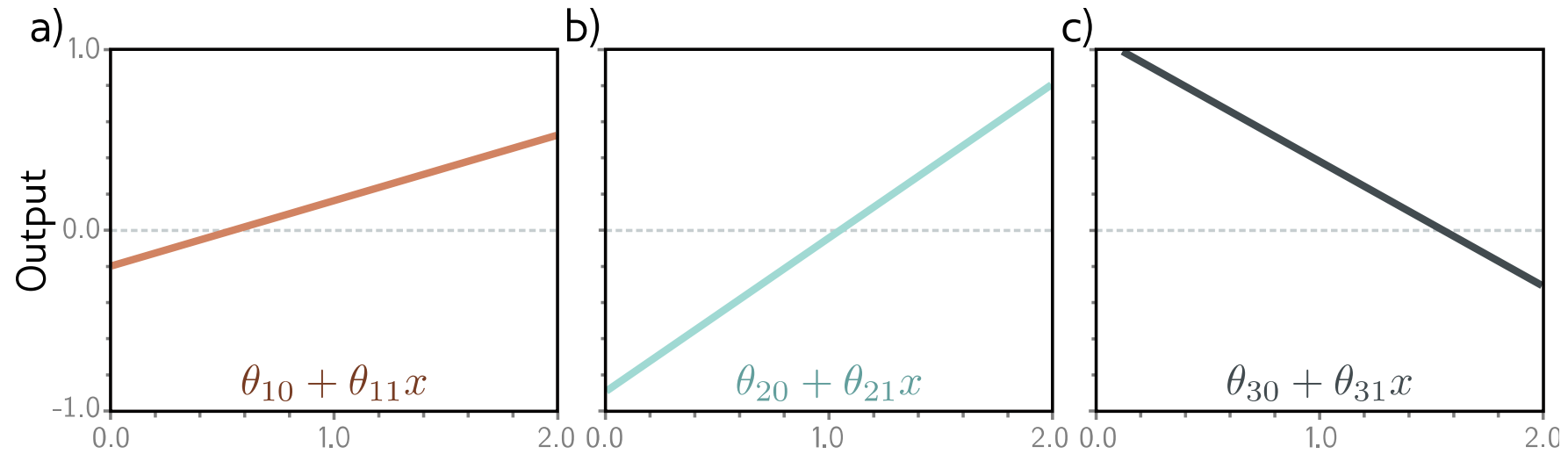
Break down into two parts:

$$y = \phi_0 + \phi_1 h_1 + \phi_2 h_2 + \phi_3 h_3$$

where:

$$\text{Hidden units} \left\{ \begin{array}{l} h_1 = a[\theta_{10} + \theta_{11}x] \\ h_2 = a[\theta_{20} + \theta_{21}x] \\ h_3 = a[\theta_{30} + \theta_{31}x] \end{array} \right.$$

1. compute three
linear functions

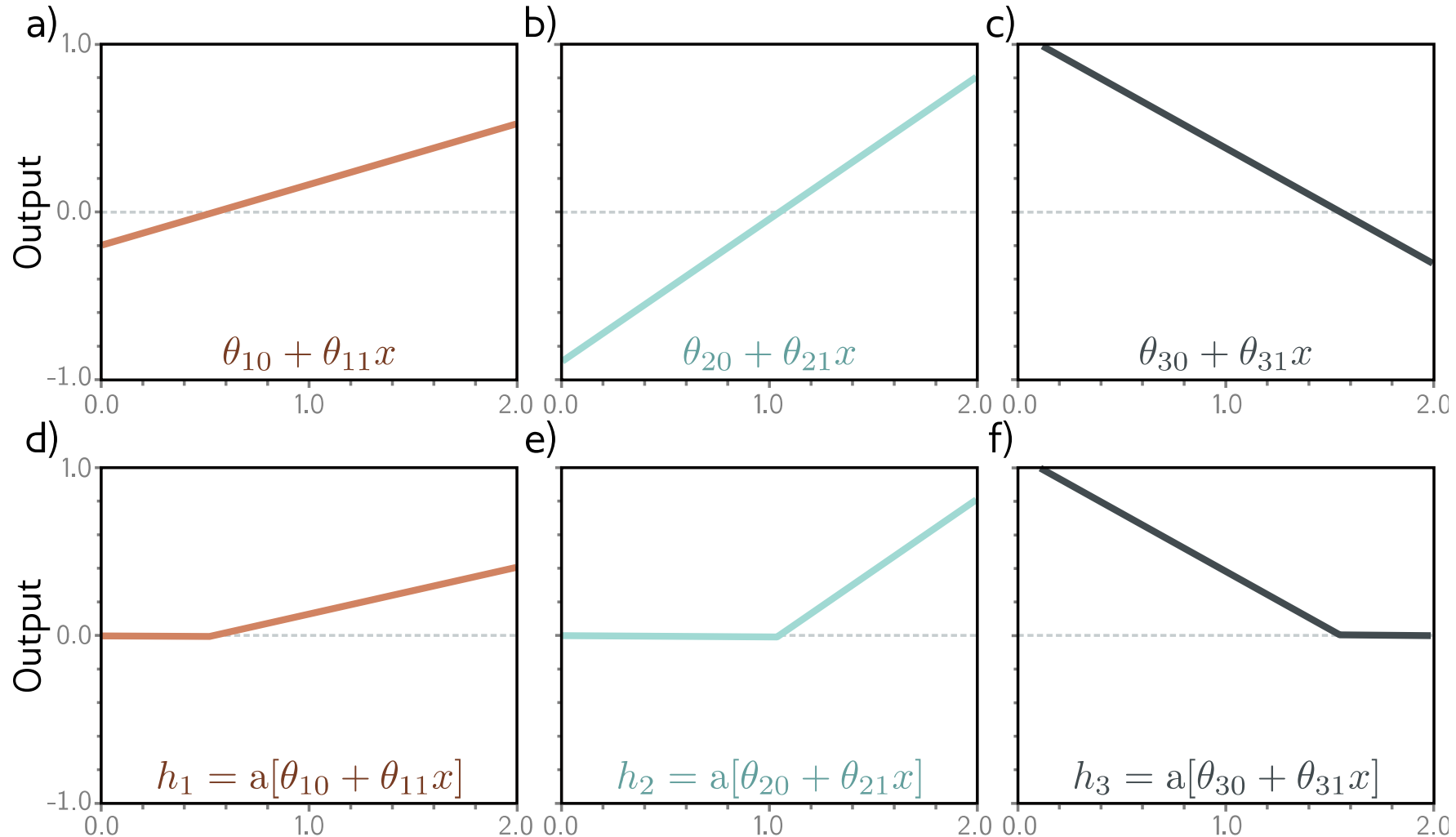


2. Pass through ReLU
functions (creates
hidden units)

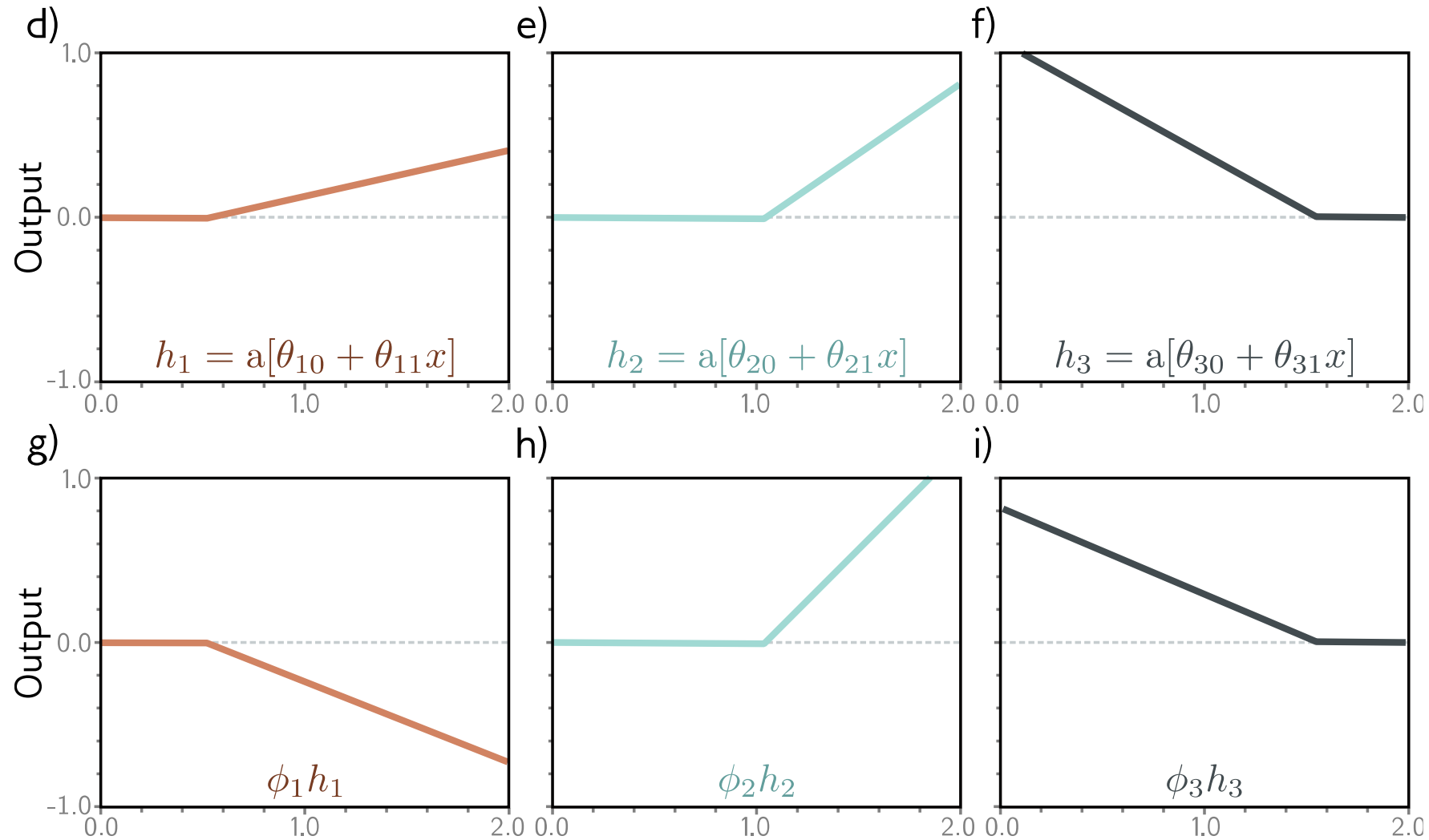
$$h_1 = a[\theta_{10} + \theta_{11}x]$$

$$h_2 = a[\theta_{20} + \theta_{21}x]$$

$$h_3 = a[\theta_{30} + \theta_{31}x],$$

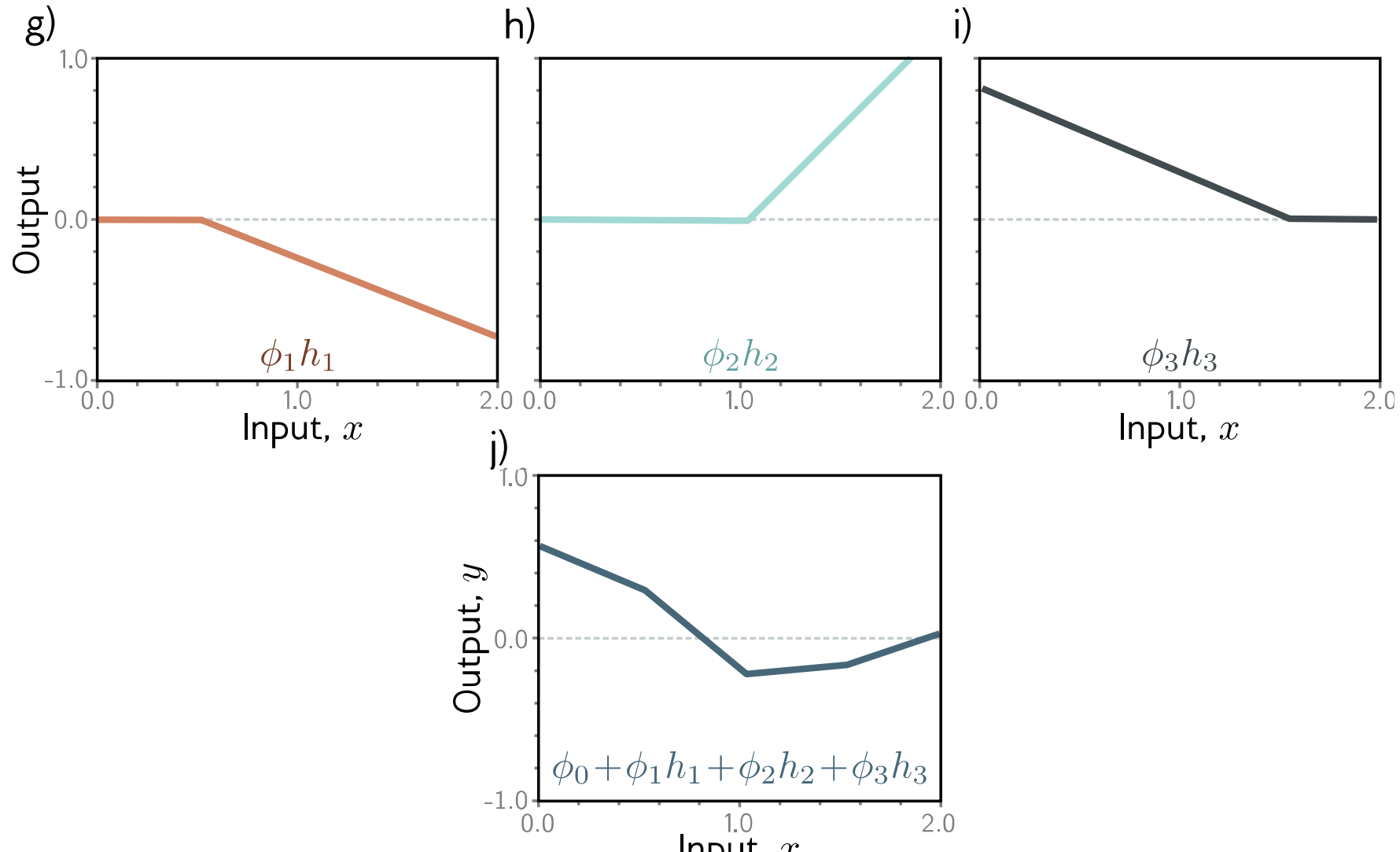


2. Weight the hidden units



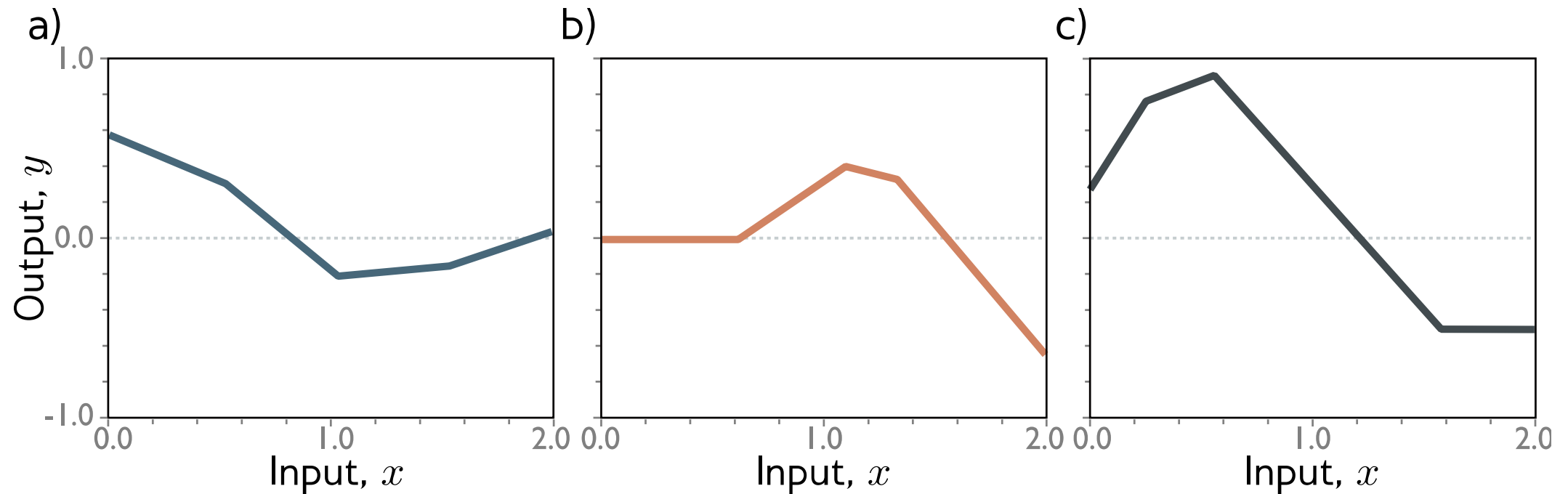
4. Sum the weighted
hidden units to create
output

$$y = \phi_0 + \phi_1 h_1 + \phi_2 h_2 + \phi_3 h_3$$



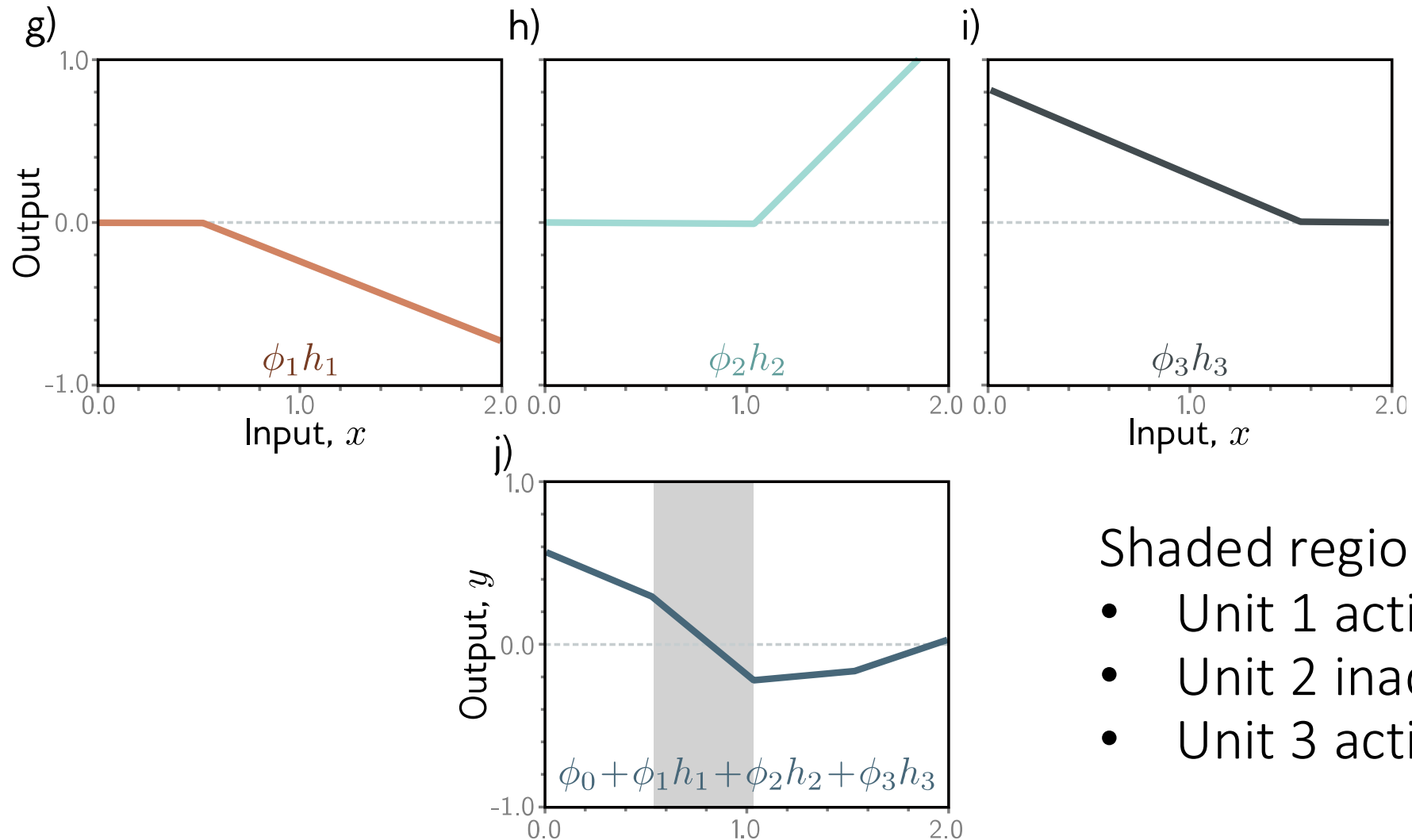
Example shallow network

$$y = \phi_0 + \phi_1 a[\theta_{10} + \theta_{11}x] + \phi_2 a[\theta_{20} + \theta_{21}x] + \phi_3 a[\theta_{30} + \theta_{31}x].$$



Example shallow network = piecewise linear functions
1 “joint” per ReLU function

Activation pattern = which hidden units are activated



Shaded region:

- Unit 1 active
- Unit 2 inactive
- Unit 3 active

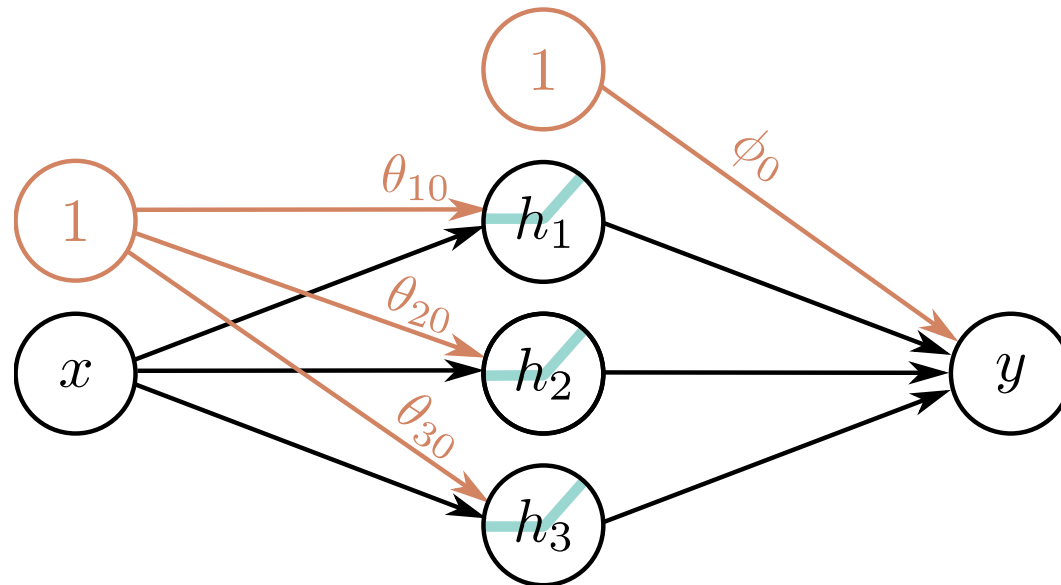
Depicting neural networks

$$h_1 = a[\theta_{10} + \theta_{11}x]$$

$$h_2 = a[\theta_{20} + \theta_{21}x]$$

$$h_3 = a[\theta_{30} + \theta_{31}x]$$

$$y = \phi_0 + \phi_1 h_1 + \phi_2 h_2 + \phi_3 h_3$$



Each parameter multiplies its source and adds to its target

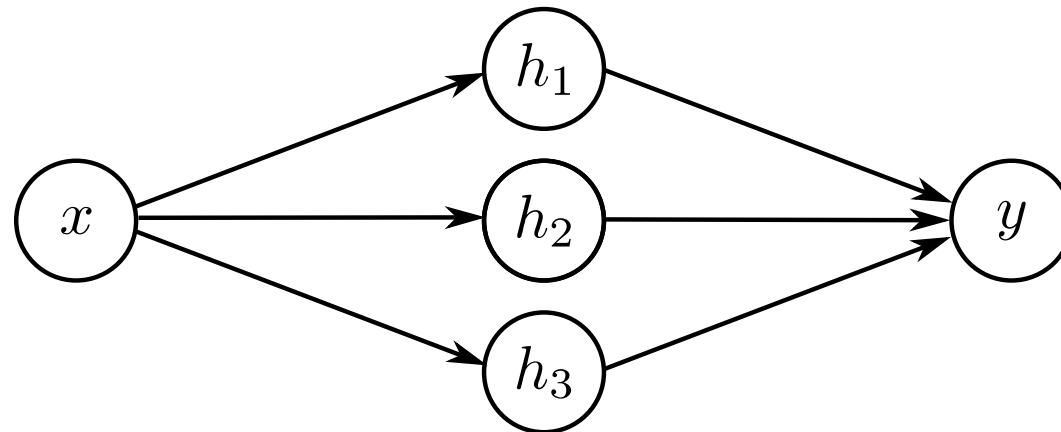
Depicting neural networks

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Shallow neural networks

- Example network, 1 input, 1 output
- Universal approximation theorem
- More than one output
- More than one input
- General case
- Number of regions
- Terminology

With 3 hidden units:

$$h_1 = a[\theta_{10} + \theta_{11}x]$$

$$h_2 = a[\theta_{20} + \theta_{21}x]$$

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$$y = \phi_0 + \phi_1 h_1 + \phi_2 h_2 + \phi_3 h_3$$

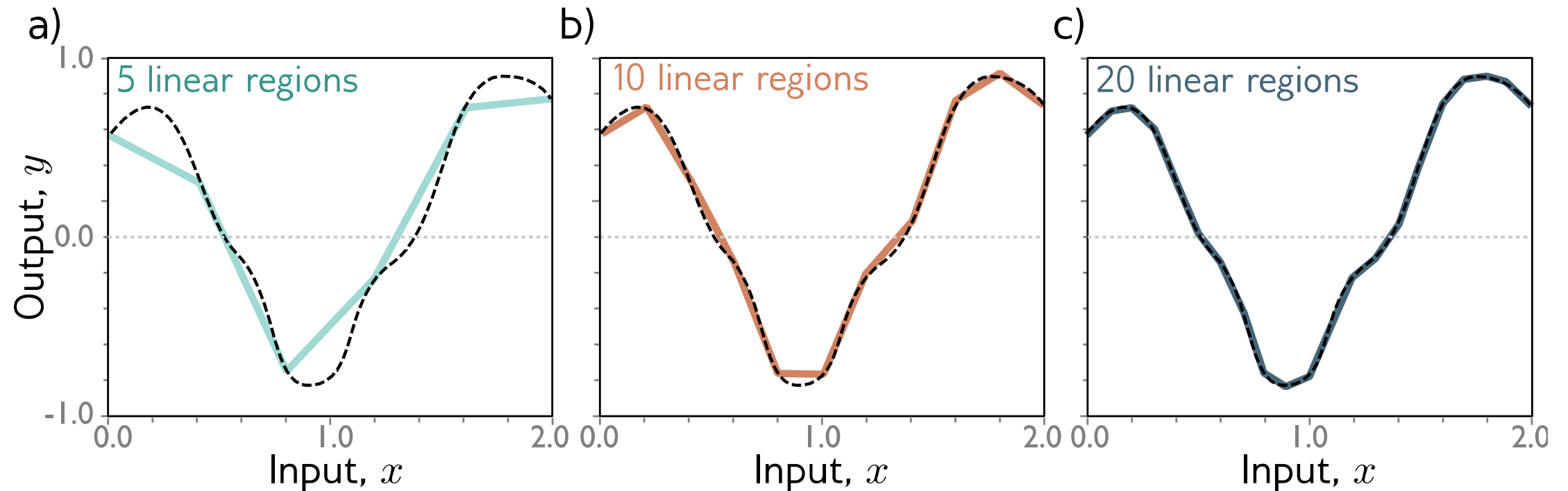
With D hidden units:

$$h_d = a[\theta_{d0} + \theta_{d1}x]$$

$$y = \phi_0 + \sum_{d=1}^D \phi_d h_d$$

With enough hidden units...

... we can describe any 1D function to arbitrary accuracy



Universal approximation theorem

“a formal proof that, with enough hidden units, a shallow neural network can describe any continuous function on a compact subset of \mathbb{R}^D to arbitrary precision”

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Two outputs

- 1 input, 4 hidden units, 2 outputs

$$h_1 = a[\theta_{10} + \theta_{11}x]$$

$$h_2 = a[\theta_{20} + \theta_{21}x]$$

$$h_3 = a[\theta_{30} + \theta_{31}x]$$

$$h_4 = a[\theta_{40} + \theta_{41}x]$$

$$y_1 = \phi_{10} + \phi_{11}h_1 + \phi_{12}h_2 + \phi_{13}h_3 + \phi_{14}h_4$$

$$y_2 = \phi_{20} + \phi_{21}h_1 + \phi_{22}h_2 + \phi_{23}h_3 + \phi_{24}h_4$$

Two outputs

- 1 input, 4 hidden units, 2 outputs

$$h_1 = a[\theta_{10} + \theta_{11}x]$$

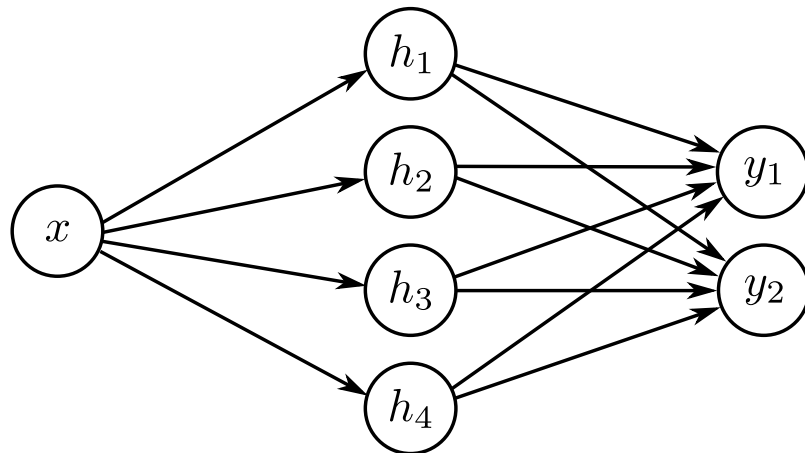
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Two outputs

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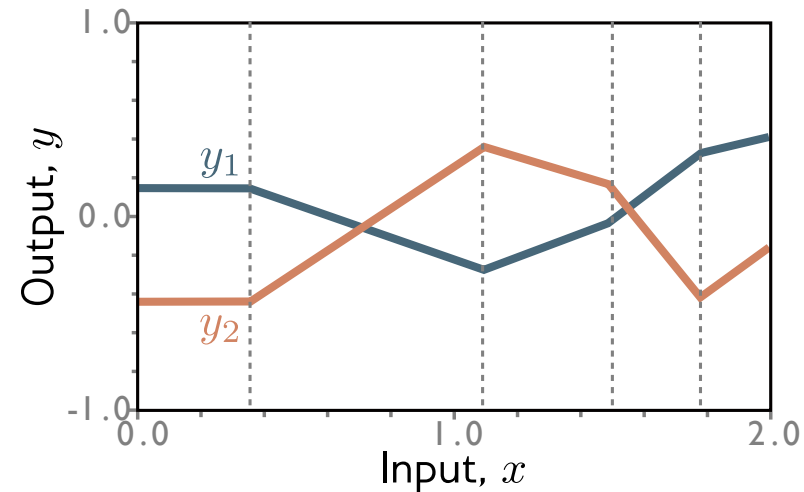
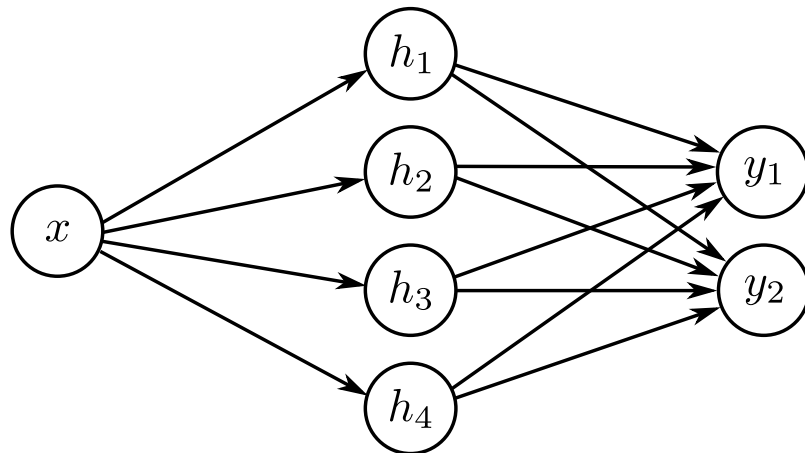
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Shallow neural networks

- Example network, 1 input, 1 output
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Two inputs

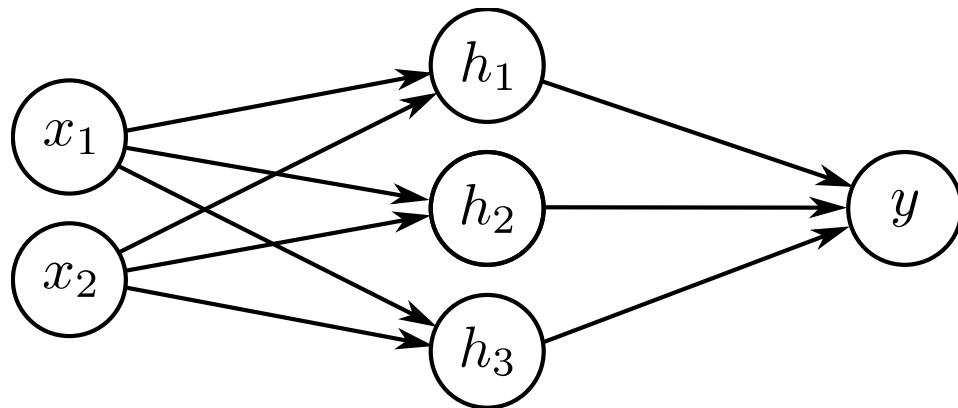
- 2 inputs, 3 hidden units, 1 output

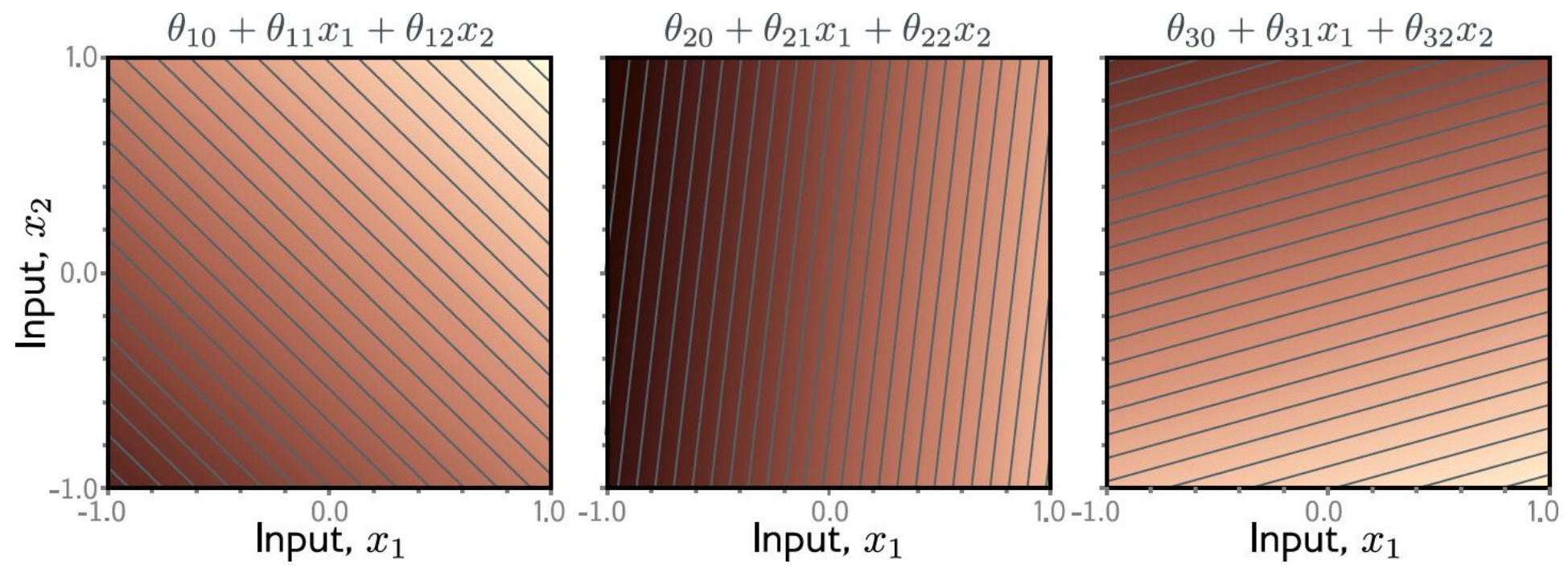
$$h_1 = a[\theta_{10} + \theta_{11}x_1 + \theta_{12}x_2]$$

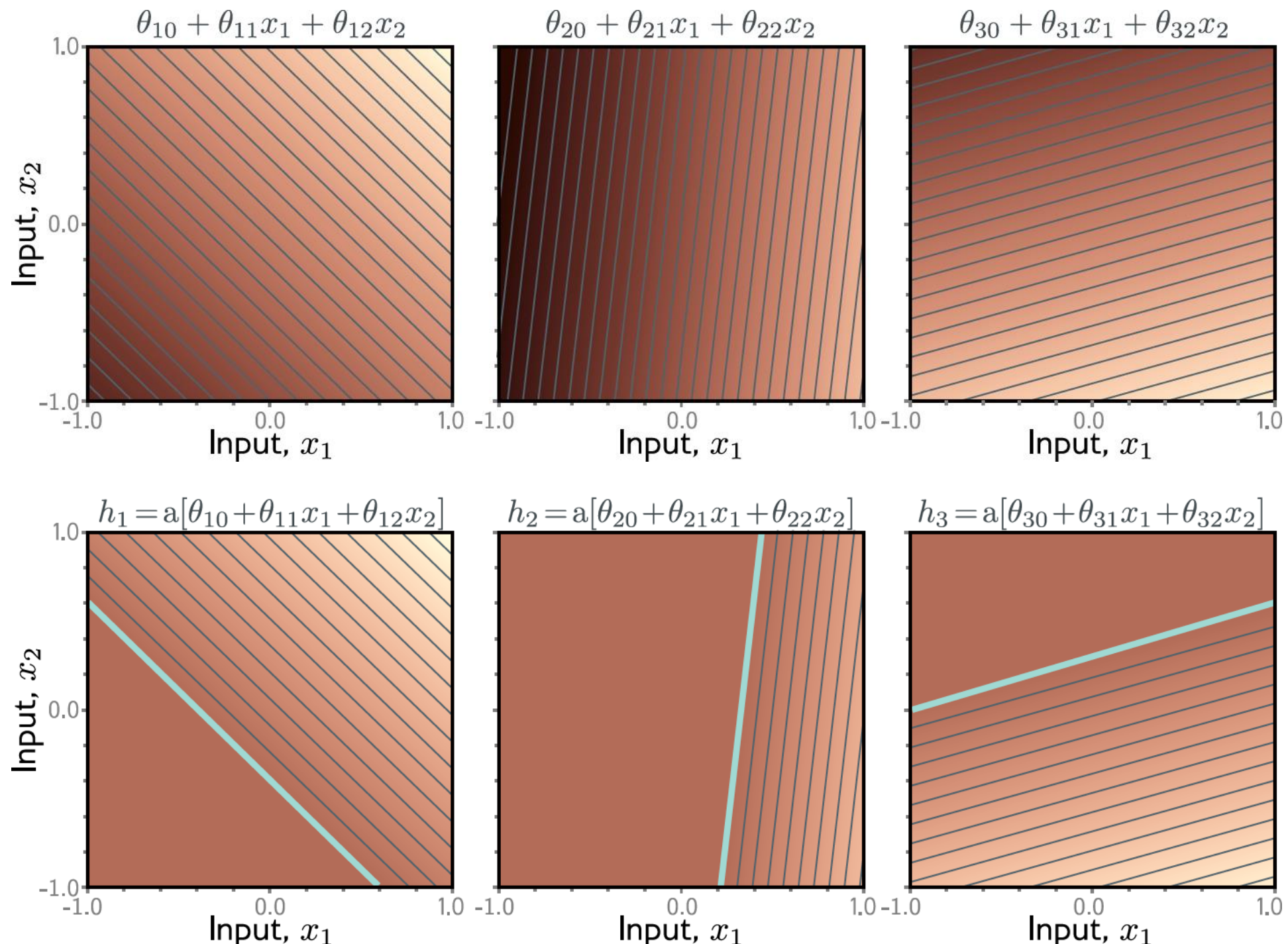
$$h_2 = a[\theta_{20} + \theta_{21}x_1 + \theta_{22}x_2]$$

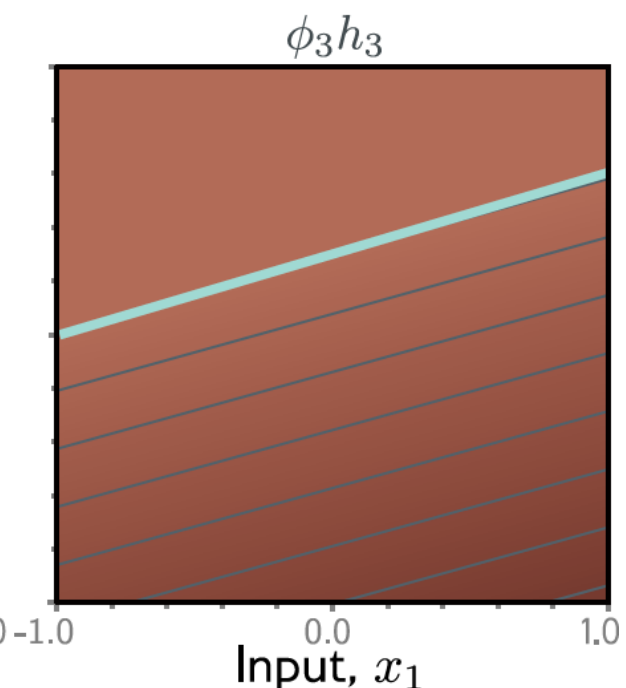
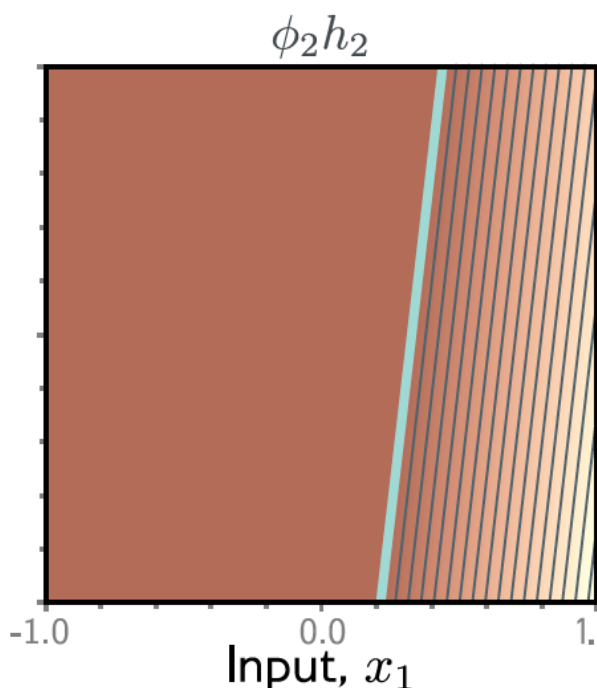
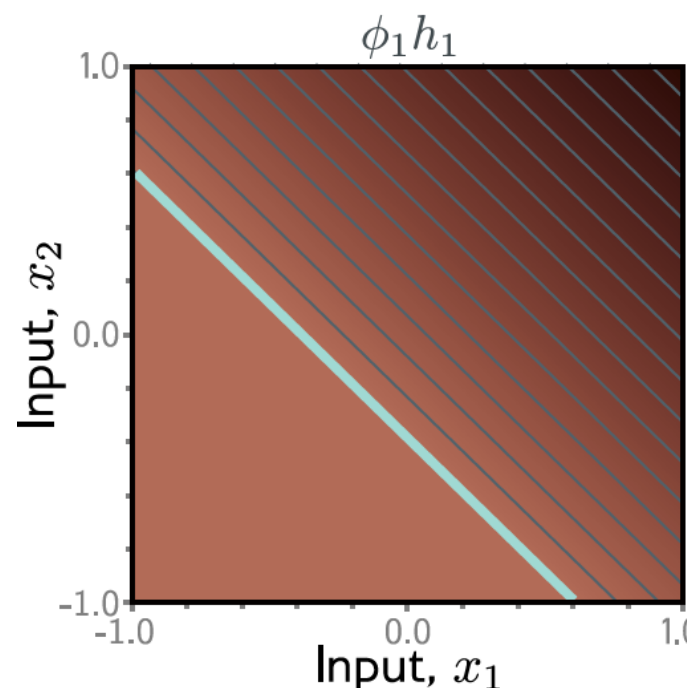
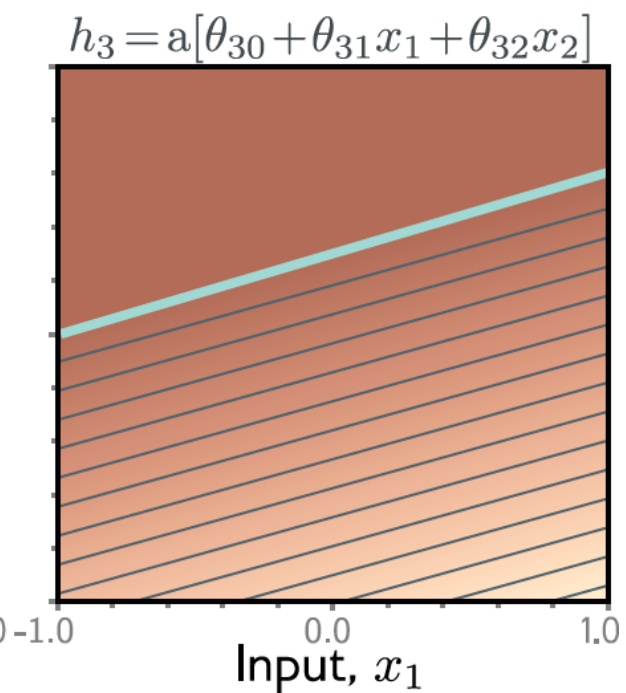
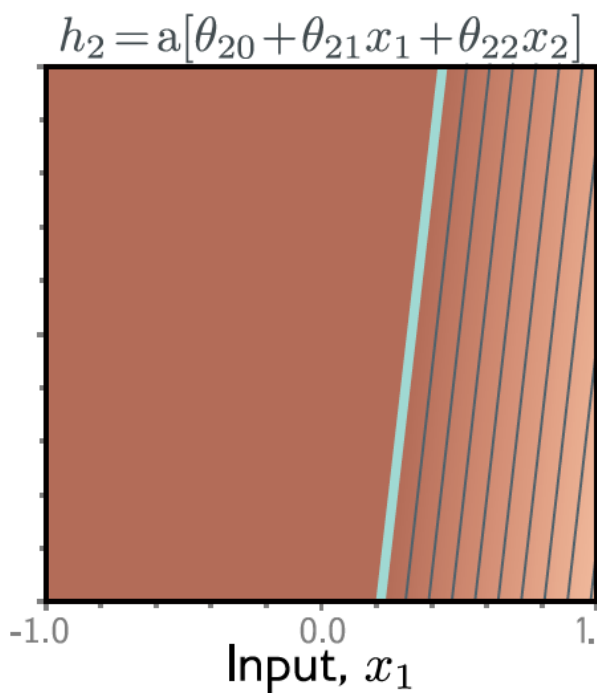
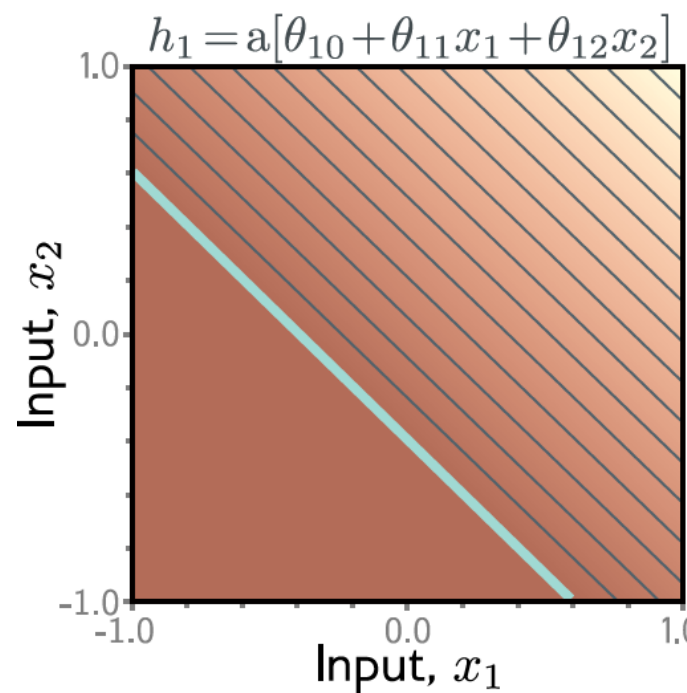
$$h_3 = a[\theta_{30} + \theta_{31}x_1 + \theta_{32}x_2]$$

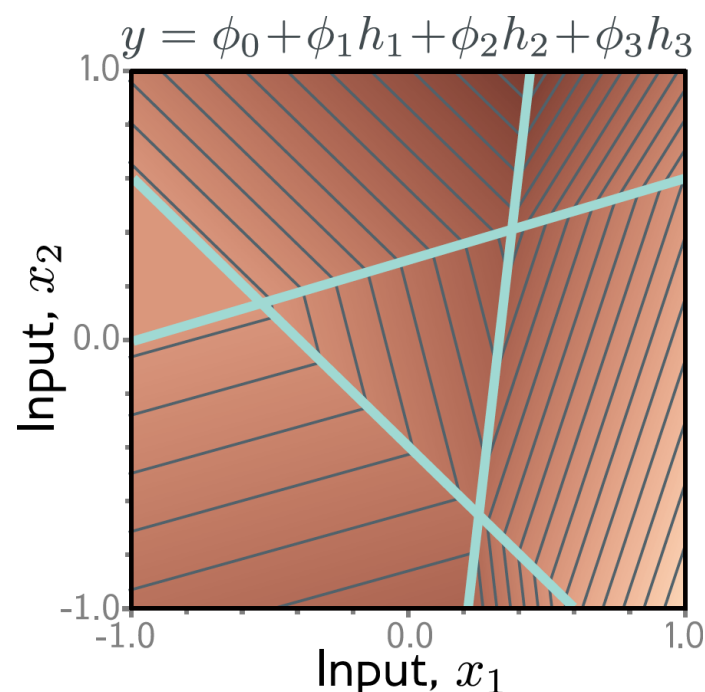
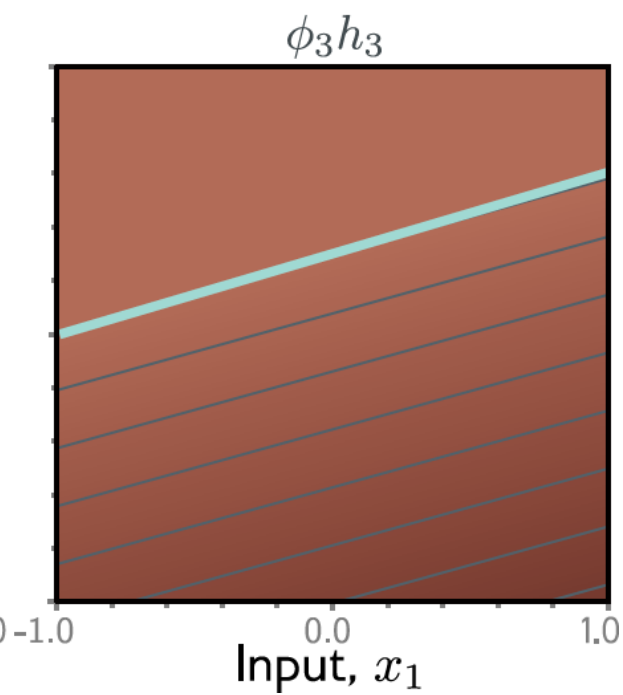
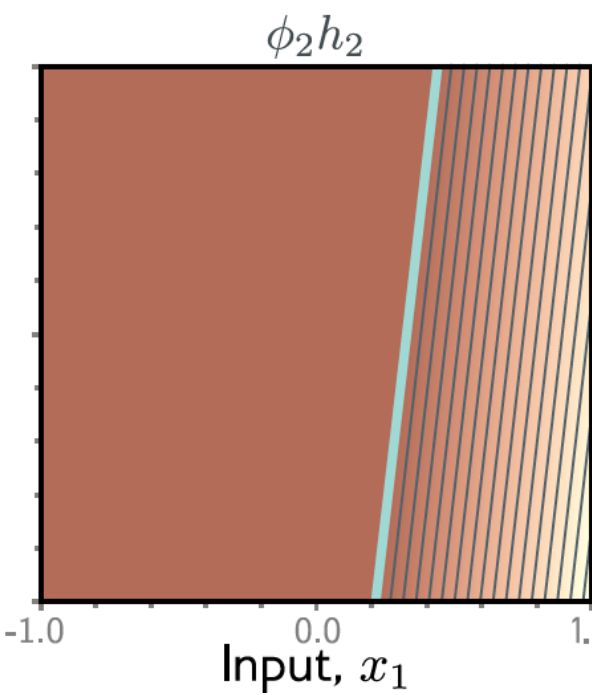
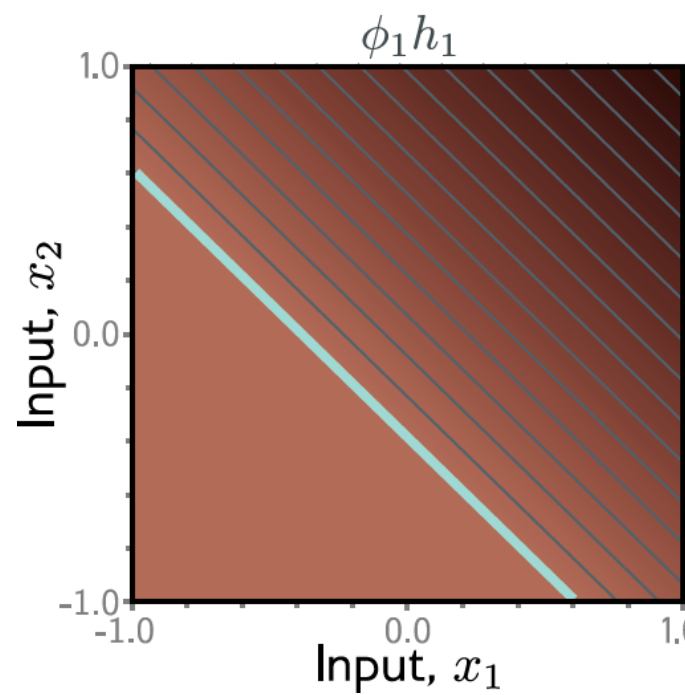
$$y = \phi_0 + \phi_1h_1 + \phi_2h_2 + \phi_3h_3$$

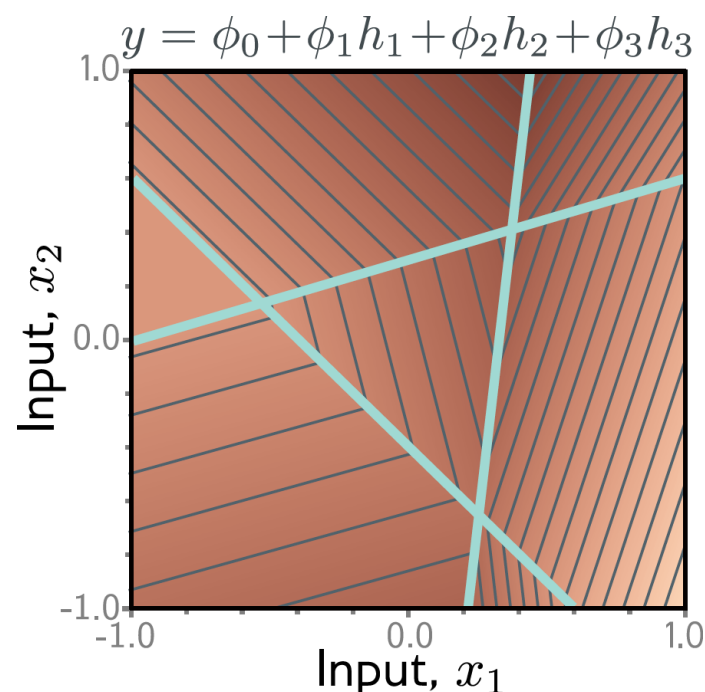
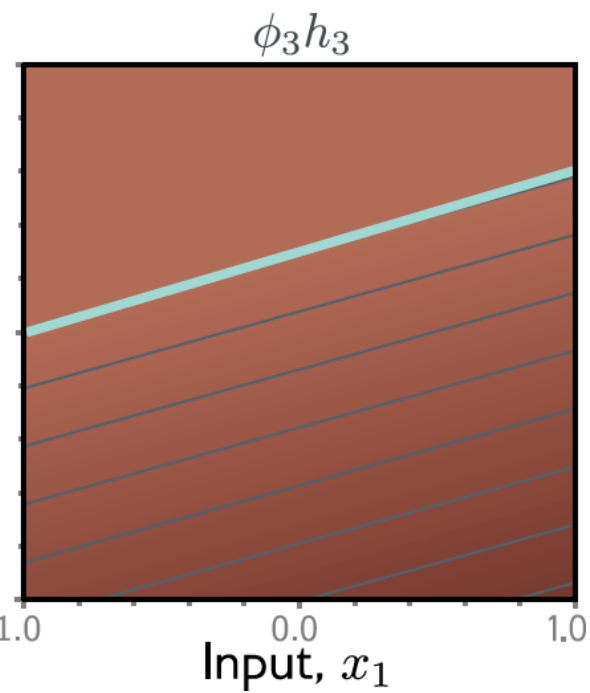
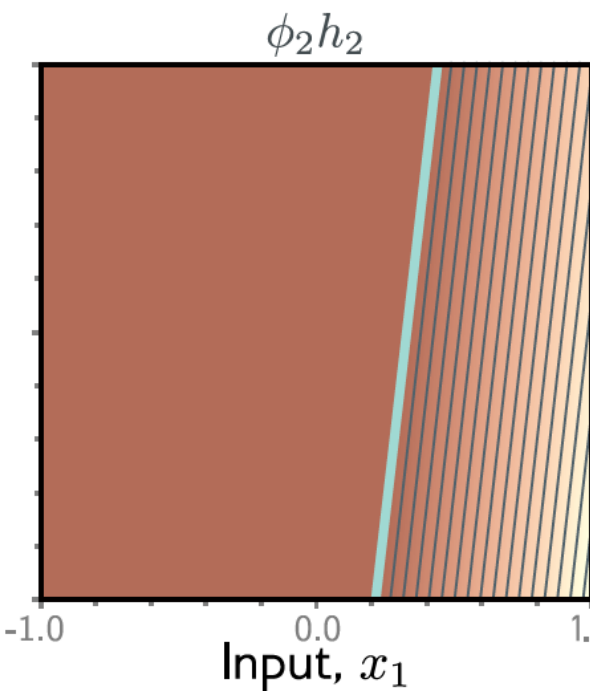
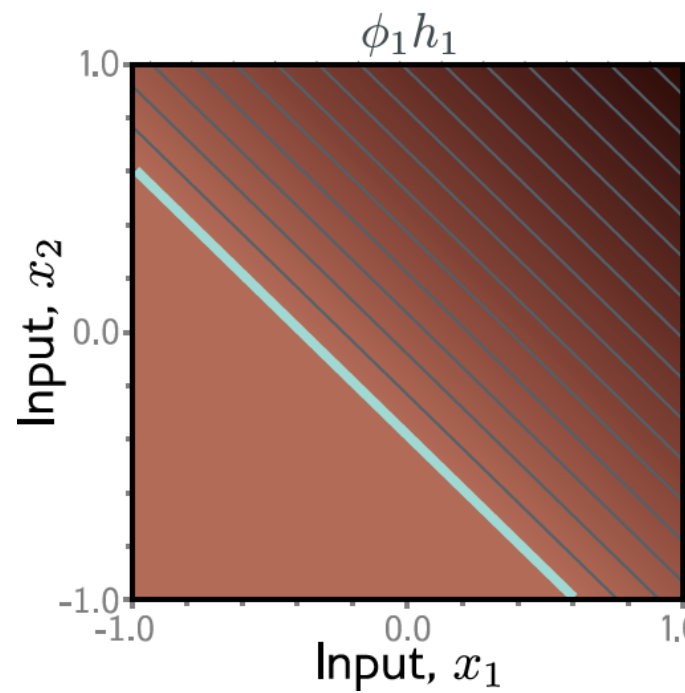






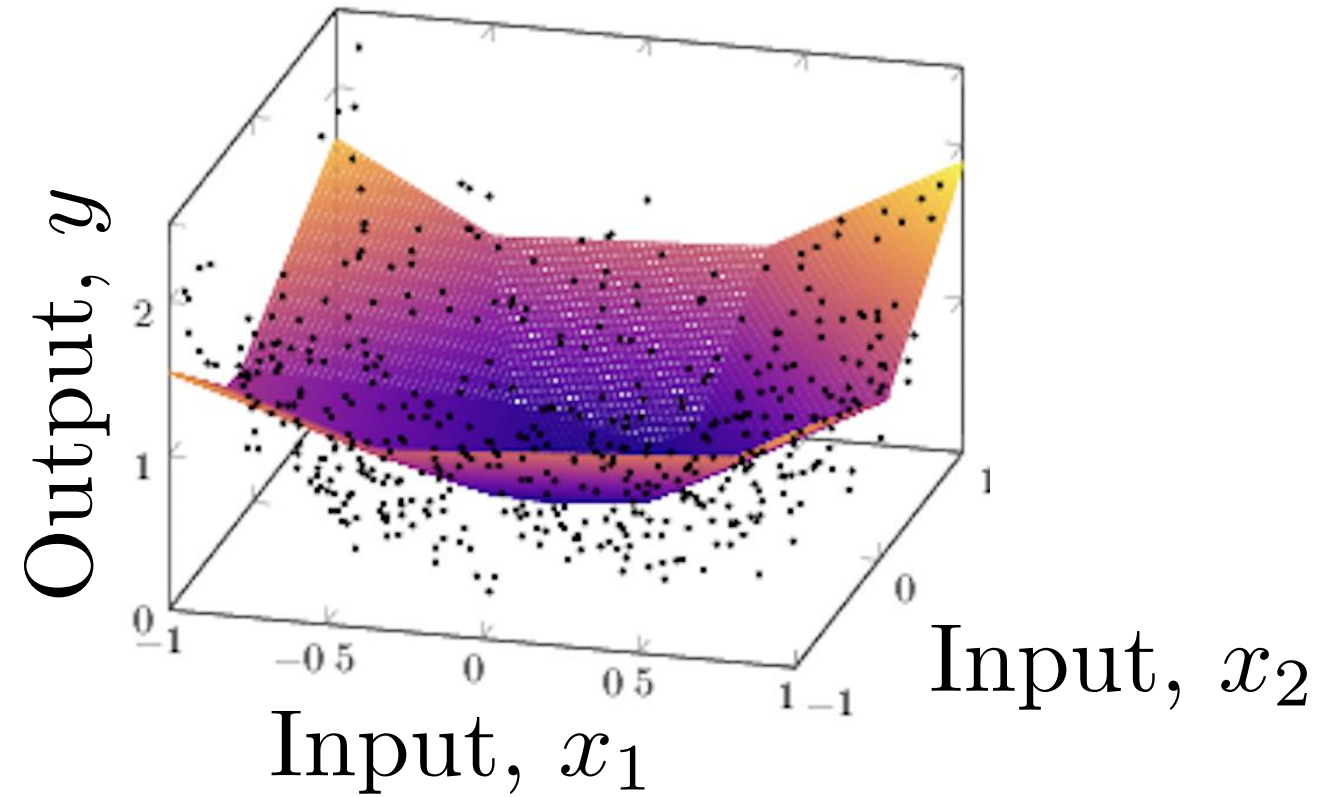
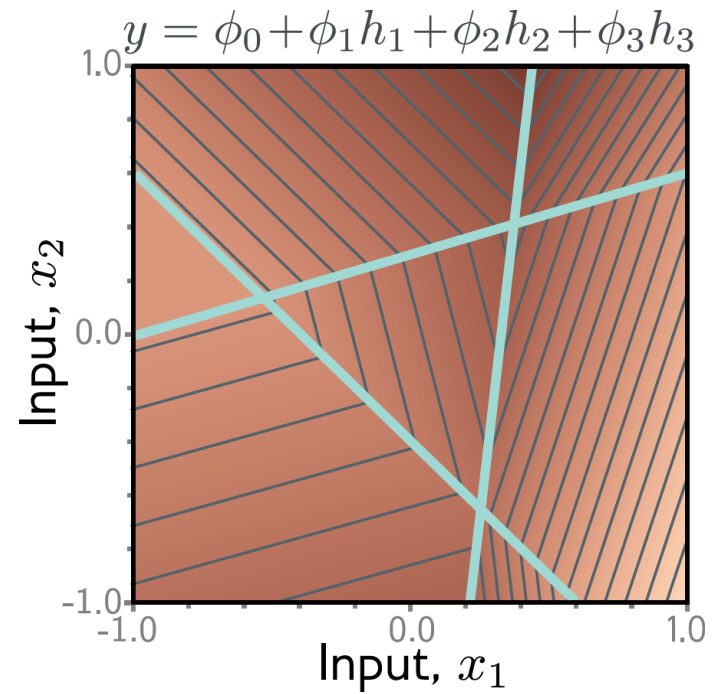






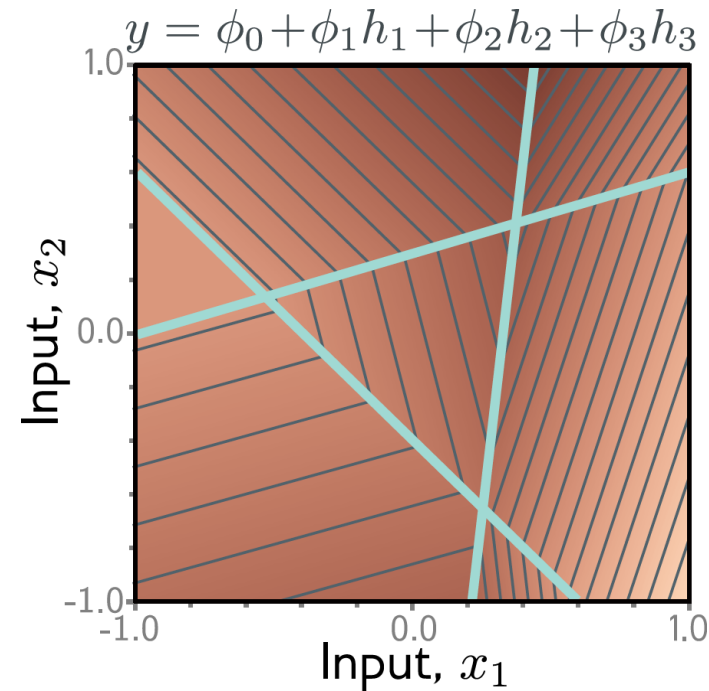
Convex polygons

Fitting



Question:

- For the 2D case, what if there were two outputs?
- If this is one of the outputs, what would the other one look like?



Shallow neural networks

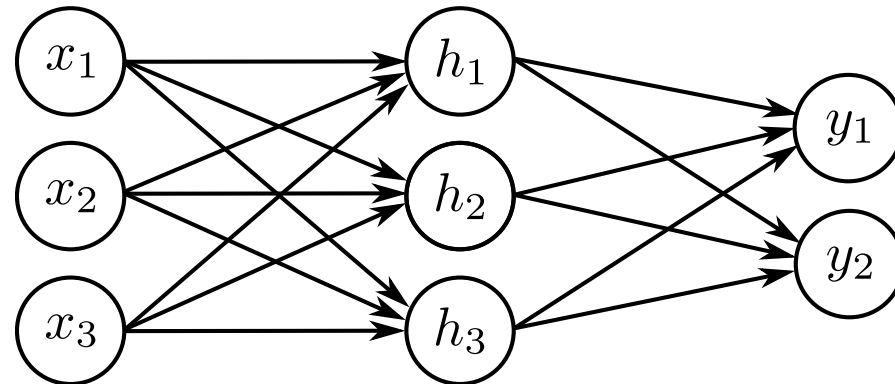
- Example network, 1 input, 1 output
- Universal approximation theorem
- More than one output
- More than one input
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Arbitrary inputs, hidden units, outputs

- D_o Outputs, D hidden units, and D_i inputs

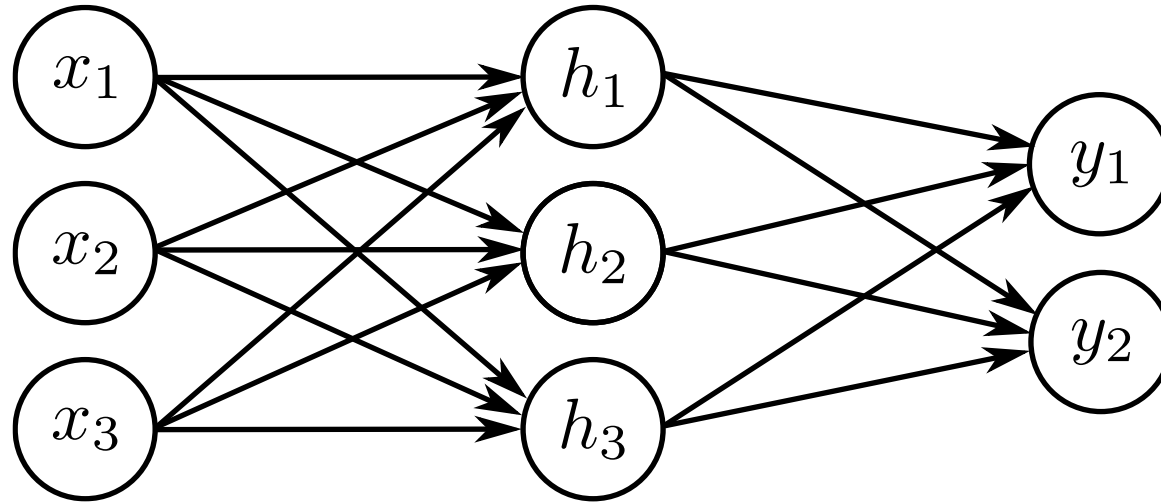
$$h_d = a \left[\theta_{d0} + \sum_{i=1}^{D_i} \theta_{di} x_i \right] \quad y_j = \phi_{j0} + \sum_{d=1}^D \phi_{jd} h_d$$

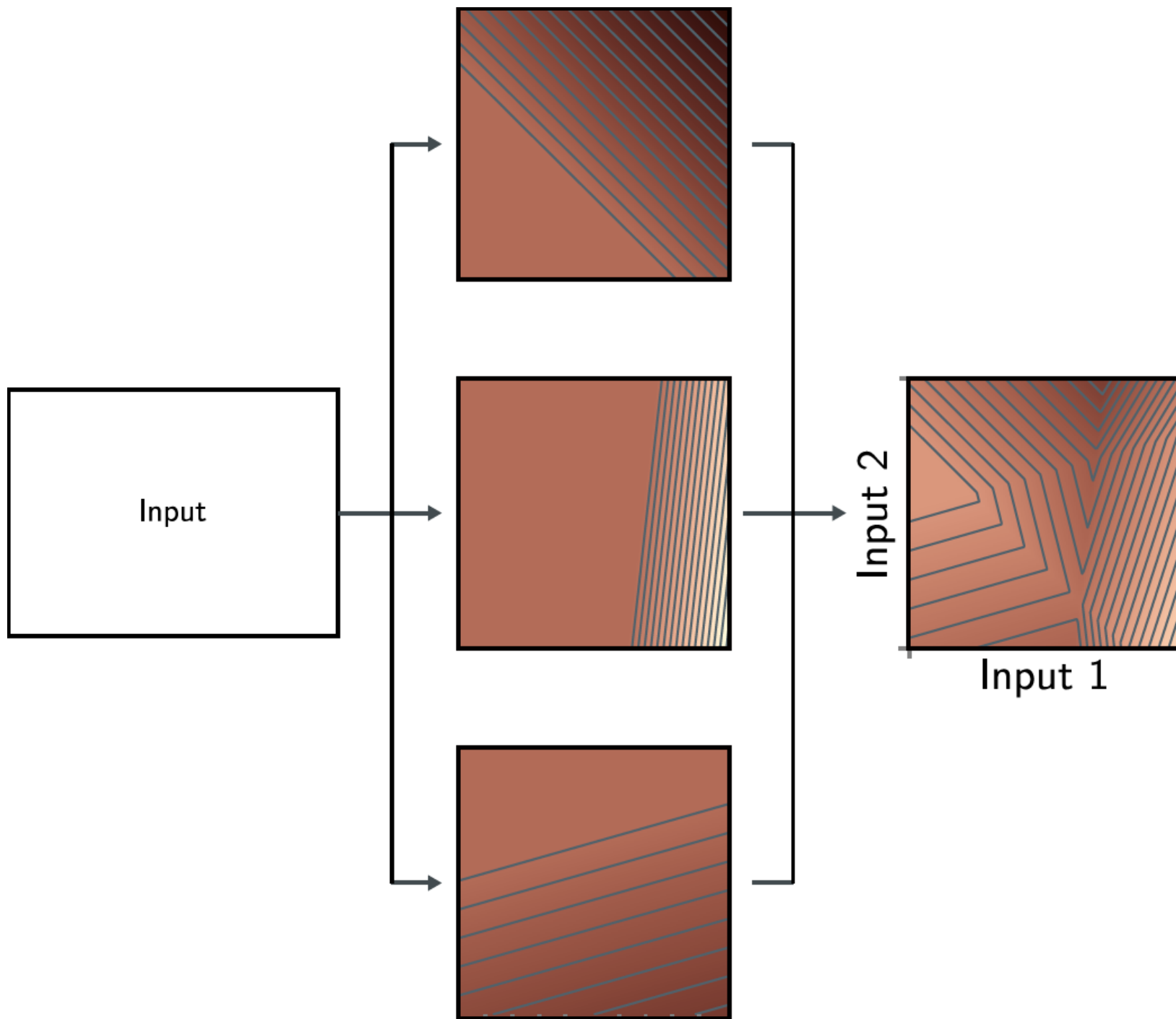
- e.g., Three inputs, three hidden units, two outputs

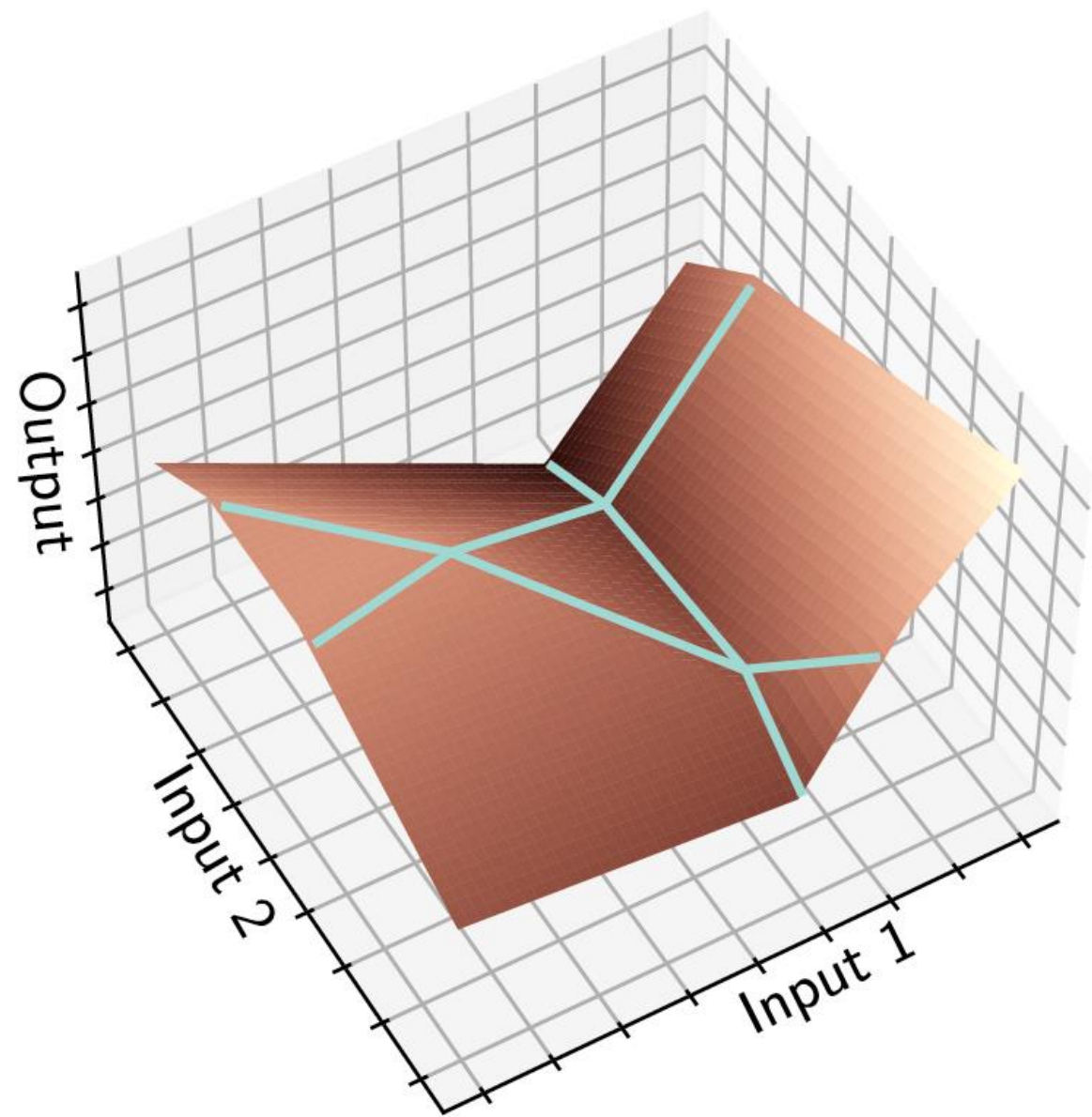
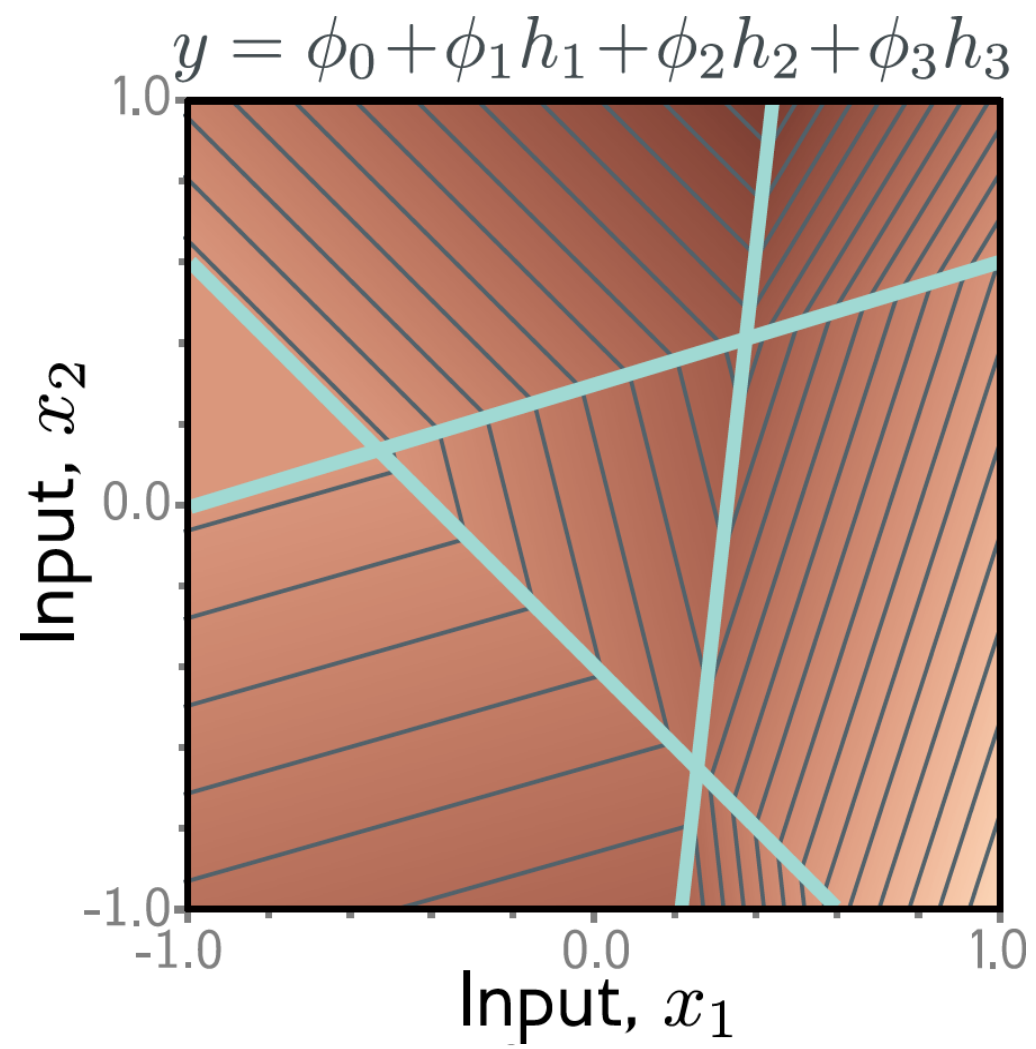


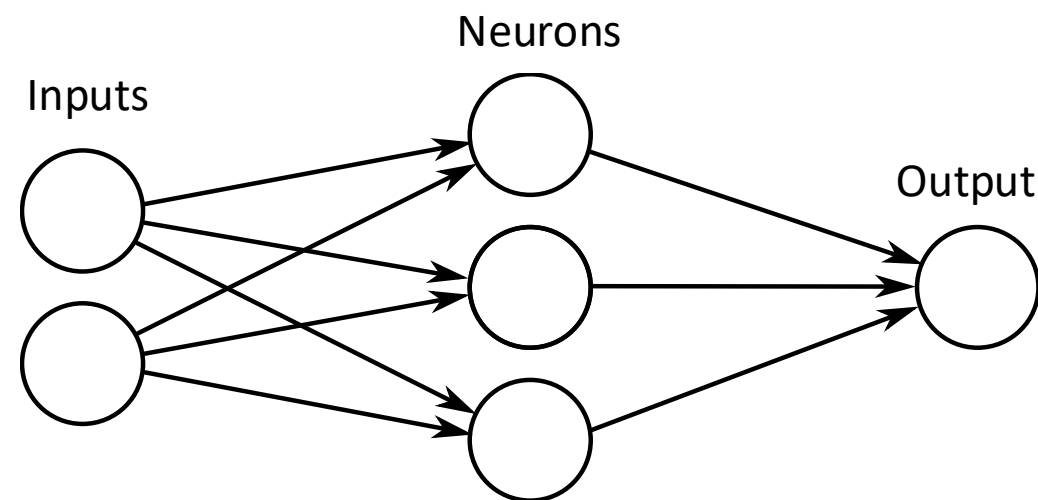
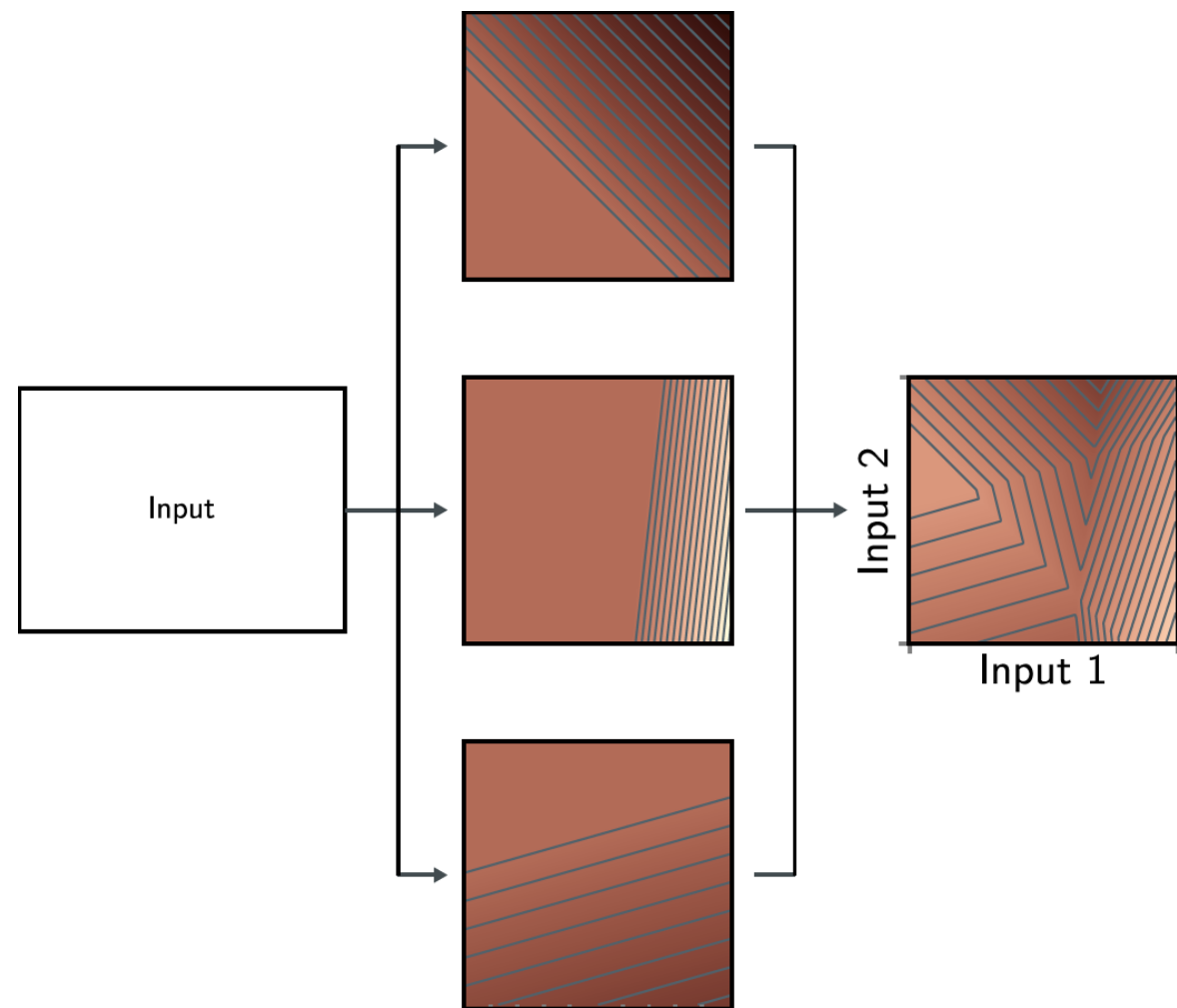
Question:

- How many parameters does this model have?









“neural network”

$$y = \phi_0 + \phi_1 h_1 + \phi_2 h_2 + \phi_3 h_3$$

$$h_1 = a[\theta_{10} + \theta_{11}x_1 + \theta_{12}x_2]$$

$$h_2 = a[\theta_{20} + \theta_{21}x_1 + \theta_{22}x_2]$$

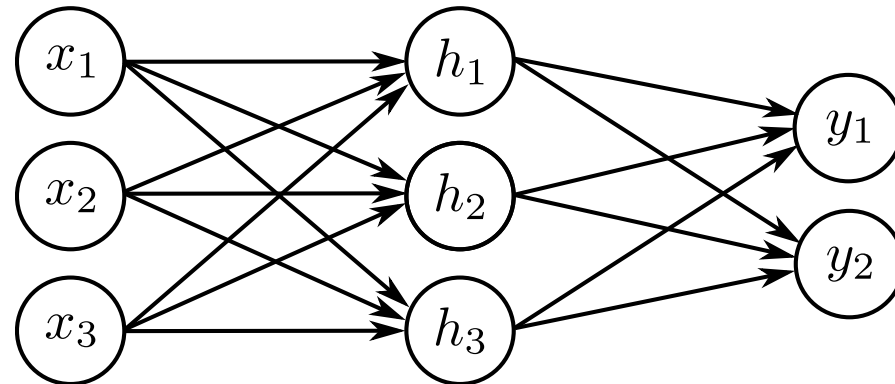
$$h_3 = a[\theta_{30} + \theta_{31}x_1 + \theta_{32}x_2]$$

Arbitrary inputs, hidden units, outputs

- D_o Outputs, D hidden units, and D_i inputs

$$h_d = a \left[\theta_{d0} + \sum_{i=1}^{D_i} \theta_{di} x_i \right] \quad y_j = \phi_{j0} + \sum_{d=1}^D \phi_{jd} h_d$$

- e.g., Three inputs, three hidden units, two outputs

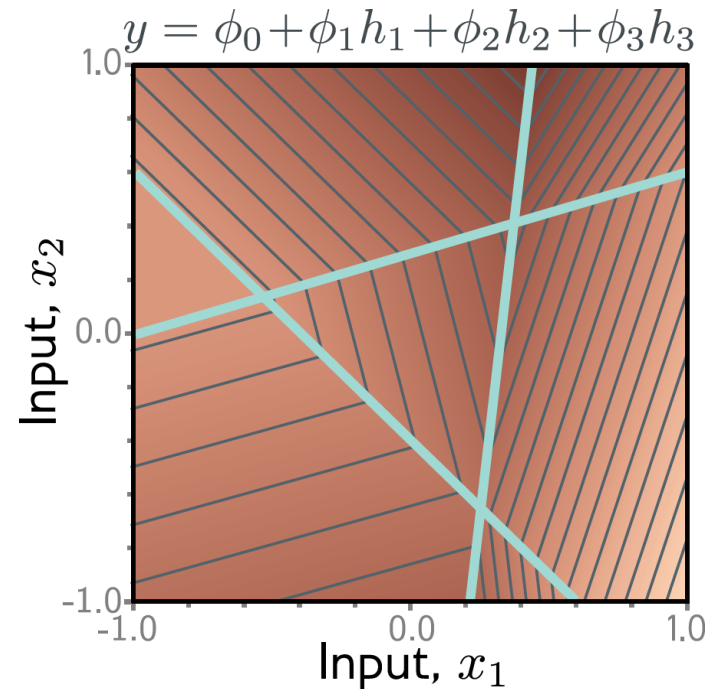


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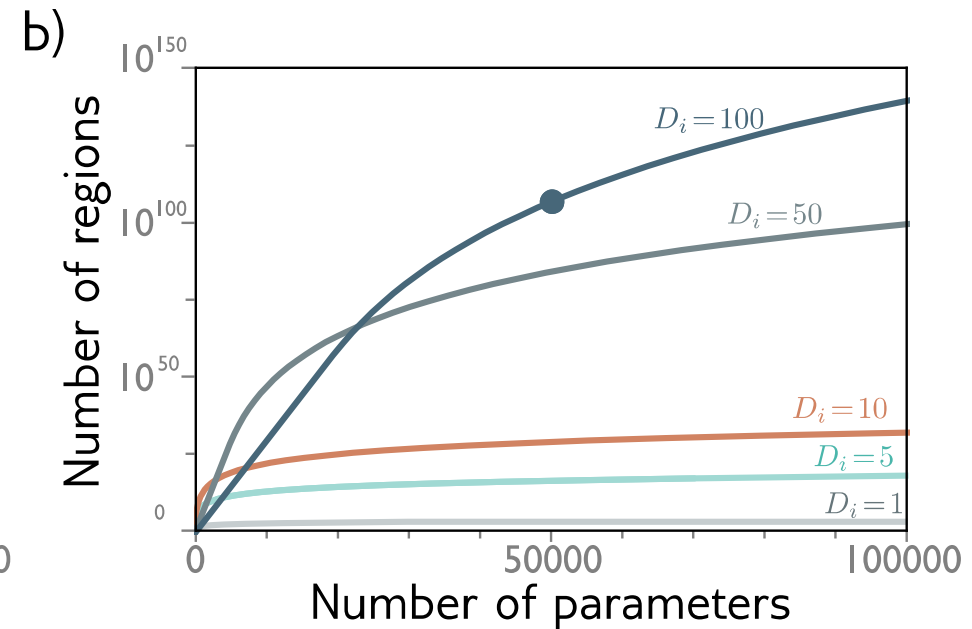
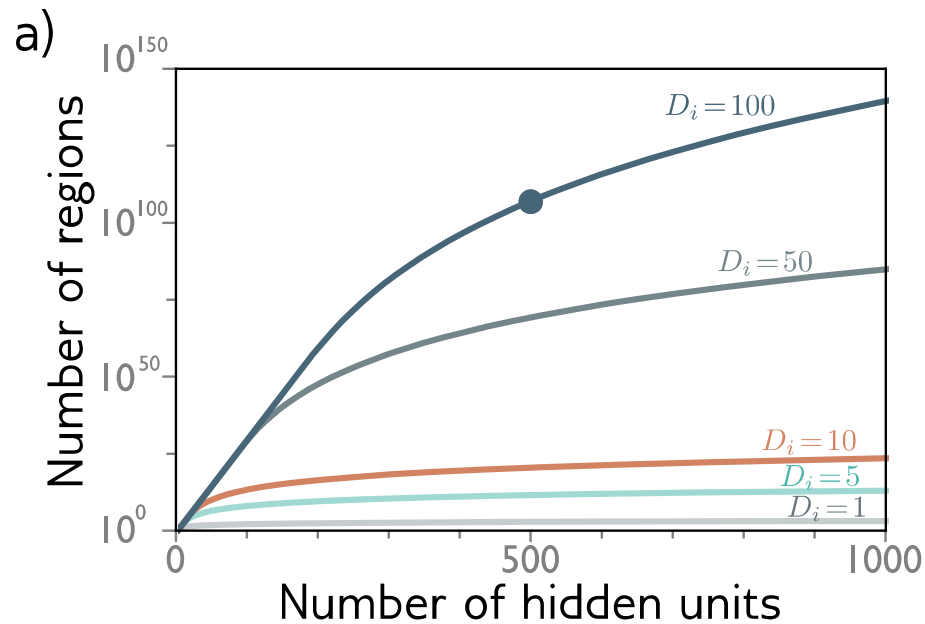
Number of output regions

- In general, each output consists of D dimensional **convex polytopes**
- With two inputs, and three outputs, we saw there were seven polygons:



Number of output regions

- In general, each output consists of D dimensional **convex polytopes**
- How many?



Highlighted point = 500 hidden units or 51,001 parameters

Number of regions:

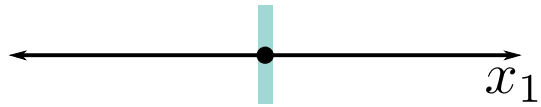
- Number of regions created by $D > D_i$ planes in D_i dimensions was proved by Zaslavsky (1975) to be:

$$\sum_{j=0}^{D_i} \binom{D}{j} \leftarrow \text{Binomial coefficients!}$$

- How big is this? It's greater than 2^{D_i} but less than 2^D .

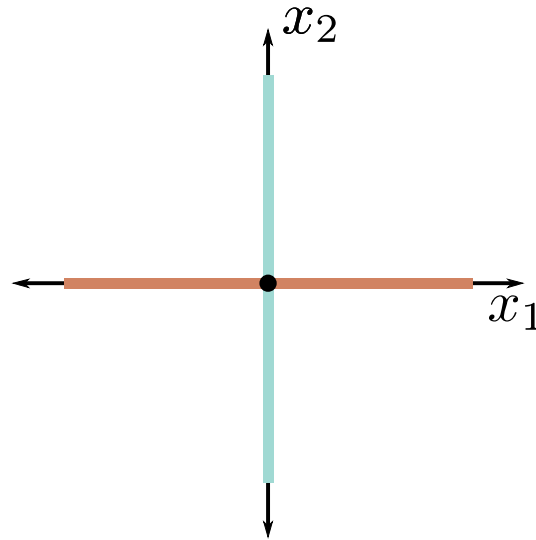
Proof that more regions than 2^{Di}

a)



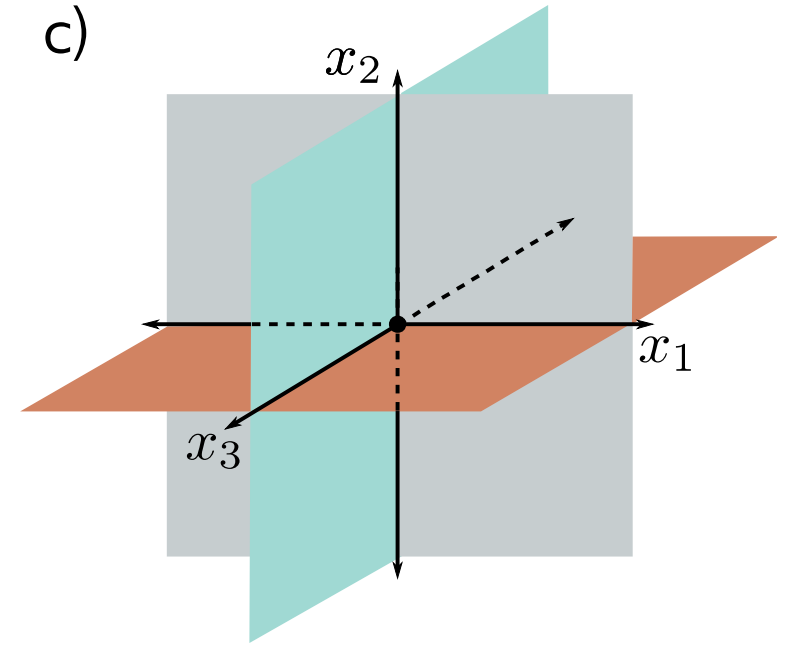
1D input with 1 hidden
unit creates two regions
(one joint)

b)



2D input with 2 hidden
units creates four regions
(two lines)

c)

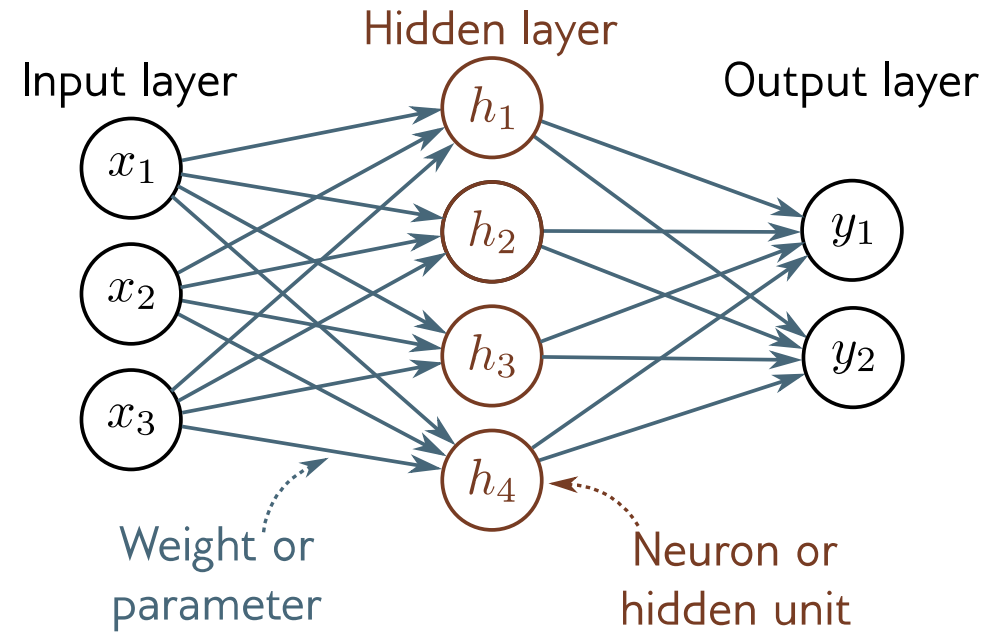


3D input with 3 hidden
units creates eight regions
(three planes)

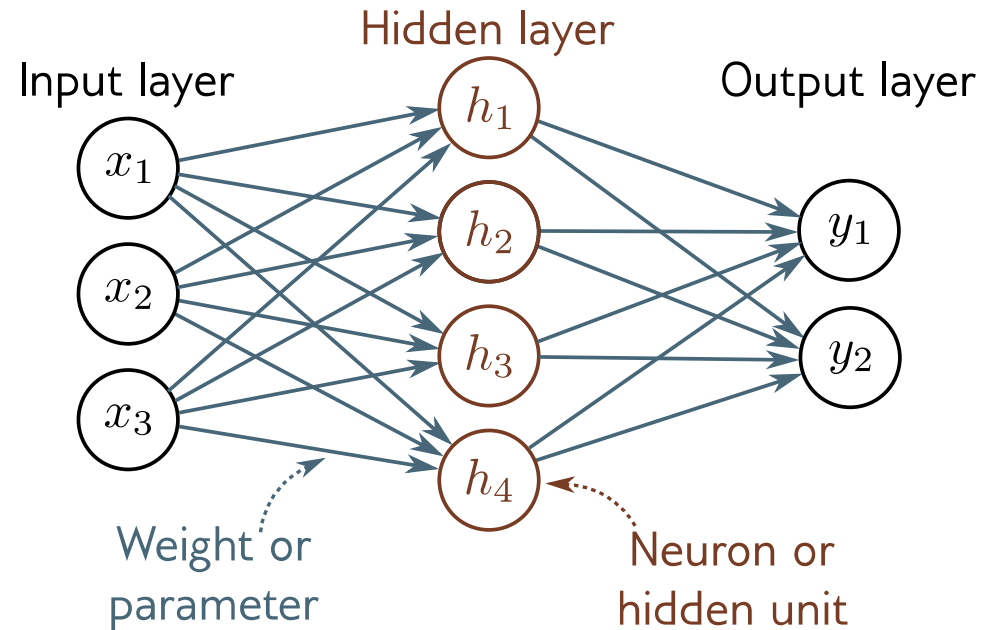
Shallow neural networks

- Example network, 1 input, 1 output
- Universal approximation theorem
- More than one output
- More than one input
- General case
- Number of regions
- Terminology

Nomenclature

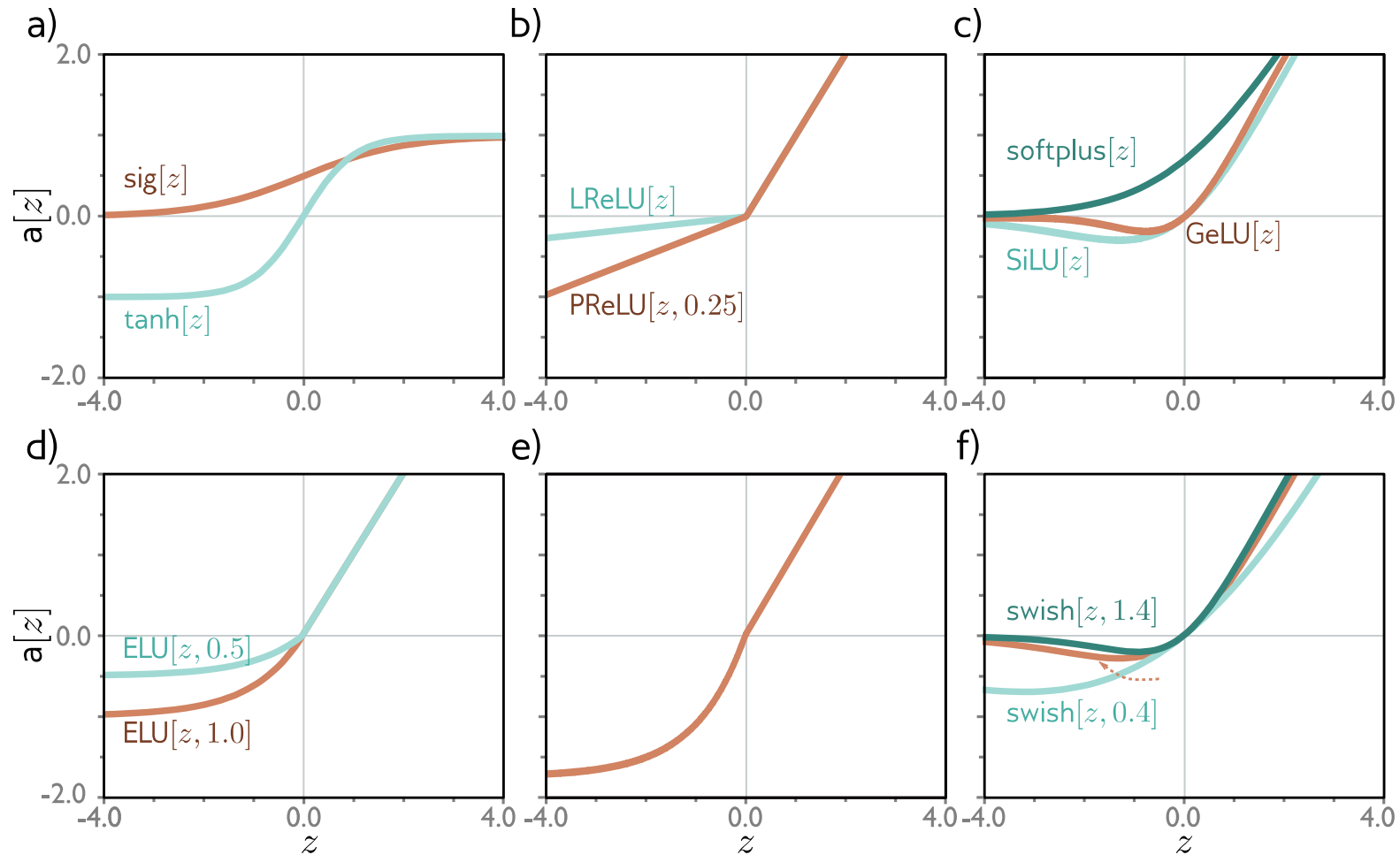


Nomenclature

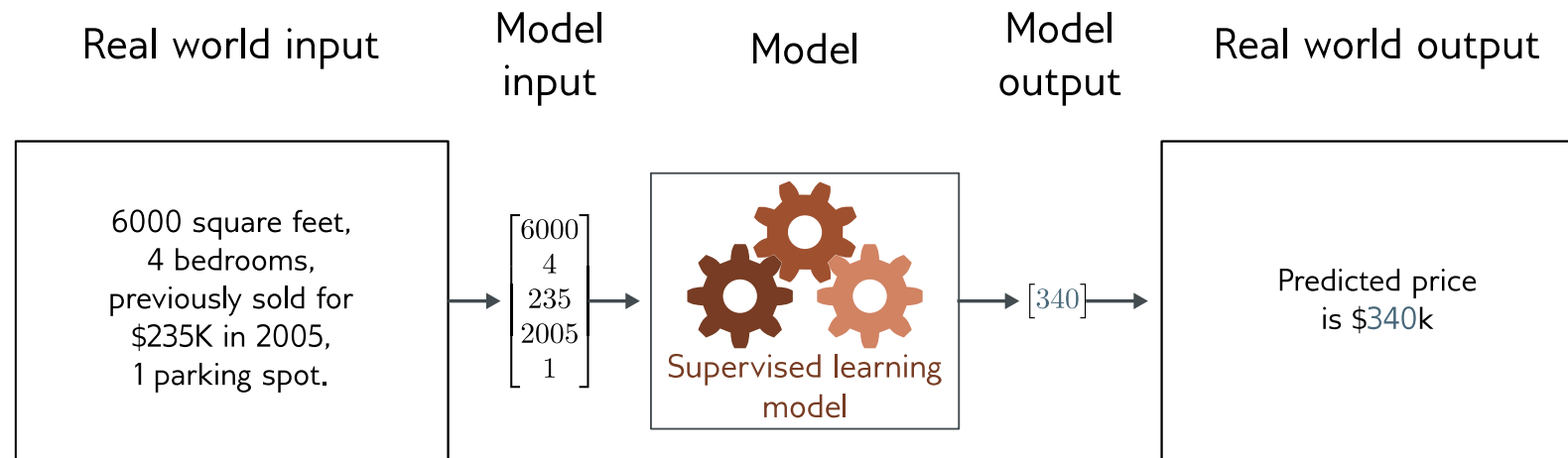


- Y-offsets = **biases**
- Slopes = **weights**
- Everything in one layer connected to everything in the next = **fully connected network**
- No loops = **feedforward network**
- Values after ReLU (activation functions) = **activations**
- Values before ReLU = **pre-activations**
- One hidden layer = **shallow neural network**
- More than one hidden layer = **deep neural network**
- Number of hidden units \approx **capacity**

Other activation functions



Regression



We have built a model that can:

- take an arbitrary number of inputs
- output an arbitrary number of outputs
- model a function of arbitrary complexity between the two

$$h_d = a \left[\theta_{d0} + \sum_{i=1}^{D_i} \theta_{di} x_i \right] \qquad y_j = \phi_{j0} + \sum_{d=1}^D \phi_{jd} h_d$$

Next time:

- What happens if we feed one neural network into another neural network?



Feedback