Instructions to follow the structure of code.

1. The main file is ***eigenface.m*** which calls other peripheral functions.
2. ***Eigenface.m*** file utilizes the function call to ***comAccu.m*** to compute the accuracy for application of each of the distance metrics studied.
3. Upon running the code, accuracies are captured in the variables namely ***acc\_Mahal, acc\_Eucl, acc\_CityBlo*** computed for the respective distance metrics as coded in the variable names.
4. Matrices ***comp\_CityBlo, comp\_Eul, comp\_mahal*** store the comparison results for testing images ground truth vs inferred in the order. So, column one represents the ground truth; column2 represents the inferred mapping. Accuracies are computed subsequently from these matrices.