

#### Checkmate with Al

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#### Historical Background

#### Historical Progression

- Rooted in trial-and-error learning (Thorndike's Law of Effect)
- Incorporates dynamic programming and Markov Decision Processes

#### Advance in Games

- Samuel's Checkers Player (1959): Demonstrated RL in game strategies
  - Used a value function for state evaluation
  - Pioneered the use of minimax strategy combined with RL concepts
- **TD-Gammon** (1992): Combined RL with neural networks for complex games (e.g., backgammon)



#### Introduction

Supervised

Data: (x,y)

x is the data, y is the label

Goal: Learn function to map

x **→** y

Apple Example:



This object is an apple

UnSupervised

Data: (x,y)

x is the data, no labels!

Goal: Learn underlying structure

Apple Example:





This object is like the other object

Reinforcement Learning

Data: State Action Pairs

Goal: Maximize future rewards

Apple Example:

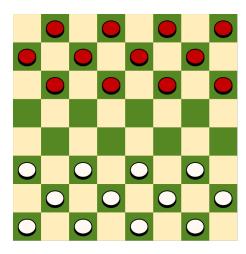


Eat this thing because it will keep you alive



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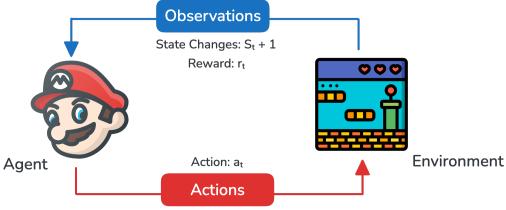
- Checkers is a strategy game involving diagonal moves of pieces and captures by jumping over opponent pieces
- The objective of the project is to create an Al player using reinforcement learning
- Techniques: Q-learning and Deep Q-Networks (DQN)





## What is Reinforcement Learning?

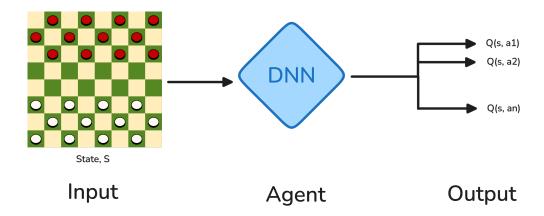
- A machine learning paradigm focused on training agents to make sequences of decisions
- Key components:
  - Agent: Learns to act in an environment
- Environment: The system with which the agent interacts
- Reward: Feedback signal indicating the success of an action
- Goal: Maximize cumulative rewards over time





## Deep Q-Learning

- reinforcement learning technique to find the optimal action-value function Q(s,a)
- It maps state-action pairs to their expected future rewards







#### Deep Q-Learning: Q-update rule

$$Q^{\mathsf{new}}(s_t, a_t) \leftarrow Q(s_t, a_t) + \underbrace{\alpha}_{\mathsf{learning \ rate}} \cdot \underbrace{\left(r_t + \underbrace{\gamma}_{\mathsf{discount \ factor}} \cdot \underbrace{\max_{a} Q(s_{t+1}, a)}_{\mathsf{estimate \ of \ optimal \ future \ value}} - \underbrace{Q(s_t, a_t)}_{\mathsf{old \ value}}\right)}_{\mathsf{discount \ factor}}$$



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Challenge: Traditional Q-learning fails for large or continuous state spaces



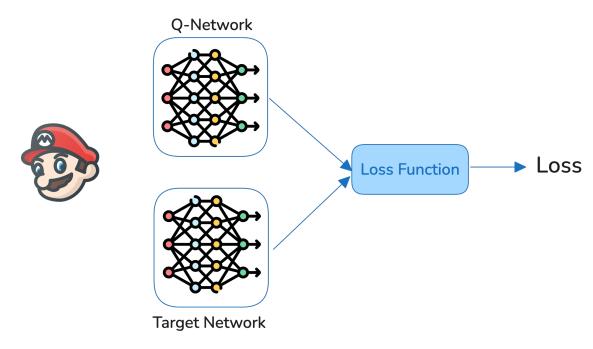


#### Deep Q-Learning: Solution

Use a **Deep Neural Network** (DNN) as a function approximator for Q(s, a) instead of a table

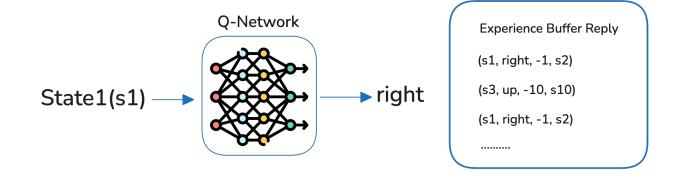
- Input: State s, Output: Q-values for all actions a
- Target Network: stabilizes training by holding fixed weights for a few updates
- Experience Replay: samples random batches of past experiences (s, a, r, s') to break correlation in training data













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Q-Network  $Q(s, a; \theta)$  and Target Network  $Q'(s, a; \theta^-)$ 



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Use an arepsilon- greedy policy to balance exploration vs. exploitation



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Add (s, a, r, s') to a replay buffer



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- 4. Train the Network:
  - sample a minibatch from the buffer
  - Compute target Q-values:  $y = r + \gamma \max_{a'} Q'(s', a'; \theta^-)$
  - Minimize loss:  $L(\theta) = (y Q(s, a; \theta))^2$



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- 5. Update Target Network:

Periodically copy weights:  $\theta^- \leftarrow \theta$ 



# Key Improvements and Applications

#### Improvements:

- Double DQN: Reduces overestimation of Q-values
- **Dueling DQN**: Separates value and advantage functions
- Prioritized Experience Replay: Samples important experiences more frequently





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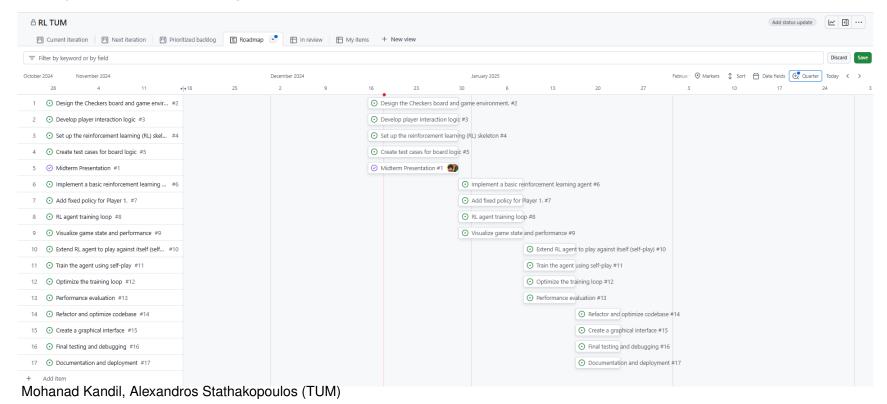
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#### Applications:

- Games
- robotics
- autonomous systems



## Project Planning & Timeline





#### Software Stack

- Python
- numpy (for matrix calculations)
- pygame (fast UI)
- Web frameworks
- tensorflow (for ML implementation)



#### **Future Work**

- Fine-tuning the DQN model for improved decision-making
- Incorporating advanced techniques like Double DQN and Dueling DQN
- Testing against human players to evaluate real-world performance
- Extending the approach to other board games or strategy games (some side-projects)



#### Thank You

