

# OCaml in Practice : Building Functional systems

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## **PART I**

# ***Part 1 : First Steps***

## PART II

# *Part 2 : Storage Engine*

## CHAPTER 1

# *Log Structured Merge*

## PART III

# *Part 3 : Distributed Consensus*

## CHAPTER 2

# *RAFT Distributed consensus protocol*

### Abstract

The Raft consensus Algorithm was designed by Diego Ongaro and John Ousterhout at Stanford University. Apart from other characteristics they argue that it is designed for **Understandability**.

The following primary characteristics are what the Raft authors mention.

- Consensus is agreement of shared state
- System is up if majority of servers are up
- Needed for consistent, fault-tolerant storage systems



## 2.1 Remote Procedure Calls and State Machine

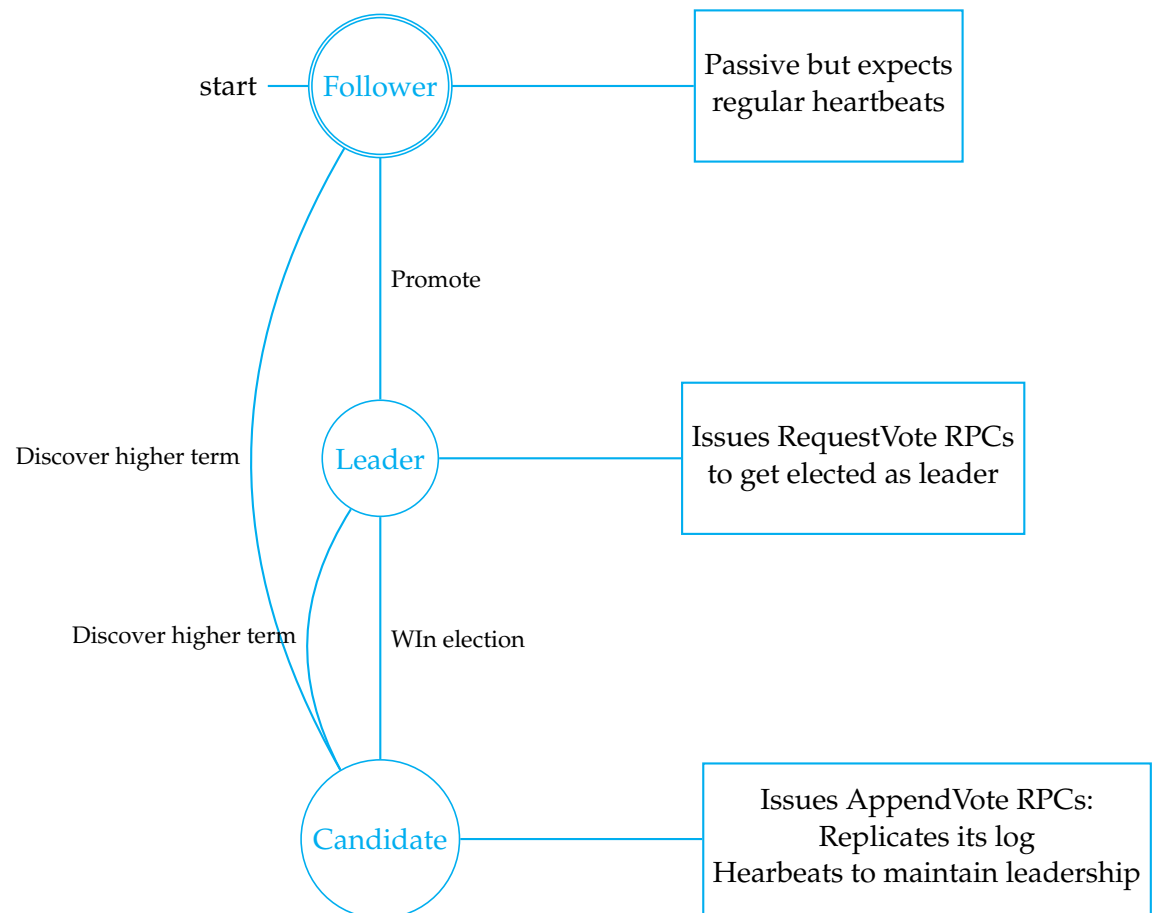


Figure 2.1

## 2.2 Leader Election

## 2.3 The Term

A term is a value that is sent with every RPC and received in every response. It is used to identify obsolete information (*e.g*) If a peer has a later term, the term is updated and the status is reverted to *Follower*. Every server maintains its own term and so there is no-*Global view*.

```
1  let get_state = function
2    | `Leader -> "leader."
3    | `Follower -> "follower."
4    | `Candidate -> "candidate."
5    | `Dead -> "_dead."
```

*Code 2.1: A example with parameter in a environment.*

- RequestVote : Solicits votes from other members of the cluster
- AppendEntries : Replicates the log and can also server as a heartbeat

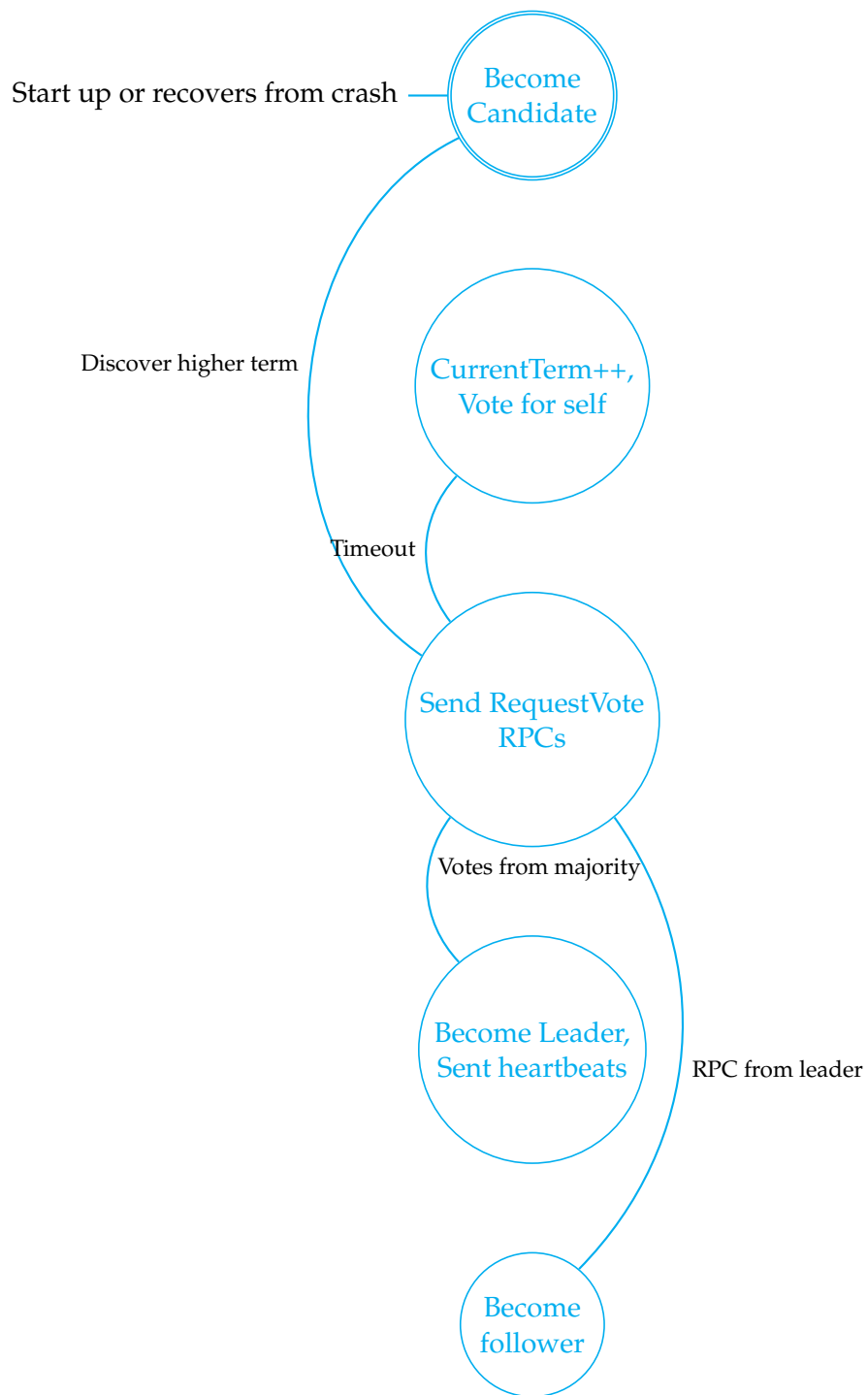


Figure 2.2: John Ousterhout's presentation.

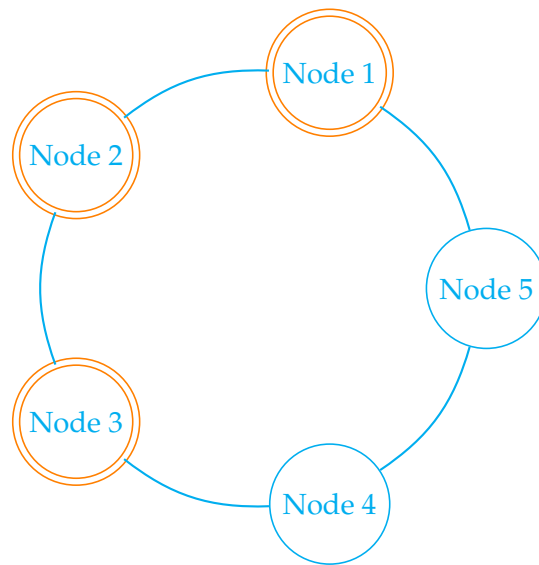


Figure 2.3: John Outershout's presentation

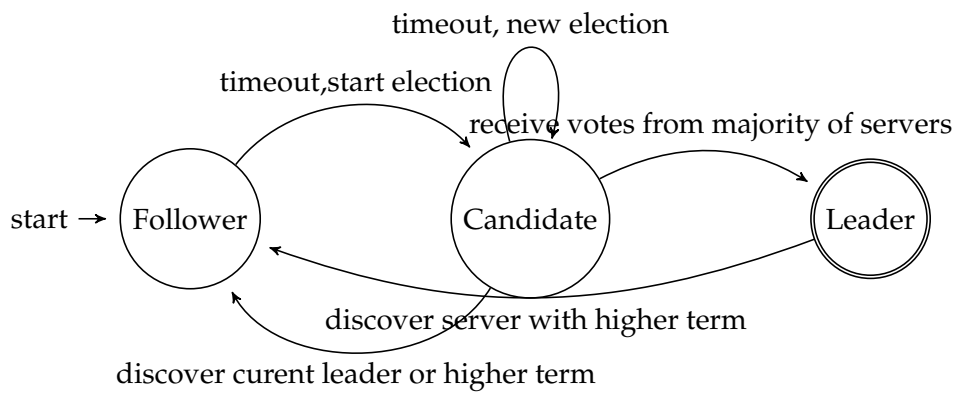


Figure 2.4