	<pre>import pandas as pd import time import os from sklearn.decomposition import TruncatedSVD</pre>
	Attention: This assignment is computationally heavy, and inefficient implementations may not pass the autograding even if they technically produce the correct results. To avoid this, make sure you read and understand all the instructions before starting to implement the tasks. Failure to follow the instructions closely will most likely cause timeouts. It is your responsibility to make sure your implementation is not only correct, but also as efficient as
	possible. If you follow all the instructions provided, you should be able to have all the cells evaluated in under 10 minutes. *Assignment Summary CIFAR-10 is a dataset of 32x32 images in 10 categories, collected by Alex Krizhevsky, Vinod Nair, and Geoffrey Hinton. It is often used to evaluate machine learning algorithms. You can download this dataset from https://www.cs.toronto.edu/~kriz/cifar.html. • For each category, compute the mean image and the first 20 principal components. Plot the error
	resulting from representing the images of each category using the first 20 principal components against the category. • Compute the distances between mean images for each pair of classes. Use principal coordinate analysis to make a 2D map of the means of each categories. For this exercise, compute distances by thinking of the images as vectors. • Here is another measure of the similarity of two classes. For class A and class B, define E(A B) to be the average error obtained by representing all the images of class A using the mean of class A and the first 20 principal components of class B. Now define the similarity between classes to be (1/2)(E(A B) + E(B A)). If A and B are very similar, then this error should be small, because A's principal components should be good at representing B. But if they are very different, then A's principal components should represent B poorly. In turn, the similarity measure should be big. Use principal coordinate analysis to make a 2D map of the classes. Compare this map to the map in the previous exercise? are they different? why?
	 O.1 Description CIFAR-10 is a dataset of 32x32 images in 10 categories, collected by Alex Krizhevsky, Vinod Nair, and Geoffrey Hinton. It is often used to evaluate machine learning algorithms. You can download this dataset from https://www.cs.toronto.edu/~kriz/cifar.html. O.2 Information Summary Input/Output: This data has a set of 32 pixel rows, 32 pixel columns, and 3 color channels. Therefore, each single image, is vectorized, will consist of 32 × 32 × 3 elements (i.e., each image has 3072 dimensions). There are a total of 60000 samples labelled from 10 class. The data set is balanced with each class having exactly 6000 samples. Missing Data: There is no missing data. Final Goal: We want to understand the data using multi-dimensional scaling methods. Compute mean image for ea of 10 categories and first 20 principal components.
	 Plot the error resulting from representing the images of each category using the first 20 principal components against the category. (?) Compute the distances between mean image vectors for each pair of classes. (90 pairs) Use principal coordinate analysis to make a 2D map of the means of each categories. For this exercise, compute distances by thinking of the images as vectors. Here is another measure of the similarity of two classes. For class A and class B, define: E(A B): average error obtained by representing all the images of class A using the mean of class A and the first 20 principal components of class B. similarity(A, B) = (1/2)(E(A B) + E(B A)). If A and B are very similar, then this error should be small, because A's principal components should be good at representing B. But if they are very different, then A's principal components should represent B poorly. In turn, the similarity measure should be big. Use principal coordinate analysis to make a 2D map of the classes. Compare this map to the map in the previous exercise? are they different? why? Each image is 32x32x3 N = 60k O.3 Loading The Data If you are curious how the original data was obtained, we used the torchvision API to download and preprocess it. The ready-to-use data is stored in numpy format for easier access.
In [2]: In [3]:	<pre>np_file = np.load('/PCA-lib/cifar10.npz') train_images_raw = np_file['train_images_raw'] train_labels = np_file['train_labels'] eval_images_raw = np_file['eval_images_raw'] eval_labels = np_file['eval_labels'] else: import torchvision import shutil download_ = not os.path.exists('/PCA-lib/cifar10/') data_train = torchvision.datasets.CIFAR10('/PCA-lib/cifar10', train=True, trans data_eval = torchvision.datasets.CIFAR10('/PCA-lib/cifar10', train=False, trans shutil.rmtree('/PCA-lib/cifar10/') train_images_raw = data_train.data train_labels = np.array(data_train.targets) eval_images_raw = data_eval.data eval_labels = np.array(data_eval.targets) np.savez('/PCA-lib/cifar10.npz', train_images_raw=train_images_raw, train_label</pre>
<pre>In [4]: Out[4]:</pre>	'horse': 7, 'ship': 8, 'truck': 9} images_raw = np.concatenate([train_images_raw, eval_images_raw], axis=0) labels = np.concatenate([train_labels, eval_labels], axis=0) images_raw.shape, labels.shape ((60000, 32, 32, 3), (60000,)) 1. Principal Component Analysis 1. Let's say we have Data Matrix X with N rows (i.e., data points) and d columns (i.e., features). $X = [\cdots]_{N \times d}$
	2. Let's perform SVD on the X . $X=U_xS_xV_x^T$ Let's assume $N>d$ (We have 6000 data points per class, which is more than the 3072 dimenstions). By the way SVD works, we should have $U_x=[\cdots]_{N\times d}$ $S_x=[\cdots]_{d\times d}$ $V_x=[\cdots]_{d\times d}$ and $U_x^TU_x=I_{d\times d}$ $V_x^TV_x=I_{d\times d}$
	1. The textbook says we need the following decomposition for the covariance matrix Σ : $\Sigma \mathcal{U} = \mathcal{U}\Lambda$ 2. We assume that X has mean zero (i.e., we already subtracted the feature averages). If X has N rows (i.e., data items), we have $\Sigma = \frac{1}{N}X^TX$ 3. Let's find Σ in terms of U_x , S_x , and V_x $\Sigma = \frac{1}{N}X^TX = \frac{1}{N}V_xS_xU_x^TU_xS_xV_x^T = V_x\frac{S_x^2}{N}V_x^T$ $\Rightarrow \Sigma V_x = V_x\frac{S_x^2}{N}$
	4. By comparison, we have $\mathcal{U}=V_x$ $\Lambda=\frac{S_x^2}{N}$ Considering the above: 1. There is no need to compute the covariance matrix Σ and then find its diagonalization; You can
	easily perform SVD on the data matrix X , and get what you need! 2. In fact, you do not even need the matrices V_x and U_x for computing the mean squared error; You can infer the mean squared error using only the S_x matrix. • Numpy's SVD function <code>np.linalg.svd</code> has an argument <code>compute_uv</code> that turns off returning the U and U matrices for better efficiency. Therefore, you may be able to save some runtime in large data sets if you only care about the mean squared error! Task 1 Write a function <code>pca_mse</code> that takes two arguments as input 1. <code>data_raw</code> : a numpy array with the shape (N, \cdots) , where V is the number of samples, and there may be many excess dimensions denoted by V you will have to reshape this input <code>data_raw</code> matrix to obtain a shape of V where V is the vectorized data's dimension. For example, <code>data_raw</code> could have an input shape of V you. So,
	 2. num_components: This is the number of PCA components that we want to retain. This variable is denoted by r in the PCA definition in the textbook. and returns the variable mse which is the mean squared error of the PCA projection into the designated number of principal components. Important Note: Make sure you use np.linalg.svd for the SVD operation. Do not use any other matrix factorization function for this question (such as np.linalg.eig). Important Note: Make sure you read and understand the notes from the previous cells before you start implementing. Failing to properly set the arguments for np.linalg.svd or trying to find the mean squared error by calculating the reconstruction error may cause extreme delays and timeouts for your implementation. Hint: If you don't know how to extract the mean squared error of the PCA projection, or don't have a fresh
	probability and statistics memory, take a look at the Principal Component Analysis chapter of the most recent version of the textbook; the subsection titled "The error in a low-dimensional representation" explains how to find the mean squared error of the PCA projection as a function of the eigenvalues that were dropped. p.linalg.svd argument compute_uv turns off U and V. It's useful if you only care about the mean squared error!** Find MSE of PCA projection as function of eigenvalues that were dropped: Principal Component Analysis chapter > "The error in a low-dimensional representation" (5.1.4) Procedure 5.1:
In [5]:	<pre>def pca_mse(data_raw, num_components=20): #MoCode0 #reshape n dim to 2 dim #multiply dim 2 * dim 3 * * dim n d = np.prod(data_raw.shape[1:]) N = data_raw.shape[0] data_raw = data_raw.reshape(N, d) #calculate the mean of each column with axis = 0 to get a column vector and reshamean_raw = np.mean(data_raw, axis = 0).reshape(1, d) data_raw = data_raw - mean_raw r = num_components #calculate MSE of the PCA projection into the designated number of principal comp # a is factorized as u @ np.diag(s) @ vh = (u * s) @ vh, where u and vh are 2D un # returns: s(, K) array: Vector(s) with the singular values, within each vector #The first a.ndim - 2 dimensions have the same size as those of the input a. s = np.linalg.svd(data_raw, compute_uv = False) lams = s**2/N #mse = sum(lams[r:d+1]) mse = sum(lams[r:d+1]) #MoCode0 assert np.isscalar(mse) return np.float64(mse)</pre>
<pre>In [6]: In [7]: In [8]:</pre>	<pre># Performing sanity checks on your implementation some_data = (np.arange(35).reshape(5,7) ** 13) % 20 some_mse = pca_mse(some_data, num_components=2) assert some_mse.round(3) == 37.903 # Checking against the pre-computed test database test_results = test_case_checker(pca_mse, task_id=1) assert test_results['passed'], test_results['message'] # This cell is left empty as a seperator. You can leave this cell as it is, and you s</pre>
<pre>In [9]: In [10]:</pre>	class_names = [] class_mames = [] for cls_name, cls_label in class_to_idx.items(): data_raw = images_raw[labels == cls_label,:,:,:] start_time = time.time() print(f'Processing Class {cls_name}', end='') cls_mse = pca_mse(data_raw, num_components=20) print(f' (The SVD operation took %.3f seconds)' % (time.time()-start_time)) class_names.append(cls_name) class_mses.append(cls_mse) Processing Class airplane (The SVD operation took 8.876 seconds) Processing Class bird (The SVD operation took 8.722 seconds) Processing Class cat (The SVD operation took 8.722 seconds) Processing Class deer (The SVD operation took 8.775 seconds) Processing Class dog (The SVD operation took 8.806 seconds) Processing Class frog (The SVD operation took 8.806 seconds) Processing Class horse (The SVD operation took 8.810 seconds) Processing Class ship (The SVD operation took 8.681 seconds) Processing Class ship (The SVD operation took 8.610 seconds) Processing Class truck (The SVD operation took 8.610 seconds) Processing Class truck (The SVD operation took 8.746 seconds)
In [11]:	<pre>if perform_computation: fig, ax = plt.subplots(figsize=(9,4.), dpi=120) sns.barplot(class_names, class_mses, ax=ax) ax.set_title('The Mean Squared Error of Representing Each Class by the Principal ax.set_xlabel('Class') _ = ax.set_ylabel('Mean Squared Error')</pre> The Mean Squared Error of Representing Each Class by the Principal Components 4000000 3500000 15000000 1500000 150000000 150000000 15000000 15000000 15000000 15000000 150000000 1500000000
In [12]:	<pre>for cls_label in sorted(class_to_idx.values()): data_raw = images_raw[labels == cls_label,:,:,:] class_mean = np.mean(data_raw, axis=0).reshape(1,-1) class_mean_list.append(class_mean) class_means = np.concatenate(class_mean_list, axis=0)</pre>
	Task 2 Write a function mean_image_squared_distances that takes the matrix class_means as an input and return the SquaredDistances matrix as output. class_means is a numpy array like a traditional data matrix; it has a shape of (N, d) where there are N individual data-points where each is stored in a single d dimensional row. (N, d) could be anything, so do not make assumptions about it. Your job is to produce the numpy array SquaredDistances whose i^{th} row and j^{th} column is the squared Euclidean distance between the i^{th} row of class_means and j^{th} row of class_means. Obviously • The diagonal elements should be zero. • The SquaredDistances should be symmetric. Euclidean distance = $\sqrt{\Sigma(A_i-B_i)^2}$ numpy.linalg.norm(a-b)
In [13]: In [14]:	<pre>def mean_image_squared_distances(class_means): # Mo code 0 N = class_means.shape[0] SquaredDistances = np.zeros((N,N), dtype=float) for i in range(N): for j in range(N): #calculate squared L2 norm of 1D vector SquaredDistances[i, j] = np.linalg.norm(class_means[i] - class_means[j])* # Mo code 1 return SquaredDistances # Performing sanity checks on your implementation some_data = ((np.arange(35).reshape(5,7) ** 13) % 20) / 7.</pre>
In [15]:	<pre>some_dist = mean_image_squared_distances(some_data) assert np.array_equal(some_dist.round(3), np.array([[0.</pre>
	 Task 3 Read and implement the Principal Coordinate Analysis procedure from your textbook by writing the function PCoA which takes the following arguments: 1. SquaredDistances: A numpy array which is square in shape, symmetric, and is the square of a distance matrix of some unknown set of points. The output of the mean_image_squared_distances function you wrote previously will be fed as this argument. 2. r: This is the dimension of the visualization space, and corresponds to the same r variable in the
	 Things to keep in mind: There is an erratum in the textbook's description of the PCoA procedure. There is a missing negative sign when computing the matrix W; the correct definition of W is W := -½ AD⁽²⁾ A^T. It is vital to make sure that eigenvalues are sorted as the textbook mentioned, and the eigenvectors are also ordered accordingly. Some decomposition functions such as numpy 's np.linalg.eig do not guarantee to return the eigenvalues and eigenvectors in any sorted way, and np.linalg.eigh guarantees to return them in ascending order; you will have to make sure they are sorted as the textbook says.
	 Note: You should only use np.linalg.eigh for matrix factorization in this question since we're dealing with a symmetric matrix; do not use np.linalg.eig, np.linalg.svd, or any other matrix decomposition function in this question. Procedure: 6.2 Principal Coordinate Analysis Assume we have a matrix D⁽ⁿ⁾ consisting of the squared differences between each pair of N points. (We do not need to know the points.) We wish to compute a set of points in s dimensions, such that the distances between these points are as similar as possible to the distances in D⁽ⁿ⁾. 1. Form A = (I - ½ 11 IT) 2. Form W = -½ AD(2) AT 3. Form U, Λ, such that WU = UΛ. U: eigenvectors of W and , Λ: eigenvalues of W. Ensure that the entries of Λ are sorted in the decreasing order. Notice that you need only the top s eigenvalues and their eigenvectors, and many packages can extract these rather faster than constructing all. 4. Choose s, the number of dimensions you wish to represent. 5. Form Λs, the top left s × s block of Λ. 6. Form Λs, the top left s × s block of the first s columns of U. 7. Form Us, the matrix consisting of the first s columns of U.
	 8. Then Y = UsΣs = [y1yN] is the set of points to plot. linalg.eigh(a): Return the eigenvalues and eigenvectors of a complex Hermitian (conjugate symmetric) or a real symmetric matrix. Returns: w(, M) a 1-D ndarray: The eigenvalues of a in ascending order, each repeated according to its multiplicity. v{(, M, M) ndarray, (, M, M) matrix}
In [16]:	The column v[:, i] is the normalized eigenvector corresponding to the eigenvalue w[i]. 2-D square array or matrixWill return a matrix object if a is a matrix object. Sort the eigenvalues and then associate the eigenvectors with them. Use np.argsort on lam to get the sorted index. Use the sorted indext to retrieve the corresponding eigenvectors. Then select top r selection, sqrt, and dot product on the sorted lam and U.
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