

→ Data

Data refers to distinct pieces of information that are collected, stored, and processed to provide insight, knowledge, or support decision-making. Data can be any representation of facts, numbers, texts, symbols, images, audio, video, or more that has some meaning. Data can be raw or processed, and it serves as the foundation for generating information and knowledge.

→ Data structure

A data structure is a storage that is used to store and organize data. It is a way of arranging data on a computer. So that it can access and update efficiently.

A data structure is used for organizing the data. It is also used for processing, retrieving, and storing data.

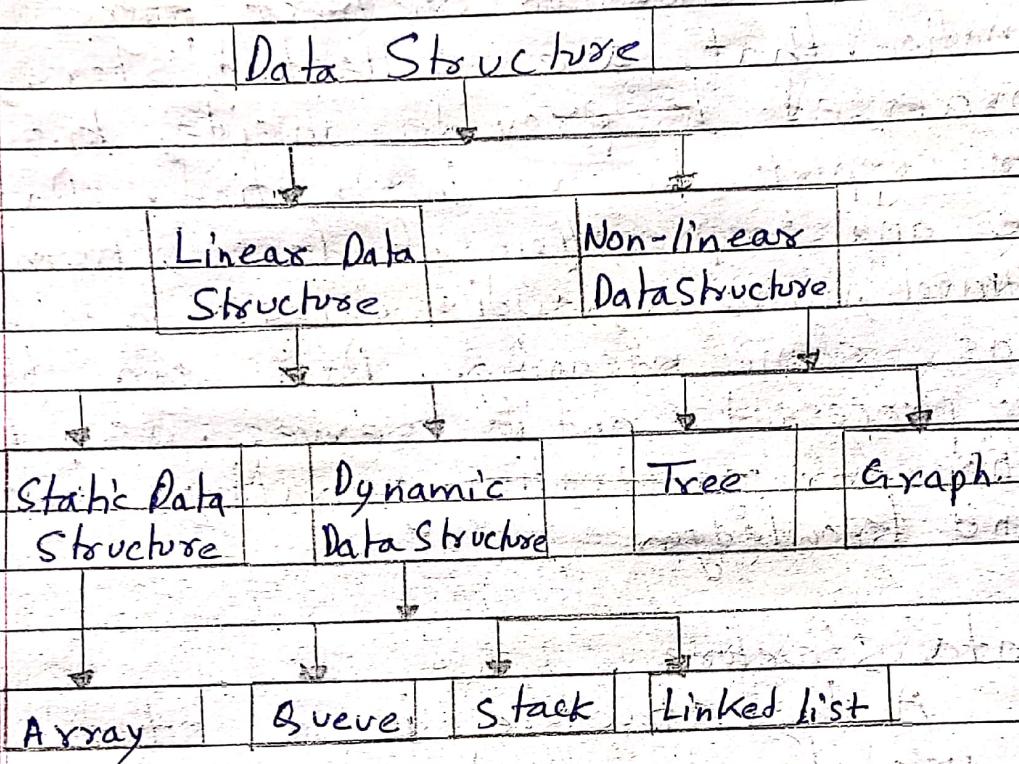
→ Information

Information is known as facts provided or learned about something, or someone.

→ Data type

The Data Type is basically a type of data that can be used in different computer program. It signifies the types like integer, float etc., the space like `#integer` will take 4-bytes.

→ Classification of Data Structure.



→ Linear Data Structure

Data structure in which data elements are arranged in sequence or linearly, where each element is attached to its previous and next adjacent elements is called a linear Data Structure.

Example:-

- 1) Array
- 2) Stack
- 3) Queue
- 4) Linked list.



→ Static Data Structure.

Static Data Structure has a fix amount of memory size. It is easier to access the elements in a data in a static data structure. Example of this data structure is an array.

→ Dynamic Data Structure.

In Dynamic Data Structure the size is not fix. It can be randomly updated during the run time. which may be consider efficient concerning the memory complete of code. Example:- Queue, Stack or linked list.

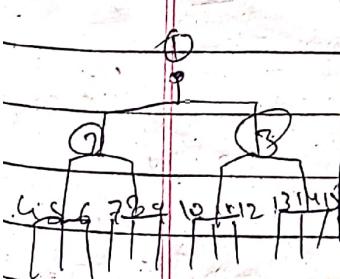
→ Non-linear Data Structure.

Data Structure where data element are not placed sequencly or linearly are called Non-linear Data Structure. In a Non Linear Data Structure we can't travers all the element in a single run only. Example:- tree or graph.

① Note:-

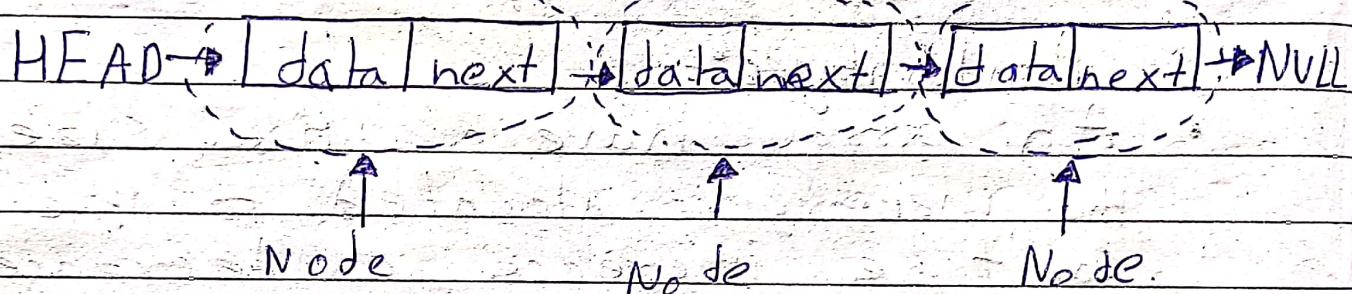
Queue → FIFO (First in first out)

Stack → LIFO (Last in First out)



→ Linked List

A linked list is linear data structure, in which the elements are not stored at contiguous memory location. The elements in linked list is linked using pointers as shown in the below image.



→ Stack

A stack is an abstract data type that holds an ordering linear sequence of items. In contrast to ~~a queue~~, a stack is a last in, first out (LIFO) structure.

A real life ~~example~~ is a stack of ~~is~~ plates. You can only take a plate from a top of a

stack and you can only add a plate to the top of the stack.

→ Queue

A queue is defined as a linear data structure, that is open at both ends, and the operation performed first in first out (FIFO) order. If we define a queue to be list in which all addition to the list are made at one end & all deletion from the list are made at other end.

→ Tree

Tree hierarchical data structure with a root node and child node.

Each node have zero or more child node.

Binary tree are common type tree with which each having at most two children.

Example include:- binary tree, binary search tree; AVL-tree, heap tree.

→ Graphs

Graphs consists of nodes (vertices) and edges (connection) bet' those nodes.

They can represent complex relationship, networks and various real world Scenery.

Graphs can be directed (edge have

direction) or Undirected (edges have no direction).

Example includes social networks, road networks and computer networks.

→ Different types of trees:

1) Binary tree:

A tree in which each node has at most two children, which are referred to as left child and right child.

The structure is a complete and inverted tree, with the single node at top called the root, and branching downward into sub-tree. Binary trees are common used in computer science and have various applications including data storage and retrieval, expression, evolution, network routing and game AI. They can also be used to implement various algorithms such as searching, sorting and graph algorithm.

→ Operations on binary tree

- 1) Inserting a binary element.
- 2) Removing a binary element
- 3) Searching a binary element
- 4) Deletion for a binary element
- 5) Traversing a binary element.

Operation on Data Structure.

1) Traversing:-

Traversing data structure means to visit every element stored in it. It's visits a data in a systematic manner. This can be done by any type of data structure.

2) Searching:-

Searching means to find the particular element in the given data structure. It is considered as successful random requirement if element is found. Searching is the operation which we can perform on data structure like array, linked list, tree, graph.

3) Insertion/Insertion:-

It is the operation which is applied on all the data structures. Insertion means to add an element in a given data structure. The operation of insertion is successful when the required is added to the required data structure. It is unsuccessful in some cases when the size of data structure is full and when there is no space in the data structure to add any additional elements.

The insertion has the same name has the as an insertion data structure as - a array, linked list, graph, & tree. In stack, these operation is called push. In the queue, this operation is called enqueue.

3) Deletion:-

It is the operation in which applied all data structure. Deletion mean to delete element to the given data structure. The operation of deletion. It's successful when the required element is deleted from the data structure. The deletion have the same name as a deletion in the data structure as an array, linked list, tree, etc. In Stack, these operation is called pop. In queue these operation is called de-queue.

4) Creation:-

It reserve memory for program element by declaring them. The creation of data structure can be done during:-

- 1) Compiled time
- 2) Run time

we can use malloc()

function.

Selection:-

It's like select specific data from present data. You can select any specific data by giving condition on loop.

Update:-

It update the data structure. You can also specific data by giving some condition in a loop like select approach.

Sort:-

Sorting data on a particular data (ascending and descending)

Merge:-

Merging data of two different orders in a specific data structure may ascend or descend. We use merge sort to merge sort data

Split data:-

Dividing data into different sub-parts to make the process complete in less time.

Asymptotic Notation.

A symptotic Notation used to describe the running time of an algorithm. How much time an algorithm take with a given input ans. There are three different notation. (O , Θ , Ω)

1) Big O , Big Θ , Big Ω . Big O is used when the running time is same for all cases, Big O for the worst case running time. Big Ω for the best case running time.

1) Big O Notation:-

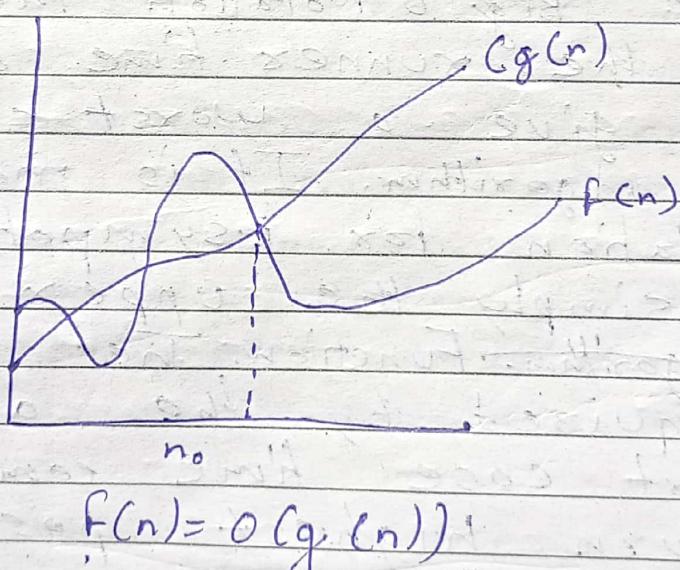
Big O Notation represent the upper bound of the running time of algorithm. Therefore it give a worst case complexity of an algorithm. It's most widely used. Notation for asymptotic analysis. It is simply the upper bound of an algorithm. Function. The \max time required by the algorithm or the worst case time complexity. It return highest possible $\text{output value}(O)$ for a given input.

The above expression can be describe as a function $f(n)$ belongs to the set $Og(n)$. If there exist a positive constant C such that it lies betw O and $Cg(n)$ for

sufficiently large n_0 , for any value of n the running time of an algorithm doesn't cross the time provided by $O(g(n))$:

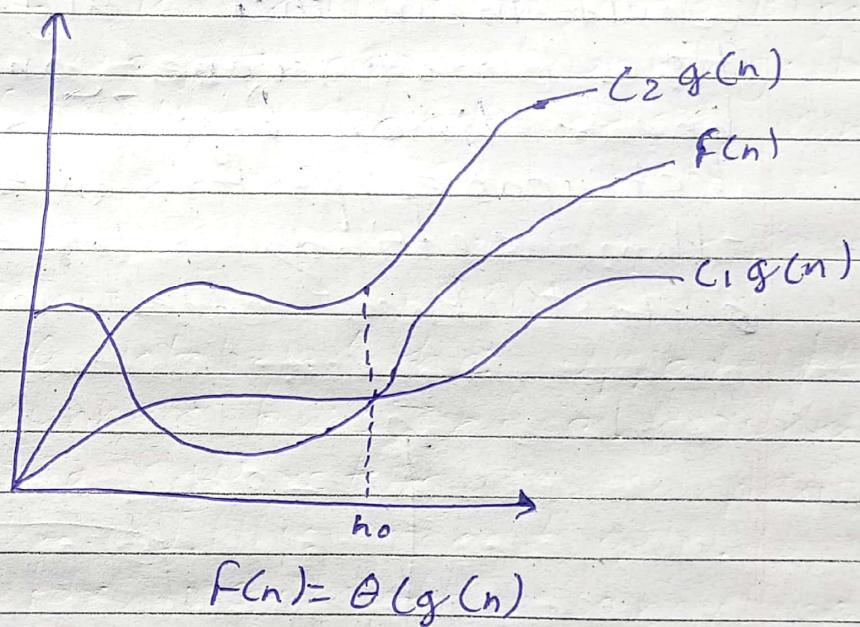
$O(g(n)) = \{ f(n) \text{ there exist positive constant } C \text{ and } \exists n_0 \text{ such that } 0 \leq f(n) \leq Cg(n) \text{ for all } n \geq n_0 \}$

Since it gives the worst case running time of an algorithm it's widely used to analyse an algorithm as we are always interested in the worst case scenario.



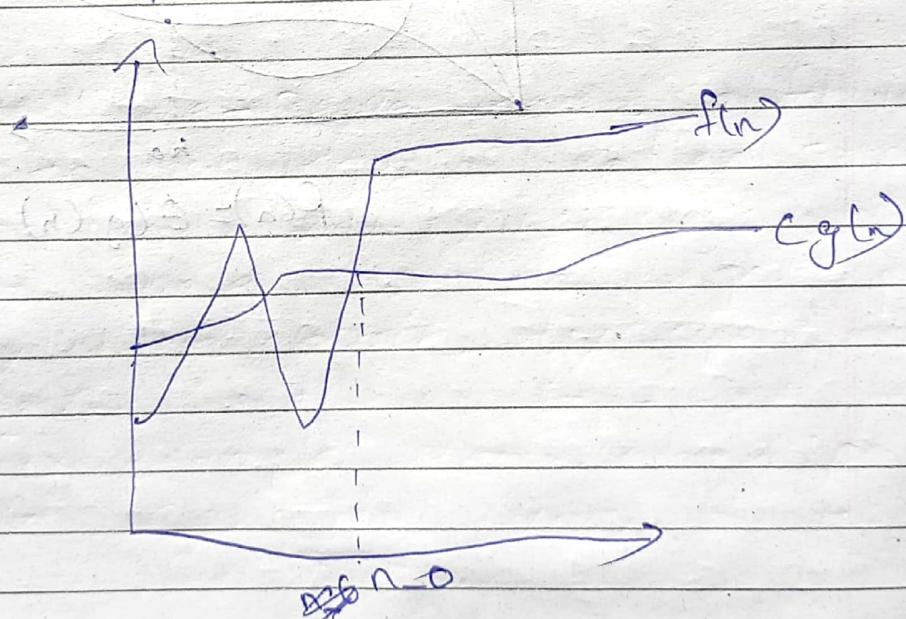
Big O

Θ notation encloses the function from above and below. Since it represents the upper and lower bound of the running time of an algⁿ, It is used for analysis's the average case of an algorithm.



Big Ω

The big Ω notation gives you a lower bound of the running time of an algorithm. So $\Omega(n)$ means the algorithms run at least at the time but could actually take a lot longer. The big O notation gives you an upper bound so $O(n)$ would mean the algorithms run in its worst case in an ~~or~~ linear time. Big Ω represent the best case performance for an algorithm, setting a lower bound on how fast the code can perform.



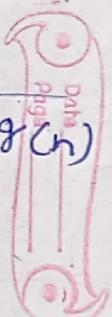
$$f_n = \Omega(g(n))$$

Big O

Big Ω

Big Θ

1 It is like (\leq) rate of grow of an algorithm's time less than a specific value.	It is like (\geq) rate of grow in (\geq) to a specific value.	It is like ($=$) in meaning the rate of growth is Θ specific for a value.
2 The upper bound of an algorithm represented by big O notation is given by $\Theta(n^k)$. Only the above function bound by big O. Asymptotic behaviour is given by big O notation.	The algorithm lower bound is represented by $\Omega(n^k)$. The asymptotic notation is given by $\Omega(n^k)$.	The bounding of function from above and below is represented by Θ notation. The exact asymptotic behaviour is done by this Θ notation.
3 Big O is upper bound.	Big Ω is lower bound	Big Θ is tight bound.
4 It is defined as upper bound. And upper bound on an algorithm is most amount of time required (the worst case performance).	It is defined as lower bound on an algorithm bound. And highest time required (the most that the algorithm can take in efficient way, in other word best case).	It is defined as tightest bound. And highest the best case time.
5 Mathematically $O \leq F(n) \leq g(n)$ for all $n \geq n_0$.	Mathematically $\Omega \leq G(n) \leq f(n)$, for all $n \geq n_0$.	Mathematically Θ is $O \leq c_1 g(n) \leq c_2 g(n)$ for $n \geq n_0$.



The Time-Space trade off.

A Time-Space trade off also known as Time-Memory trade off algorithms Space-time in computer science is a case where algorithms or programs trade's increase space uses where it decrease time.

A Time-Space trade off is a way of solving a problem or calculation in less time. ~~my by~~ using more storage. Space or by solving a problem in very little space by spending a long time.

Types of trade-off

1) Compressed/~~and~~ Uncompressed Data:- A space-time off can be applied to the problem of data storage. If data is stored uncompressed, it takes more space less time. If the data stored compressed, it takes less space but more time to run the decompression algorithm.

2) Redundancy (store images):

Storing only the source and sending it as an image every time ~~at the~~ page is requested would be trading time for space more time & use but less space.

↳ Storing the images would be trading time & space for time more space used. but less time.

3) Small code (with loop) large code (without loop)

Small code occupied less space in memory but it requires high computation time which is required for jumping back to the beginning back of the loop or at the end of iteration.

Large code or loop unrolling can be trade for higher program speed.

- It occupied more space in memory but required less computation time

3) Lookup Table / recalculation:-

In lookup table, an implementation table can include entire table which reduces computing time but increase the amount of memory needed.

It can recalculates & i.e computable entries entries as needed increasing computing time but reducing memory requirement.

Operation of Stack:-

A stack is a data structure which is used to store data in a linear fashion. It is an abstract data type in which data is inserted and deleted from a single end which is the stack's top. It follows the Last in first out (LIFO) principle i.e. the data which is inserted most recently in the stack will be deleted first from the stack.

Operation of Stack:

Expression passing.

The way to write ~~algorithmic~~ arithmetic expression i.e known as a Notation. An expression can be written in three equivalent notations i.e without changing the essence or output of an expression. These notation are:-

1) Infix Notation:

We write expression in infix notation, i.e $a - b + c$, where operators are used in between operands. It is easy for us human to read, write and speak in infix notation but the same doesn't goes well in computing devices. An Algorithmic infix notation could be difficult and costly in terms of time & space consumption.

2) Pre-fix Notation:-

In this notation, pre-fix operator is pre-fix to operands. i.e. operator is written in written is.

For example, $+tab$. This is equivalent to ~~infix~~ pre-fix notation. It's also known as Polish notation.

3) Post-fix Notation:-

This notation type is known as reversed post polished notation. In this notation style the operator is

post-fix to the operands i.e. the operator is written after the operands for example $a+b$. This is equivalent to its infix notation $a+b$.

The following table briefly try to show the difference in all the three notation.

SN	In Fix	Prefix	Post fix
1	$a+b$	$+ab$	$ab+$
2	$(a+b)-c$	$-+abc$	$abc+-$
3	$a*(b+c)$	$*ab+c$	$abc+*$
4	$a/b+c/d$	$/ab/cd$	$ab/cd/$
5	$(a+b)*c+d$	$*+abcd$	$ab+cd+*$
6	$(a+b)*c-d$	$-*+abcd$	$ab+c*d-$

What is the analysis of the Algorithm.

Analysis of an algorithm is the process of finding the computational complexity of any algorithm. By computational complexity, we are referring to the amount of time taken, space, and any other resources needed to execute (run) the algorithm.

The goal of algorithm analysis is to compare different algorithms that are used to solve the ^{same} problem. This is done to evaluate which method solves a certain problem more quickly, efficiently, and memory-wise.

Usually, the time complexity is determined by the size of the algorithm's input to the number of steps taken to execute it. Also, the space complexity is mostly determined by the amount of storage needed to run the algorithm + execute.

What is algorithm? Full Explanation.

- The step by step description of any
- An algorithm is a well defined list of steps for solving a particular problem.

Example of algorithm.

A algorithm for add two numbers.

Step 1: Begin

Step 2: Input two numbers a & b

Step 3: sum of a & b

Step 4: Display output of addition

Step 5: Exit.

Properties of algorithm:-

Input

Algorithm Complexity (performance):-

Algorithm complexity refers to the analysis of an algorithm performance in terms of time and space required as a function of input size.

i) Space complexity:-

Total amount of memory required by an algorithm for its complete execution.

a) Constant Space complexity:-

Example: int sqrt(int n)
{
 return (n * n);
}

b) Linear space complexity:-

Example: int add(int arr[], int n)

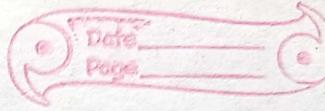
```
{  
    int sum = 0;  
    for (i=0; i<n; i++)  
        sum = sum + arr[i];  
    return sum;  
}
```

ii) Time complexity:-

Total amount of time required by an algorithm to its complete execution called time complexity.

a) Constant time complexity:-

Example: int sqrt(int n)
{
 return n * n;
}



$n \times n = 1$ unit of time
 $\text{return} = 1$ unit of time.

b) Linear time complexity.

Example :-

```
int add(int arr[], int n)
{
    int sum=0, i;
    for (i=0; i<=n; i++)
        sum = sum + arr[i];
    return sum;
}
```

Application of stack.

- 1) Memory Management.
- 2) Function call.
- 3) Experian Bank tracking.
- 4) Browser History.
- 5) Task management OS.