

MA1511 Cheat Sheet

Mixed Derivatives Theorem

$f_{xy} = f_{yx}$

(1)

Chain Rule

$\frac{dz}{dt} = \frac{\partial z}{\partial x} \times \frac{dx}{dt} + \frac{\partial z}{\partial y} \times \frac{dy}{dt}$

(2)

Gradient Vector

$\nabla f = \langle f_x, f_y, f_z \rangle$

(3)

The gradient vector is always perpendicular to the level surface $f = c$.

$\vec{r} \cdot \nabla f = \nabla f \cdot \langle x_0, y_0, z_0 \rangle$

(4)

Use this to find the equation of the tangent plane when $f(x, y, z) = c$ at the point (x_0, y_0, z_0) .

Directional Derivatives

$D_u f(x, y) = \nabla f \cdot \vec{u}$

(5)

where \vec{u} is the unit vector in the desired direction.

Derivatives Test

Critical points of f can be found by setting $f_x = 0$ and $f_y = 0$.

$D = f_{xx} \cdot f_{yy} - (f_{xy})^2$

(6)

Local Maximum $D > 0$ and $f_{xx} < 0$

Local Minimum $D > 0$ and $f_{xx} > 0$

Saddle otherwise

Lagrange Multipliers

The minimum/maximum of a function $f(x, y)$ subject to the constraint $g(x, y) = c$ occurs at points that satisfy these three equations.

$f_x = \lambda \cdot g_x$

(7)

$f_y = \lambda \cdot g_y$

(8)

$g(x, y) = c$

(9)

where λ is some constant called the lagrange multiplier.

Iterated Integrals

If $f(x, y) = a(x) \cdot b(y)$ for functions a and b ,

$\int_b^a \int_d^c f(x, y) dx dy = (\int_b^a a(x) dx) \cdot (\int_d^c b(y) dy)$

(10)

Type 1 Domain $(x, y) : a \leq x \leq b, g(x) \leq y \leq h(x)$

Type 2 Domain $(x, y) : c \leq y \leq d, g(y) \leq x \leq h(y)$

Polar Coordinates

$x = r \cos \theta$

(11)

$y = r \sin \theta$

(12)

$\iint_D f(x, y) dA = \int_{r_s}^{r_e} \int_{\theta_s}^{\theta_e} f(r \cos \theta, r \sin \theta) r dr d\theta$

(13)

Vector Differentiation

Let \mathbf{C} be a constant vector and $\mathbf{u}(t)$ and $\mathbf{u}(t)$ be vector-valued functions.

$\frac{d}{dt} \vec{C} = \vec{0}$

$\frac{d}{dt} f(t) \vec{u}(t) = f'(t) \vec{u}(t) + f(t) \vec{u}'(t)$

$\frac{d}{dt} \vec{u}(t) \cdot \vec{v}(t) = \vec{u}'(t) \cdot \vec{v}(t) + \vec{v}'(t) \cdot \vec{u}(t)$

$\frac{d}{dt} \vec{u}(t) \times \vec{v}(t) = \vec{u}'(t) \times \vec{v}(t) + \vec{u}(t) \times \vec{v}'(t)$

$\frac{d}{dt} \vec{u}(f(t)) = f'(t) \vec{u}'(f(t))$

Vector Integration

$r(t) = (f(t))\vec{i} + (g(t))\vec{j} + (h(t))\vec{k}$

(14)

$\int r(t) dt = (\int f(t) dt) \vec{i} + (\int g(t) dt) \vec{j} + (\int h(t) dt) \vec{k}$

(15)

The same applies for definite integrals.

Arc Length

$L = \int_a^b \sqrt{(f'(t))^2 + (g'(t))^2 + (h'(t))^2} dt$

(16)

Line Integrals

$\int_C f(x, y) ds = \int_a^b f(x(t), y(t)) \sqrt{(x'(t))^2 + (y'(t))^2} dt$

(17)

Parameterizing Line Segments

The line segment joining (x_1, y_1, z_1) and (x_2, y_2, z_2) has the following parametric equation:

$r(t) = (1 - t) \begin{pmatrix} x_1 \\ y_1 \\ z_1 \end{pmatrix} + t \begin{pmatrix} x_2 \\ y_2 \\ z_2 \end{pmatrix}, 0 \leq t \leq 1$

(18)

Parametric Surfaces

$r(u, v) = x(u, v)\vec{i} + y(u, v)\vec{j} + z(u, v)\vec{k}$

(19)

Surfaces explicitly defined by $z = g(x, y)$ can be parameterized as follows:

$x = u, y = v, z = g(u, v)$

(20)

To find the equation of the plane tangent to a parametric surface $r(u, v)$ at the point $u = u_0, v = v_0$,

$\vec{n} = r_u \times r_v$

(21)

$\begin{pmatrix} x \\ y \\ z \end{pmatrix} \cdot \vec{n} = \vec{n} \cdot r(u_0, v_0)$

(22)

Line Integrals of Vector Fields

$\int_C \vec{F} \cdot d\vec{r} = \int_a^b \vec{F}(r(t)) \cdot r'(t) dt$

(23)

If $\vec{F} = P(x, y)\vec{i} + Q(x, y)\vec{j}$ and $r(t) = x(t)\vec{i} + y(t)\vec{j}$,

$\int_C \vec{F} \cdot d\vec{r} = \int_a^b P(x(t), y(t)) \cdot x'(t) + Q(x(t), y(t)) \cdot y'(t) dt$

(24)

Conservative Fields

If there exists a scalar function f such that $\vec{F} = \nabla f$, the vector field \vec{F} is said to be conservative. The scalar function f is the potential function.

$\int_C \vec{F} \cdot d\vec{r} = f(r(b)) - f(r(a))$

(25)

For a closed curve, the above quantity is always 0 for a conservative field.

\vec{F} is conservative if $P_y = Q_x, Q_z = R_y$ and $R_x = P_z$.

Green's Theorem

$\oint_C P dx + Q dy = \iint_D Q_x - P_y dA$

(26)

Curl and Divergence

$curl(\vec{F}) = \begin{pmatrix} R_y - Q_z \\ P_z - R_x \\ Q_x - P_y \end{pmatrix}$

(27)

$div(\vec{F}) = P_x + Q_y + R_z$

(28)

A vector field is incompressible if $div(\vec{F}) = 0$.

Standard Limits

$\lim_{n \rightarrow \infty} a^{\frac{1}{n}} = 1, a \neq 0$

(29)

$\lim_{n \rightarrow \infty} n^{\frac{1}{n}} = 1$

(30)

$\lim_{n \rightarrow \infty} r^n = 0, -1 < r < 1$

(31)

$\lim_{n \rightarrow \infty} (1 + \frac{a}{n})^n = e^a$

(32)

Limit Laws

$\lim_{n \rightarrow \infty} ca_n = cA$

(33)

$\lim_{n \rightarrow \infty} c + a_n = c + A$

(34)

$\lim_{n \rightarrow \infty} a_n b_n = AB$

(35)

$\lim_{n \rightarrow \infty} \frac{a_n}{b_n} = \frac{A}{B}, B \neq 0 \wedge b_n \neq 0 \forall n$

(36)

$\lim_{n \rightarrow \infty} f(a_n) = f(A)$

(37)

Infinite Series

For $-1 < r < 1, \sum_{k=1}^{\infty} ar^{k-1} = \frac{a}{1-r}$.
 $\sum_{k=1}^{\infty} a_k$ is convergent if and only if $\sum_{k=m}^{\infty} a_k$ is convergent.

Divergence Test

If a_n does not converge to 0, then the series $\sum_{k=1}^{\infty} a_k$ is divergent.

p-series test

The series $\sum_{k=1}^{\infty} \frac{1}{k^p}$ is convergent if $p > 1$ and divergent if $p \leq 1$.

Power Series

Ratio Test

$L = \lim_{k \rightarrow \infty} | \frac{a_{k+1}}{a_k} |$

(38)

Root Test

$L = \lim_{k \rightarrow \infty} | a_k^{\frac{1}{k}} |$

(39)

Let $a_k = c_k(x - a)^k$. Then the series $\sum_{k=0}^{\infty} a_k$ converges when $L < 1$ and diverges when $L > 1$. When $L = 1$, sit down and cry. To find interval of convergence, find the two extreme values of x , plug it into the equation separately and test for convergence.

Taylor Series

sum_{k=0}^inf f^{(k)}(a)/k! (x-a)^k (40)

Maclaurin Series

(when -1 < x < 1)

1/(1-x) = sum_{n=0}^inf x^n = 1 + x + x^2 + x^3 + ...
e^x = sum_{n=0}^inf x^n/n! = 1 + x + x^2/2! + x^3/3! + ...
sin x = sum_{n=0}^inf (-1)^n/(2n+1)! x^{2n+1} = x - x^3/3! + x^5/5! - ...
cos x = sum_{n=0}^inf (-1)^n/(2n)! x^{2n} = 1 - x^2/2! + x^4/4! - ...

(when -1 < x < 1)

ln(1+x) = sum_{n=1}^inf (-1)^{k+1}/k x^k = x - x^2/2 + x^3/3 + ...

(when -1 < x < 1)

(1+x)^p = sum_{k=0}^inf (p choose k) x^k
= 1 + px + p(p-1)/2! x^2 + p(p-1)(p-2)/3! x^3 + ...
arctan x = x - x^3/3 + x^5/5 + ...

Trigonometric Integration

d/dx sin^-1 x = 1/sqrt(1-x^2)
d/dx cos^-1 x = -1/sqrt(1-x^2)
d/dx tan^-1 x = 1/(1+x^2)

Integration Rules

int uv = u int vdx - int du/dx int vdx dx, LIATE (41)

d/dx (u/v) = (u'v - uv')/v^2 (42)

Trigonometric Identities

Table with 6 columns: Degrees, Radians, sin, cos, tan, and values for 0, 30, 45, 60, 90 degrees.

1 + tan^2 u = sec^2 u, 1 + cot^2 u = csc^2 u

sin(-x) = -sin x
cos(-x) = cos x
tan(-x) = -tan x

sin(pi/2 - x) = cos x, cos(pi/2 - x) = sin x
tan(pi/2 - x) = cot x, cot(pi/2 - x) = tan x
sec(pi/2 - x) = csc x, csc(pi/2 - x) = sec x

sin(x +/- y) = sin x cos y +/- cos x sin y
cos(x +/- y) = cos x cos y +/- sin x sin y
tan(x +/- y) = (tan x +/- tan y)/(1 +/- tan x tan y)

sin(2x) = 2 sin x cos x
cos(2x) = cos^2 x - sin^2 x = 2 cos^2 x - 1 = 1 - 2 sin^2 x
tan(2x) = 2 tan x / (1 - tan^2 x)

sin x/2 = +/- sqrt((1 - cos x)/2)
cos x/2 = +/- sqrt((1 + cos x)/2)
tan x/2 = (1 - cos x)/sin x = sin x/(1 + cos x)

sin^2 x = (1 - cos 2x)/2
cos^2 x = (1 + cos 2x)/2
tan^2 x = (1 - cos 2x)/(1 + cos 2x)

sin x sin y = 1/2 [cos(x-y) - cos(x+y)]
cos x cos y = 1/2 [cos(x-y) + cos(x+y)]
sin x cos y = 1/2 [sin(x+y) + sin(x-y)]
tan x tan y = (tan x + tan y)/(cot x + cot y)
tan x cot y = (tan x + cot y)/cot x + tan y

sin x + sin y = 2 sin((x+y)/2) cos((x-y)/2)
sin x - sin y = 2 cos((x+y)/2) sin((x-y)/2)
cos x + cos y = 2 cos((x+y)/2) cos((x-y)/2)
cos x - cos y = -2 sin((x+y)/2) sin((x-y)/2)
tan x +/- tan y = sin(x +/- y)/(cos x cos y)

a cos theta +/- b sin theta = R cos(theta +/- alpha)
a sin theta +/- b cos theta = R sin(theta +/- alpha)
alpha = arctan(b/a)
R = sqrt(a^2 + b^2)