Lecture 11 - Inverse by Gauss Jordan Method,

Transposes :-

Inverses & Transposes 8-

- \rightarrow Let A be a square matrix of order n_{2} , the inverse of A is the matrix B such that AB=I=BA. \rightarrow Here $B=A^{-1}$.
- → Inverse of a matrix is unique. i.e AB=BA=I&

 Ac=cA=I, then

 B=c
- To verse of the product is the product of inverses. $(ABCD)^{-1} = D^{-1} C^{-1} B^{-1} A^{-1}.$
- \rightarrow If A = LU, then $A^{-1} = U^{-1}L^{-1}$
- ⇒ Since $E_{32} \cdot E_{31} \cdot E_{21} \cdot A = U$, we have $E_{21} \cdot E_{31} \cdot E_{32} \cdot U = A$ $A^{-1} = U^{-1} \cdot E_{32} \cdot E_{31} \cdot E_{21}$ $A^{-1} = U^{-1} \cdot E_{32} \cdot E_{31} \cdot E_{21}$ $A^{-1} = E_{21} \cdot E_{32} \cdot E_{31} \cdot E_{32}$
- → A matrix A is invertible if and only if elimination produces n pivots with or without row exchanges. Elimination Solves Ax=b without explicitly finding A.
- \rightarrow If A is invertible, the only & one solution to $A \times = b$ is $X = A^{-1} \cdot b$.

The inverse of an invertible matrix is obtained by a set of row operations that transforms A to I & I to A. This process is known as Gauss Jordan method.

Town U and at the same time I reduces to C.

+ Further reduce U to I using elementary row

$$\rightarrow \quad \left[A:I \right] \longrightarrow \left[U:C \right] \rightarrow \left[I:A^{-1} \right]$$

Example 22 : compute A^{-1} using Gauss Jordan method given $A = \begin{bmatrix} 2 & 1 & 1 \\ 4 & 3 & 4 \\ -2 & 2 & 2 \end{bmatrix}$

Solution [A:I] =
$$\begin{bmatrix} 2 & 1 & 1 & 1 & 1 & 0 & 0 \\ 4 & 3 & 4 & 1 & 0 & 1 & 0 \\ -2 & 2 & 2 & 1 & 0 & 0 & 1 \end{bmatrix}$$
 $\begin{bmatrix} 2 & 1 & 1 & 1 & 1 & 0 & 0 \\ \frac{2}{3} - 2R_1 & 0 & 1 & 2 & 1 & 1 & 0 & 0 \\ 0 & 1 & 2 & 1 & 2 & 1 & 0 & 1 \end{bmatrix}$

$$\begin{bmatrix}
2 & 1 & 1 & 1 & 1 & 0 & 0 \\
0 & 1 & 2 & 1 & -2 & 1 & 0
\end{bmatrix}
\xrightarrow{R_3 - 3R_2}
\begin{bmatrix}
2 & 1 & 1 & 1 & 1 & 0 & 0 \\
0 & 1 & 2 & 1 & -2 & 1 & 0
\end{bmatrix}$$

$$\begin{bmatrix}
0 & 3 & 3 & 1 & 1 & 0 & 1
\end{bmatrix}
\xrightarrow{R_3 - 3R_2}
\begin{bmatrix}
2 & 1 & 1 & 1 & 1 & 0 & 0 \\
0 & 1 & 2 & 1 & -2 & 1 & 0
\end{bmatrix}$$

$$\begin{bmatrix} 2 & 1 & 1 & 1 & 1 & 0 & 0 \\ 0 & 1 & 2 & 1 & 2 & 1 & 0 \\ 0 & 0 & 2 & 1 & 2 & 1 & 0 \\ 0 & 0 & 0 & 3 & 1 & 2 & 3 \\ 0 & 0 & 0 & 0 & 1 & 2 & 3 \\ 0 & 0 & 0 & 0 & 1 & 2 & 3 \\ 0 & 0 & 0 & 0 & 2$$

$$\begin{bmatrix} 2 & 1 & 0 & : & \frac{10}{3} & -1 & \frac{1}{3} \\ 0 & 1 & 0 & : & \frac{8}{3} & -1 & \frac{2}{3} \\ 0 & 0 & -3 & : & 7 & -3 & 1 \end{bmatrix} \xrightarrow{R_1 - R_2} \begin{bmatrix} 2 & 0 & 0 & : & \frac{2}{3} & 0 & -\frac{1}{3} \\ 0 & 1 & 0 & : & \frac{8}{3} & -1 & \frac{2}{3} \\ 0 & 0 & -3 & : & 7 & -3 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 2 & 0 & 0 & : 2/3 & 0 & -1/3 \\ 0 & 1 & 0 & : 8/3 & -1 & 2/3 \\ 0 & 0 & -3 & : 7 & -3 & 1 \end{bmatrix} \xrightarrow{R_1 = \frac{1}{2}R_2} \begin{bmatrix} 1 & 0 & 0 & : \frac{1}{3} & 0 & -\frac{1}{6} \\ 0 & 1 & 0 & : 8/3 & -1 & 2/3 \\ 0 & 0 & -3 & : 7 & -3 & 1 \end{bmatrix} \xrightarrow{R_3 = -\frac{1}{3}R_3} \begin{bmatrix} 0 & 0 & 1 & 0 & : \frac{1}{3} & 0 & -\frac{1}{6} \\ 0 & 1 & 0 & : \frac{1}{3} & 0 & -\frac{1}{3} \\ 0 & 0 & 1 & : -\frac{7}{3} & 1 & -\frac{1}{3} \end{bmatrix}$$

$$\begin{bmatrix} I : B \end{bmatrix}$$

$$^{\circ} \circ B = A^{-1} = \begin{bmatrix} 1/3 & 0 & -1/6 \\ 8/3 & -1 & 2/3 \\ -7/3 & 1 & -1/3 \end{bmatrix}$$

Transpose of a matrix AT o-

 \rightarrow If $A = [a_1]_{m \times n}$ is an $m \times n$ motorix, then its transpose is obtained by interchanging its rows & columns and is denoted by $A^T = [a_1]_{m \times n}$

$$\Rightarrow If A = \begin{bmatrix} 2 & 1 & -3 \\ 4 & 2 & 0 \end{bmatrix}$$
 then $A = \begin{bmatrix} 2 & 4 \\ 1 & 2 \\ -3 & 0 \end{bmatrix}$



Properties

The transpose of a lower triangular matrix is an upper triangular matrix.

$$\rightarrow (AT)^{T} = A ; (AB)^{T} = B^{T} \cdot A^{T} ; (A^{-1})^{T} = (A^{T})^{-1}$$

$$\rightarrow (A \pm B)^T = A^T \pm B^T ; (A^{-1})^T \cdot A^T = (A \cdot A^{-1})^T = I$$

Symmetric matrices :-

 \rightarrow If A is a matrix of order n, then it is said to be symmetric matrix of order n if $A^T = A$.

$$\rightarrow If A = \begin{bmatrix} 2 & -3 \\ -3 & 5 \end{bmatrix} A^{T} = \begin{bmatrix} 2 & -3 \\ -3 & 5 \end{bmatrix} \Rightarrow A^{T} = A$$

Properties 8-

- > If A is Symmetric then A may or may not exist.
- → If for a symmetric matrix A exists, then A is also symmetric.
- > For a symmetric matrix A, we have $(A^{-1})^T = A^{-1}$ [00 AT = A].

Symmetric Products AAT, ATA, LDLT :-

and ATA are both symmetric.

Example of If
$$A = \begin{bmatrix} 2 & 1 & -3 \\ 4 & 2 & 0 \end{bmatrix}$$
 $AA^{T} = \begin{bmatrix} 2 & 1 & -3 \\ 4 & 2 & 0 \end{bmatrix} \begin{bmatrix} 2 & 4 \\ 4 & 2 & 0 \end{bmatrix}$ $\begin{bmatrix} -3 & 0 \\ -3 & 0 \end{bmatrix}$

$$A^{T} = \begin{bmatrix} 2 & 4 \\ 1 & 2 \\ -3 & 0 \end{bmatrix} A = \begin{bmatrix} 2 & 1 & -3 \\ 4 & 2 & 0 \end{bmatrix} \Rightarrow A^{T} A = \begin{bmatrix} 20 & 10 & -6 \\ 10 & 5 & -3 \\ -6 & -3 & 9 \end{bmatrix}$$

If A is symmetric and if A = LDU then, $A = A^{T} = LDL^{T} [0,0 \ U = L^{T} \ \% \ L = U^{T}]$

$$A = \begin{bmatrix} 1 & 2 & -1 \\ 2 & 3 & 0 \\ -1 & 0 & 4 \end{bmatrix} \xrightarrow{R_2 - 2R_1} \begin{bmatrix} 1 & 2 & -1 \\ 0 & -1 & 2 \\ 0 & 2 & 3 \end{bmatrix}$$

$$\begin{bmatrix}
1 & 2 & -1 \\
0 & -1 & 2 \\
0 & 2 & 3
\end{bmatrix}
\xrightarrow{R_3 + 2R_2}
\begin{bmatrix}
1 & 2 & -1 \\
0 & -1 & 2 \\
0 & 0 & 7
\end{bmatrix} = U$$

$$LDU = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ -1 & -2 & 1 \end{bmatrix} \cdot \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 7 \end{bmatrix} \cdot \begin{bmatrix} 1 & 2 & -1 \\ 0 & 1 & -2 \\ 0 & 0 & 1 \end{bmatrix}$$

> From which three numbers "c" is this matrix

$$A = \begin{bmatrix} 2 & c & c \\ c & c & c \\ \end{bmatrix} \xrightarrow{R_2 - c_2 R_1} \begin{bmatrix} 2 & c & c \\ 0 & c - c^2 & c - c^2 \\ \hline 8 & 7 & c \end{bmatrix} \xrightarrow{R_3 - 4R_1} \begin{bmatrix} 2 & c & c \\ 0 & 7 - 4c - 3c \end{bmatrix}$$

$$7-4C-x(c-\frac{c^2}{2})=0$$

$$\Rightarrow x(c-\frac{c^2}{2})=7-4C \Rightarrow x=\left[\frac{7-4C}{2C-C^2}\right] = R_2$$

$$\begin{bmatrix}
2 & C & C \\
0 & C - C^{2} & C - C^{2} \\
\hline
2 & 2
\end{bmatrix}
\xrightarrow{R_{3} - \left[\frac{7 - 4C}{2C - C^{2}}\right]^{2}R_{2}}
\begin{bmatrix}
2 & C & C \\
0 & C - C^{2} & C - C^{2} \\
\hline
0 & 7 - 4C - 3C
\end{bmatrix}
\xrightarrow{R_{3} - \left[\frac{7 - 4C}{2C - C^{2}}\right]^{2}R_{2}}
\begin{bmatrix}
2 & C & C \\
0 & C - C^{2} & C - C^{2} \\
\hline
0 & 0 & C - 7
\end{bmatrix}$$

$$-3c - \left[\frac{7-4c}{2\sqrt{-c^2}}\right]^{\frac{1}{2}} \qquad \left[\frac{2\sqrt{-c^2}}{2}\right]$$

$$-3c - 7 + 4c$$

- → Matrix A is not invertible for C=0,2,7
- There A will be singular and so A will not be invertible.

Example 25 Find
$$PA = LU$$
 and $PA = LDU$ for A given by $A = \begin{bmatrix} 3 & -1 & 0 \\ 6 & -2 & 0 \\ 1 & 1 & 2 \end{bmatrix}$