

- Some other hard problems:

• HAMILTONIAN PATH:

Given a graph  $G$ ,

Is there a path in  $G$  that goes through all the vertices of  $G$ ?

• Variant: Given  $G, u, v$ :

Is there such a path, from  $u$  to  $v$ ?

(CODECP)

## • HAMILTONIAN CYCLE:

Given a graph  $G$ ,

Is there a cycle through all vertices?

- We will not get to the proof that they are NP-hard, but we show that if any one of these 3 problems is NP-hard, so are others.

- Between 2 variants of the path problem:

① Given  $G$  only    ② Given  $\langle G, u, v \rangle$

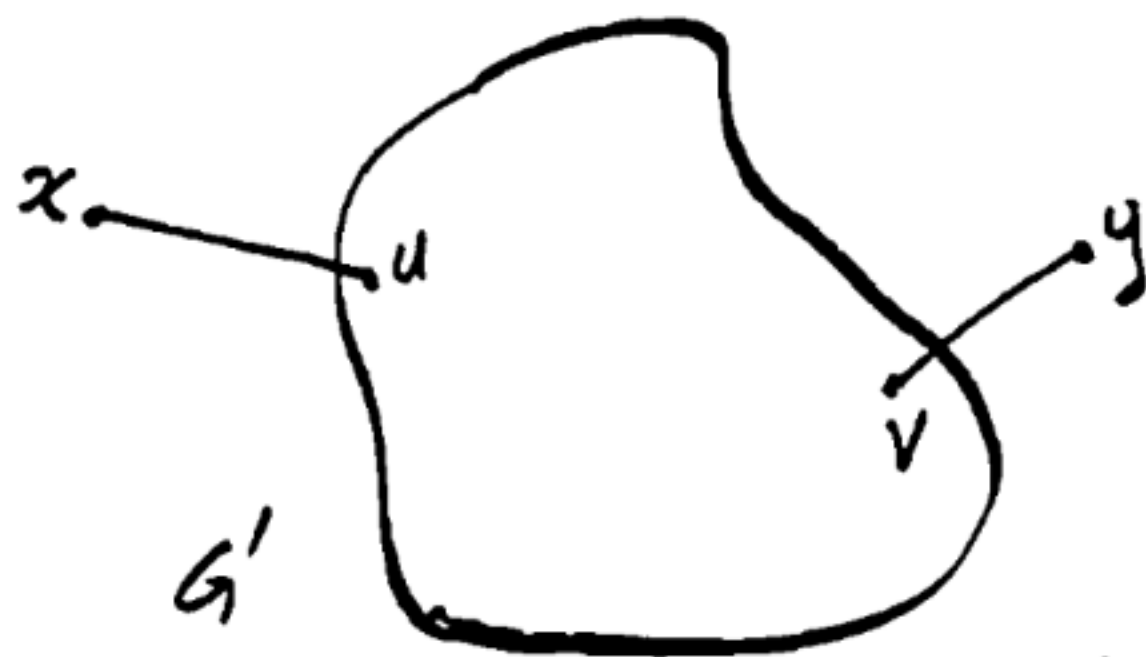
①  $\leq_p$  ② :

If ② has a poly. time algorithm,  
we can call it with every pair of vertices  
 $u \neq v$ ; to solve ①.

②  $\leq_p$  ① : If we had an algorithm for ①, how to use it to check if there exists a HAM. path between a specific pair of vertices  $u$  and  $v$ ?

- Note that ① takes only a graph  $G$  as its input.

Input  $G'$  for ①:



$G'$  has a HAM. PATH if and only if  
 $G$  has a HAM. PATH from  $u$  to  $v$ . [Argue]

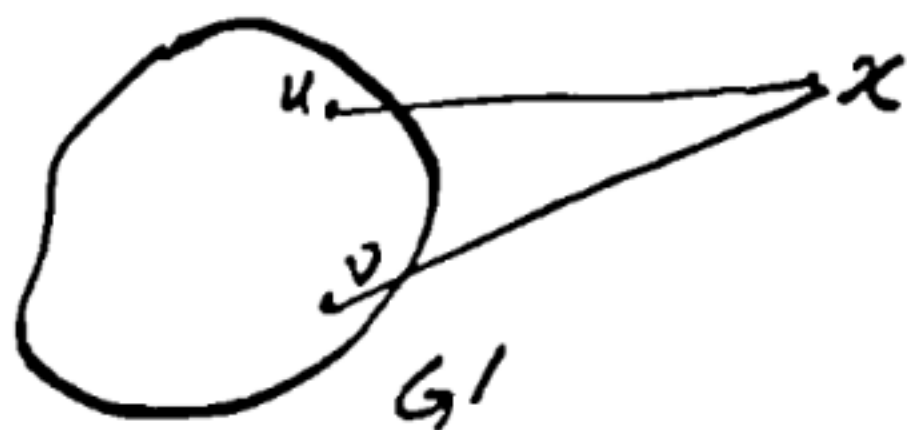
- Cycle to Path and Path to Cycle.
- Either version of the PATH is fine.
- Path to cycle reduction:

Use algorithm for HAM. CYCLE,  
to design a poly. algorithm for  
HAM. PATH.

- Using the second version:

$Q_n: \langle G, u, v \rangle$ : Is there a HAM. PATH from  $u$  to  $v$  in  $G$ ?

- Input instance for CYCLE PROBLEM:



Proof:

① YES answer is correct.

$G'$  has a HAM. CYCLE  $\Rightarrow$

$G$  has a HAM. PATH from  $u$  to  $v$ .

② NO is correct.

$G$  has a HAM. PATH from  $u$  to  $v$

$\Rightarrow G'$  has a HAM. CYCLE.



• The other way?

$\text{HAM-CYCLE} \leq_p \text{HAM-PATH}$ .

It can be done in many ways.

- One way is to remove each edge  $(u,v)$  in  $G$  and ask if there is a  $\text{HAM-PATH}$  from  $u$  to  $v$  in the resulting graph.

-Can we do with a single call?

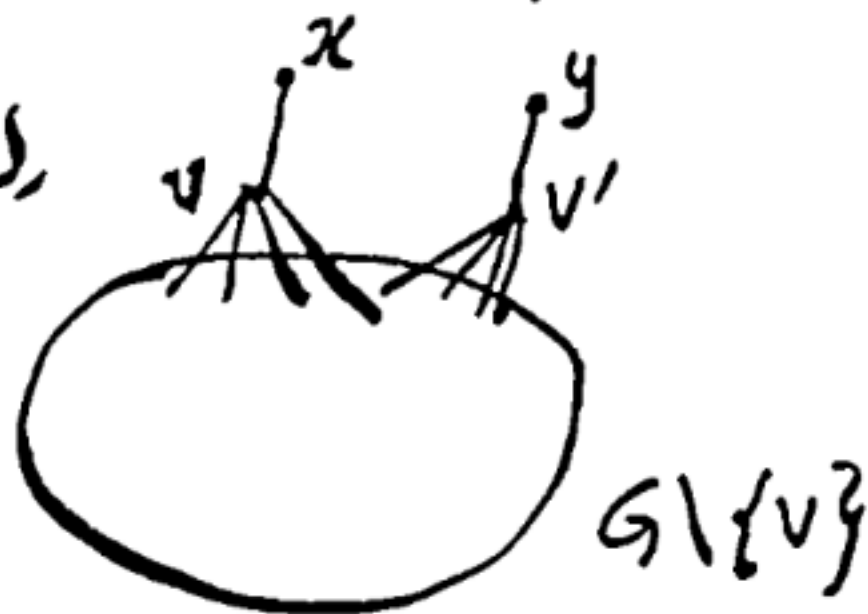
YES!

Take any vertex  $v$ , make a 'copy' of it,  $v'$ .

Add 2 new vertices,

$x$  to  $v$  and

$y$  to  $v'$ .



HAM-PATH in new graph  $G' \Leftrightarrow$  CYCLE in  $G$ .

(CODEEP)