

AI & DS - I

Assignment - 01

1 What is AI? Considering the COVID-19 pandemic situation, how AI helped to survive.

Ans AI is Artificial Intelligence. It is a knowledge desiring and storing tool or mechanism used to gain, construct, provide information in ways to ~~build~~ bring about growth in numerous domains, namely, health, education, business, finance, etc. AI is the highest form of machine learning advancement.

COVID-19 brought numerous problems along with its outbreak such as Social Distancing, No proper vaccine facility, lack of providing education, problems related to businesses and closure of factories and industries.

AI helped during these crisis situations in the following ways.

→ Education: Helped in bringing about platforms for E-learning & Smart Learning.

→ Finance & Business: Ease of carrying out transaction online.

→ Helped in identifying areas where vaccine or hospital facilities were not available, so as to reach to those areas.

2 What are AI Agents terminology, explain with examples.

Ans AI agent is an entity that perceives its environment and takes actions to achieve specific goals.

Types of AI Agents

1. Simple Reflex Agent :-

Acts only based on current percepts. - Eg: A thermostat controlling room temperature.

2. Model Based - Maintains internal memory.

Eg. A chess-playing AI ~~remember~~^{remembering} past moves.

3. Goal based Agent - Acts to achieve a specific goal.

Eg. A self driving car navigating to a destination.

4. Utility Based Agent - Selects the best action based on utility.

Eg. AI recommending investment strategies.

5. Learning Agent - Improves performance based on experience.

Eg. AI powered personal assistants like Siri and Google Assistant.

Example of working of an agent is as follows:

For Vacuum cleaner problem.

- Performance Measure: All rooms are well cleaned.
- Behaviour: Left, Right, Suck and no-op (Doing nothing)
- Percept: Location and status
- Agent function: Mapping (percept sequence, action).

Percept sequence	Action
[A, Clean]	Right
[B, Clean]	Left
[A, Dirty]	Right Suck

3. How AI technique is used to solve 8 puzzle problem.

Ans AI techniques are used to solve 8 puzzle problem by applying search algorithm & heuristic function.

1. Problem representation: The 8 puzzle is represented as a state space where each state is a 3×3 grid configuration.

Initial state :

1	2	3
4	0	6
7	5	8

Goal state :

1	2	3
4	5	6
7	8	0

Steps to solve 8 puzzle problem by A^*

1. Initialize a priority queue.

2. Insert the initial state with $f(n) = g(n) + h(n)$.

3. While queue not empty

Remove state with lowest $f(n)$.

If state = goal, return solution.

Generate valid moves (up, down, left, right)

Compute $g(n)$ and $h(n)$ for new states.

Insert new states into queue.

4. Repeat until goal is reached.

4. What is PEAS descriptor? Give PEAS descriptor for following.

Taxi Driver

Medical Diagnosis system

A music composer.

An Aircraft autolander.

An essay evaluator

A robotic sensing gun for the Kech Lab.

Ans PEAS stands for Performance, Environment, Actuators, Sensors
P → Criteria to evaluate Agent's success.
E → Surroundings/External area where agent operates.
A → Components that allow agent to take actions.
S → Components that help agent perceive its environment.

PEAS for Taxi Driver

P: Reaching Destination, fuel efficiency.
E: Roads, traffic, pedestrians.
A: Steering wheel, brakes, accelerator.
S: Camera, GPS, Speedometer.

PEAS for Medical Diagnosis System.

P: Accuracy of Diagnosis, speed of Diagnosis.
E: Medical records, test results, hospitals.
A: Recommending treatments, sending alerts to patients & doctors, updating medical records.
S: Wearable sensors, medical imaging devices.

PEAS for music composer

P: User satisfaction, quality of composition.
E: Music production studio, streaming platforms.
A: Adjusting pitch and key of compositions, suggesting chord progressions and melodies.
S: MIDI inputs, music databases, lyrics or text for ~~most~~ melody generation.

PEAS for Aircraft autolander.

P: Smooth and safer landing.
E: Weather, runway.

A : Gear, throttle, flaps.

S : Altitude sensor, GPS, wind direction sensor

PEAS for Essay Evaluator.

P : Grading accuracy, feedback quality, accuracy in error checking.

E : Educational institutes, competitive exams.

A : Highlighting grammar and spelling errors, checking for plagiarism.

S : Text input, NLP, AI based readability assessment tools.

PEAS for Robotic sentry gun for Keck lab.

P : Correctly identifying threats and targets, speed of response

E : Keck Lab, facility, research centers.

A : Tracking, alerting security personnel.

S : Cameras, motion sensors, AI based threat recognition

5. Categorise a shopping bot for an offline bookstore according to each of the six dimensions

- Ans
- Partially observable : The bot cannot fully observe customer preference or book placements.
 - Stochastic : Customer behaviour and book availability are unpredictable.
 - Sequential : Each interaction depends on previous queries & actions.
 - Dynamic : The bookstore environment constantly changes.
 - Discrete : The bot operates with a finite set of books, actions and interactions.
 - Multiagent : The bot interacts with customers, employees and inventory systems.

6. Differentiate Model based and Utility based agent.

Ans. Model based agent

1. Uses an internal model of environment to make decisions.

2. Decisions are based on past and present percepts.

3. Can be goal based but does not necessarily optimize for best outcome.

4. Example: Robot vacuum using a map to navigate.

Utility based agent.

1. Chooses actions based on utility function that measures performance.

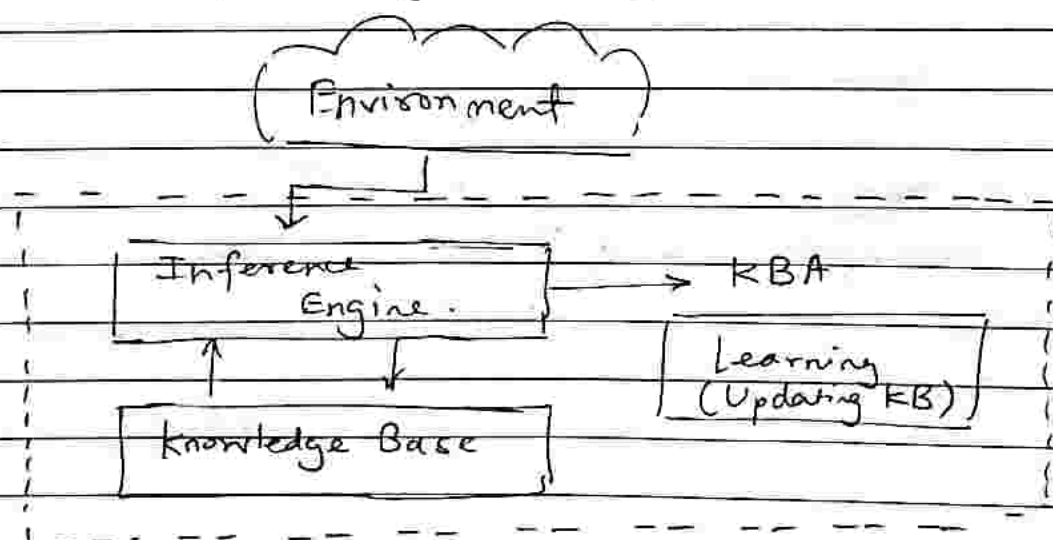
2. Selects action based on managing utility.

3. Is goal based and searches for the most optimal solution.

4. Example: A self driven car.

7. Explain the Architecture of a knowledge based agent and learning agent.

Ans. Architecture of knowledge based agent

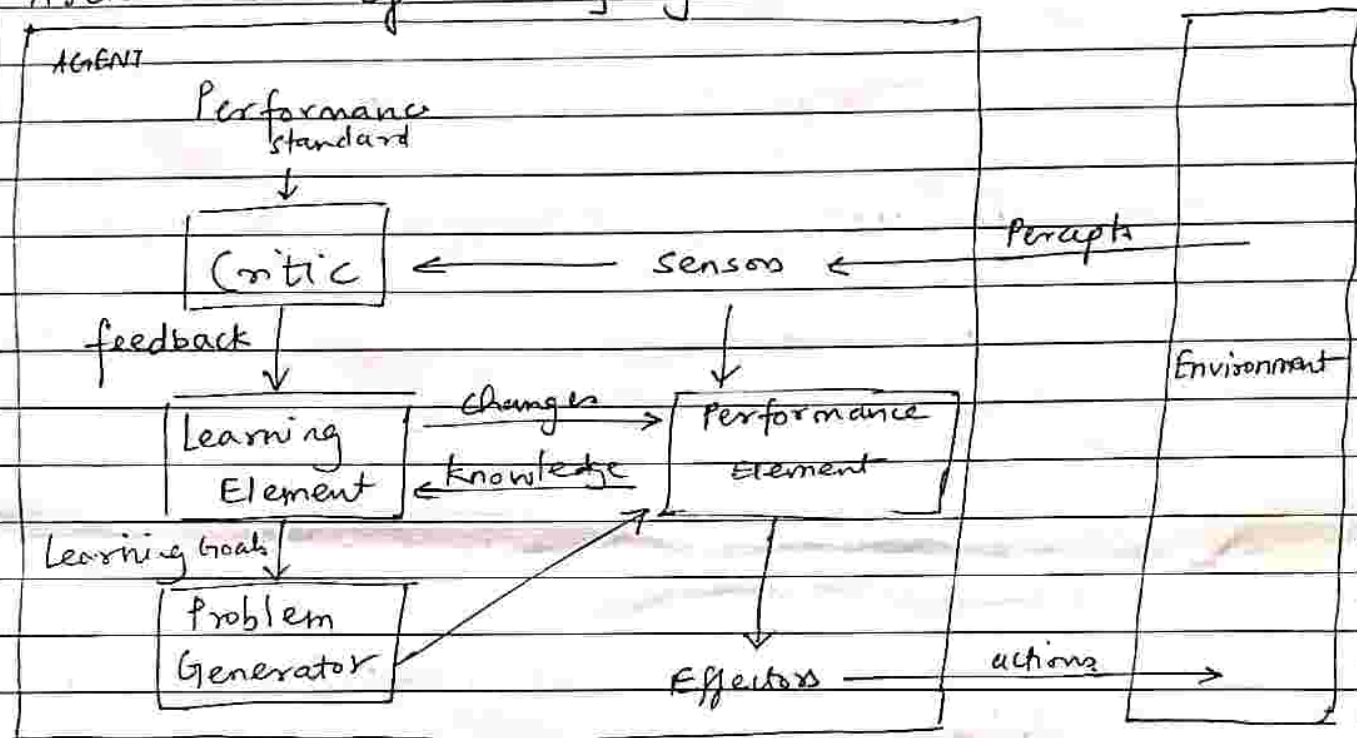


It uses stored knowledge to make decisions and consists of the following:

- Knowledge base: Stores facts, rules and logic

- Inference Engine: Uses reasoning to derive conclusions.
- Perception: Gather new information from environment
- Action mechanism: Performs appropriate action based on reasoning

Architecture of Learning Agent



It improves performance over time and consists of the following.

- Learning element: Updates knowledge based on experience
- Performance element: Decides actions based on current knowledge
- Problem generator: Suggests new actions to improve learning
- Critic: Provides feedback by evaluating action.

9. Convert the following to predicates

a. Anita travels by car if available otherwise travels by bus.

P.T.O

Car Available \rightarrow Travels By Car (Anita).

\neg Car Available \rightarrow Travels By Bus (Anita).

b. Bus goes via Andheri and Goregaon.

goes via (Bus, Andheri) \wedge Goregaon (Bus, Goregaon)

c. Car has puncture & is not available

Puncture (car)

Puncture (car) $\rightarrow \neg$ car available.

Will Anita travel via Goregaon? Use forward reasoning

From (c)

Puncture (car) is true

As Puncture (car) $\rightarrow \neg$ Car Available.

From (a)

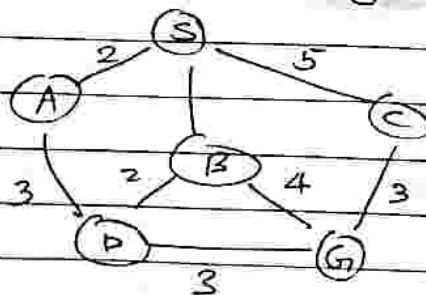
\neg Car Available, we use \neg Car Available \rightarrow Travels By Bus (Anita)

From (b)

Goes via (Bus, Goregaon)

Since Anita travels by bus she will follow this route
Thus, Anita will travel via Goregaon.

10. Find route from S to G using BFS.



1. Start at S

Queue = [S].

2. Dequeue S and explore its neighboring nodes

Queue = [A, B, C]

3. Dequeue A and explore neighbour

Queue = [B, C, D]

4. Dequeue B and explore neighbour

Queue = [C, D, G]

5. Dequeue C and explore neighbour.

Queue = [D, G]

6. Dequeue D.

Queue = [G]

7. Dequeue G.

G is our destination node, BFS will stop here

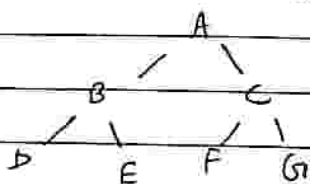
Route from S to G: $S \rightarrow B \rightarrow G$.

11. What do you mean by depth limited search? Explain iterative deepening search with examples.

Ans Depth Limited Search (DLS) is an uninformed search algorithm that modifies DFS by introducing a depth limit L preventing exploration beyond the defined level. This prevents infinite loops in graphs but risks missing goals beyond L.

Iterative deepening search combines DLS with BFS by incrementally increasing the depth limit.

Example:



Goal = G.

- Initially the depth limit is 0 for iteration = 1.
Nodes visited = A.

Goal not found.

- Iteration 2, limit = 1.

Nodes visited = A \rightarrow B \rightarrow C.

Goal not found.

Iteration 3, limit = 2.

Nodes visited = A \rightarrow B \rightarrow D \rightarrow E \rightarrow C \rightarrow F \rightarrow G.

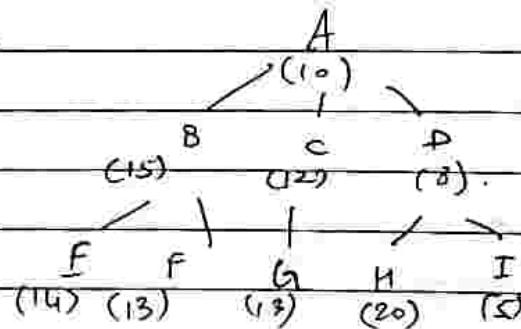
Goal G is found.

12. Explain Hill Climbing and its drawback in detail with example.

Ans. Also state limitations of steepest ascent climbing.

Ans. Hill Climbing is a local search optimization algorithm which moves forward towards a better neighboring solution until it reaches a peak.

Example



Goal = G.

Steps:

1. Start at root node A (10).
2. Compare its children B, C, D.
3. Move to child with highest value i.e. B (15).
4. Repeat for B's children E and F.

6. Terminates at $E(14)$.

The algorithm stops at $E(14)$ not reaching the Goal G .

Drawbacks.

1. Local maxima: The algorithm greedily selects the best immediate child and can thus get stuck on a local maxima.
2. Plateau: If siblings have equal values, the algorithm cannot decide the next step and gets stuck.
3. Ridges: Narrow uphill paths require backtracking which hill climbing algorithm does not support.

Limitations of steepest ascent hill climbing are as follows.

1. Computationally expensive: Evaluates all neighbours before selecting the best.
2. Can get stuck: It can still get stuck in local maxima, plateaus or ridges.
3. No global optimality: It only focuses on immediate improvements.

13. Explain simulated annealing and write its algorithm.

Ans Simulated annealing is probabilistic optimization algorithm inspired by metallurgical process of annealing where materials are heated and cooled to reduce defects. It escapes the local optima by temporarily accepting worse solution with its probability.

Algorithm.

1. Initialize-

• Set an initial solution and define an initial temperature T .

2. Repeat until stopping condition

• Generate a new neighbour solution

• Compute changes in cost.

If new solution is better than accept it.

- If worse, accept it with probability.

- Decrease temperature T .

3. Return best solution.

Example: Travelling salesman problem.

14. Explain A^* algorithm with an example.

Ans A^* is a best first search algorithm used in path finding and graph traversal. It uses the following formulas.

$$f(n) = g(n) + h(n)$$

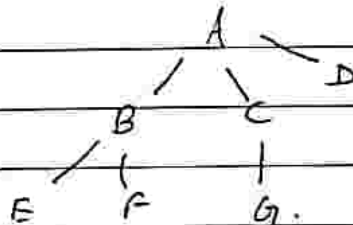
$$f(n) = g(n) + h(n).$$

$g(n)$ = cost to reach n , from start.

$h(n)$ = heuristic estimate of cost to reach from goal to n .

$f(n)$ = total estimated cost.

Goal : G



Node	$g(A, n)$	$h(n, G)$
A	0	6
B	1	4
C	2	2
D	4	7
E	3	5
F	5	3
G	6	0

Steps-

1. Start at root node A

$$f(A) = g(n) + h(n) = 0 + 6 = 6$$

2. Expand neighbours B, C, D.

$$f(B) = 1 + 4 = 5; \quad f(C) = 2 + 2 = 4; \quad f(D) = 4 + 7 = 11$$

3. Choose lowest value that is $f(C)$.

4. Expand neighbours of C.

$$f(G) = 2 + 4 + 0 = 6$$

5. Goal reached at G with total cost = 6

Advantages:

- Efficient for finding the shortest path in weighted graphs.
- Balance exploration by considering both $g(n)$ and $h(n)$.

15. Explain Min-Max algorithm and draw game tree for Tic Tac Toe game.

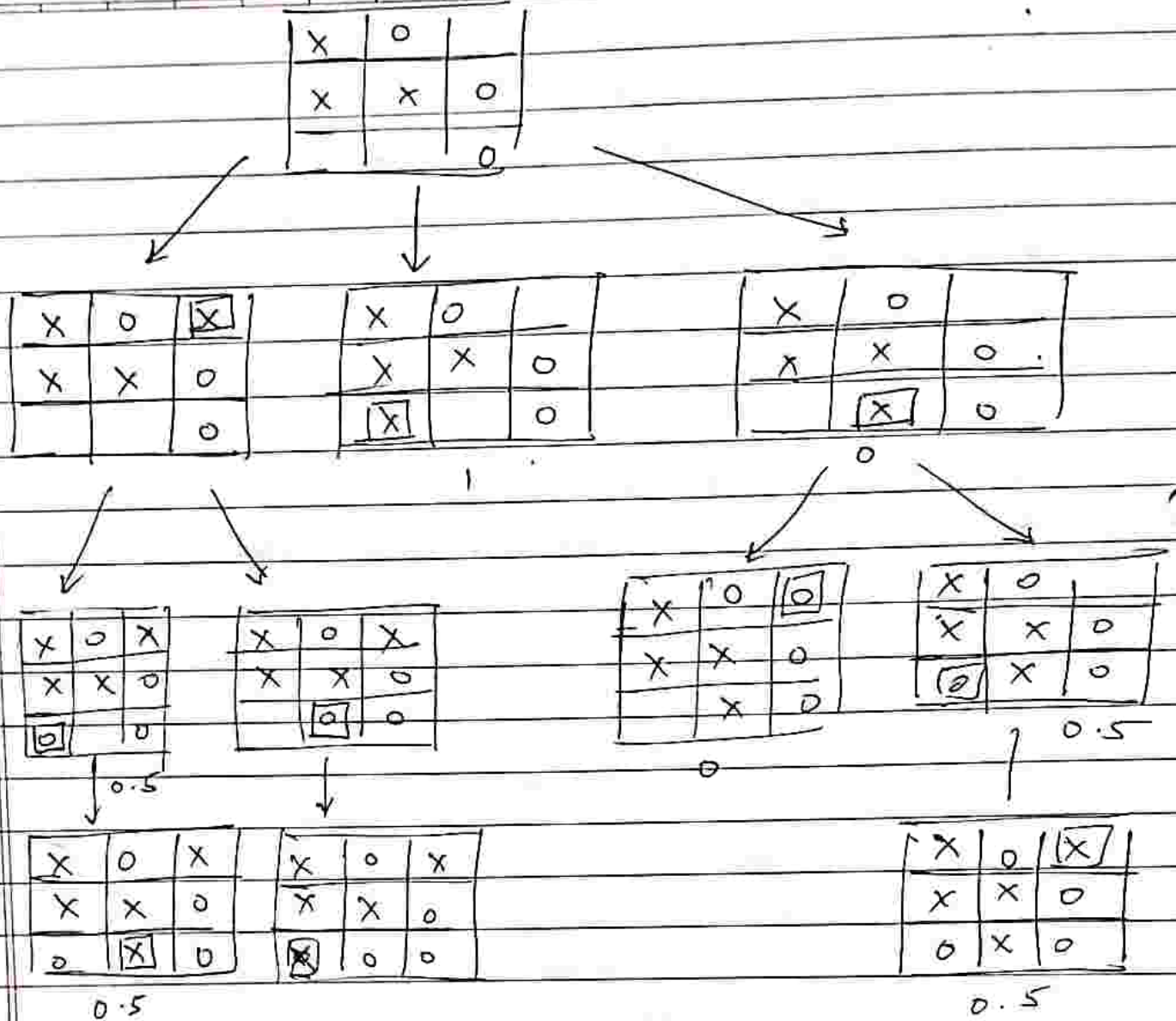
Ans The min max algorithm is a decision making algorithm used in 2 player games. It assumes

- One player (MAX) tries to maximize the score
- Other player (MIN) tries to minimize the score
- Game tree represents all possible moves.

Algorithm-

1. Generate game tree.
2. Assign scores.
3. MAX picks highest value from children
MIN picks lowest value
4. Repeat until root node is evaluated.

Game tree for tic tac toe game is as follows:



16. Explain Alpha beta pruning algorithm for adversarial search with example.

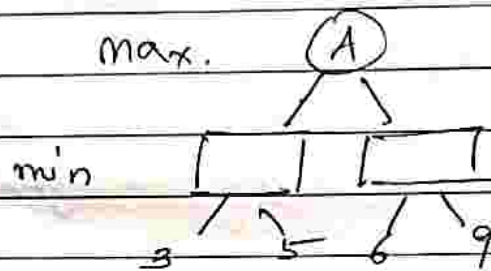
Ans Alpha Beta pruning is an optimization technique used in minimum algorithm to reduce the number of nodes evaluated in adversarial search problems like game - playing AI (eg. chess, tic-tac-toe)

Alpha Beta pruning includes:

Alpha (α): The best maximum score that the maximizing player can guarantee to far.

Beta (β): The ~~max~~ best minimum score that the minimizing player can guarantee so far.
The algorithm prunes branches that will not influence final decision.

Example.:



1. Start at root node A.

$$\alpha = -\infty, \beta = \infty.$$

2. Check left min node (child of A).

- check first child value = 3 \rightarrow update $\beta = 3$.
- check 2nd child value = 5 \rightarrow β remains 3.
- Min node returns 3 to MAX.

3. Right min node (child of A)

- Check first child value = 6 $\rightarrow \beta = 6$.
- Here, $\alpha = 3$ at MAX node but $\beta(6) > \alpha(3)$ so no pruning

• Explore 2nd child (9) \rightarrow Here pruning will occur

\therefore MIN node already has a value ≤ 6 it will never choose 9
and so we prune the node with value 9.

4. Max value = 6

17 Explain WUMPUS world environment, giving its PFA's description.
Explain new percept sequence is generated.

Ans The wumpus world environment is a simple grid-based environment used in AI to study intelligent agent behaviour.

in uncertain environments. It is a turn based environment where an agent must navigate a cave to find gold while avoiding hazards like pits and monster called WUMPUS.

PEAS one as follows:

P: The agent is rewarded for grabbing gold and ^{exiting} safely. Penalty is imposed for falling into pits and getting caught by WUMPUS.

E: 4×4 grid world containing the agent, WUMPUS, pits, gold.

A: The agent can move forward, left, right, shoot, climb.

S: Agent perceives stench (near WUMPUS), breeze (near a pit), glitter (near gold), bump and scream.

Percept sequence generation.

It is the history of all ^{perception} ~~generation~~ received by the agent. At each time step the agent perceives information based on its current location and surroundings.

Example percept sequence.

1. Agent starts at (1, 1).

• No breeze, no stench, no glitter \rightarrow safer square.

2. Agent moves to (2, 1).

• Breeze detected \rightarrow A pit is nearby ^{but} not in current square.

3. Agent moves to (1, 2).

• Stench detected \rightarrow WUMPUS is in an adjacent cell.

4. Agent moves to (2, 2).

• Glitter detected \rightarrow gold is here.

5. Agent moves back to (1, 1) and climbs out.

18. Solve the following crypto-arithmetic problem:

$$1. \text{ SEND} + \text{MORE} = \text{MONEY}$$

Ans Step 1: M must be 1. The sum of two four digit numbers cannot be more than 10,000.

$$\begin{array}{r} \text{SEND} \\ + \text{MORE} \\ \hline \text{MONEY} \end{array}$$

Step 2: Now, S must be 8 because there is 1 carry over from column E - 0 - N - 0 must be 0 (if $S=8$) and there is a 1 carried or $S=9$ and there is no 1 carried or (if $S=9$ and there is 1 carried). But 1 is already taken so 0 must be 0.

$$\begin{array}{r} \text{SEND} \\ + \text{MORE} \\ \hline \text{MONEY} \end{array}$$

Step 3: There cannot be a carry from column EON because any digits $+0 < 10$, unless there is a carry from the column NRE and $E=9$. But this cannot be the case because the N would be 0 and 0 is already taken. So $E < 9$ and there is no carry from this column. Therefore, $S=9$ because $9+1=10$.

Step 4:

Case 1: No carry: $N+R = 10 + (N-1) = N+9$.

$$R=9$$

But 9 is taken already so will not work.

Case 2: Carry: $N+R+1 = 9$.

$$R = 9-1 = 8. \text{ This must be the solution of } R.$$

Step 5:

Let us consider $E=5$ or 6.

$$E = 5.$$

then $D = 7$, & $Y = 3$. So this part will work but look at the column $N8E$. There is a carry from the column DEY , $N + 8 + 1 = 16$. But then $N = 7$ and 7 is taken by D therefore $E = 5$.

$$\begin{array}{r} 95ND. \\ + 1085 \\ \hline 10N5Y. \end{array}$$

Now,

$$N + 8 + 1 = 15, N = 6.$$

$$\begin{array}{r} 956D. \\ + 1085 \\ \hline 1065Y. \end{array}$$

Step 6:

The digits left are 7, 4, 3 & 2. We know there is a carry from column $D5Y$, so only pair that works is $D = 7$ & $Y = 2$.

$$\begin{array}{r} 9567 \\ + 1085 \\ \hline 10652 \end{array}$$

19. Consider the following axioms.

All the people who are graduating are happy

All happy people are smiling

Someone is graduating.

Ans. Representing these axioms in first order predicate logic.

We define the following predicates.

• $G(x)$: x is graduating.

• $H(x)$: x is happy

- $S(x)$: x is smiling

Translating axiom into predicate logic:

1. All people who are graduating are happy.
 $\forall x (G(x) \rightarrow H(x))$.

2. All happy people are smiling.
 $\forall x (H(x) \rightarrow S(x))$.

3. Someone is graduating
 $\exists x G(x)$

Convert each formula to clause form.

1. Convert implication to clausal form.

$$\forall x (G(x) \rightarrow H(x)).$$

- Using implication removal.

$$\forall x (\neg G(x) \vee H(x)).$$

- In clause form.

$$\{ \neg G(x), H(x) \}.$$

2. $\forall x (H(x) \rightarrow S(x))$

- Using implication removal.

$$\forall x (\neg H(x) \vee S(x)).$$

- In clausal form.

$$\{ \neg H(x), S(x) \}.$$

3. $\exists x G(x)$

- In clausal form: $\{ G(x) \}$

Prove "is someone smiling" using resolution.

1. Collect clauses.

(1) $\{ \neg G(x), H(x) \}$.

(2) $\{ \neg H(x), S(x) \}$.

(3) $\{ G(x) \}$.

2. Apply resolution.

• Resolve (1) $\{ \neg G(x), H(x) \}$ with (3).

$\{ G(a) \}$.

Substituting $x=a$

$\{ \neg G(a), H(a) \}$.

\therefore we have $G(a)$, resolving gives

$\{ H(a) \}$.

• Resolve (2) $\{ \neg H(x), S(x) \}$ with $\{ H(a) \}$.

Substituting $x=a$.

$\{ \neg H(a), S(a) \}$

• Since, we have $H(a)$ resolving gives

$\{ S(a) \}$

Since, we derived $S(a)$, we conclude that someone (a) is smiling.

20. Explain modus ponens with suitable example.

Ans Modus ponens is a fundamental rule of inference in ~~propositional~~ propositional logic that allows us to deduce a conclusion from a conditional statement and its antecedent.

It follows the form.

1. $P \rightarrow Q$ (if P then Q)

2. P (P is true)

$\therefore Q$ (Q must be true)

Example

1. If it rains, the ground will be wet

$$\rightarrow P \rightarrow Q$$

2. It is raining $\rightarrow P$

\therefore Ground is wet $\rightarrow Q$

Q1. Explain forward chaining and backward chaining algorithm with the help of example.

Ans Forward chaining: It starts with given facts and applies inference rules to derive new facts until the goal is reached. It is a data driven approach because it begins with known data and works forward to reach a conclusion.

Example: Diagnosing a disease.

Rules:

1. If a person has a fever and cough they might have flu.
2. If a person has sore throat and fever, they might have cold.

Facts:

- The patient has a fever.
- The patient has cough

Inference

1. Fever + cough \rightarrow flu (rule 1 applies)
2. Conclusion; The patient might have flu.

Backward chaining: It starts with goal and works to backward by checking what facts are needed to support it. It is a goal driven approach.

Example: Diagnosing a disease

Goal: Determine if a patient has flu.

Rules

1. $(\text{Fever} \wedge \text{Cough}) \rightarrow \text{Flu}$.
2. $(\text{Sore Throat} \wedge \text{Fever}) \rightarrow \text{Cold}$.

Process using backward chaining.

1. We want to prove flu.
2. Looking at rule 1: $(\text{Fever} \wedge \text{cough}) \rightarrow \text{Flu}$, we need to check if patient has fever and cough.
3. We check our known facts.
 - Patient has fever.
 - Patient has cough.
4. Since, both ~~conclusion~~ conditions are met, we confirm flu is true.