

## Online Assignment2 (WTP2)

Department: **Electronics & Communication Engineering.**

School:

Course Code: **ECE397**

Course Title: Workshop on Microcontroller Based Data Logger System.

Time duration: N.A. Max. Marks: **50** Section: **EE021** Marks Obtained:

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Reg. Number: **\_\_11904463\_\_**

Roll Number: **\_\_15\_\_**

Q. 8051 based project, along with the project report containing the following:

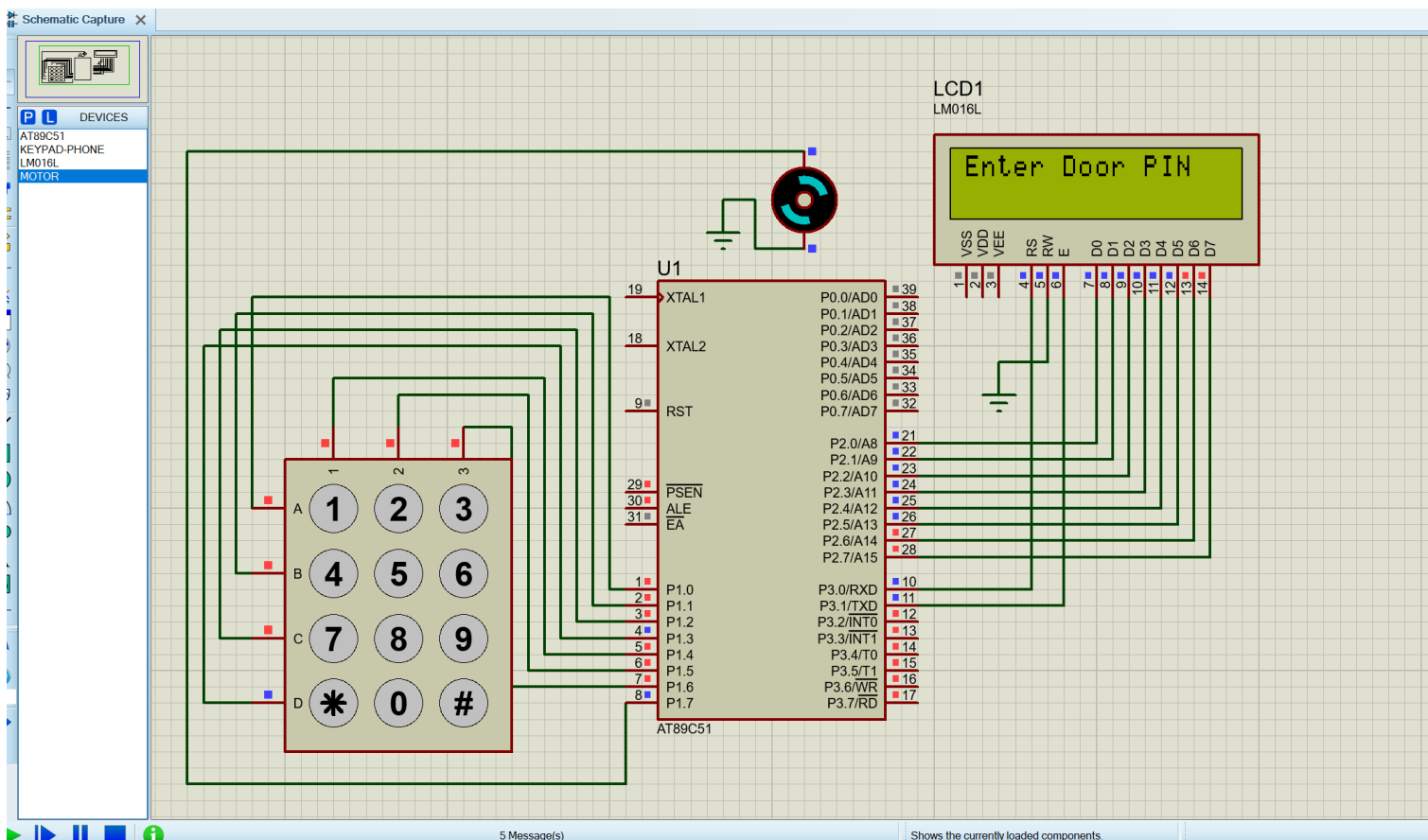
## Title: Door Password System.

**Objective:** To make door system more secure by adding password on it.

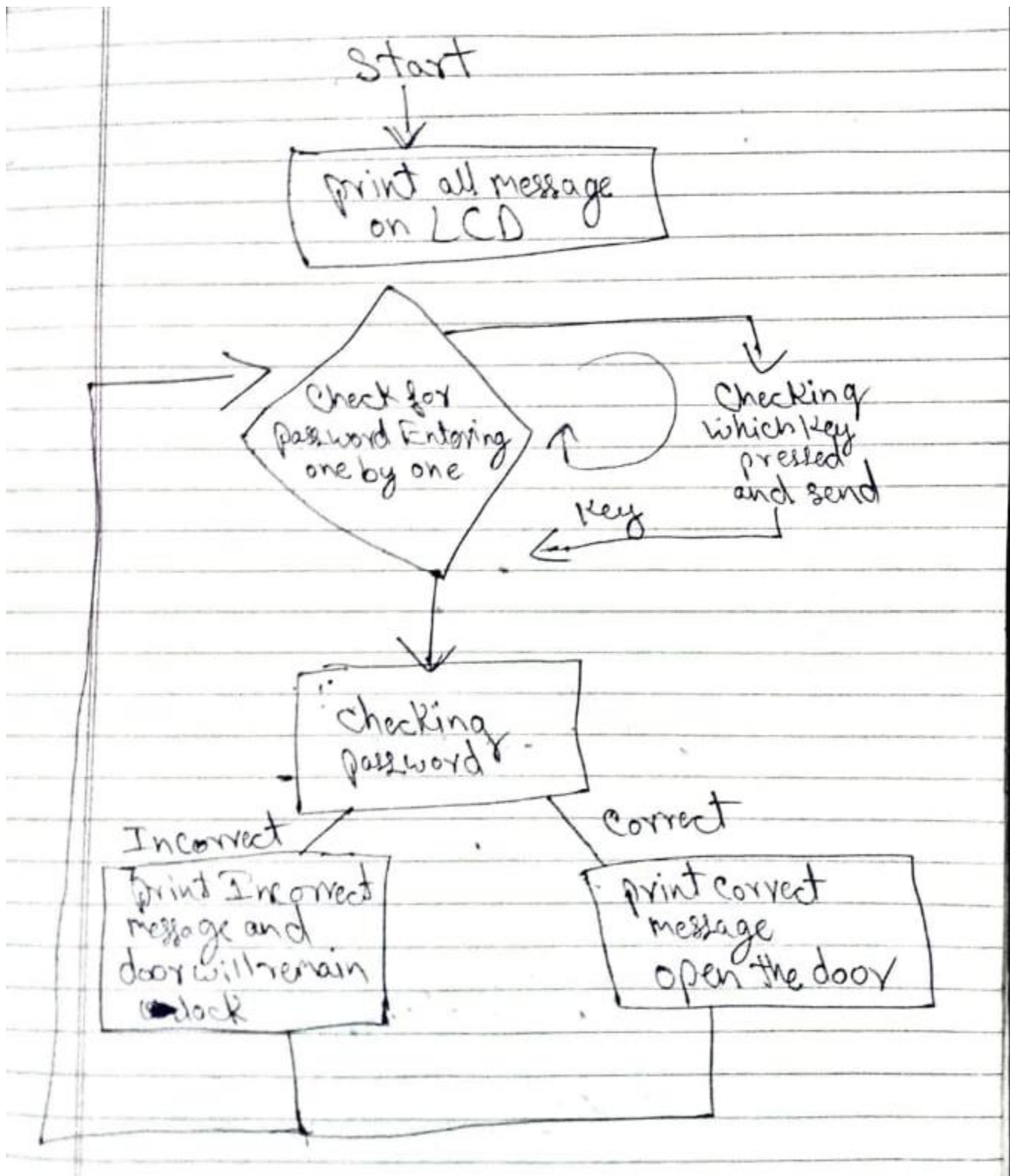
**Components (Hardware):** 8051 micro-Controller, Keypad-Phone , LCD, Motor.

**Software tools requirements:** Proteus & Keil.

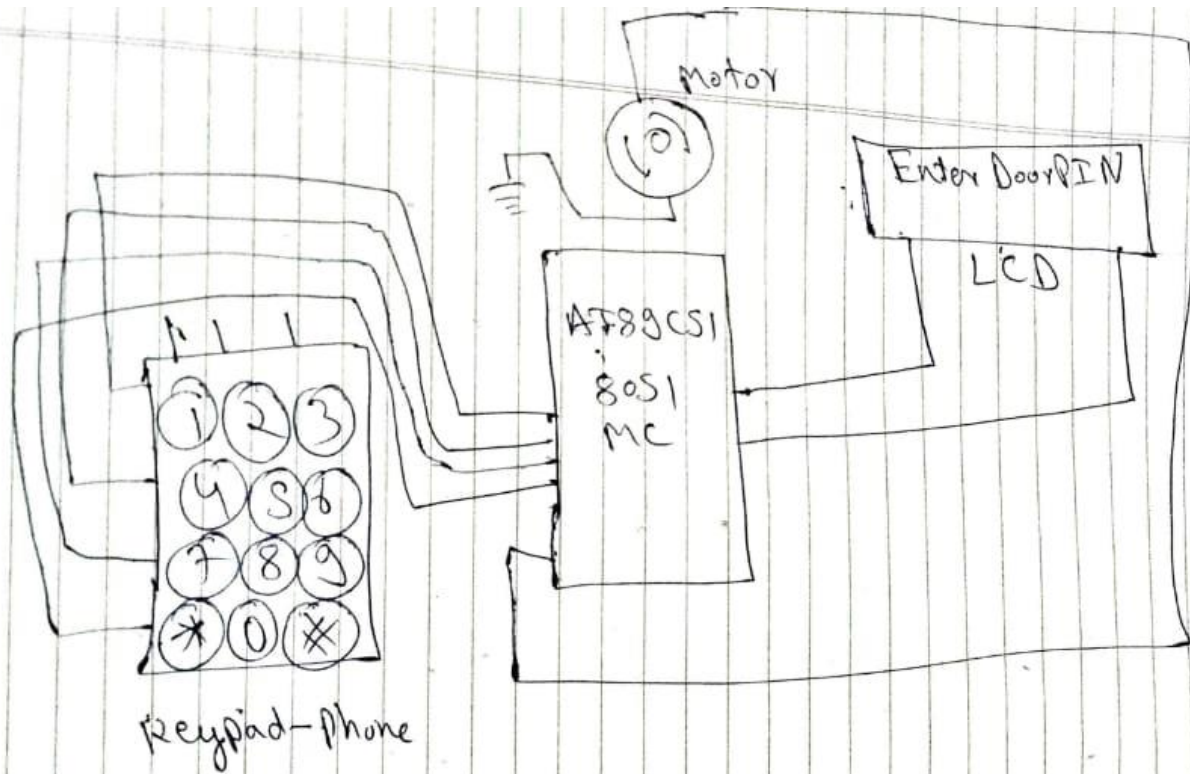
**Circuit diagram:**



block diagram:



Flow chart/Approach of the overall project:



Introduction:

## Introduction.

This project is all about security related to door system. This project is made with Microcontroller 8051 which is a general purpose microcontroller, LCD (16x2), Keypad-phone and motor and programming is written in C language.

The software used is Proteus which is used to make all circuits and Keil which is used to write code and to build hex file by which microcontroller will work.

By using digital system in door, we can get rid of from key to missed somewhere or stolen by someone and later misuse.

The door will open only when the correct password will be entered otherwise door will remain closed.

## Application:

- i) Secure main door or further we can connect it with mobile Application.
- ii) Alarm lock to secure important documents or jewellery.

**Theory related to all the components used :**



## 8051 Microcontroller.

The 8051 microcontroller is a general purpose microcontroller use in many small application like traffic light, microwave, washing machine etc. Microcontroller have inbuilt RAM & ROM which is suitable for small projects. Although it can make some complicate projects also.

### Keypad - Phone (4x3)

Keypad - phone is the basic and simple technique keypad which used row and column to detect which key is pressed and send signal to microcontroller.

### LCD (LM016L) (16x2)

A simple 16x2 Liquid Crystal Display can handle 8bit number or command at a time and can display 32 characters at once at whole display.

### Motor :

Simple motor to unlock or lock door operated by Microcontroller.

Program/Sketch/Code:

Door\_Password\_System.c

```
1#include<reg51.h>
2#define LCD P2
3sbit RS = P3^0;
4sbit E = P3^1;
5
6sbit key_r1 = P1^0;
7sbit key_r2 = P1^1;
8sbit key_r3 = P1^2;
9sbit key_r4 = P1^3;
10
11sbit key_c1 = P1^4;
12sbit key_c2 = P1^5;
13sbit key_c3 = P1^6;
14
15sbit door_motor = P1^7;
16
17unsigned char pin[] = {"9885"};
18unsigned char epin[4];
19
20void delay(unsigned int time){
21    unsigned int i, j;
22    for(i=1;i<time;i++)
23        for(j=1;j<1275;j++);
24}
25
26void lcd_command(unsigned char c){
27    LCD = c;
28    RS = 0;
29    E = 1;
30    delay(4);
31    E = 0;
32}
33void print(unsigned char d){
34    LCD = d;
35    RS = 1;
36    E = 1;
37    delay(4);
38    E = 0;
39}
40void init_lcd(){
41    lcd_command(0x38);
42    lcd_command(0x01);
43    lcd_command(0x06);
44}
```

## Door\_Password\_System.c

```

40 void init_lcd(){
41     lcd_command(0x38);
42     lcd_command(0x01);
43     lcd_command(0x06);
44     lcd_command(0x0c);
45     lcd_command(0x80);
46 }
47 void printl(unsigned char* str){
48     unsigned int i=0;
49     while(str[i] != '\0'){
50         print(str[i]);
51         i++;
52     }
53 }
54
55 unsigned char GetKey(){
56     while(1){
57         key_r1 = 0;
58         key_r2 = 1;
59         key_r3 = 1;
60         key_r4 = 1;
61         if(key_c1 == 0){
62             return '1';
63         }
64         if(key_c2 == 0){
65             return '2';
66         }
67         if(key_c3 == 0){
68             return '3';
69         }
70         key_r1 = 1;
71         key_r2 = 0;
72         key_r3 = 1;
73         key_r4 = 1;
74         if(key_c1 == 0){
75             return '4';
76         }
77         if(key_c2 == 0){
78             return '5';
79         }
80         if(key_c3 == 0){
81             return '6';
82         }

```

## Door\_Password\_System.c

```

79     }
80     if(key_c3 == 0){
81         return '6';
82     }
83     key_r1 = 1;
84     key_r2 = 1;
85     key_r3 = 0;
86     key_r4 = 1;
87     if(key_c1 == 0){
88         return '7';
89     }
90     if(key_c2 == 0){
91         return '8';
92     }
93     if(key_c3 == 0){
94         return '9';
95     }
96     key_r1 = 1;
97     key_r2 = 1;
98     key_r3 = 1;
99     key_r4 = 0;
100    if(key_c1 == 0){
101        return '*';
102    }
103    if(key_c2 == 0){
104        return '0';
105    }
106    if(key_c3 == 0){
107        return '#';
108    }
109    delay(20);
110 }
111 }
112
113 void checkPassword(){
114     init_lcd();
115     if(epin[0] == pin[0] && epin[1] == pin[1] && epin[2] == pin[2] && epin[3] == pin[3]){
116         printl("Correct PIN");
117         door_motor = 1;
118         lcd_command(0xc0);
119         printl("Door Opened");
120     }
121     else{

```

```
Door_Password_System.c
104     return '0';
105 }
106 if(key_c3 == 0){
107     return '#';
108 }
109 delay(20);
110 }
111 }
112
113 void checkPassword(){
114     init_lcd();
115     if(epin[0] == pin[0] && epin[1] == pin[1] && epin[2] == pin[2] && epin[3] == pin[3]){
116         printl("Correct PIN");
117         door_motor = 1;
118         lcd_command(0xc0);
119         printl("Door Opened");
120     }
121     else{
122         printl("Incorrect PIN");
123         lcd_command(0xc0);
124         printl("Try Again Later");
125     }
126     delay(1000);
127     door_motor = 0;
128 }
129
130 void main(){
131     while(1){
132         unsigned int i = 0;
133         door_motor = 0;
134         init_lcd();
135         printl("Enter Door PIN");
136         lcd_command(0xc0);
137         while(pin[i] != '\0'){
138             epin[i] = GetKey();
139             print('*');
140             delay(50);
141             i++;
142         }
143         checkPassword();
144     }
145 }
146
```

```
#include<reg51.h>
```

```
#define LCD P2
```

```
sbit RS = P3^0;
```

```
sbit E = P3^1;
```

```
sbit key_r1 = P1^0;
```

```
sbit key_r2 = P1^1;
```

```
sbit key_r3 = P1^2;
```

```
sbit key_r4 = P1^3;
```

```
sbit key_c1 = P1^4;
```

```
sbit key_c2 = P1^5;
```

```
sbit key_c3 = P1^6;
```

```
sbit door_motor = P1^7;
```

```
unsigned char pin[] = {"9885"};
```

```
unsigned char epin[4];
```



```

void delay(unsigned int time){
    unsigned int i, j;
    for(i=1;i<time;i++)
        for(j=1;j<1275;j++);
}

void lcd_command(unsigned char c){
    LCD = c;
    RS = 0;
    E = 1;
    delay(4);
    E = 0;
}

void print(unsigned char d){
    LCD = d;
    RS = 1;
    E = 1;
    delay(4);
    E = 0;
}

void init_lcd(){
    lcd_command(0x38);
    lcd_command(0x01);
    lcd_command(0x06);
    lcd_command(0x0c);
    lcd_command(0x80);
}

void printl(unsigned char* str){
    unsigned int i=0;
    while(str[i] != '\0'){
        print(str[i]);
        i++;
    }
}

unsigned char GetKey(){
    while(1){
        key_r1 = 0;
        key_r2 = 1;
        key_r3 = 1;
        key_r4 = 1;
        if(key_c1 == 0){
            return '1';
        }
        if(key_c2 == 0){
            return '2';
        }
        if(key_c3 == 0){
            return '3';
        }
    }
}

```

```

    }
    key_r1 = 1;
    key_r2 = 0;
    key_r3 = 1;
    key_r4 = 1;
    if(key_c1 == 0){
        return '4';
    }
    if(key_c2 == 0){
        return '5';
    }
    if(key_c3 == 0){
        return '6';
    }
    key_r1 = 1;
    key_r2 = 1;
    key_r3 = 0;
    key_r4 = 1;
    if(key_c1 == 0){
        return '7';
    }
    if(key_c2 == 0){
        return '8';
    }
    if(key_c3 == 0){
        return '9';
    }
    key_r1 = 1;
    key_r2 = 1;
    key_r3 = 1;
    key_r4 = 0;
    if(key_c1 == 0){
        return '*';
    }
    if(key_c2 == 0){
        return '0';
    }
    if(key_c3 == 0){
        return '#';
    }
    delay(20);
}
}

```

```

void checkPassword(){
    init_lcd();
    if(epin[0] == pin[0] && epin[1] == pin[1] && epin[2] == pin[2] && epin[3] == pin[3]){
        printl("Correct PIN");
        door_motor = 1;
    }
}

```

```

        lcd_command(0xc0);
        printf("Door Opened");
    }
    else{
        printf("Incorrect PIN");
        lcd_command(0xc0);
        printf("Try Again Later");
    }
    delay(1000);
    door_motor = 0;
}

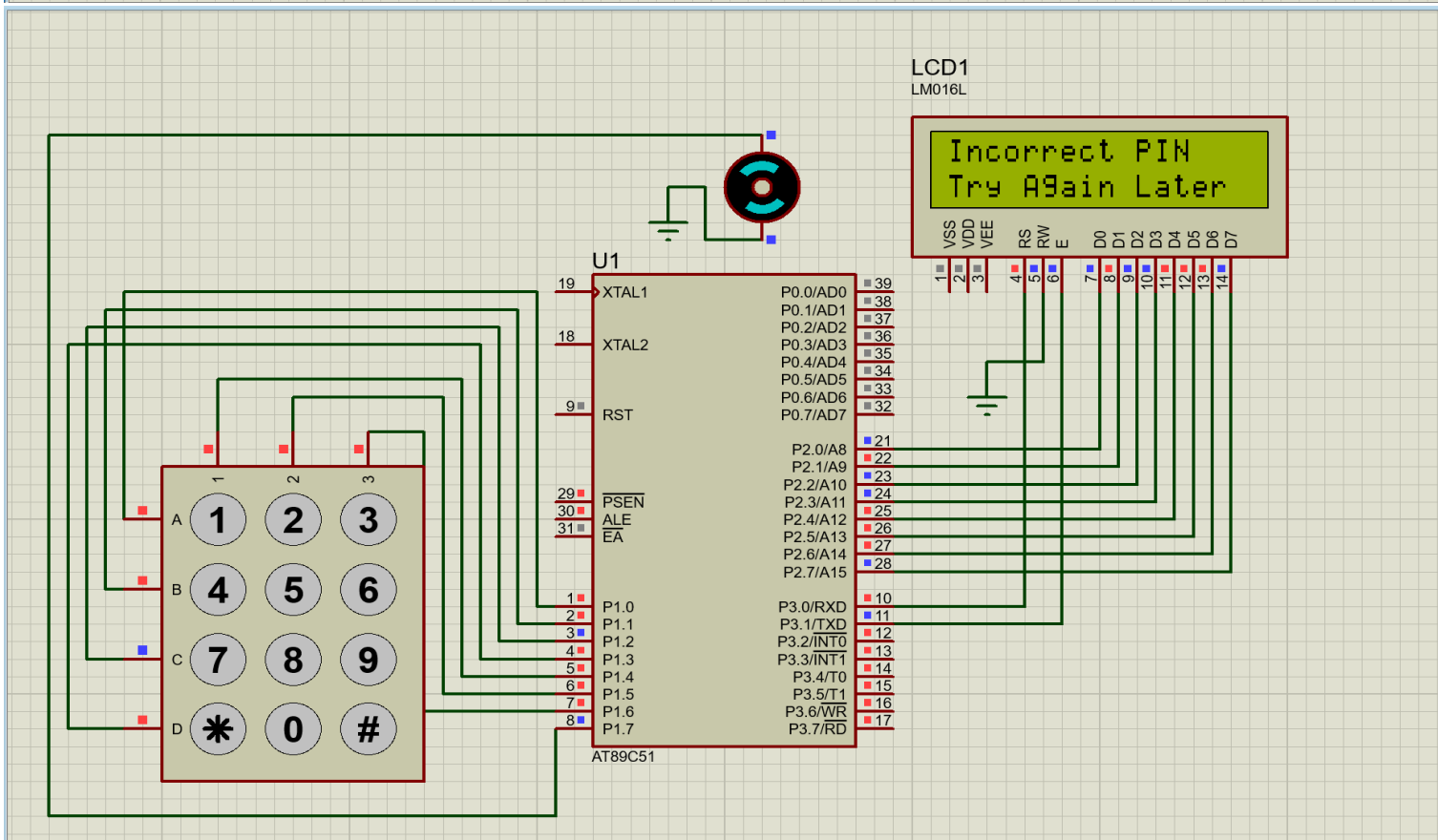
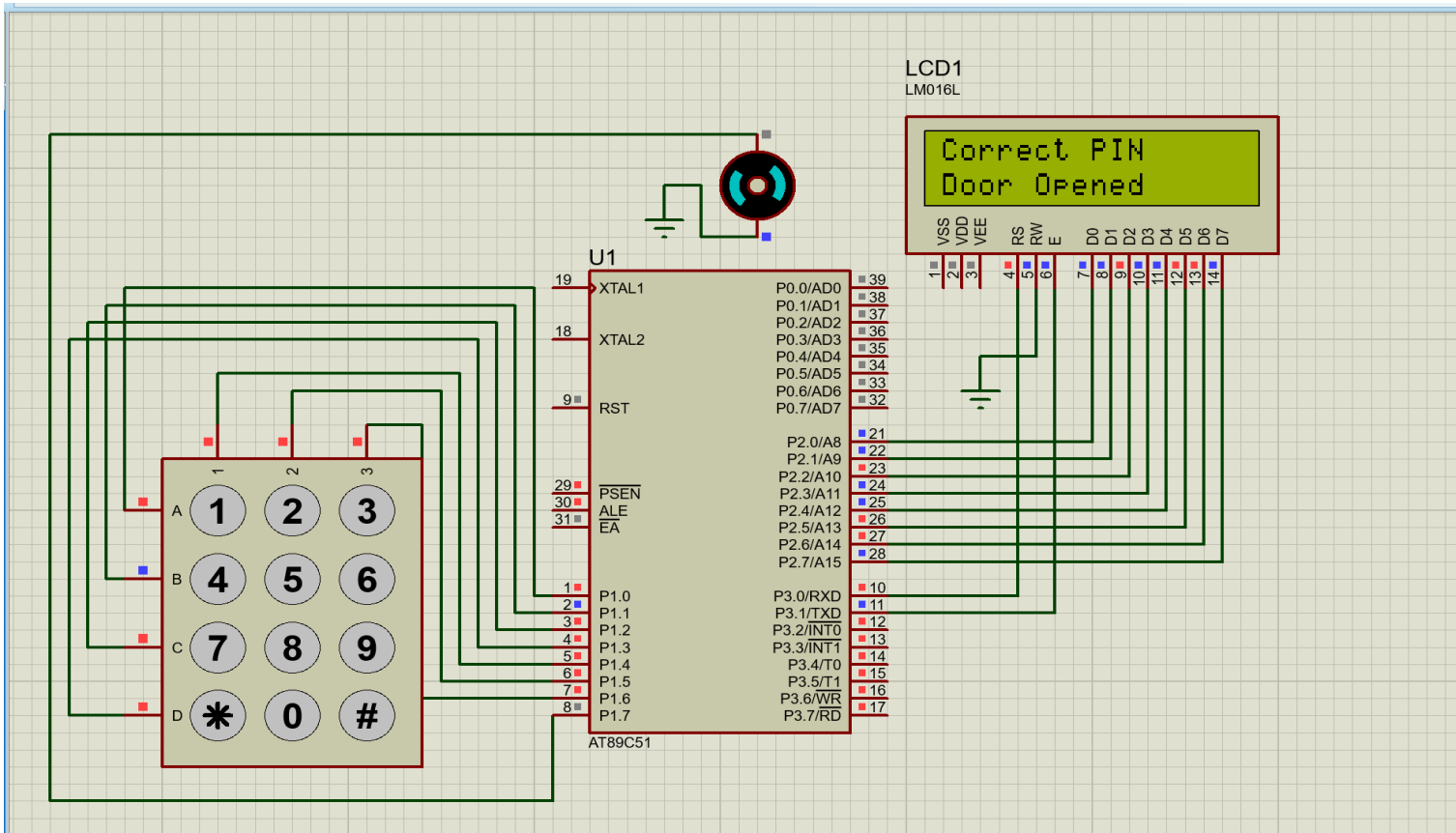
```

```

void main(){
while(1){
    unsigned int i = 0;
    door_motor = 0;
    init_lcd();
    printf("Enter Door PIN");
    lcd_command(0xc0);
    while(pin[i] != '\0'){
        epin[i] = GetKey();
        print('*');
        delay(50);
        i++;
    }
    checkPassword();
}
}

```

## Result and Discussion:



## **Learning outcome:**

1. **Learnt about the 8051 micro-Controller.**
2. **Learnt about the KEYPAD-PHONE.**
3. **Learnt about the LCD (LM016L).**
4. **Learnt about the motor.**
5. **Learnt to do code using C language.**
6. **Learnt circuit design in Proteus.**

## **References:**

<https://github.com/kmhmunin/Password-based-doorlock-system-in-8051-microprocessor>  
<https://youtu.be/6WdycpGuhRY>