SWC_USART

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Data Structure Index

Data Structures

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File List

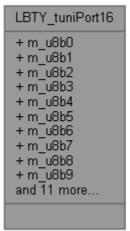
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Data Structure Documentation

LBTY_tuniPort16 Union Reference

#include <LBTY_int.h>
Collaboration diagram for LBTY_tuniPort16:



Data Fields

- struct {
- <u>u8 m_u8b0</u>:1
- <u>u8 m_u8b1</u>:1
- <u>u8 m u8b2</u>:1
- <u>u8 m_u8b3</u>:1
- <u>u8 m u8b4</u>:1
- <u>u8 m_u8b5</u>:1
- <u>u8 m u8b6</u>:1
- <u>u8 m u8b7</u>:1
- <u>u8 m_u8b8</u>:1
- <u>u8 m u8b9</u>:1
- <u>u8 m_u8b10</u>:1
- <u>u8 m u8b11</u>:1
 <u>u8 m_u8b12</u>:1
- <u>u8 m_u8b13</u>:1
- <u>u8 m_u8b13</u>.1
- <u>u8 m_u8b15</u>:1
- } <u>sBits</u>
- struct {
- <u>u8</u> <u>m_u8low</u>
- <u>u8</u> <u>m</u> u8high
- } sBytes
- <u>u16 u u16Word</u>

Field Documentation

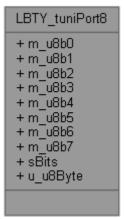
```
u8 m_u8b0
u8 m_u8b1
u8 m_u8b10
u8 m_u8b11
u8 m_u8b12
u8 m_u8b13
u8 m_u8b14
u8 m_u8b15
u8 m_u8b2
u8 m_u8b3
u8 m_u8b4
<u>u8</u> m_u8b5
u8 m_u8b6
u8 m_u8b7
u8 m_u8b8
u8 m_u8b9
u8 m_u8high
u8 m_u8low
struct { ... } sBits
struct { ... } sBytes
<u>u16</u> u_u16Word
```

The documentation for this union was generated from the following file:

• H:/0/Workspaces/MCU Drivers/ATmega32/MCAL/SWC_BSW/<u>LBTY int.h</u>

LBTY_tuniPort8 Union Reference

#include <LBTY_int.h>
Collaboration diagram for LBTY_tuniPort8:



Data Fields

- struct {
- <u>u8 m_u8b0</u>:1
- <u>u8 m u8b1</u>:1
- <u>u8 m_u8b2</u>:1
- <u>u8 m_u8b3</u>:1
- <u>u8 m_u8b4</u>:1
- <u>u8 m_u8b5</u>:1
- <u>u8 m_u8b6</u>:1
- <u>u8 m_u8b7</u>:1
- } <u>sBits</u>
- <u>u8 u_u8Byte</u>

Detailed Description

Union Byte bit by bit

Field Documentation

```
      u8 m_u8b0

      u8 m_u8b1

      u8 m_u8b2

      u8 m_u8b3

      u8 m_u8b4

      u8 m_u8b5

      u8 m_u8b6

      u8 m_u8b7

      struct {...} sBits

      u8 u_u8Byte
```

The documentation for this union was generated from the following file:

• H:/0/Workspaces/MCU Drivers/ATmega32/MCAL/SWC_BSW/<u>LBTY_int.h</u>

UCSRA_type Union Reference

Collaboration diagram for UCSRA_type:



Data Fields

- <u>u8 u_Reg</u>
- struct {
- <u>IO u8 m MPCM</u>: 1
- <u>IO u8 m U2X</u>: 1
- <u>I u8 m PE</u>: 1
- <u>I u8 m_DOR</u>: 1
- <u>I u8 m FE</u>: 1
- <u>I u8 m_UDRE</u>: 1
- <u>IO u8 m TXC</u>: 1
- <u>I u8 m_RXC</u>: 1
- } <u>sBits</u>

Detailed Description

: Type define of Union bit field of "USART Control and Status RegA"

Type: Union Unit: None

Field Documentation

__<u>l u8</u> m_DOR

Data OverRun

Frame Error

__IO u8 m_MPCM

Multi-processor Communication Mode

```
__lu8 m_PE
Parity Error

__lu8 m_RXC
USART Receive Complete

__lou8 m_TXC
USART Transmit Complete

__lou8 m_U2X
Double the USART Transmission Speed
__lu8 m_UDRE
USART Data Register Empty

struct {...} sBits

u8 u_Reg
```

The documentation for this union was generated from the following file:

USART_priv.h

UCSRB_type Union Reference

Collaboration diagram for UCSRB_type:



Data Fields

- u8 u_Reg
- struct {
- <u>IO u8 m TXB8</u>: 1
- <u>I u8 m RXB8</u>: 1
- <u>IO u8 m UCSZ2</u>: 1
- <u>IO u8 m_TXEN</u>: 1
- <u>IO u8 m RXEN</u>: 1
- <u>IO u8 m_UDRIE</u>: 1
- <u>IO u8 m TXCIE</u>: 1
- <u>IO u8 m_RXCIE</u>: 1
- } <u>sBits</u>

Detailed Description

: Type define of Union bit field of "USART Control and Status RegB"

Type: Union Unit: None

Field Documentation

__I u8 m_RXB8

Receive Data Bit 8

__IO u8 m_RXCIE

RX Complete Interrupt Enable

__IO u8 m_RXEN

Receiver Enable

Transmit Data Bit 8

IO u8 m_TXCIE

TX Complete Interrupt Enable

__<u>IO</u> u8 m_TXEN

Transmitter Enable

__<u>IO</u> <u>u8</u> m_UCSZ2

Character Size

__<u>IO</u> u8 m_UDRIE

USART Data Register Empty Interrupt Enable

struct { ... } sBits

u8 u_Reg

The documentation for this union was generated from the following file:

USART_priv.h

UCSRC_type Union Reference

: Type define of Union bit field of "USART Control and Status RegC" #include <USART_priv.h>

Collaboration diagram for UCSRC_type:



Data Fields

- <u>u8 u_Reg</u>
- struct {
- <u>IO u8 m UCPOL</u>: 1
- <u>IO u8 m_UCSZ0</u>: 1
- <u>IO u8 m UCSZ1</u>: 1
- <u>IO u8 m_USBS</u>: 1
- <u>IO u8 m UPM</u>: 2
- <u>IO u8 m_UMSEL</u>: 1
- <u>IO u8 m_URSEL</u>: 1
- } <u>sUCSRC</u>
- struct {
- <u>IO u8 m UBRR</u>: 4
- <u>IO u8</u>: 3
- <u>IO u8 m_URSEL</u>: 1
- } <u>sUBRRH</u>

Detailed Description

: Type define of Union bit field of "USART Control and Status RegC"

Type: Union Unit: None

Field Documentation

__IO u8 m_UBRR

USART Baud Rate High

```
__<mark>IO</mark> u8 m_UCPOL
    Clock Polarity
10 u8 m_UCSZ0
    Character Size 0
__<u>IO</u> <u>u8</u> m_UCSZ1
    Character Size 1
__<u>IO</u> u8 m_UMSEL
    USART Mode Select
__<u>IO</u> <u>u8</u> m_UPM
    Parity Mode
__<u>IO</u> u8 m_URSEL
    Register Select
<u>10</u> <u>u8</u> m_USBS
    Stop Bit Select
struct { ... } sUBRRH
struct { ... } sUCSRC
<u>IO u8</u>
    Reversed
u8 u_Reg
```

The documentation for this union was generated from the following file:

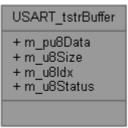
USART_priv.h

USART_tstrBuffer Struct Reference

: UART TX/RX Buffer

#include <USART_priv.h>

Collaboration diagram for USART_tstrBuffer:



Data Fields

- pu8 m_pu8Data
- <u>u8 m u8Size</u>
- <u>u8</u> <u>m_u8Idx</u>
- <u>u8</u> <u>m</u> <u>u8Status</u>

Detailed Description

: UART TX/RX Buffer

Type : Struct Unit : None

Field Documentation

pu8 m_pu8Data

Data Pointer

u8 m_u8ldx

Index of Data

u8 m_u8Size

Size of Data Bytes

u8 m_u8Status

Current Status

The documentation for this struct was generated from the following file:

USART_priv.h

USART_tstrConfiguration Struct Reference

: type define of structure for UART/USART Configuration

#include <USART int.h>

Collaboration diagram for USART_tstrConfiguration:

USART_tstrConfiguration + m_Mode + m_Polarity + m_Speed + m_BuadRate + m_Size + m_Parity + m_Stop + m_TXEN + m_RXEN + m_TXIE + m_RXIE + m_Empty

Data Fields

- <u>USART_tenumModeSelect m_Mode</u>
- <u>USART tenumClockPolarity m Polarity</u>
- USART_tenumSpeed m_Speed
- USART_tenumBuadRate m_BuadRate
- <u>USART tenumCharSize m Size</u>
- <u>USART_tenumParityMode m_Parity</u>
- <u>USART tenumStopBit m Stop</u>
- LBTY_tenuFlagStatus m_TXEN
- LBTY tenuFlagStatus m RXEN
- LBTY tenuFlagStatus m TXIE
- <u>LBTY tenuFlagStatus m RXIE</u>
- LBTY tenuFlagStatus m Empty

Detailed Description

: type define of structure for UART/USART Configuration

Type: struct **Unit**: None

Field Documentation

<u>USART_tenumBuadRate</u> m_BuadRate

BaudRate Register Value

LBTY_tenuFlagStatus m_Empty

EmptyInterrupt Enable Flag

USART tenumModeSelect m_Mode

Sync or Async Mode

USART_tenumParityMode m_Parity

Parity Bit

USART_tenumClockPolarity m_Polarity

Clock Polarity

LBTY_tenuFlagStatus m_RXEN

RX Enable Flag

LBTY_tenuFlagStatus m_RXIE

RX Interrupt Enable Flag

USART tenumCharSize m_Size

Data Register Size

USART_tenumSpeed m_Speed

Speed Gain

USART tenumStopBit m_Stop

Stop Bit

LBTY_tenuFlagStatus m_TXEN

TX Enable Flag

LBTY_tenuFlagStatus m_TXIE

TX Interrupt Enable Flag

The documentation for this struct was generated from the following file:

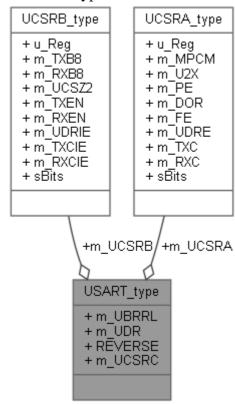
USART int.h

USART_type Struct Reference

: UART Registers

#include <USART priv.h>

Collaboration diagram for USART_type:



Data Fields

- <u>IO u8 m_UBRRL</u>
- <u>IO UCSRB type m UCSRB</u>
- <u>IO UCSRA type m UCSRA</u>
- <u>IO u8 m_UDR</u>
- <u>I u8 REVERSE</u> [19]
- __IO u8 m_UCSRC

Detailed Description

: UART Registers

Type: Struct **Unit**: None

Field Documentation

__<u>IO</u> <u>u8</u> m_UBRRL

USART Baud Rate

IO UCSRA type m_UCSRA

USART Control and Status Reg A

IO UCSRB type m_UCSRB

USART Control and Status Reg B

__IO u8 m_UCSRC

USART Control and Status Reg C

__<u>IO</u> u8 m_UDR

USART Data Reg

__I <u>u8</u> REVERSE[19]

Reversed

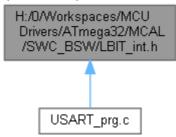
The documentation for this struct was generated from the following file:

USART_priv.h

File Documentation

H:/0/Workspaces/MCU Drivers/ATmega32/MCAL/SWC_BSW/LBIT_int.h File Reference

This graph shows which files directly or indirectly include this file:



Macros

- #define BV(bit) (1u<<(bit))
- #define \underline{SET} \underline{BIT} (REG, bit) ((REG) |= (1u<<(bit)))
- #define CLR BIT(REG, bit) ((REG) &= \sim (1u<<(bit)))
- #define TOG_BIT(REG, bit) ((REG) ^= (1u<<(bit)))
- #define \underline{SET} $\underline{BYTE}(REG, bit)$ ((REG) |= (0xFFu << (bit)))
- #define $\overline{\text{CLR}_B\text{YTE}}(\text{REG}, \text{ bit})$ ((REG) &= ~(0xFFu<<(bit)))
- #define TOG BYTE(REG, bit) ((REG) ^= (0xFFu<<(bit)))
- #define $\underline{SET MASK}(REG, MASK)$ ((REG) |= (MASK))
- #define CLR_MASK(REG, MASK) ((REG) &= ~(MASK))
- #define <u>TOG_MASK(REG, MASK)</u> ((REG) ^= (MASK))
- #define GET_MASK(REG, MASK) ((REG) & (MASK))
- #define <u>SET_REG(REG)</u> $((REG) = \sim (0u))$
- #define $\underline{CLR_REG}(REG)$ ((REG) = (0u))
- #define $\underline{TOG_REG}(REG)$ ((REG) $^= \sim (0u)$)
- #define GET BIT(REG, bit) (((REG)>>(bit)) & 0x01u)
- #define GET_NIB(REG, bit) (((REG)>>(bit)) & 0x0Fu)
- #define GET BYTE(REG, bit) (((REG)>>(bit)) & 0xFFu)
- #define ASSIGN_BIT(REG, bit, value) $((REG) = ((REG) \& \sim (0x01u << (bit)))$ | (((value) & 0x01u) << (bit)))
- #define <u>ASSIGN_NIB</u>(REG, bit, value) $((REG) = ((REG) \& \sim (0x0Fu << (bit))) | (((value) \& 0x0Fu) << (bit)))$
- #define $\underline{ASSIGN\ BYTE}(REG,\ bit,\ value)\ ((REG) = ((REG) \& \sim (0xFFu << (bit)))$ (((value) & 0xFFu)<<(bit)))
- #define <u>CON_u8Bits</u>(b7, b6, b5, b4, b3, b2, b1, b0)

(0b##b7##b6##b5##b4##b3##b2##b1##b0)

• #define <u>CON_u16Bits</u>(b15, b14, b13, b12, b11, b10, b9, b8, b7, b6, b5, b4, b3, b2, b1, b0)

(0b##b15##b14##b13##b12##b11##b10##b9##b8##b7##b6##b5##b4##b3##b2##b1##b0)

Macro Definition Documentation

```
#define BV(bit) (1u<<(bit))
#define ASSIGN_BIT( REG, bit, value) ((REG) = ((REG) & \sim(0x01u<<(bit)))
                                                                            I
(((value) & 0x01u)<<(bit)))
#define ASSIGN BYTE( REG, bit, value) ((REG) = ((REG) & ~(0xFfu<<(bit)))
                                                                            Τ
(((value) & 0xFFu)<<(bit)))
#define ASSIGN_NIB( REG, bit, value) ((REG) = ((REG) & \sim(0x0Fu<<(bit)))
                                                                            I
(((value) & 0x0Fu)<<(bit)))
#define CLR_BIT( REG, bit) ((REG) &= ~(1u<<(bit)))
#define CLR_BYTE( REG, bit) ((REG) &= ~(0xFFu<<(bit)))
#define CLR_MASK( REG, MASK) ((REG) &= ~(MASK))
#define CLR_REG( REG) ((REG) = (0u))
#define CON_u16Bits( b15, b14, b13, b12, b11, b10, b9, b8, b7, b6, b5,
b4, b3, b2, b1, b0)
       (0b##b15##b14##b13##b12##b11##b10##b9##b8##b7##b6##b5##b4##b3##b2##
b1##b0)
#define CON_u8Bits( b7, b6, b5, b4, b3, b2, b1, b0)
      (0b##b7##b6##b5##b4##b3##b2##b1##b0)
#define GET_BIT( REG, bit) (((REG)>>(bit)) & 0x01u)
#define GET_BYTE( REG, bit) (((REG)>>(bit)) & 0xFFu)
#define GET_MASK( REG, MASK) ((REG) & (MASK))
#define GET_NIB( REG, bit) (((REG)>>(bit)) & 0x0Fu)
#define SET_BIT( REG, bit) ((REG) |= (1u<<(bit)))
   Bitwise Operation
```

```
#define SET_BYTE( REG, bit) ((REG) |= (0xFFu<<(bit)))

#define SET_MASK( REG, MASK) ((REG) |= (MASK))

#define SET_REG( REG) ((REG) = ~(0u))

#define TOG_BIT( REG, bit) ((REG) ^= (1u<<(bit)))

#define TOG_BYTE( REG, bit) ((REG) ^= (0xFFu<<(bit)))

#define TOG_MASK( REG, MASK) ((REG) ^= (MASK))

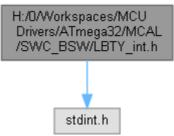
#define TOG_REG( REG) ((REG) ^= ~(0u))
```

LBIT_int.h

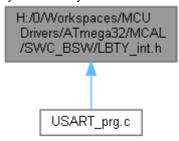
```
Go to the documentation of this file.1 /*
3 /* **********
4 /* File Name : LBIT_int.h
5 /* Author : MAAM
6 /* Version : v01
7 /* date : Mar 24, 2023
8 \ /* \ description : Bitwise Library
9 /* *********
11 /* ***********
12
13 #ifndef LBIT INT H
14 #define LBIT INT H
15
17 /* ***************** TYPE DEF/STRUCT/ENUM SECTION **************** */
19
23
24 #define _BV(bit)
                                              (1u<<(bit))
25
27 #define SET BIT(REG, bit)
                                           ((REG) \mid = (1u << (bit)))
28 #define CLR BIT(REG, bit)
                                           ((REG) &= ~(1u<<(bit)))
29 #define TOG_BIT(REG, bit)
                                           ((REG) ^= (1u<<(bit)))
30
                                          ((REG) |= (0xFFu<<(bit)))
((REG) &= ~(0xFFu<<(bit)))
31 #define SET_BYTE(REG, bit)
32 #define CLR BYTE (REG, bit)
33 #define TOG BYTE (REG, bit)
                                           ((REG) ^= (0xFFu<<(bit)))
34
                                           ((REG) |= (MASK))
35 #define SET MASK (REG, MASK)
36 #define CLR MASK (REG, MASK)
                                           ((REG) &= ~(MASK))
                                           ((REG) ^= (MASK))
((REG) & (MASK))
37 #define TOG_MASK(REG, MASK)
38 #define GET MASK(REG, MASK)
39
                                           ((REG) = \sim (0u))
((REG) = (0u))
40 #define SET REG(REG)
41 #define CLR REG(REG)
42 #define TOG REG(REG)
                                           ((REG) ^= \sim (Ou))
43
44 #define GET BIT(REG, bit)
                                           (((REG) >> (bit)) \& 0x01u)
45 #define GET NIB(REG, bit)
                                           (((REG)>>(bit)) & 0x0Fu)
46 #define GET BYTE (REG, bit)
                                           (((REG)>>(bit)) & 0xFFu)
47
48 #define ASSIGN BIT (REG, bit, value)
                                          ((REG) = ((REG) \& \sim (0x01u << (bit)))
| (((value) \& 0x01u) << (bit)))
49 #define ASSIGN NIB(REG, bit, value)
                                          ((REG) = ((REG) \& \sim (0x0Fu << (bit)))
| (((value) & 0x0Fu)<<(bit)))
50 #define ASSIGN_BYTE(REG, bit, value)
                                          ((REG) = ((REG) & \sim (0xFFu << (bit)))
| (((value) & 0xFFu) << (bit)))
51
52 /*
53 #define ASSIGN BIT(REG, bit, value)
                                           do{
54
                                            REG &= \sim (0 \times 01 u << bit);
55
                                            REG \mid= ((value & 0x01u)<<bit);
56
                                           }while(0)
57 */
58
       bits together in an u8 register
59 /*
60 #define CON_u8Bits(b7, b6, b5, b4, b3, b2, b1, b0)
61
(0b##b7##b6##b5##b4##b3##b2##b1##b0)
62
63 /* bits together in an ul6 register
64 #define CON u16Bits(b15, b14, b13, b12, b11, b10, b9, b8, b7, b6, b5, b4, b3, b2, b1,
b0) \
```

H:/0/Workspaces/MCU Drivers/ATmega32/MCAL/SWC_BSW/LBTY_int.h File Reference

#include <stdint.h>
Include dependency graph for LBTY_int.h:



This graph shows which files directly or indirectly include this file:



Data Structures

• union LBTY tuniPort8union LBTY tuniPort16

Macros

- #define __IO volatile
- #define O volatile
- #define __I volatile const
- #define <u>LBTY_u8vidNOP()</u>
- #define <u>LBTY NULL</u> ((void *) 0U)
- #define $LBTY_u8ZERO$ ((u8)0x00U)
- #define <u>LBTY u8MAX</u> ((<u>u8</u>)0xFFU)
- #define LBTY 88MAX ((88)0x7F)
- #define <u>LBTY_s8MIN</u> ((<u>s8</u>)0x80)
- #define LBTY u16ZERO ((u16)0x0000U)
- #define <u>LBTY_u16MAX</u> ((<u>u16</u>)0xFFFFU)
- #define LBTY s16MAX ((u16)0x7FFF)
- #define <u>LBTY s16MIN</u> ((<u>u16</u>)0x8000)
- #define <u>LBTY u32ZERO</u> ((<u>u32</u>)0x0000000UL)
- #define <u>LBTY u32MAX</u> ((<u>u32</u>)0xFFFFFFFUL)
- #define LBTY_s32MAX ((u32)0x7FFFFFFL)
- #define <u>LBTY s32MIN</u> ((<u>u32</u>)0x80000000L)
- #define <u>LBTY_u64ZERO</u> ((<u>u64</u>)0x000000000000000ULL)
- #define <u>LBTY u64MAX</u> ((<u>u64</u>)0xFFFFFFFFFFFFFFULL)
- #define <u>LBTY_s64MAX</u> ((<u>u64</u>)0x7FFFFFFFFFFFFFLL)
- #define <u>LBTY_s64MIN</u> ((<u>u64</u>)0x8000000000000000LL)

Typedefs

- typedef uint8_t <u>u8</u>
- typedef uint16_t <u>u16</u>
- typedef uint32_t <u>u32</u>
- typedef uint64_t <u>u64</u>
- typedef int8_t <u>s8</u>
- typedef int16_t <u>s16</u>
- typedef int32_t <u>s32</u>
- typedef int64_t <u>s64</u>
- typedef float <u>f32</u>
- typedef double <u>f64</u>
- typedef <u>u8</u> * <u>pu8</u>
- typedef <u>u16</u> * <u>pu16</u>
- typedef <u>u32</u> * <u>pu32</u>
- typedef <u>u64</u> * <u>pu64</u>
- typedef $\underline{s8} * \underline{ps8}$
- typedef <u>s16</u> * <u>ps16</u>
- typedef $\underline{s32} * \underline{ps32}$
- typedef <u>s64</u> * <u>ps64</u>

Enumerations

- enum <u>LBTY_tenuFlagStatus</u> { <u>LBTY_RESET</u> = 0, <u>LBTY_SET</u> = !LBTY_RESET }
- enum <u>LBTY tenuBoolean</u> { <u>LBTY TRUE</u> = 0x55, <u>LBTY FALSE</u> = 0xAA }
- enum <u>LBTY_tenuErrorStatus</u> { <u>LBTY_OK</u> = (u16)0, <u>LBTY_NOK</u>, <u>LBTY_NULL_POINTER</u>, <u>LBTY_INDEX_OUT_OF_RANGE</u>, <u>LBTY_NO_MASTER_CHANNEL</u>, <u>LBTY_READ_ERROR</u>, <u>LBTY_WRITE_ERROR</u>, <u>LBTY_UNDEFINED_ERROR</u>, <u>LBTY_IN_PROGRESS</u> }

Macro Definition Documentation

```
#define I volatile const
#define __IO volatile
#define O volatile
#define LBTY_NULL ((void *) 0U)
#define LBTY_s16MAX ((u16)0x7FFF)
#define LBTY_s16MIN ((u16)0x8000)
#define LBTY_s32MAX ((u32)0x7FFFFFFL)
#define LBTY_s32MIN ((<u>u32</u>)0x80000000L)
#define LBTY_s64MAX ((u64)0x7FFFFFFFFFFFLL)
#define LBTY s64MIN ((u64)0x800000000000000LL)
#define LBTY_s8MAX ((s8)0x7F)
#define LBTY_s8MIN ((s8)0x80)
#define LBTY_u16MAX ((u16)0xFFFFU)
#define LBTY_u16ZERO ((<u>u16</u>)0x0000U)
#define LBTY_u32MAX ((u32)0xFFFFFFFUL)
#define LBTY_u32ZERO ((<u>u32</u>)0x0000000UL)
#define LBTY_u64MAX ((u64)0xFFFFFFFFFFFFFULL)
#define LBTY_u64ZERO ((<u>u64</u>)0x00000000000000ULL)
#define LBTY_u8MAX ((u8)0xFFU)
#define LBTY_u8vidNOP()
#define LBTY_u8ZERO ((u8)0x00U)
   Data Types Limitation
```

Typedef Documentation

typedef float f32

Standard Real Decimal number

```
typedef double f64
typedef s16* ps16
typedef s32* ps32
typedef <u>s64</u>* <u>ps64</u>
typedef s8* ps8
   Standard Pointer to Signed Byte/Word/Long_Word
typedef u16* pu16
typedef u32* pu32
typedef u64* pu64
typedef u8* pu8
   Standard Pointer to Unsigned Byte/Word/Long_Word
typedef int16_t s16
typedef int32_t s32
typedef int64_t s64
typedef int8_t s8
   Standard Signed Byte/Word/Long_Word
typedef uint16_t u16
typedef uint32_t u32
typedef uint64_t u64
typedef uint8_t u8
   Data Types New Definitions Standard Unsigned Byte/Word/Long_Word
```

Enumeration Type Documentation

enum <u>LBTY_tenuBoolean</u>

Boolean type

Enumerator:

```
LBTY_TRUE

LBTY_FALSE

96 {
97  LBTY TRUE = 0x55,
98  LBTY FALSE = 0xAA
99 } LBTY tenuBoolean;
```

enum <u>LBTY_tenuErrorStatus</u>

Error Return type

Enumerator:

```
LBTY_OK
       LBTY_NOK
  LBTY_NULL_PO
            INTER
  LBTY_INDEX_O
   UT_OF_RANGE
   LBTY_NO_MAS
   TER_CHANNEL
  LBTY_READ_ER
              ROR
  LBTY_WRITE_E
             RROR
  LBTY_UNDEFIN
       ED_ERROR
  LBTY_IN_PROG
             RESS
102
103 LBTY OK = (u16)0,
104 LBTY NOK,
105 LBTY NULL POINTER,
106 LBTY INDEX OUT OF RANGE,
107 LBTY NO MASTER CHANNEL,
107 LBTY NO MASTER CHANNEL,
108 LBTY READ ERROR,
      LBTY WRITE ERROR,
LBTY UNDEFINED ERROR,
109
110
111 LBTY IN PROGRESS
                                /* Error is not available, wait for availability */
112 } LBTY tenuErrorStatus;
```

enum <u>LBTY_tenuFlagStatus</u>

Flag Status type

Enumerator:

```
LBTY_RESET

LBTY_SET

90
91
LBTY_RESET = 0,
92
LBTY_SET = !LBTY_RESET
93 } LBTY_tenuflagStatus;
```

LBTY int.h

```
Go to the documentation of this file.1 /*
3 /* ***********
4 /* File Name : LBTY_int.h
5 /* Author : MAAM
6 /* Version : v01
7 /* date : Mar 23, 2023
8 /* description : Basic Library
9 /* **********
11 /* ************
12
13 #ifndef _LBTY_INT_H_
14 #define _LBTY_INT_H_
15
16 #include <stdint.h>
17
21
               <u>u8</u>;
<u>u16</u>;
<u>u32</u>;
<u>u64</u>;
24 typedef uint8 t
25 typedef uint1\overline{6} t
26 typedef uint32 t
27 typedef uint64_t
28
               <u>sb</u>
<u>s16;</u>
<u>s32;</u>
<u>s64</u>
30 typedef int8 t
31 typedef int16_t
32 typedef int32 t
33 typedef int64_t
34
36 typedef float
37 typedef double
                 <u>f64</u>;
38
40 typedef u8*
              pu16;
pu32;
pu64;
41 typedef u16*
42 typedef \overline{u32}*
43 typedef <u>u64</u>*
44
46 typedef s8*
                ps8 ;
47 typedef <u>s16</u>*
              <u>ps16;</u>
<u>ps32;</u>
<u>ps64</u>;
48 typedef \frac{1}{832}*
49 typedef <u>s64</u>*
50
54
60
61 #define LBTY u8vidNOP()
62 #define LBTY NULL
                    ((void *) OU)
63
65 #define LBTY_u8ZERO ((u8)0x00U)
66 #define LBTY_u8MAX ((u8)0xFFU)
67 #define LBTY_s8MAX ((s8)0x7F)
68 #define LBTY_s8MIN ((s8)0x80)
69
70 #define LBTY_u16ZERO ((u16)0x0000U)
71 #define LBTY_u16MAX ((u16)0xFFFFU)
72 #define LBTY_s16MAX ((u16)0x7FFF)
73 #define LBTY_s16MIN ((u16)0x8000)
74
75 #define LBTY_u32ZERO ((u32)0x00000000UL)
76 #define LBTY_u32MAX ((u32)0xFFFFFFFFUL)
77 #define LBTY_s32MAX ((u32)0x7FFFFFFFFL)
77 #define LBTY_s32MAX
78 #define LBTY_s32MIN
                     ((u32)0x7FFFFFFFL)
                  ((u32)0x7FFFFFFFL)
((u32)0x80000000L)
79
```

```
80 #define LBTY u64ZERO ((u64)0x000000000000000ULL)
81 #define LBTY_u64MAX ((u64)0xFFFFFFFFFFFFFFFLLL)

82 #define LBTY_s64MAX ((u64)0x7FFFFFFFFFFFFLL)

83 #define LBTY_s64MIN ((u64)0x8000000000000000LL)
84
87 /* **************
88
90 typedef enum {
    LBTY RESET = 0,
LBTY SET = !LBTY RESET
91
92
93 } LBTY tenuFlagStatus;
94
96 typedef enum {
97 LBTY TRUE = 0x55,
98 \overline{LBTY FALSE} = 0xAA
99 } LBTY_tenuBoolean;
100
102 typedef enum {
     \underline{LBTY OK} = (\underline{u16}) 0,
103
104 <u>LBTY NOK</u>,
105 LBTY NULL POINTER,
106 LBTY INDEX OUT OF RANGE,
107 LBTY NO MASTER CHANNEL,
108 LBTY READ ERROR,
      LBTY READ ERROR,
109 LBTY WRITE ERROR,
110 LBTY UNDEFINED ERROR,
111 LBTY IN PROGRESS
                              /* Error is not available, wait for availability */
112 } LBTY tenuErrorStatus;
113
116 /* ****************
117
119 typedef union {
120 struct {
                       // LSB
      <u>u8</u> <u>m u8b0</u> :1;
121
      <u>u8</u> <u>m u8b1</u> :1;
<u>u8</u> <u>m u8b2</u> :1;
122
123
124
       <u>u8</u> <u>m u8b3</u> :1;
<u>u8</u> <u>m u8b4</u> :1;
125
126
       u8 m u8b5 :1;

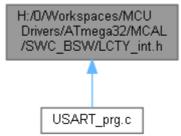
    u8
    m
    u8b6
    :1;

    u8
    m
    u8b7
    :1;

127
128
                         // MSB
129 } sBits;
130 <u>u8 u u8Byte</u>;
131 } LBTY tuniPort8;
132
133 typedef union {
134 struct {
    <u>u8</u> <u>m</u> u8b0
       <u>u8</u> <u>m u8b0</u> :1;
u8 <u>m u8b1</u> :1;
135
                           // LSB
136
                  :1;
      u8 m u8b2
u8 m u8b3
137
138
                   :1;
139
     u8 m u8b4 :1;
       <u>u8</u> <u>m u8b5</u>
<u>u8</u> <u>m u8b6</u>
140
                   :1;
                  :1;
141
142
       <u>u8</u> <u>m u8b7</u>
                  :1;
143
       u8 m u8b8
                  :1;
144
       u8 m u8b9 :1;
145
      <u>u8</u> <u>m_u8b10</u> :1;
       u8 m u8b11 :1;
146
<u>u8</u> <u>m u8b15</u> :1;
                          // MSB
150
151 } sBits;
152 struct {
    u8 m u8low;
u8 m u8high;
153
154
155 } sBytes;
156
      u16 u u16Word;
157 } LBTY tuniPort16;
158
159 /* ***************************
```

H:/0/Workspaces/MCU Drivers/ATmega32/MCAL/SWC_BSW/LCTY_int.h File Reference

This graph shows which files directly or indirectly include this file:



Macros

- #define LCTY_PROGMEM __attribute__((__progmem__))
- #define <u>LCTY PURE</u> __attribute__((__pure__))
- #define <u>LCTY_INLINE</u> __attribute__((always_inline)) static inline
- #define <u>LCTY INTERRUPT</u> __attribute__((interrupt))
- #define <u>CTY_PACKED</u> __attribute__((__packed__))
- #define LCTY_CONST __attribute__((__const__))
- #define <u>LCTY_DPAGE</u> __attribute__((dp))
- #define <u>LCTY_NODPAGE</u> __attribute__((nodp))
- #define <u>LCTY_SECTION</u>(section) __attribute__((section(# section)))
- #define LCTY_ASM(cmd) __asm__ _volatile__ (# cmd ::)

Macro Definition Documentation

```
#define CTY_PACKED __attribute__((__packed__))

#define LCTY_ASM( cmd) __asm____volatile__ ( # cmd ::)

#define LCTY_CONST __attribute__((_const__))

#define LCTY_DPAGE __attribute__((dp))

#define LCTY_INLINE __attribute__((always_inline)) static inline

#define LCTY_INTERRUPT __attribute__((interrupt))

#define LCTY_NODPAGE __attribute__((nodp))

#define LCTY_PROGMEM __attribute__((_progmem__))

#define LCTY_PURE __attribute__((_pure__))

#define LCTY_SECTION( section) __attribute__((section( # section)))
```

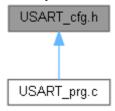
LCTY_int.h

```
Go to the documentation of this file.1 /*
3 /* ***********
4 /* File Name : LCTY_int.h
5 /* Author : MAAM
6 /* Version : v00
7 /* date : Apr 26, 2023
8 \ /* \ description : Compiler Library
9 /* ***********
11 /* ************
12
13 #ifndef LCTY INT H
14 #define LCTY INT H
15
17 /* **************** TYPE DEF/STRUCT/ENUM SECTION **************** */
19
21 /* ***************** MACRO/DEFINE SECTION ***********************************
23
24 /* prog memory attribute */
25 #define LCTY PROGMEM
                    attribute (( progmem ))
26
27 /* pure attribute */
28 #define LCTY PURE
                    __attribute__((__pure__))
29
30 /* Abstraction for inlining */
31 //#define LCTY_INLINE
                    static inline
32 #define LCTY INLINE
                    __attribute__((always_inline)) static inline
33
34 /* define function as interrupt handler */
                    __attribute__((interrupt))
35 #define LCTY INTERRUPT
36
37 /* Memory packed to pass Memory padding */
38 #define CTY PACKED
                   __attribute__((__packed ))
39
40 /* Const attribute */
41 #define LCTY CONST
                    __attribute__((__const__))
42
43 /* place variable in direct page */
44 #define LCTY_DPAGE
                     attribute ((dp))
45
46 /* do not place variable in direct page */
47 #define LCTY_NODPAGE __attribute__((nodp))
48
49 /* Sections */
50 #define LCTY SECTION(section)
                   attribute ((section( # section)))
51
52 /* Abstraction for assembly command */
53 # define LCTY_ASM(cmd) __asm____volatile__ ( # cmd ::)
54
55 /* ****************
58
62
66
67
68 #endif /* LCTY INT H */
```

main.c File Reference

USART_cfg.h File Reference

This graph shows which files directly or indirectly include this file:



Macros

- #define USART_OPERATION_MODE USART_Asynchronous
- #define USART OPERATION POLARITY USART Transmit Rising Receive Falling
- #define <u>USART OPERATION SPEED</u> <u>USART Speed x1</u>
- #define <u>USART OPERATION MULTI PROCESSOR</u> <u>LBTY RESET</u>
- #define <u>USART OPERATION FREQ</u> F_CPU
- #define <u>USART_BUAD_RATE_INIT_USART_BuadRate_9600</u>
- #define <u>USART CHAR SIZE INIT</u> <u>USART 8 bit</u>
- #define <u>USART_PARITY_BIT_INIT_USART_Parity_Even</u>
- #define <u>USART STOP BIT INIT</u> <u>USART Stop 1 bit</u>
- #define <u>USART_TRANSMIT_INIT_LBTY_SET</u>
- #define <u>USART_RECEIVE_INIT_LBTY_SET</u>
- #define <u>USART_TRANSMIT_COMPLETE_INT_LBTY_RESET_</u>
- #define USART_RECEIVE_COMPLETE_INT LBTY_RESET
- #define <u>USART_DATA_REG_EMPTY_INT_LBTY_RESET_</u>

Macro Definition Documentation

```
#define USART_BUAD_RATE_INIT USART BuadRate 9600

#define USART_CHAR_SIZE_INIT USART 8 bit

#define USART_DATA_REG_EMPTY_INT LBTY_RESET

#define USART_OPERATION_FREQ F_CPU

#define USART_OPERATION_MODE USART Asynchronous

#define USART_OPERATION_MULTI_PROCESSOR LBTY_RESET

#define USART_OPERATION_POLARITY USART Transmit Rising Receive Falling

#define USART_OPERATION_SPEED USART_Speed_x1

#define USART_PARITY_BIT_INIT USART Parity Even

#define USART_RECEIVE_COMPLETE_INT LBTY_RESET

#define USART_RECEIVE_INIT USART_Stop_1_bit

#define USART_TRANSMIT_COMPLETE_INT LBTY_RESET

#define USART_TRANSMIT_COMPLETE_INT LBTY_RESET

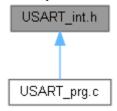
#define USART_TRANSMIT_INIT LBTY_SET
```

USART_cfg.h

```
Go to the documentation of this file.1 /*
****************
2 /* ************************* FILE DEFINITION SECTION ************************
3 /* ***********
4 /* File Name : USART_cfg.h
11
12 #ifndef USART_CFG_H_
13 #define USART CFG H
14
18
22
#define USART_OPERATION_MODE USART_Asynchronous
#define USART_OPERATION_POLARITY USART_Transmit_Rising_Receive_Falling
#define USART_OPERATION_SPEED USART_Speed_x1
#define USART_OPERATION_MULTI_PROCESSOR LBTY_RESET
#define USART_OPERATION_FREQ F_CPU
28
29 #define USART_BUAD_RATE_INIT
                  USART_BuadRate_9600
                  USART_8_bit
30 #define USART_CHAR_SIZE_INIT
31
 #define USART PARITY BIT INIT
                   USART Parity Even
32 #define USART STOP BIT INIT
                  USART Stop 1 bit
33
34 #define USART_TRANSMIT_INIT
                  LBTY SET
35 #define USART RECEIVE INIT
36
37 #define USART TRANSMIT COMPLETE INT
                  LBTY RESET
                 LBTY RESET
38 #define USART_RECEIVE_COMPLETE_INT
39 #define USART_DATA_REG_EMPTY_INT
40
44
47 /* *************************
48
52
53
54 #endif /* USART CFG H */
```

USART int.h File Reference

This graph shows which files directly or indirectly include this file:



Data Structures

struct USART tstrConfiguration: type define of structure for UART/USART Configuration

Enumerations

- enum <u>USART_tenumModeSelect</u> { <u>USART_Asynchronous</u> = (u8)0u, <u>USART_Synchronous</u> }
- enum <u>USART tenumSpeed</u> { <u>USART Speed x1</u> = (u8)0u, <u>USART Speed x2</u> }
- enum USART_tenumClockPolarity { USART_Transmit_Rising_Receive_Falling = (u8)0u, USART_Transmit_Falling_Receive_Rising }
- enum <u>USART tenumCharSize</u> { <u>USART 5 bit</u> = (u8)0u, <u>USART 6 bit</u>, <u>USART 7 bit</u>, USART_8_bit, USART_9_bit = (u8)7u }
- enum USART tenumParityMode { USART Parity Disable = (u8)0u, USART Parity Reserved, USART Parity Even, USART Parity Odd }
- enum <u>USART_tenumStopBit</u> { <u>USART_Stop_1_bit</u> = (u8)0u, <u>USART_Stop_2_bit</u> }
- enum <u>USART tenumBuadRate</u> { <u>USART BuadRate 1200</u> = 1200u, <u>USART BuadRate 2400</u> = 2400u, <u>USART BuadRate 4800</u> = 4800u, <u>USART BuadRate 9600</u> = 9600u, USART_BuadRate_14400 = 14400u, USART_BuadRate_19200 = 19200u, <u>USART BuadRate 28800</u> = 28800u, <u>USART BuadRate 38400</u> = 38400u,
 - <u>USART_BuadRate_57600</u> = 57600u, <u>USART_BuadRate_76600</u> = 76600u,

 - <u>USART_BuadRate_115200</u> = 115200u, <u>USART_BuadRate_230400</u> = 230400u,
 - <u>USART BuadRate 250000</u> = 250000u, <u>USART BuadRate 500000</u> = 500000u,
 - <u>USART BuadRate 1000000</u> = 1000000u }

Functions

- void USART vidSetConfig (USART tstrConfiguration const *const pstrConfig)
- void USART vidResetConfig (USART tstrConfiguration *const pstrConfig)
- void UART vidInit (void)
- void USART vidTransmitterEnable (void)
- void <u>USART_vidTransmitterDisable</u> (void)
- void USART vidReceiverEnable (void)
- void USART vidReceiverDisable (void)
- <u>LBTY_tenuErrorStatus_USART_u8SetBuadRate_(USART_tenumBuadRate_u32BuadRate)</u>
- LBTY tenuErrorStatus USART u8SetCharSize (USART tenumCharSize u8CharSize)
- LBTY_tenuErrorStatus USART_u8SetParityMode (USART_tenumParityMode u8Parity)
- LBTY tenuErrorStatus USART u8SetStopBit (USART tenumStopBit u8Stop)
- u8 USART u8Available (void)
- void USART vidFlush (void)
- <u>LBTY tenuErrorStatus USART u8SetTransmit</u> (void *pvidTransmit)
- <u>LBTY_tenuErrorStatus_USART_u8GetTransmit</u> (void *pvidTransmit)
- void <u>USART vidSetChar</u> (<u>u8</u> u8Char)
- void <u>USART_vidGetChar</u> (u8 *pu8Char)
- void USART vidSetStrLine (u8 *pu8Transmit)

- void <u>USART_vidSetStr</u> (<u>u8</u> *pu8Transmit)
- void <u>USART vidGetStr</u> (<u>u8</u> *pu8Receive)
- <u>LBTY tenuErrorStatus USART u8SendBuffer (u8</u> *pu8Data, <u>u8</u> u8Size)
- <u>LBTY tenuErrorStatus USART u8ReceiveBuffer (u8 *pu8Data, u8 u8Size)</u>
- void <u>USART_vidEnableReceiveCompleteINT</u> (void)
- void <u>USART vidEnableTransmitCompleteINT</u> (void)
- void <u>USART vidEnableDataRegEmptyINT</u> (void)
- void <u>USART vidDisableReceiveCompleteINT</u> (void)
- void USART vidDisableTransmitCompleteINT (void)
- void <u>USART_vidDisableDataRegEmptyINT</u> (void)
- void <u>USART vidSetCallBack Empty</u> (void(*pCallBack)(void))
- void <u>USART_vidSetCallBack_TX</u> (void(*pCallBack)(void))
- void <u>USART_vidSetCallBack_RX</u> (void(*pCallBack)(void))

Enumeration Type Documentation

enum <u>USART_tenumBuadRate</u>

Enumerator:

```
USART_BuadRate
              1200
  USART BuadRate
              2400
  USART_BuadRate
              4800
  USART_BuadRate
              9600
  USART BuadRate
             14400
  USART_BuadRate
            _19200
  USART_BuadRate
            28800
  USART_BuadRate
            _38400
  USART_BuadRate
             57600
  USART_BuadRate
             76600
  USART BuadRate
            115200
  USART_BuadRate
           230400
  USART_BuadRate
            250000
  USART_BuadRate
            500000
  USART_BuadRate
          _1000000
54
55
       USART BuadRate 1200
                               = 1200u,
56
       USART BuadRate 2400
                               = 2400u,
       USART BuadRate 4800
USART BuadRate 9600
57
                               = 4800u,
                               = 9600u,
58
59
       USART BuadRate 14400
                               = 14400u,
       USART BuadRate 19200
                               = 19200u,
       USART BuadRate 28800
                               = 28800u,
61
62
       USART BuadRate 38400
                               = 38400u
```

```
USART BuadRate 57600
                                      = 57600u,
63
        USART BuadRate 76600 = 76600u,
USART BuadRate 115200 = 115200u,
                                       = 76600u,
64
65
                                      = 230400u,
66
         USART BuadRate 230400
        USART BuadRate 250000 = 250000u,
USART BuadRate 500000 = 500000u,
67
68
         <u>USART BuadRate 1000000</u> = 1000000u,
69
70 }USART tenumBuadRate;
```

enum <u>USART_tenumCharSize</u>

Enumerator:

enum <u>USART_tenumClockPolarity</u>

Enumerator:

```
USART_Transmit
_Rising_Receive_
Falling

USART_Transmit
_Falling_Receive_
Rising

29

30
    USART Transmit Rising Receive Falling = (u8) 0u,
31
    USART Transmit Falling Receive Rising,
32
}USART tenumClockPolarity;
```

enum <u>USART_tenumModeSelect</u>

Enumerator:

```
USART_Asynchro
nous
USART_Synchron
ous

19 {
20    USART_Asynchronous = (u8) 0u,
21    USART_Synchronous,
22 }USART_tenumModeSelect;
```

enum <u>USART_tenumParityMode</u>

Enumerator:

USART_Parity_Di	
sable	
USART_Parity_R	
eserved	
USART_Parity_E	
ven	

enum <u>USART_tenumSpeed</u>

Enumerator:

enum <u>USART_tenumStopBit</u>

Enumerator:

```
USART_Stop_1_b
it
USART_Stop_2_b
it

49

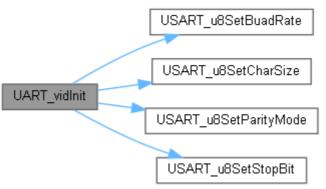
50
USART Stop 1 bit = (u8) 0u,
51
USART Stop 2 bit,
52 }USART tenumStopBit;
```

Function Documentation

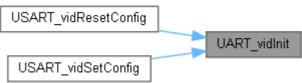
void UART_vidInit (void)

```
107
108
          strucsrc.sucsrc.m ursel = Usart ucsrc reg;
strucsrc.sucsrc.m umsel = strusart config GLB.m Mode;
109
110
           strUCSRC.sUCSRC.m UCPOL = strUSART Config GLB.m Polarity;
111
112
           S USART->m UCSRC = strUCSRC.u Reg;
113
          S USART->m_UCSRA.sBits.m_MPCM = USART OPERATION MULTI PROCESSOR;
S USART->m_UCSRA.sBits.m_U2X = strUSART Config GLB.m_Speed;
114
115
116
          USART u8SetBuadRate
USART u8SetCharSize (strUSART Config GLB.m BuadRate);
117
118
119
           USART u8SetParityMode(strUSART Config GLB.m Parity);
120
          USART u8SetStopBit
                                      (strUSART Config GLB.m Stop);
121
          strucsrc.sucsrc.m ursel = usart ucsrc reg;
if(strucsrc.sucsrc.m ursel == usart synchronous){
122
123
                GPIO_u8SetPinDirection(USART XCK PORT, USART XCK PIN, PIN_OUTPUT);
124
125
                                                             , <u>USART TX PIN</u> , PIN OUTPUT);
126
          GPIO u8SetPinDirection(USART PORT
127
          GPIO_u8SetPinDirection(<u>USART_XCK_PORT</u>, <u>USART_RX_PIN</u> , PIN_INPUT );
128
          S USART->m_UCSRB.sBits.m_UDRIE = strUSART Config GLB.m_Empty;
S USART->m_UCSRB.sBits.m_TXCIE = strUSART Config GLB.m_TXIE;
S USART->m_UCSRB.sBits.m_RXCIE = strUSART Config GLB.m_RXIE;
129
130
131
132
           S_USART->m_UCSRB.sBits.m_TXEN = strUSART_Config_GLB.m_TXEN;
133
134
           S USART->m UCSRB.sBits.m RXEN = strUSART Config GLB.m RXEN;
135 }
```

Here is the call graph for this function:



Here is the caller graph for this function:



u8 USART_u8Available (void)

```
252 {
253 return <u>S_USART</u>->m_UCSRA.sBits.m_RXC;
254 }
```

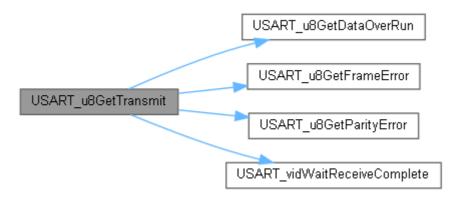
Here is the caller graph for this function:



<u>LBTY_tenuErrorStatus</u> USART_u8GetTransmit (void * pvidTransmit)

```
277
278
       LBTY_tenuErrorStatus u8RetErrorState = LBTY_OK;
279
280
       if(pvidTransmit == LBTY NULL) {
           u8RetErrorState = LBTY NULL POINTER;
281
282
       }else{
283
          USART vidWaitReceiveComplete();
284
           if(USART_u8GetFrameError() || USART_u8GetDataOverRun() ||
USART u8GetParityError()){
              if(strUSART Config GLB.m Size == USART 9 bit){
285
                  *((u16*)pvidTransmit) = LBTY u16MAX;
286
287
288
                  *((u8*)pvidTransmit) = LBTY u8MAX;
289
290
              u8RetErrorState = LBTY NOK;
291
           }else{
292
              if(strUSART Config GLB.m Size == USART 9 bit){
293
294
              }else{
295
                  *((u8*)pvidTransmit) = S USART->m UDR;
296
297
298
299
       return u8RetErrorState;
300 }
```

Here is the call graph for this function:



LBTY_tenuErrorStatus USART_u8ReceiveBuffer (u8 * pu8Data, u8 u8Size)

```
352
        LBTY tenuErrorStatus u8RetErrorState = LBTY OK;
353
        if(pu8Data == LBTY NULL){
354
355
             u8RetErrorState = LBTY NULL POINTER;
356
         }else{
357
            if(strRX GLB.m u8Status == RX IDLE) {
                 strRX GLB.m pu8Data = pu8Data;
358
                 strRX GLB.m u8Size = u8Size;
strRX GLB.m u8Idx = LBTY u8ZERO;
359
360
                 strRX GLB.m u8Idx
361
                 strRX GLB.m u8Status = RX BUSY;
362
363
                 USART vidEnableReceiveCompleteINT();
364
             }else{
365
                 u8RetErrorState = LBTY NOK;
366
367
368
369
        return u8RetErrorState;
370 }
```

Here is the call graph for this function:

LBTY_tenuErrorStatus USART_u8SendBuffer (u8 * pu8Data, u8 u8Size)

```
328
329
         LBTY tenuErrorStatus u8RetErrorState = LBTY OK;
330
         if(pu8Data == LBTY NULL) {
331
              u8RetErrorState = LBTY NULL POINTER;
332
333
         }else{
334
             if(strTX GLB.m u8Status == TX IDLE){
                  strTX GLB.m pu8Data
strTX GLB.m u8Size
strTX GLB.m u8Idx = pu8Data;
strTX GLB.m u8Idx = LBTY u8ZERO;
335
336
337
338
                  strTX GLB.m u8Status = TX BUSY;
339
340
                  if(S USART->m_UCSRA.sBits.m_UDRE){
341
                       S USART->m_UDR = strTX GLB.m pu8Data[strTX GLB.m u8Idx++];
342
343
                  USART vidEnableDataRegEmptyINT();
344
              }else{
                  u8RetErrorState = <u>LBTY_NOK</u>;
345
346
347
348
349
         return u8RetErrorState;
350 }
```

Here is the call graph for this function:

USART_u8SendBuffer USART_vidEnableDataRegEmptyINT

<u>LBTY_tenuErrorStatus</u> USART_u8SetBuadRate (<u>USART_tenumBuadRate</u> u32BuadRate)

```
150
151
        LBTY tenuErrorStatus u8RetErrorState = LBTY OK;
152
        u16 u16UBRR = LBTY u16ZERO;
153
154
        switch(strUCSRC.sUCSRC.m UMSEL) {
155
            case USART Asynchronous:
156
               switch(S USART->m UCSRA.sBits.m U2X) {
157
                   case USART Speed x1:
158
                        u16UBRR = (u16) (F CPU / (16.0f * (u32)u32BuadRate)) - 1;
159
                        break;
                    case USART Speed x2:
160
161
                        u16UBRR = (u16) (F CPU / (8.0f * (u32)u32BuadRate)) - 1;
162
                        break;
163
                    default:
164
                        u8RetErrorState = LBTY NOK;
165
166
                break;
            case USART Synchronous:
167
168
               ul6UBRR = (u16) (USART OPERATION FREQ / (2.0f * (u32))u32BuadRate)) -
1;
169
170
            default:
171
               u8RetErrorState = LBTY NOK;
172
173
        if(u8RetErrorState == LBTY OK) {
174
            strUSART Config GLB.m BuadRate = u32BuadRate;
175
176
            strUCSRC.sUBRRH.m URSEL = USART UBRRH Reg;
177
            strUCSRC.sUBRRH.m UBRR = GET NIB(u16UBRR, 8);
178
            S USART->m UCSRC = strUCSRC.u Reg;
179
180
            S USART->m UBRRL = GET BYTE (u16UBRR, 0);
181
182
        return u8RetErrorState;
183 }
```

Here is the caller graph for this function:



LBTY_tenuErrorStatus USART_u8SetCharSize (USART_tenumCharSize u8CharSize)

```
185
186
         LBTY tenuErrorStatus u8RetErrorState = LBTY OK;
187
         switch(u8CharSize){
188
189
            case <u>USART 5 bit</u>:
190
              case USART 6 bit:
             case USART 7 bit:
191
              case USART 8 bit:
case USART 9 bit:
192
193
194
                  strUCSRC.sUCSRC.m URSEL = USART UCSRC Reg;
                   strUCSRC.sUCSRC.m UCSZ0 = GET BIT(u8CharSize, USART UCSZ0 BIT);
strUCSRC.sUCSRC.m UCSZ1 = GET BIT(u8CharSize, USART UCSZ1 BIT);
195
196
                   S USART->m UCSRB.sBits.m UCSZ2 = GET BIT (u8CharSize,
197
USART UCSZ2 BIT);
198
199
                   S USART->m UCSRC = strUCSRC.u Reg;
200
                   strUSART Config GLB.m Size = u8CharSize;
201
                  break;
202
              default:
203
                  u8RetErrorState = LBTY NOK;
204
         }
205
206
         return u8RetErrorState;
207 }
```

Here is the caller graph for this function:

<u>LBTY_tenuErrorStatus</u> USART_u8SetParityMode (<u>USART_tenumParityMode</u> u8Parity)

```
210
         LBTY tenuErrorStatus u8RetErrorState = LBTY OK;
211
212
        switch (u8Parity) {
            case <u>USART Parity Disable</u>: case <u>USART Parity Even</u>:
213
214
215
            case USART Parity Odd:
216
                  strucsrc.sucsrc.m ursel = usart ucsrc reg;
                  strucsrc.sucsrc.m upm = strusart Config GLB.m Parity = u8Parity;
217
218
                  S USART->m_UCSRC = strUCSRC.u Reg;
219
                  break:
220
             default: u8RetErrorState = LBTY NOK;
221
        }
222
         return u8RetErrorState;
223
224 }
```

Here is the caller graph for this function:



LBTY_tenuErrorStatus USART_u8SetStopBit (USART_tenumStopBit u8Stop)

```
227
          LBTY tenuErrorStatus u8RetErrorState = LBTY OK;
228
          switch (u8Stop) {
229
              case <u>USART Stop 1 bit:</u> case <u>USART Stop 2 bit:</u>
230
231
                    strucsrc.sucsrc.m ursel = Usart ucsrc reg;
strucsrc.sucsrc.m usbs = strusart config Glb.m Stop = u8Stop;
232
233
234
                    S USART->m UCSRC = strUCSRC.u Reg;
235
                    break:
236
               default: u8RetErrorState = LBTY NOK;
237
238
          return u8RetErrorState;
239
240 }
```

Here is the caller graph for this function:



<u>LBTY_tenuErrorStatus</u> USART_u8SetTransmit (void * pvidTransmit)

```
263
264
        LBTY tenuErrorStatus u8RetErrorState = LBTY OK;
265
266
        if(pvidTransmit == LBTY NULL) {
267
            u8RetErrorState = LBTY NULL POINTER;
268
        }else{
269
            USART vidWaitDataRegEmpty();
270
            S USART->m_UDR = *((u8*)pvidTransmit);
271
            if(strUSART Config GLB.m Size == USART 9 bit){
272
                S USART->m UCSRB.sBits.m TXB8 = GET BIT(*((u16*)pvidTransmit), 8);
273
274
275
        return u8RetErrorState;
```

```
276 }
Here is the call graph for this function:
             USART_u8SetTransmit
                                              USART vidWaitDataRegEmpty
void USART vidDisableDataRegEmptyINT (void )
   380 {S USART->m UCSRB.sBits.m UDRIE = LBTY RESET;}
void USART_vidDisableReceiveCompleteINT (void )
   378 {S USART->m UCSRB.sBits.m RXCIE = LBTY RESET;}
void USART_vidDisableTransmitCompleteINT (void )
   379 {S USART->m UCSRB.sBits.m TXCIE = LBTY RESET;}
void USART_vidEnableDataRegEmptyINT (void )
   376 {S USART->m_UCSRB.sBits.m_UDRIE = LBTY SET;}
Here is the caller graph for this function:
                                          USART_vidEnableDataRegEmptyINT
           USART_u8SendBuffer
void USART_vidEnableReceiveCompleteINT (void )
   374 {S USART->m UCSRB.sBits.m RXCIE = LBTY SET;}
Here is the caller graph for this function:
         USART_u8ReceiveBuffer
                                           USART_vidEnableReceiveCompleteINT
void USART vidEnableTransmitCompleteINT (void )
   375 {S USART->m UCSRB.sBits.m TXCIE = LBTY SET;}
void USART_vidFlush (void )
   256
   257
           u8 dummy;
   258
           while (USART u8Available()) {
   259
               dummy = S USART -> m UDR;
   260
   261 }
Here is the call graph for this function:
                     USART_vidFlush
                                                USART_u8Available
void USART_vidGetChar (u8 * pu8Char)
   306
   307
            USART vidWaitReceiveComplete();
            *pu8Char = S USART->m UDR;
   308
   309 }
Here is the call graph for this function:
              USART vidGetChar
                                           USART_vidWaitReceiveComplete
Here is the caller graph for this function:
                     USART_vidGetStr
                                                 USART vidGetChar
void USART vidGetStr (u8 * pu8Receive)
   321
   322
   323
                USART vidGetChar (pu8Receive);
   324
            }while(*pu8Receive++ != '\r');
   325
            *pu8Receive = '\0';
   326 }
```

Here is the call graph for this function:

```
USART_vidGetStr USART_vidGetChar USART_vidWaitReceiveComplete
```

void USART_vidReceiverDisable (void)

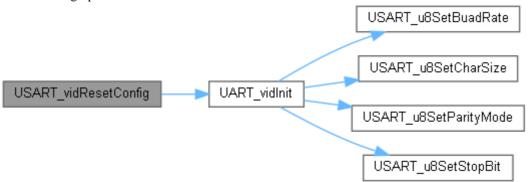
void USART_vidReceiverEnable (void)

```
143
144
S USART->m_UCSRB.sBits.m_RXEN = strusART Config GLB.m_RXEN = LBTY SET;
145 }
```

void USART_vidResetConfig (<u>USART_tstrConfiguration</u> *const_pstrConfig)

```
88
       strUSART Config GLB.m Mode
                                           = USART OPERATION MODE;
89
       strUSART Config GLB.m Polarity
                                          = USART OPERATION POLARITY;
90
       strUSART Config GLB.m Speed
                                            USART OPERATION SPEED;
91
       strUSART Config GLB.m BuadRate
                                          = USART BUAD RATE INIT;
                                           = USART CHAR SIZE INIT;
92
       strUSART Config GLB.m Size
                                          = USART PARITY BIT
93
       strUSART Config GLB.m Parity
94
       strUSART Config GLB.m Stop
                                           = USART STOP BIT INIT;
                                          = USART TRANSMIT INIT;
95
       strUSART Config GLB.m TXEN
96
       strUSART Config GLB.m RXEN
                                          = USART RECEIVE INIT;
                                          = USART TRANSMIT COMPLETE INT;
97
       strUSART Config GLB.m TXIE
       strUSART Config GLB.m RXIE
strUSART Config GLB.m Empty
                                          = USART RECEIVE COMPLETE INT;
= USART DATA REG EMPTY INT;
98
99
100
101
        if(pstrConfig != LBTY NULL) {
102
             *pstrConfig = strUSART Config GLB;
103
104
        UART vidInit();
105 }
```

Here is the call graph for this function:

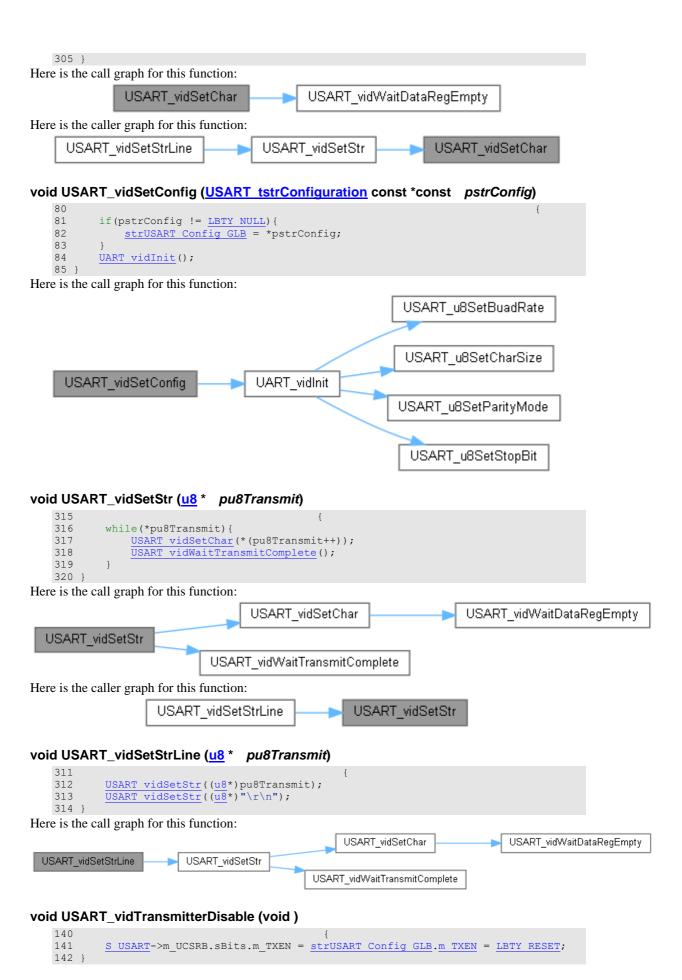


void USART vidSetCallBack Empty (void(*)(void) pCallBack)

void USART_vidSetCallBack_RX (void(*)(void) pCallBack)

void USART_vidSetCallBack_TX (void(*)(void) pCallBack)

void USART_vidSetChar (u8 u8Char)



void USART_vidTransmitterEnable (void)

```
137
138
S USART->m UCSRB.sBits.m TXEN = strUSART Config GLB.m TXEN = LBTY SET;
139 }
```

USART_int.h

```
Go to the documentation of this file.1 /*
3 /* **********
11
12 #ifndef USART_INT_H_
13 #define USART INT H
14
18
19 typedef enum{
   <u>USART Asynchronous</u> = (<u>u8</u>)0u,
<u>USART Synchronous</u>,
20
21
22 } USART tenumModeSelect;
23
24 typedef enum{
   \underline{\text{USART Speed x1}} = (u8)0u,
25
26
     USART Speed x2,
27 }USART tenumSpeed;
28
29 typedef enum{
30 <u>USART Transmit Rising Receive Falling</u> = (u8)0u,
31
     USART Transmit Falling Receive Rising,
32 }USART tenumClockPolarity;
33
34 typedef enum{
35
    USART 5 bit = (u8)0u,
     USART 6 bit,
USART 7 bit,
36
37
    <u>USART 8 bit</u>,

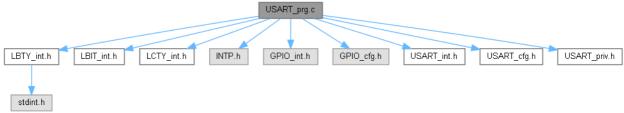
<u>USART 9 bit</u> = (<u>u8</u>)7u,
38
39
40 }USART tenumCharSize;
41
42 typedef enum{
43
   <u>USART Parity Disable</u> = (u8)0u,
     USART Parity Reserved,
USART Parity Even,
44
45
46
     USART Parity Odd,
47 } USART tenumParityMode;
48
49 typedef enum{
   <u>USART_Stop_1_bit</u> = (<u>u8</u>)0u,
50
     USART Stop 2 bit,
51
52 }USART tenumStopBit;
53
54 typedef enum{
55
    USART_BuadRate_1200
                       = 120011.
56
     USART BuadRate 2400
                       = 2400u,
57
     USART BuadRate 4800
                        = 4800u,
     USART BuadRate 9600
58
                        = 9600u,
    USART BuadRate 14400
USART BuadRate 19200
59
                        = 1440011
                        = 19200u,
60
                        = 28800u,
61
    USART BuadRate 28800
     USART BuadRate 38400
USART BuadRate 57600
                        = 38400u,
62
                        = 57600u,
63
                        = 76600u,
    USART BuadRate 76600
64
                       = 115200u,
65
     USART BuadRate 115200
     USART BuadRate 230400
                        = 230400u,
66
     USART BuadRate 250000
USART BuadRate 500000
67
                        = 250000u,
                        = 500000u,
68
     <u>USART BuadRate 1000000</u> = 1000000u,
69
70 }USART tenumBuadRate;
```

```
73
76 typedef struct{
77 /* HW Config */
78
   USART tenumModeSelect
                      m Mode;
     USART tenumClockPolarity m Polarity;
79
    USART tenumSpeed m Speed;
80
m BuadRate;
                     m Size;
83
     USART_tenumCharSize
     USART tenumParityMode m Parity;
USART tenumStopBit m Stop;
84
   USART tenumStopBit
85
86 /* TX/RX Status */
   LBTY tenuFlagStatus
                       m TXEN:
87
                     m TXEN;
m_RXEN;
88
     LBTY tenuFlagStatus
89 /* TX/RX Interrupt */
   LBTY tenuFlagStatus
90
                        m TXIE;
                      m RXIE;
m Empty;
91
     LBTY tenuFlagStatus
92
     LBTY tenuFlagStatus
93 }USART tstrConfiguration;
94
95 /*
99 //#define USART_vidSetChar USART_vidSetTransmit
100 //#define USART_vidGetChar USART_vidGetTransmi
100 //#define USART vidGetChar
                          USART vidGetTransmit
101
105
109
113
114 extern void USART vidSetConfig(USART tstrConfiguration const* const pstrConfig);
115 extern void USART vidResetConfig(USART tstrConfiguration* const pstrConfig);
116
117 extern void UART vidInit(void);
118
119 extern void USART vidTransmitterEnable(void);
120 extern void USART vidTransmitterDisable (void);
121 extern void USART vidReceiverEnable (void);
122 extern void <a href="USART vidReceiverDisable">USART vidReceiverDisable</a> (void);
123
124 extern LBTY tenuErrorStatus USART u8SetBuadRate(USART tenumBuadRate u32BuadRate);
125 extern LBTY tenuErrorStatus USART u8SetCharSize(USART tenumCharSize u8CharSize);
126 extern LBTY tenuErrorStatus USART u8SetParityMode (USART tenumParityMode u8Parity);
127 extern LBTY tenuErrorStatus USART u8SetStopBit(USART tenumStopBit u8Stop);
128
129
131 extern u8 USART u8Available (void);
132 extern void USART vidFlush(void);
133
134 extern <u>LBTY tenuErrorStatus</u> <u>USART u8SetTransmit</u>(void* pvidTransmit);
135 extern LBTY tenuErrorStatus USART u8GetTransmit (void* pvidTransmit);
136
137 extern void <a href="USART_vidSetChar">USART_vidSetChar</a> (u8 u8Char);
138 extern void USART vidGetChar(u8* pu8Char);
139
140 extern void USART vidSetStrLine(u8* pu8Transmit);
141 extern void <u>USART vidSetStr</u>(<u>u8</u>* pu8Transmit);
142 extern void <u>USART vidGetStr</u>(u8* pu8Receive);
144 extern LBTY tenuErrorStatus USART u8SendBuffer(u8* pu8Data, u8 u8Size); 145 extern LBTY tenuErrorStatus USART u8ReceiveBuffer(u8* pu8Data, u8 u8Size);
146
```

USART_prg.c File Reference

```
#include "LBTY_int.h"
#include "LBIT_int.h"
#include "LCTY_int.h"
#include "INTP.h"
#include "GPIO_int.h"
#include "GPIO_cfg.h"
#include "USART_int.h"
#include "USART_cfg.h"
#include "USART_priv.h"
```

Include dependency graph for USART_prg.c:



Functions

- static void <u>voidCallBack</u> (void)
- void <u>USART_vidSetConfig</u> (<u>USART_tstrConfiguration</u> const *const pstrConfig)
- void <u>USART vidResetConfig</u> (<u>USART tstrConfiguration</u> *const pstrConfig)
- void UART vidInit (void)
- void <u>USART vidTransmitterEnable</u> (void)
- void <u>USART_vidTransmitterDisable</u> (void)
- void <u>USART_vidReceiverEnable</u> (void)
- void USART vidReceiverDisable (void)
- <u>LBTY_tenuErrorStatus_USART_u8SetBuadRate_(USART_tenumBuadRate_u32BuadRate)</u>
- <u>LBTY_tenuErrorStatus_USART_u8SetCharSize</u> (<u>USART_tenumCharSize_u8CharSize</u>)
- LBTY tenuErrorStatus USART_u8SetParityMode (USART_tenumParityMode u8Parity)
- LBTY tenuErrorStatus USART u8SetStopBit (USART tenumStopBit u8Stop)
- LCTY INLINE void USART vidWaitDataRegEmpty (void)
- LCTY_INLINE void USART_vidWaitTransmitComplete (void)
- LCTY INLINE void USART vidWaitReceiveComplete (void)
- <u>LCTY_INLINE u8 USART_u8GetFrameError</u> (void)
- LCTY INLINE u8 USART u8GetDataOverRun (void)
- <u>LCTY INLINE u8 USART u8GetParityError</u> (void)
- <u>u8 USART_u8Available</u> (void)
- void <u>USART vidFlush</u> (void)
- LBTY tenuErrorStatus USART u8SetTransmit (void *pvidTransmit)
- LBTY tenuErrorStatus USART u8GetTransmit (void *pvidTransmit)
- void <u>USART vidSetChar</u> (<u>u8</u> u8Char)
- void <u>USART_vidGetChar</u> (<u>u8</u> *pu8Char)
- void <u>USART vidSetStrLine</u> (<u>u8</u> *pu8Transmit)
- void USART_vidSetStr (u8 *pu8Transmit)
- void <u>USART vidGetStr</u> (<u>u8</u> *pu8Receive)
- LBTY_tenuErrorStatus USART_u8SendBuffer (u8 *pu8Data, u8 u8Size)
- LBTY tenuErrorStatus USART u8ReceiveBuffer (u8 *pu8Data, u8 u8Size)
- void <u>USART vidEnableReceiveCompleteINT</u> (void)
- void USART_vidEnableTransmitCompleteINT (void)
- void USART vidEnableDataRegEmptyINT (void)
- void <u>USART_vidDisableReceiveCompleteINT</u> (void)

- void USART_vidDisableTransmitCompleteINT (void)
- void <u>USART vidDisableDataRegEmptyINT</u> (void)
- void <u>USART vidSetCallBack Empty</u> (void(*pCallBack)(void))
- void <u>USART vidSetCallBack TX</u> (void(*pCallBack)(void))
- void USART_vidSetCallBack_RX (void(*pCallBack)(void))
- ISR (USART RXC vect)
- <u>ISR</u> (USART_UDRE_vect)
- <u>ISR</u> (USART_TXC_vect)

Variables

- static volatile UCSRC type strUCSRC
- static void(* <u>pvidfunc_Empty_CallBak</u>)(void) = <u>voidCallBack</u>
- static void(* <u>pvidfunc Tx CallBak</u>)(void) = <u>voidCallBack</u>
- static void(* pvidfunc_Rx_CallBak)(void) = _voidCallBack
- static <u>USART tstrBuffer strTX GLB</u>
- static USART_tstrBuffer strRX_GLB
- static volatile <u>USART_tstrConfiguration_strUSART_Config_GLB</u>

Function Documentation

static void voidCallBack (void)[static]

```
43 { asm("NOP");}
```

ISR (USART_RXC_vect)

```
392
393
        if((S USART->m UCSRA.sBits.m RXC) && (strRX GLB.m u8Idx <
strRX GLB.m u8Size) && (strRX GLB.m u8Status == RX BUSY)){
            strRX GLB.m pu8Data[strRX GLB.m u8Idx++] = S USART->m UDR;
394
395
        }else{
396
           strRX GLB.m u8Status = RX IDLE;
397
           //USART vidDisableReceiveCompleteINT();
398
           pvidfunc_Rx_CallBak();
399
400 }
```

ISR (USART TXC vect)

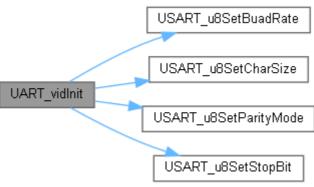
ISR (USART_UDRE_vect)

```
401
402
        if((S USART->m UCSRA.sBits.m UDRE) && (strTX GLB.m u8Idx <
strTX GLB.m u8Size) && (strTX GLB.m u8Status == TX BUSY)) {
403
            S USART->m UDR = strTX GLB.m pu8Data[strTX GLB.m u8Idx++];
404
        }else{
405
        strTX GLB.m u8Status = TX IDLE;
406
            //USART vidDisableDataRegEmptyINT();
407
            pvidfunc Empty CallBak();
408
        }
409 }
```

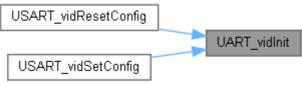
void UART_vidInit (void)

```
113
114
        S USART->m_UCSRA.sBits.m_MPCM = USART OPERATION MULTI PROCESSOR;
115
         S USART->m UCSRA.sBits.m U2X = strUSART Config GLB.m Speed;
116
        117
118
        USART u8SetParityMode(strUSART Config GLB.m Parity);
119
120
        USART u8SetStopBit
                                (strUSART Config GLB.m Stop);
121
        strUCSRC.sUCSRC.m URSEL = USART UCSRC Reg;
if(strUCSRC.sUCSRC.m UMSEL == USART Synchronous){
122
123
124
             GPIO_u8SetPinDirection(USART_XCK_PORT, USART_XCK_PIN, PIN_OUTPUT);
125
126
        GPIO u8SetPinDirection(USART PORT
                                                , <u>USART TX PIN</u> , PIN_OUTPUT);
        GPIO_u8SetPinDirection(<u>USART XCK PORT</u>, <u>USART RX PIN</u> , PIN INPUT );
127
128
129
        S USART->m UCSRB.sBits.m UDRIE = strUSART Config GLB.m Empty;
        S_USART->m_UCSRB.sBits.m_TXCIE = strUSART_Config_GLB.m_TXIE;
S_USART->m_UCSRB.sBits.m_RXCIE = strUSART_Config_GLB.m_RXIE;
130
131
132
133
         <u>S USART->m_UCSRB.sBits.m_TXEN = strUSART Config GLB.m_TXEN;</u>
134
        S USART->m UCSRB.sBits.m RXEN = strUSART Config GLB.m RXEN;
135 }
```

Here is the call graph for this function:



Here is the caller graph for this function:



u8 USART_u8Available (void)

```
252 {
253    return <u>S USART</u>->m_UCSRA.sBits.m_RXC;
254 }
```

Here is the caller graph for this function:



LCTY INLINE u8 USART_u8GetDataOverRun (void)

```
249 {return <u>S USART->m_UCSRA.sBits.m_DOR;</u>}
```

Here is the caller graph for this function:



<u>LCTY_INLINE</u> <u>u8</u> USART_u8GetFrameError (void)

```
248 {return <u>S_USART</u>->m_UCSRA.sBits.m_FE;}
```

Here is the caller graph for this function:



LCTY_INLINE u8 USART_u8GetParityError (void)

250 {return S USART->m UCSRA.sBits.m PE;}

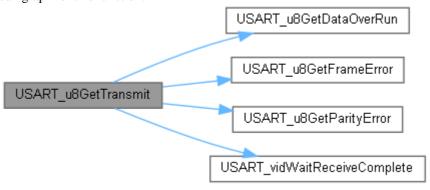
Here is the caller graph for this function:

```
USART_u8GetTransmit USART_u8GetParityError
```

LBTY tenuErrorStatus USART_u8GetTransmit (void * pvidTransmit)

```
277
278
        LBTY tenuErrorStatus u8RetErrorState = LBTY OK;
279
280
        if(pvidTransmit == LBTY_NULL) {
281
            u8RetErrorState = LBTY NULL POINTER;
282
        }else{
            USART vidWaitReceiveComplete();
283
            if(USART u8GetFrameError() || USART u8GetDataOverRun() ||
284
USART u8GetParityError()){
                 if(strUSART Config GLB.m Size == USART 9 bit){
285
286
                     *((u16*)pvidTransmit) = LBTY u16MAX;
287
                 }else{
288
                     *((\underline{u8}^*)pvidTransmit) = \underline{LBTY} u8MAX;
289
290
                u8RetErrorState = LBTY NOK;
291
            }else{
292
                if(strUSART Config GLB.m Size == USART 9 bit){
                    *((u16))pvidTransmit) = (u16)S USART->m_UDR |
293
(u16) (S USART->m UCSRB.sBits.m TXB8 << 8);
                }else{
295
                     *((u8*)pvidTransmit) = S USART->m UDR;
296
297
298
299
        return u8RetErrorState;
300 }
```

Here is the call graph for this function:



LBTY tenuErrorStatus USART_u8ReceiveBuffer (u8 * pu8Data, u8 u8Size)

```
351
352
         LBTY tenuErrorStatus u8RetErrorState = LBTY OK;
353
         if(pu8Data == LBTY_NULL){
354
355
             u8RetErrorState = LBTY NULL POINTER;
356
         }else{
357
             if(strRX GLB.m u8Status == RX IDLE) {
358
                  strRX GLB.m pu8Data = pu8Data;
                  strRX GLB.m u8Size = u8Size;

strRX GLB.m u8Size = u8Size;

EV CIR m u8Idx = LBTY u8ZERO;
359
360
361
                  strRX GLB.m u8Status = RX BUSY;
362
363
                  USART vidEnableReceiveCompleteINT();
364
             }else{
365
                  u8RetErrorState = LBTY NOK;
366
367
         }
368
         return u8RetErrorState;
369
370 }
```

Here is the call graph for this function:

```
USART_u8ReceiveBuffer USART_vidEnableReceiveCompleteINT
```

LBTY_tenuErrorStatus USART_u8SendBuffer (u8 * pu8Data, u8 u8Size)

```
329
        LBTY tenuErrorStatus u8RetErrorState = LBTY OK;
330
331
        if(pu8Data == LBTY NULL) {
332
           u8RetErrorState = LBTY NULL POINTER;
333
        }else{
            if(strTX GLB.m u8Status == TX IDLE) {
334
335
                strTX GLB.m pu8Data = pu8Data;
336
                strTX GLB.m u8Size
                                     = u8Size;
337
                                     = LBTY u8ZERO;
                strTX GLB.m u8Idx
                strTX GLB.m u8Status = TX BUSY;
338
339
340
                if(S USART->m UCSRA.sBits.m UDRE){
341
                    S USART->m UDR = strTX GLB.m pu8Data[strTX GLB.m u8Idx++];
342
343
                USART vidEnableDataRegEmptyINT();
344
            }else{
345
                u8RetErrorState = LBTY NOK;
346
347
        }
348
349
        return u8RetErrorState;
350 }
```

Here is the call graph for this function:

USART_vidEnableDataRegEmptyINT

<u>LBTY_tenuErrorStatus</u> USART_u8SetBuadRate (<u>USART_tenumBuadRate</u> u32BuadRate)

```
150
151
        LBTY tenuErrorStatus u8RetErrorState = LBTY OK;
        u16 u16UBRR = LBTY u16ZERO;
152
153
154
        switch (strucsrc.sucsrc.m umsel) {
            case USART Asynchronous:
155
156
                switch (S USART->m UCSRA.sBits.m U2X) {
                    case USART Speed x1:
157
                         u16UBRR = (u16) (F_CPU / (16.0f * (u32)u32BuadRate)) - 1;
158
159
                         break;
160
                     case USART Speed x2:
                        u16UBRR = (<u>u16</u>) (F_CPU / (8.0f * (<u>u32</u>) u32BuadRate)) - 1;
161
162
                         break;
163
                     default:
164
                         u8RetErrorState = LBTY NOK;
165
                 }
166
                break;
167
            case <u>USART Synchronous</u>:
168
                u16UBRR = (u16) (USART OPERATION FREQ / (2.0f * (u32)u32BuadRate)) -
1;
169
                break;
170
            default:
171
                u8RetErrorState = LBTY_NOK;
172
        if(u8RetErrorState == LBTY OK) {
173
174
            strUSART Config GLB.m BuadRate = u32BuadRate;
175
176
            strUCSRC.sUBRRH.m URSEL = USART UBRRH Reg;
177
            strUCSRC.sUBRRH.m UBRR = GET NIB(u16UBRR, 8);
178
179
            S USART->m UCSRC = strUCSRC.u Reg;
            S USART->m UBRRL = GET BYTE (u16UBRR, 0);
180
181
182
        return u8RetErrorState;
183 }
```

Here is the caller graph for this function:

```
USART_vidResetConfig

UART_vidInit

USART_u8SetBuadRate

USART_vidSetConfig
```

<u>LBTY_tenuErrorStatus</u> USART_u8SetCharSize (<u>USART_tenumCharSize</u> u8CharSize)

```
186
         LBTY tenuErrorStatus u8RetErrorState = LBTY OK;
187
188
         switch (u8CharSize) {
            case <u>USART 5 bit</u>:
case <u>USART 6 bit</u>:
189
190
191
             case <u>USART 7 bit</u>:
192
             case USART 8 bit:
193
             case USART 9 bit:
                  strUCSRC.sUCSRC.m URSEL = USART UCSRC Reg;
strUCSRC.sUCSRC.m UCSZ0 = GET BIT(u8CharSize, USART UCSZ0 BIT);
194
195
                  strUCSRC.sUCSRC.m UCSZ1 = GET BIT (u8CharSize, USART UCSZ1 BIT);
196
197
                   S USART->m UCSRB.sBits.m UCSZ2 = GET BIT(u8CharSize,
USART UCSZ2 BIT);
198
                  S USART->m_UCSRC = strUCSRC.u Reg;
199
200
                  strUSART Config GLB.m Size = u8CharSize;
201
                  break;
202
              default:
203
                  u8RetErrorState = LBTY NOK;
204
         }
205
206
         return u8RetErrorState;
207 }
```

Here is the caller graph for this function:



<u>LBTY_tenuErrorStatus</u> USART_u8SetParityMode (<u>USART_tenumParityMode</u> u8Parity)

```
210
        <u>LBTY tenuErrorStatus</u> u8RetErrorState = <u>LBTY OK</u>;
211
212
         switch(u8Parity){
         case <u>USART Parity Disable</u>:
case <u>USART Parity Even</u>:
213
214
215
             case USART Parity Odd:
216
                 strucsrc.sucsrc.m ursel = usart ucsrc reg;
217
                  strUCSRC.sUCSRC.m UPM = strUSART Config GLB.m Parity = u8Parity;
218
                  S USART->m UCSRC = strUCSRC.u Reg;
219
                  break:
220
             default: u8RetErrorState = LBTY NOK;
221
222
         return u8RetErrorState;
223
```

Here is the caller graph for this function:



LBTY_tenuErrorStatus USART_u8SetStopBit (USART_tenumStopBit u8Stop)

```
226 {
227     <u>LBTY tenuErrorStatus</u> u8RetErrorState = <u>LBTY OK;</u>
228
229     switch(u8Stop) {
```

```
230
             case USART Stop 1 bit:
231
             case <u>USART Stop 2 bit</u>:
                   strucsrc.sucsrc.m ursel = usart ucsrc req;
strucsrc.sucsrc.m usbs = strusart config GLB.m Stop = u8Stop;
232
233
234
                   S_USART->m_UCSRC = strUCSRC.u_Reg;
235
                   break:
236
              default: u8RetErrorState = LBTY NOK;
237
238
239
         return u8RetErrorState;
240 }
```

Here is the caller graph for this function:



<u>LBTY_tenuErrorStatus</u> USART_u8SetTransmit (void * pvidTransmit)

```
LBTY tenuErrorStatus u8RetErrorState = LBTY OK;
264
265
266
       if(pvidTransmit == LBTY NULL) {
267
            u8RetErrorState = LBTY NULL POINTER;
        }else{
268
            USART vidWaitDataRegEmpty();
269
270
            S USART->m UDR = *((u8*)pvidTransmit);
271
            if(strUSART Config GLB.m Size == USART 9 bit){
272
                S USART->m UCSRB.sBits.m TXB8 = GET BIT(*((u16*)pvidTransmit), 8);
273
274
275
        return u8RetErrorState;
276 }
```

Here is the call graph for this function:

void USART_vidDisableDataRegEmptyINT (void)

```
380 {<u>S_USART</u>->m_UCSRB.sBits.m_UDRIE = <u>LBTY_RESET;</u>}
```

void USART_vidDisableReceiveCompleteINT (void)

```
378 {S USART->m UCSRB.sBits.m RXCIE = LBTY RESET;}
```

void USART_vidDisableTransmitCompleteINT (void)

```
379 {<u>S_USART</u>->m_UCSRB.sBits.m_TXCIE = <u>LBTY_RESET</u>;}
```

void USART_vidEnableDataRegEmptyINT (void)

```
376 {S USART->m UCSRB.sBits.m UDRIE = LBTY SET;}
```

Here is the caller graph for this function:

void USART_vidEnableReceiveCompleteINT (void)

```
374 {S USART->m UCSRB.sBits.m_RXCIE = LBTY SET;}
```

Here is the caller graph for this function:

void USART_vidEnableTransmitCompleteINT (void)

```
375 {S_USART->m_UCSRB.sBits.m_TXCIE = LBTY_SET;}
```

void USART_vidFlush (void)

```
256 {
```

```
257 <u>u8</u> dummy;

258 while(<u>USART u8Available</u>()) {

259 dummy = <u>S USART</u>->m_UDR;

260 }

261 }
```

Here is the call graph for this function:

```
USART_vidFlush USART_u8Available
```

void USART_vidGetChar (u8 * pu8Char)

Here is the call graph for this function:



Here is the caller graph for this function:

void USART_vidGetStr (u8 * pu8Receive)

Here is the call graph for this function:

void USART_vidReceiverDisable (void)

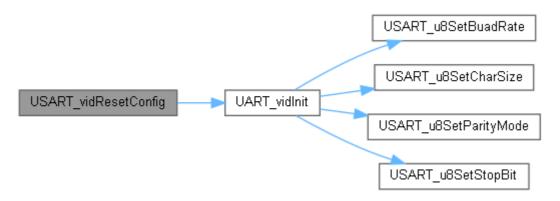
void USART_vidReceiverEnable (void)

```
143
144
S USART->m_UCSRB.sBits.m_RXEN = strUSART Config GLB.m_RXEN = LBTY SET;
145 }
```

void USART_vidResetConfig (<u>USART_tstrConfiguration</u> *const pstrConfig)

```
88
       strUSART Config GLB.m Mode
                                        = USART OPERATION MODE;
       strUSART Config GLB.m Polarity
                                       = USART OPERATION POLARITY;
89
90
       strUSART Config GLB.m Speed
                                       = USART OPERATION SPEED;
91
       strUSART Config GLB.m BuadRate = USART BUAD RATE INIT;
92
       strUSART Config GLB.m Size
                                       = USART CHAR SIZE INIT;
93
                                       = USART PARITY BIT INIT;
       strUSART Config GLB.m Parity
94
       strUSART Config GLB.m Stop
                                       = USART
                                                STOP BIT INIT;
95
       strUSART Config GLB.m TXEN
                                       = USART TRANSMIT INIT;
96
                                       = USART RECEIVE INIT;
       strUSART Config GLB.m RXEN
97
       strUSART Config GLB.m TXIE
                                       = USART TRANSMIT COMPLETE INT;
98
       strUSART Config GLB.m RXIE
                                       = USART RECEIVE COMPLETE INT;
99
                                       = USART DATA REG EMPTY INT;
       strUSART Config GLB.m Empty
100
101
        if(pstrConfig != LBTY NULL) {
102
            *pstrConfig = strUSART Config GLB;
103
104
        UART vidInit();
105 }
```

Here is the call graph for this function:



void USART_vidSetCallBack_Empty (void(*)(void) pCallBack)

void USART_vidSetCallBack_RX (void(*)(void) pCallBack)

void USART_vidSetCallBack_TX (void(*)(void) pCallBack)

void USART_vidSetChar (u8 u8Char)

Here is the call graph for this function:



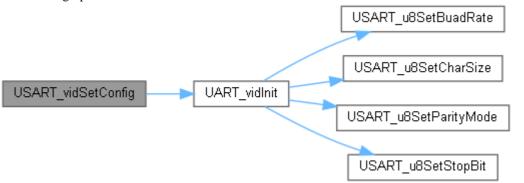
Here is the caller graph for this function:



void USART_vidSetConfig (<u>USART_tstrConfiguration</u> const *const pstrConfig)

```
80
81    if(pstrConfig != <u>LBTY NULL</u>) {
82         strUSART Config GLB = *pstrConfig;
83    }
84         <u>UART vidInit</u>();
85 }
```

Here is the call graph for this function:



USART vidWaitTransmitComplete();

Here is the call graph for this function:

318

319 320 }



Here is the caller graph for this function:



void USART_vidSetStrLine (u8 * pu8Transmit)

Here is the call graph for this function:



void USART_vidTransmitterDisable (void)

void USART_vidTransmitterEnable (void)

LCTY_INLINE void USART_vidWaitDataRegEmpty (void)

```
244 {while(!(S USART->m UCSRA.sBits.m UDRE));}
```

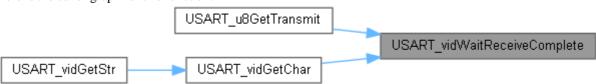
Here is the caller graph for this function:



LCTY_INLINE void USART_vidWaitReceiveComplete (void)

```
246 {while(!(S USART->m UCSRA.sBits.m RXC));}
```

Here is the caller graph for this function:



LCTY_INLINE void USART_vidWaitTransmitComplete (void)

```
245 {while(!(<u>S_USART</u>->m_UCSRA.sBits.m_TXC));}
```

Here is the caller graph for this function:



Variable Documentation

```
void(* pvidfunc_Empty_CallBak) (void) (void ) = _voidCallBack[static]
void(* pvidfunc_Rx_CallBak) (void) (void ) = _voidCallBack[static]
void(* pvidfunc_Tx_CallBak) (void) (void ) = _voidCallBack[static]
```

USART_tstrBuffer strRX_GLB[static]

```
Initial value:= {
    .m_pu8Data = LBTY NULL,
    .m_u8Size = LBTY u8ZERO,
    .m_u8Idx = LBTY u8ZERO,
    .m_u8Status = RX IDLE,
}
```

USART_tstrBuffer strTX_GLB[static]

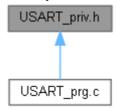
```
Initial value:= {
    .m_pu8Data = LBTY NULL,
    .m_u8Size = LBTY u8ZERO,
    .m_u8Idx = LBTY u8ZERO,
    .m_u8Status = TX IDLE,
}
```

volatile UCSRC_type strUCSRC[static]

volatile <u>USART_tstrConfiguration</u> strUSART_Config_GLB[static]

USART_priv.h File Reference

This graph shows which files directly or indirectly include this file:



Data Structures

struct <u>USART_tstrBuffer</u>: *UART TX/RX Buffer*

union UCSRC type: Type define of Union bit field of "USART Control and Status RegC" union UCSRB type: Type define of Union bit field of "USART Control and Status RegB" union UCSRA_type: Type define of Union bit field of "USART Control and Status RegA" struct **USART_type**: UART Registers

Macros

- #define S USART ((USART type* const)0x29U)
- #define <u>UBRRL</u> (*(volatile <u>u8</u>* const)0x29U)
- #define UCSRB (*(volatile u8* const)0x2AU)
- #define <u>UCSRA</u> (*(volatile <u>u8</u>* const)0x2BU)
- #define <u>UDR</u> (*(volatile <u>u8</u>* const)0x2CU)
- #define <u>UCSRC</u> (*(volatile <u>u8</u>* const)0x40U)
- #define <u>UBRRH</u> (*(volatile <u>u8</u>* const)0x40U)
- #define USART_UCSZ0_BIT Ou
- #define USART UCSZ1 BIT 1u
- #define USART UCSZ2 BIT 2u
- #define USART XCK PORT B
- #define <u>USART_XCK_PIN</u> GPIO_USART_XCK
- #define <u>USART_PORT</u> D
- #define <u>USART_RX_PIN_</u> GPIO_UART_RX
- #define <u>USART_TX_PIN</u> GPIO_UART_TX

Enumerations

- enum <u>USART tstrStatus</u> { <u>TX IDLE</u>, <u>TX BUSY</u>, <u>RX IDLE</u>, <u>RX BUSY</u> } : Type define of TX/RX Status
- enum <u>USART tenumRegSelect</u> { <u>USART UBRRH Reg</u> = (u8)0u, <u>USART UCSRC Reg</u> } : Type define of UCSRC Register Selection

Macro Definition Documentation

```
#define S_USART ((USART_type* const)0x29U)
   USART
#define UBRRH (*(volatile u8* const)0x40U)
#define UBRRL (*(volatile u8* const)0x29U)
#define UCSRA (*(volatile <u>u8</u>* const)0x2BU)
#define UCSRB (*(volatile u8* const)0x2AU)
#define UCSRC (*(volatile u8* const)0x40U)
#define UDR (*(volatile u8* const)0x2CU)
#define USART_PORT D
#define USART_RX_PIN GPIO_UART_RX
#define USART_TX_PIN GPIO_UART_TX
#define USART_UCSZ0_BIT 0u
#define USART_UCSZ1_BIT 1u
#define USART_UCSZ2_BIT 2u
#define USART_XCK_PIN GPIO_USART_XCK
#define USART_XCK_PORT B
```

Enumeration Type Documentation

enum <u>USART_tenumRegSelect</u>

: Type define of UCSRC Register Selection

Type: Enum **Unit**: None

Enumerator:

enum <u>USART_tstrStatus</u>

: Type define of TX/RX Status

Type: Enum **Unit**: None

Enumerator:

USART_priv.h

```
Go to the documentation of this file.1 /*
3 /* ***********
4 /* File Name : USART_priv.h
11
12 #ifndef USART_PRIV_H_
13 #define USART PRIV H
14
18
21 typedef enum{
  TX IDLE,
22
23
24
  RX IDLE,
25 RX BUSY,
26 }USART tstrStatus;
27
30 typedef struct{
   pu8 m pu8Data;
31

        u8
        m
        u8Size;

        u8
        m
        u8Idx;

        u8
        m
        u8Status;

32
33
34
35 }USART tstrBuffer;
36
38
41 typedef enum{
  <u>USART UBRRH Reg</u> = (<u>u8</u>)0u,
42
    USART UCSRC Reg,
43
44 } USART_tenumRegSelect;
45
47
50 typedef union{
   u8 u Reg;
51
52
    struct {
    _____IO u8 m UCPOL: 1;
53
       IO U8 M UCSZO: 1;
IO U8 M UCSZO: 1;
IO U8 M UCSZI: 1;
IO U8 M USBS: 1;
54
55
56
       IO u8 m UPM
57
                 : 2;
       10 u8 m UMSEL: 1;
10 u8 m URSEL: 1;
58
59
59 <u>IO</u>
60 }sUCSRC;
61 struct {
62
    <u>IO u8</u> : 3;
<u>IO u8 m_URSEL: 1;</u>
63
64
   }sUBRRH;
65
66 }UCSRC type;
67
69
72 typedef union{
73
   u8 u Reg;
74
    struct {
75
       <u>IO</u> <u>u8</u> <u>m TXB8</u> : 1;
       <u>I</u> <u>u8</u> <u>m RXB8</u> : 1;
76
       10 u8 m UCSZ2: 1;
10 u8 m TXEN : 1;
77
78
       <u>IO u8 m RXEN</u> : 1;
79
80
           u8 m UDRIE: 1;
       <u>IO u8 m TXCIE</u>: 1;
81
82
       ____IO u8 m_RXCIE: 1;
```

```
83 }sBits;
84 } UCSRB type;
8.5
86 /***********
87
90 typedef union{
91 <u>u8</u> <u>u</u> Reg;
92
    struct {
      93
      IO US M UZX : 1;

I US M PE : 1;

I US M DOR : 1;
94
95
96
      I u8 m FE : 1;
I u8 m UDRE: 1;
97
98
99 <u>TO u8 m TXC</u>: 1;
100 <u>I u8 m RXC</u>: 1;
101 }sBits;
102 } UCSRA type;
103
105
108 typedef struct{
109 <u>IO U8 m UBRRL;</u>
110 <u>IO UCSRB type m UCSRB;</u>
111
    _____IO UCSRA type m UCSRA;
116
119 /* *************
120
122 #define S_USART ((USART_type* const)0x29U)
123 #define UBRRL (*(volatile u8* const)0x29
124 #define UCSRR (*(volatile u8* const)0x28
               (*(volatile u8* const)0x29U)
(*(volatile u8* const)0x2AU)
124 #define UCSRB
               (*(volatile u8* const)0x2BU)
125 #define UCSRA
126 #define UDR
               (*(volatile u8* const)0x2CU)
127
               (*(volatile u8* const)0x40U)
(*(volatile u8* const)0x40U)
128 #define UCSRC
129 #define UBRRH
130
132
133 #define USART_UCSZ0_BIT
134 #define USART_UCSZ1_BIT
                     0 u
                      1u
135 #define USART UCSZ2 BIT
136
137 #define USART_XCK_PORT
138 #define USART_XCK_PIN
                     GPIO USART XCK
139
140 #define USART PORT
141 #define USART_RX_PIN
142 #define USART_TX_PIN
                     GPIO_UART_RX
GPIO UART TX
143
147
150 /* **********************
151
155
```