## ECE 57000 Assignment 7 Exercise

Your Name:

Objective: Build different transformer components and test them.

```
import numpy as np
import string
import time
import torch
import pdb
import math
import torch.nn as nn
from torch.autograd import Variable
from torch.nn import functional as F
np.random.seed(124)
```

NOTE: In this assignment, we will use the convention of having the batch dimension first so tensors will have shapes of (N, L, D) where N is the batch dimension, L is the max sequence length, and D is the feature dimension.

The default in PyTorch is for the sequence dimension to be first, i.e., (L, N, D) but most functions in PyTorch can be altered to make the batch dimension to be first by using batch\_first=True, see for example the arguments for torch.nn.LSTM.

# Exercise 1: Positional Encoder (20 points)

The positional encoder is a simple function that takes a 3D tensor of shape (batch\_size, sequence\_length, encoding\_size), i.e., (N, L, D), and returns a 3D tensor of the same shape where positional encoding embedding has been added. The positional encoder is a function of the position of the token in the sequence. The positional encoder is defined as:

$$PE_{(pos,2i)} = \sin(pos/10000^{2i/d_{model}})$$
  $PE_{(pos,2i+1)} = \cos(pos/10000^{2i/d_{model}})$ 

where pos is the position and i is the dimension. That is, each dimension of the positional encoding corresponds to a sinusoid. The wavelengths form a geometric progression from  $2\pi$  to  $10000 \cdot 2\pi$ .

In practice, the positional encoding is added to the embedding vector. This is done by first creating a tensor of shape (1, sequence\_length, d\_model) and then adding it to the embedding

vector. This ensures that the positional encoding is added to every element in the batch via broadcasting.

Hints:

• If done correctly the output of the code below should look like:

```
torch.Size([1, 4, 512])
False
input_pe: tensor([0.0100, 0.0200, 0.0300, 0.0400, 0.0500])
output_pe: tensor([0.2263, 1.4525, 0.6788, 1.9051, 1.1314])
input_pe: tensor([0.0100, 0.0200, 0.0300, 0.0400, 0.0500])
output_pe: tensor([1.0677, 1.0222, 1.4808, 1.5285, 1.8931])
input_pe: tensor([5.0800, 5.0900, 5.1000, 5.1100, 5.1200])
output_pe: tensor([115.9473, 115.1735, 116.3998, 115.6261, 116.8524])
```

```
In [11]: class PositionalEncoder(nn.Module):
             def __init__(self, d_model, max_seq_len = 80):
                 super().__init__()
                 self.d_model = d_model
                 # create constant 'pe' matrix with values dependant on
                 # pos and i
                 pe = torch.zeros(max_seq_len, d_model)
                 #### YOUR CODE HERE ####
                 # Loop over the positions and the embedding dimensions
                 # and calculate the positional encoding for each dimension
                 # and position
                 # If you want extra challenge, try to do this without loops.
                 for pos in range(max seq len):
                   for i in range(0, d_model, 2):
                     pe[pos, i] = math.sin(pos / (10000**(i/self.d_model)))
                     pe[pos, i + 1] = math.cos(pos / (10000**(i/self.d model)))
                 #### END YOUR CODE ####
                 pe = pe.unsqueeze(0)
                 # Register this as something to keep when saving a model
                 # but that is not a learnable parameter
                 self.register_buffer('pe', pe)
             def forward(self, x):
                 # make embeddings relatively larger than pe
                 x = x * math.sqrt(self.d_model)
                 # add constant positional encoding to embedding
                 seq len = x.size(1)
                 x = x + Variable(self.pe[:,:seq_len], requires_grad=False)
                 return x
         pe = PositionalEncoder(512)
         input pe = torch.arange(1, 513)*0.01
         input_pe = input_pe.repeat(1, 4, 1).float()
         output_pe = pe(input_pe)
```

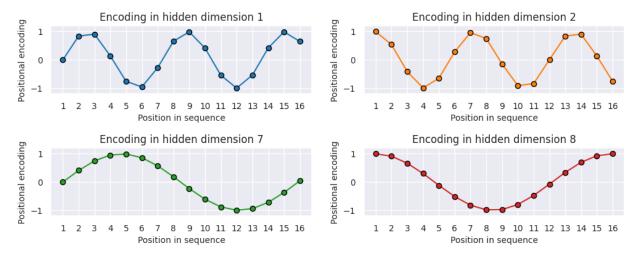
```
print(output_pe.shape)

# check the difference between the two embeddings
print(torch.equal(input_pe, output_pe)) # They should not be equal after adding positi
print(f"input_pe: {input_pe[0, 0, 0:5]} \noutput_pe: {output_pe[0, 0, 0:5]}")
print(f"input_pe: {input_pe[0, 1, 0:5]} \noutput_pe: {output_pe[0, 1, 0:5]}")
print(f"input_pe: {input_pe[0, 2, -5:]} \noutput_pe: {output_pe[0, 1, 0:5]}")

torch.Size([1, 4, 512])
False
input_pe: tensor([0.0100, 0.0200, 0.0300, 0.0400, 0.0500])
output_pe: tensor([0.2263, 1.4525, 0.6788, 1.9051, 1.1314])
input_pe: tensor([0.0100, 0.0200, 0.0300, 0.0400, 0.0500])
output_pe: tensor([1.0677, 0.9929, 1.5007, 1.4748, 1.9333])
input_pe: tensor([5.0800, 5.0900, 5.1000, 5.1100, 5.1200])
output_pe: tensor([115.9473, 115.1738, 116.3998, 115.6263, 116.8524])
```

To understand the positional encoding, we will generate an image of the positional encoding over the hidden dimensionality and position in a sequence. Below we visualize the positional encoding (encoding\_size = 64) for the hidden dimensions 1, 2, 7 and 8 where sine and cosine waves with different wavelengths encode the position in the hidden dimensions.

```
In [12]:
         import seaborn as sns
         import matplotlib.pyplot as plt
         p encode = PositionalEncoder(64)
         pe = p encode.pe.squeeze().T.cpu().numpy()
         sns.set_theme()
         fig, ax = plt.subplots(2, 2, figsize=(12,4))
         dims = [1, 2, 7, 8]
         ax = [a for a_list in ax for a in a list]
         for i in range(len(ax)):
             ax[i].plot(np.arange(1,17), pe[dims[i]-1,:16], color=f'C{i}', marker="o", markers
             ax[i].set title(f"Encoding in hidden dimension {dims[i]}")
             ax[i].set_xlabel("Position in sequence", fontsize=10)
             ax[i].set_ylabel("Positional encoding", fontsize=10)
             ax[i].set_xticks(np.arange(1,17))
             ax[i].tick_params(axis='both', which='major', labelsize=10)
             ax[i].tick params(axis='both', which='minor', labelsize=8)
             ax[i].set_ylim(-1.2, 1.2)
         fig.subplots_adjust(hspace=0.8)
         sns.reset_orig()
         plt.show()
```



# Exercise 2: Scaled Dot-Product Attention (30 points)

In this exercise, you will implement a version of attention used in transformers. The key difference from the one described in class is that the attention scores (pre-softmax) are scaled by a factor of  $\frac{1}{\sqrt{d_k}}$ , where  $d_k$  is the dimension of the keys (and the queries):

$$A(Q,K,V) = \operatorname{softmax}\left(rac{QK^T}{\sqrt{d_k}}
ight)V$$

where  $Q \in \mathbb{R}^{L \times d_k}$ ,  $K \in \mathbb{R}^{L \times d_k}$ , and  $V \in \mathbb{R}^{L \times d_v}$ , where  $d_v$  is the dimension of the values. The softmax is across the column dimension. The output of attention should be a matrix  $A \in \mathbb{R}^{L \times d_v}$ .

Additionally, we will implement a **batched version** of this that can be used for multiple sequences at the same time. To do this, you will need to use the following **batched** version(s) of matrix multiplication either torch.bmm or torch.matmul for both the  $QK^T$  and the product of the attention matrix and V. We recommend that you use torch.bmm as it is more explicit.

#### Hint:

- You will need to transpose the matrices in the k tensor. Specifically, you will need to swap the last and second to last dimension so that it has shape (batch\_size, d\_k, seq\_len). One way to do this is via the transpose function.
- If done correctly, the output should be like below: Is shape of output correct? True Is shape of att\_values correct? True Do attention values sum to 1? True Output check (first): tensor([-1.3709, -0.6827, 0.3234, 0.8677, -0.1474, -0.9653, -0.7344, 0.8126, 0.1219, 0.3224, 0.6257, -0.0958, -0.1664, -0.0667, -0.2810, 0.3068,

```
def attention(q, k, v):
In [38]:
             Inputs:
             q: query vector of shape (batch_size, seq_len, d_k)
             k: key vector of shape (batch size, seg len, d k)
             v: value vector of shape (batch_size, seq_len, d_v)
             Returns:
             output: attention weighted sum of the value vectors
                 of shape (batch size, seg len, d k)
             scores: attention weights of shape (batch_size, seq_len, seq_len)
             d_k = k.size(-1)
             assert d_k = q.size(-1), 'q and k should have the same dimensionality'
             d v = v.size(-1)
             #### YOUR CODE HERE ####
             k T = k.transpose(-2,-1)
             scores = torch.bmm(q, k_T) / (d_k**0.5)
             att_values = F.softmax(scores, dim = -1)
             output = torch.bmm(att_values, v)
             #### END YOUR CODE ####
             return output, att_values
         # test the attention function with some random values
         torch.manual_seed(42) # Do not change random seed
         q = torch.randn(2, 5, 512)
         k = torch.randn(2, 5, 512)
         v = torch.randn(2, 5, 256)
         output, att_values = attention(q, k, v)
         print(f"Is shape of output correct? {output.shape == v.shape}")
         print(f"Is shape of att_values correct? {att_values.shape == torch.Size([q.shape[0], content
         print(f"Do attention values sum to 1? {torch.allclose(torch.sum(att_values, dim=-1), t
         # Last 25 values of last sample and last token
         print(f"Output check (first): \n{output[0,0,:25]}")
         print(f"Output check (last): \n{output[-1,-1,-25:]}")
         # Compare with Pytorch Implementation
         out = F.scaled_dot_product_attention(q,k,v)
```

```
print(f'Is the implementation similar to Pytorch implementation?'
      f' {torch.allclose(output, out, atol=1e-3, rtol=1)}')
Is shape of output correct? True
Is shape of att values correct? True
Do attention values sum to 1? True
Output check (first):
tensor([-1.3709, -0.6827, 0.3234, 0.8677, -0.1474, -0.9653, -0.7344, 0.8126,
        0.1219, 0.3224, 0.6257, -0.0958, -0.1664, -0.0667, -0.2810, 0.3068,
       -0.7030, -0.6719, 0.4364, -1.0071, 0.3534, 0.3160, 0.0326, -0.7315,
       -0.5165])
Output check (last):
tensor([-0.2094, 1.3784, 0.2855, -0.1716, 0.1597, -0.6656, 0.3981, -0.9903,
        -0.6043, -0.6398, 0.0563, -1.5367, -0.0225, -0.8317, 0.0572, 0.2014,
        0.1324, -0.4563, 0.3832, 0.1051, 0.0653, -0.2076, 0.6225, -0.4946,
       -0.2935])
Is the implementation similar to Pytorch implementation? True
```

### Exercise 3: Attention modules (50 points)

#### Task 1: Self-attention module

Implement a self-attention module that takes in x and computes q, k, v internally using 3 linear layers. Then, use your function from above to compute the output and attention and return it. The attention module should take as constructor parameters the  $input\_dim$ ,  $key\_dim$ , and the  $output\_dim$ .

Your output should look like the following:

```
input shape: torch.Size([4, 10, 512])
            output shape: torch.Size([4, 10, 512])
            Input:
            tensor([-0.1988, -0.3060, 0.6383, 0.5713, 1.2769])
            tensor([ 8.6836e-02, -4.1725e-02, -2.5798e-01, -9.6712e-02, 3.0079e-
            05],
                   grad fn=<SliceBackward>)
            Does the module exhibit permutation-equivaraince? True
            The following two lines should be the same:
            tensor([ 0.1849,  0.3706,  0.1488,  0.0898,  0.2528,  0.4277,
            0.4572,
                     0.1172,
                      0.0893, -0.2081], grad_fn=<SliceBackward>)
            tensor([ 0.1849,  0.3706,  0.1488,  0.0898,  0.2528,  0.4277,
            0.4572, 0.1172,
                     0.0893, -0.2081], grad_fn=<SliceBackward>)
In [47]: class SelfAttention(nn.Module):
            def __init__(self, input_dim, key_dim, output_dim):
                super().__init__()
```

#### YOUR CODE HERE ####

```
self.linear q = nn.Linear(input dim, key dim)
        self.linear k = nn.Linear(input dim, key dim)
        self.linear v = nn.Linear(input dim, output dim)
        #### END YOUR CODE ####
    def forward(self, x):
        `x` has shape (batch dim, sequence length, input dim) or (N, L, D in)
       The output should have shape (batch dim, sequence length, output dim) or (N, I
       #### YOUR CODE HERE ####
        q = self.linear q(x)
        k = self.linear_k(x)
        v = self.linear_v(x)
        output, att values = attention(q,k,v)
        #### FND YOUR CODF ####
        return output
# test the self-attention module with some random values
torch.manual_seed(48)
input dim = 512
key_dim = 64
output dim = 512
self attn = SelfAttention(input dim, key dim, output dim)
x = torch.randn(4, 10, 512)
output = self_attn(x)
print(f"input shape: {x.shape}")
print(f"output shape: {output.shape}")
print(f'Input: \n{x[0,0,:5]}\nOutput: \n{output[0,0,:5]}\n')
# For self-attention, let's check the "permutation-equivariant" property,
# i.e., permute the input sequence and check if the output sequence is also permuted \ell
# This is a nice sanity check that self-attention is working properly.
random permutation = torch.randperm(x.size(1))
reverse_permutation = torch.zeros_like(random_permutation)
reverse permutation[random_permutation] = torch.arange(len(random_permutation))
assert torch.all(x[:, random permutation, :][:, reverse permutation, :] == x), 'invers'
x prime = x[:, random permutation, :] # Permute input
output_prime = self_attn(x_prime)
output prime permuted = output prime[:, reverse permutation, :] # Reverse permutation
print(f'Does the module exhibit permutation-equivaraince?'
      f' {torch.allclose(output, output_prime_permuted, atol=1e-5, rtol=1)}')
print(f'The following two lines should be the same:')
print(output[-1,-1,:10])
print(output prime permuted[-1,-1,:10])
```

### Task 2: Cross Attention module

For cross attention, there will be an first input x that will correspond to the query and a second input y that will correspond to the keys and values. (In self-attention, x and y were equal). This should be the same basic idea except that there is a linear layer to compute q from x and linear layers to compute k and v from y.

The output should look like the following:

```
In [51]:
    class CrossAttention(nn.Module):
        def __init__(self, x_input_dim, y_input_dim, key_dim, output_dim):
            super().__init__()
            #### YOUR CODE HERE ####
            self.linear_q = nn.Linear(x_input_dim, key_dim)
            self.linear_k = nn.Linear(y_input_dim, key_dim)
            self.linear_v = nn.Linear(y_input_dim, output_dim)

#### END YOUR CODE ####

def forward(self, x, y):
            #### YOUR CODE HERE ####
            q = self.linear_q(x)
```

```
k = self.linear k(y)
        v = self.linear_v(y)
        output, att_weight = attention(q,k,v)
        #### END YOUR CODE ####
        return output
# test the attention module with some random values
torch.manual seed(14)
x_{input_dim} = 512
y_{input_dim} = 256
key_dim = 64
output dim = 128
cross_attn = CrossAttention(x_input_dim, y_input_dim, key_dim, output_dim)
x = torch.randn(3, 10, x_input_dim)
y = torch.randn(3, 10, y_input_dim)
output = cross attn(x, y)
print(f"input shape x and y: {x.shape}, {y.shape}")
print(f"output shape: {output.shape}")
print(f'x\n{x[0,0,:10]}')
print(f'y\n{y[0,0,:10]}')
print(f'output\n{output[0,0,:10]}')
input shape x and y: torch.Size([3, 10, 512]), torch.Size([3, 10, 256])
output shape: torch.Size([3, 10, 128])
tensor([-0.0385, 0.9773, -1.4370, 0.8719, -2.1034, -0.2877, 0.3034, -1.9151,
         1.1799, 0.6151])
tensor([-2.1565, 0.2397, 0.5872, 0.3950, -0.6114, 0.3489, -0.3467, 0.2792,
        -1.2541, 0.4053])
output
tensor([-0.1544, 0.0847, 0.2329, 0.0549, -0.1424, 0.0711, 0.0105, -0.2139,
        -0.0208, -0.1942], grad fn=<SliceBackward0>)
```

#### Task 3: Multi-headed self-attention module

Multi-headed self-attention merely passes the the input to each attention module, concatenates all the outputs, and then applies a linear layer to get the final output. Implement multi-headed attention below.

Output should look like:

```
class MultiHeadedAttention(nn.Module):
In [67]:
             def __init__(self, attn_modules, final_output_dim):
                 super(). init ()
                 #### YOUR CODE HERE ####
                 # 1) Save the attn_modules as a nn.ModuleList
                 # 2) Setup a linear layer
                    Hint for 2: Need to compute the concatenated dimensionality to
                 # setup linear layer by extracting the output dimension from each
                 # attention module.
                 self.module_list = nn.ModuleList()
                 self.module_list.extend(attn_modules)
                 output dim = 0
                 for module in self.module list:
                     output_dim += module.linear_v.out_features
                 self.linear = nn.Linear(output_dim, final_output_dim)
                 #### END YOUR CODE ####
             def forward(self, x):
                 #### YOUR CODE HERE ####
                 # 1) Concatenate outputs of each self-attention module
                 # 2) Apply final linear layer
                 output = torch.cat([module(x) for module in self.module_list], dim = -1)
                 output = self.linear(output)
                 #### END YOUR CODE ####
                 return output
         # test the multi-headed attention module with some random values
         torch.manual seed(10)
         input dim = 256
         key_dim = 128
         output_dim = 64
         final_output_dim = 32
         num\ heads = 8
         attn modules = [SelfAttention(input dim, key dim, output dim//num heads) for in rang
         multi_attn = MultiHeadedAttention(attn_modules, final_output_dim)
         x = torch.randn(3, 10, input_dim)
         output = multi_attn(x)
         print(f"input shape: {x.shape}")
         print(f"output shape: {output.shape}")
         print(f'x\n{x[0,0,:10]}\noutput\n{output[0,0,:10]}')
```

# (Optional, ungraded) Masked attention module

Try to implement the masked attention module for the decoder in a transformer.

In [ ]: