

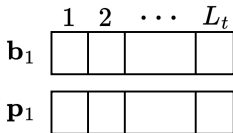
Robot 1



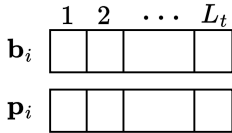
...

Robot i 

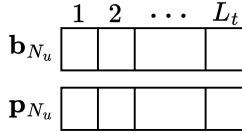
...

Robot N_u 

...



...



Available tasks



Task 1

...

Task j

...

Task N_t