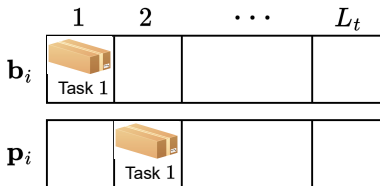


Robot i



Available tasks



Task 1

...



Task j

...



Task N_t