

Robot i



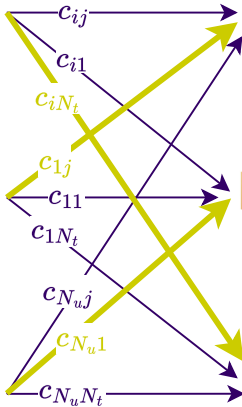
\vdots

Robot 1



\vdots

Robot N_u



Task j



\vdots

Task 1



\vdots

Task N_t

