

Robot i



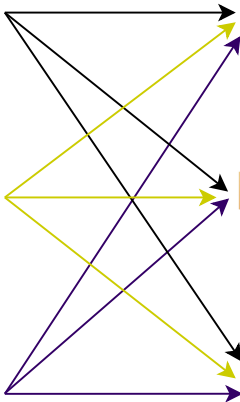
⋮

Robot 1



⋮

Robot N_u



Task j



⋮

Task 1



⋮

Task N_t

