Mohsen Alizadeh Noghani

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Education

Ph.D. in Mechanical Engineering — 2022-present
University of Notre Dame — *Notre Dame, U.S.*
GPA: 3.97

M.Sc. in Applied & Computational Mathematics & Statistics (Statistics track) — 2022-present
University of Notre Dame — *Notre Dame, U.S.*
GPA: 4.00

M.Sc. in Mechanical Engineering — 2019-2021
University of Maine — *Orono, U.S.*
GPA: 4.00

B.Sc. in Mechanical Engineering — 2013-2018
Ferdowsi University of Mashhad — *Mashhad, Iran*
GPA: 17.65

Publications

Mohsen Alizadeh Noghani, Ehsan Sharafian M., Ben Sidaway, Babak Hejrati. (2024). **Increasing Thigh Extension with Haptic Feedback Affects Leg Coordination during Gait**. *Under review*.

Mohsen Alizadeh Noghani, Edgar Bolivar-Nieto. (2024). **Prediction of Whole-Body Center of Mass using Joint Angles and Ground Reaction Forces: A Framework for Human Intent Prediction**. *2024 10th IEEE RAS/EMBS International Conference for Biomedical Robotics and Biomechatronics (BioRob). In press.*

Jacob Bloom, **Mohsen Alizadeh Noghani**, Babak Hejrati. (2023). **A Wearable Upper Extremity Rehabilitation Device for Inducing Arm Swing in Gait Training**. *2023 International Conference on Rehabilitation Robotics (ICORR)*. [DOI]

Md. Tanzid Hossain, **Mohsen Alizadeh Noghani**, Ben Sidaway, Babak Hejrati. (2023). **Investigating the Efficacy of a Tactile Feedback System to Increase the Gait Speed of Older Adults**. *Human Movement Science*. [DOI]

Mohsen Alizadeh Noghani, Md. Tanzid Hossein, Babak Hejrati. (2023). **Modulation of Arm Swing Frequency and Gait Using Rhythmic Tactile Feedback**. *IEEE Transactions on Neural Systems and Rehabilitation Engineering*. [DOI]

Mohsen Alizadeh Noghani, Mohsen Shahinpoor, Babak Hejrati. (2022). **Design and Validation of a Smartphone-based Haptic Feedback System for Gait Training**. *IEEE Robotics and Automation Letters*. [DOI]

Mohsen Alizadeh Noghani, Drew Browning, Vincent Caccese, Elizabeth DePoy, Stephen Gilson, Ryan Beaumont, Babak Hejrati. (2021). **Design and Evaluation of the Afari: A Three-wheeled Mobility and Balance Support Device for Outdoor Exercise**. *Assistive Technology*. [DOI]

Conference Abstracts & Presentations

Mohsen Alizadeh Noghani, Edgar Bolivar-Nieto. (2024) **A Framework for Prediction of Center of Mass Trajectory**, *Workshop: AI-Based Estimation and Control of Wearable Robotic Systems for Enhancing Human Mobility, BioRob 2024, Heidelberg, Germany*

Mohsen Alizadeh Noghani, Edgar Bolivar-Nieto. (2024). **A Framework for Prediction of Center of Mass Trajectory**. *Dynamic Walking 2024. Pensacola, FL, U.S.* [Video abstract] [Poster]

Mohsen Alizadeh Noghani, Edgar Bolivar-Nieto. (2023). **Prediction of Human Center of Mass Position from Ground Reaction Forces**. *2023 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS). Detroit, MI, U.S.* [Abstract] [Poster]

Mohsen Alizadeh Noghani, Mohsen Shahinpoor, Babak Hejrati (2021). **Design and Validation of a Smartphone-based Haptic Feedback System for Gait Training**. *2021 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS). Virtual.* [Video presentation]

Theses

Development of a Novel Haptic Feedback System for Gait Training Applications. (2021). *University of Maine*. [PDF]

Analysis and Optimization of a 4-UPS Parallel Robot. (2018). *Ferdowsi University of Mashhad*.

Experience

Wearable Robotics Lab, University of Notre Dame 2022-present
Research Assistant *Notre Dame, U.S.*

- Development of predictive control methods for robotic prosthetic legs

Biorobotics & Biomechanics Lab, University of Maine 2019-2022
Research Assistant *Orono, ME*

- Developed a wireless haptic feedback system for gait training controlled by a smartphone
- Contributed to the NIH R15 grant "A Wearable Haptic Feedback System for Home-based Gait Training for Older Adults" and the NSF CAREER grant "Interlimb Neural Coupling to Enhance Gait Rehabilitation"

Department of Mechanical Engineering, University of Maine 2019-2021
Teaching Assistant *Orono, ME*

- Teaching Assistant for "Robot Dynamics and Control", "Engineering Dynamics", and "Mechanism Analysis and Design"

FUM Center for Advanced Rehabilitation and Robotics Research (FUM CARE) 2017-2018
Undergraduate Research Assistant *Mashhad, Iran*

- Developed a real-time EtherCAT motion control system in PREEMPT_RT Linux (worst-case jitter: 37 μs. 99.5 percentile jitter: less than 6 μs)
- Optimized the design of a 4-UPS parallel robot for a large workspace, small size, and low power usage using the genetic algorithm

Professional Activities

Peer review

- Journal of NeuroEngineering and Rehabilitation
- Scientific Reports
- IEEE Transactions on Neural Systems and Rehabilitation Engineering
- BioMedical Engineering OnLine
- IEEE International Conference on Biomedical Robotics and Biomechatronics (BioRob)
- IEEE International Conference on Robotics and Automation (ICRA)

Training

- Bootlin Real-Time Linux with PREEMPT_RT [Certificate]
- Bootlin Embedded Linux Kernel and Driver Development [Certificate]

Courses

Statistics, applied mathematics, and machine learning

- Applied Probability; Applied Bayesian Statistics; Advanced Biostatistical Methods; Statistical Inference; SQL for Data Science; Applied Linear Models; Statistical Methods in Data Mining and Prediction; Deep Neural Networks; Optimization for Data Science

Computer Science and engineering

- Cluster Computing; Embedded Systems; Operating Systems; Computer Vision;