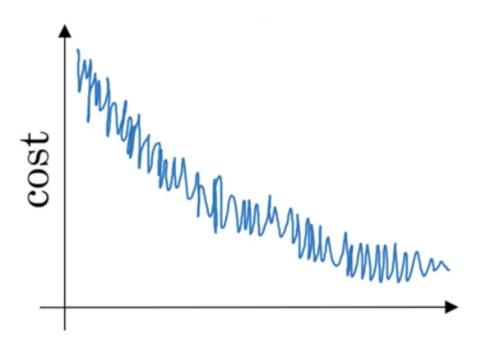
| 1. | Which notation would you use to denote the 3rd layer's activations when the input is the 7th example from the 8th minibatch?  |  |  |  |
|----|---|--|--|--|
|    | $igo a^{[3]\{8\}(7)}$   |  |  |  |
|    | $\bigcirc \ a^{[8]\{7\}(3)}$  |  |  |  |
|    | $\bigcirc \ a^{[8]\{3\}(7)}$  |  |  |  |
|    | $\bigcirc \ a^{[3]\{7\}(8)}$  |  |  |  |
|    |   |  |  |  |
| 2. | Which of these statements about mini-batch gradient descent do you agree with?  |  |  |  |
|    | You should implement mini-batch gradient descent without an explicit for-loop over different mini-batches, so that the algorithm processes all mini-batches at the same time (vectorization). |  |  |  |
|    | Training one epoch (one pass through the training set) using mini-batch gradient descent is faster than training one epoch using batch gradient descent.                                      |  |  |  |
|    | One iteration of mini-batch gradient descent (computing on a single mini-batch) is faster than one iteration of<br>batch gradient descent.  |  |  |  |
| 3. | Why is the best mini-batch size usually not 1 and not m, but instead something in-between?  |  |  |  |
|    | If the mini-batch size is 1, you lose the benefits of vectorization across examples in the mini-batch.  |  |  |  |
|    | If the mini-batch size is m, you end up with batch gradient descent, which has to process the whole training set<br>before making progress.   |  |  |  |
|    | If the mini-batch size is 1, you end up having to process the entire training set before making any progress.   |  |  |  |
|    | If the mini-batch size is m, you end up with stochastic gradient descent, which is usually slower than mini-batch gradient descent.   |  |  |  |
|    |   |  |  |  |

4. Suppose your learning algorithm's cost J, plotted as a function of the number of iterations, looks like this:



Which of the following do you agree with?

- Whether you're using batch gradient descent or mini-batch gradient descent, something is wrong.
- If you're using mini-batch gradient descent, this looks acceptable. But if you're using batch gradient descent, something is wrong.
- Of If you're using mini-batch gradient descent, something is wrong. But if you're using batch gradient descent, this looks acceptable.
- Whether you're using batch gradient descent or mini-batch gradient descent, this looks acceptable.

5. Suppose the temperature in Casablanca over the first three days of January are the same:

Jan 1st: 
$$\theta_1=10^{o}C$$

Jan 2nd: 
$$heta_2 10^o C$$

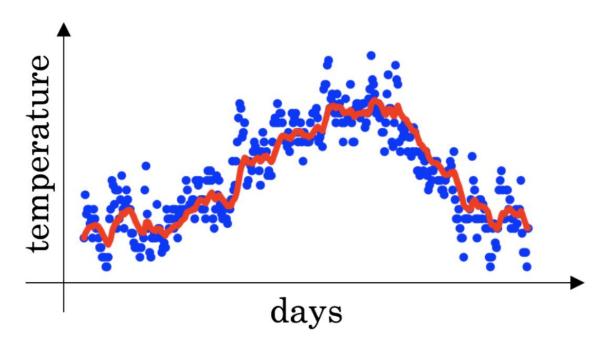
(We used Fahrenheit in lecture, so will use Celsius here in honor of the metric world.)

Say you use an exponentially weighted average with  $\beta=0.5$  to track the temperature:  $v_0=0$ ,  $v_t=\beta v_{t-1}+(1-\beta)\theta_t$ . If  $v_2$  is the value computed after day 2 without bias correction, and  $v_2^{corrected}$  is the value you compute with bias correction. What are these values? (You might be able to do this without a calculator, but you don't actually need one. Remember what is bias correction doing.)

- $\bigcirc v_2 = 10$ ,  $v_2^{corrected} = 10$
- $\bigcirc \ v_2=10, v_2^{\it corrected}=7.5$
- $\bigcirc \quad v_2 = 7.5, v_2^{corrected} = 7.5$
- 6. Which of these is NOT a good learning rate decay scheme? Here, t is the epoch number.

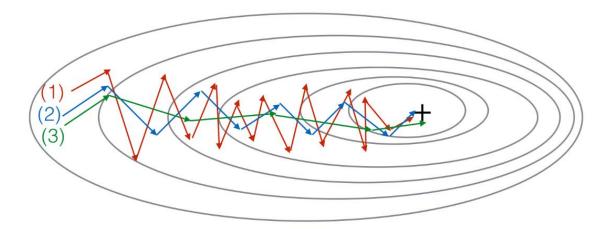
  - $\bigcap \ lpha = rac{1}{1+2*t}lpha_0$
  - $\bigcirc \ \alpha = \frac{1}{\sqrt{t}}\alpha_0$
  - $\bigcirc \ \alpha = 0.95^t \alpha_0$

7. You use an exponentially weighted average on the London temperature dataset. You use the following to track the temperature:  $v_t = \beta v_{t-1} + (1-\beta)\theta_t$ . The red line below was computed using  $\beta = 0.9$ . What would happen to your red curve as you vary  $\beta$ ? (Check the two that apply)



- Decreasing  $\beta$  will shift the red line slightly to the right.
- ightharpoonup Increasing eta will shift the red line slightly to the right.
- $\checkmark$  Decreasing  $\beta$  will create more oscillation within the red line.
- $\hfill \square$  Increasing  $\beta$  will create more oscillations within the red line.

## 8. Consider this figure:



These plots were generated with gradient descent; with gradient descent with momentum ( $\beta$  = 0.5) and gradient descent with momentum ( $\beta$  = 0.9). Which curve corresponds to which algorithm?

- (1) is gradient descent with momentum (small  $\beta$ ). (2) is gradient descent. (3) is gradient descent with momentum (large  $\beta$ )
- (1) is gradient descent. (2) is gradient descent with momentum (large  $\beta$ ). (3) is gradient descent with momentum (small  $\beta$ )
- (1) is gradient descent. (2) is gradient descent with momentum (small  $\beta$ ). (3) is gradient descent with momentum (large  $\beta$ )
- (1) is gradient descent with momentum (small  $\beta$ ), (2) is gradient descent with momentum (small  $\beta$ ), (3) is gradient descent

| 9.  | Suppose batch gradient descent in a deep network is taking excessively long to find a value of the parameters that achieves a small value for the cost function $\mathcal{J}(W^{[1]},b^{[1]},,W^{[L]},b^{[L]})$ . Which of the following techniques could help find parameter values that attain a small value for $\mathcal{J}$ ? (Check all that apply) |
|-----|---|
|     | Try better random initialization for the weights  |
|     | ✓ Try mini-batch gradient descent   |
|     | ✓ Try using Adam  |
|     | Try initializing all the weights to zero  |
|     | igspace Try tuning the learning rate $lpha$   |
| 10. | Which of the following statements about Adam is False?  |
|     | We usually use "default" values for the hyperparameters $\beta_1,\beta_2$ and $\varepsilon$ in Adam ( $\beta_1=0.9,\beta_2=0.999,\varepsilon=10^{-8}$ )   |
|     | Adam should be used with batch gradient computations, not with mini-batches.  |
|     | $\bigcirc$ The learning rate hyperparameter $lpha$ in Adam usually needs to be tuned.   |
|     | Adam combines the advantages of RMSProp and momentum  |
|     |   |
|     |   |