

scipy-mathematical-optimization-1

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[ ]: '''Optimization is closely related to equation solving because at an optimal_
    ↪value of
a function, its derivative, or gradient in the multivariate case, is zero. The_
    ↪converse,
however, is not necessarily true, but a method to solve optimization problems_
    ↪is to
solve for the zeros of the derivative or the gradient and test the resulting_
    ↪candidates
for optimality. This approach is not always feasible though, and often it is_
    ↪required to
take other numerical approaches, many of which are closely related to the_
    ↪numerical
methods for root finding.'''
'''In this chapter we are concerned with the optimization of realvalued_
    ↪functions of one or
several variables, which optionally can be subject to a set of constraints that_
    ↪restricts the
domain of the function. A general optimization problem of the type considered_
    ↪here can be formulated as a
minimization problem,  $\min_x f(x)$ , subject to sets of  $m$  equality constraints_
    ↪ $g(x) = 0$  and
 $p$  inequality constraints  $h(x) \leq 0$ . Note that maximizing  $f(x)$  is equivalent to
minimizing  $-f(x)$ , so without loss of generality, it is sufficient to consider_
    ↪only
minimization problems.'''
'''The problem is univariate or one dimensional if  $x$  is a scalar,  $x \in \mathbb{R}$ , and_
    ↪multivariate or
multidimensional if  $x$  is a vector,  $x \in \mathbb{R}^n$ . If the objective function and the_
    ↪constraints
all are linear, the problem is a linear optimization problem, or linear_
    ↪programming
problem. If either the objective function or the constraints are nonlinear, it_
    ↪is a
nonlinear optimization problem, or a nonlinear programming problem. With respect
to constraints, important subclasses of optimization are unconstrained_
    ↪problems, and
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those with linear and nonlinear constraints. Finally, handling equality and
↳inequality
constraints requires different approaches.'''
'''We will discuss using SciPy's optimization module optimize for nonlinear
optimization problems, and we will briefly explore using the convex
↳optimization library
cvxopt for linear optimization problems with linear constraints. This library
↳also has
powerful solvers for quadratic programming problems.'''
!pip install cvxopt

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[17]: #Univariate Limits Constrained optimization:
from scipy.optimize import *
from numpy import *
# Define the objective function
def objective_function(x):
    return x**2 + 5*sin(x)
# Define bounds for the optimization
bounds = (-5, 5)
# Perform bounded univariate optimization
result = minimize_scalar(objective_function, bounds=bounds) #minimize_scalar is
↳a scipy function for univariate optimization
# Print the optimized result
print("Optimized value within bounds:", result.x)
print("Objective function value at the optimized point:", result.fun)

```

Optimized value within bounds: -1.1105110510992415

Objective function value at the optimized point: -3.2463942726905684

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[19]: #Multivariate Non-constrained optimization:
# Define the objective function to be minimized
def objective_function(x):
    return x[0]**2 + x[1]**2 # Example objective function:  $x^2 + y^2$ 
# Initial guess for the optimization algorithm
initial_guess = array([1.0, 1.0])
# Perform unconstrained optimization using the minimize function
result = minimize(objective_function, initial_guess, method='BFGS') #minimize
↳is a scipy function for multivariate optimization
#BFGS', which stands for Broyden-Fletcher-Goldfarb-Shanno algorithm used for
↳such problems
# Print the optimization result
print("Optimized parameters:", result.x)
print("Optimal function value:", result.fun)

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Optimized parameters: [-1.07505143e-08 -1.07505143e-08]

Optimal function value: 2.311471135620994e-16

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[22]: #Multivariate Limits constrained optimization:
# Define the objective function to be minimized
def objective_function(x):
    return x[0]**2 + x[1]**2 # Example objective function:  $x^2 + y^2$ 
# Initial guess for the optimization algorithm
initial_guess = array([1.0, 1.0])
# Define the bounds for each variable
bounds = [(0, None), (0, None)] # Lower bound of 0 for both variables, no
    ↪upper bounds
# Perform unconstrained optimization with bounds using the L-BFGS-B method
result = minimize(objective_function, initial_guess, method='L-BFGS-B',
    ↪bounds=bounds)
#L-BFGS-B method is efficient for problems with bounded variables and can
    ↪handle multivariate optimization effectively.
# Print the optimization result
print("Optimized parameters:", result.x)
print("Optimal function value:", result.fun)
```

Optimized parameters: [0. 0.]

Optimal function value: 0.0

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[61]: #Linear Equalities and Inequalities constrained optimization(Linear
    ↪Programming):
'''Consider the problem of minimizing the function  $f(x) = -x_0 + 2x_1 - 3x_2$ ,
    ↪subject to the three inequality
constraints  $x_0 + x_1 \leq 1$ ,  $-x_0 + 3x_1 \leq 2$ , and  $-x_1 + x_2 \leq 3$ . . On the standard form, we
    ↪have  $c = (-1, 2, -3)$  Coefficients
for the variables  $x_0, x_2$  and  $x_3$  in  $f(x)$ ,  $b = (1, 2, 3)$  Right-hand side of the
    ↪constraints and matrix
A =[1 1 0
    1 3 0
    0 1 1] Coefficients for the variables  $x_0, x_2$  and  $x_3$  in the constraints.
'''
from numpy import *
import cvxopt
c = array([-1.0, 2.0, -3.0])
A = array([[ 1.0, 1.0, 0.0],
    [-1.0, 3.0, 0.0],
    [ 0.0, -1.0, 1.0]])
b = array([1.0, 2.0, 3.0])
A_ = cvxopt.matrix(A)
b_ = cvxopt.matrix(b)
c_ = cvxopt.matrix(c)
#The cvxopt library uses its own classes for representing matrices and vectors,
    ↪hence we first create numpy arrays and then convert them to cvx objects.
sol = cvxopt.solvers.lp(c_, A_, b_)
x = array(sol['x'])
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print('x=',x)
print('f(x)=',sol['primal objective'])
```

Optimal solution found.

x= [[0.25]

 [0.75]

 [3.75]]

f(x)= -10.0