

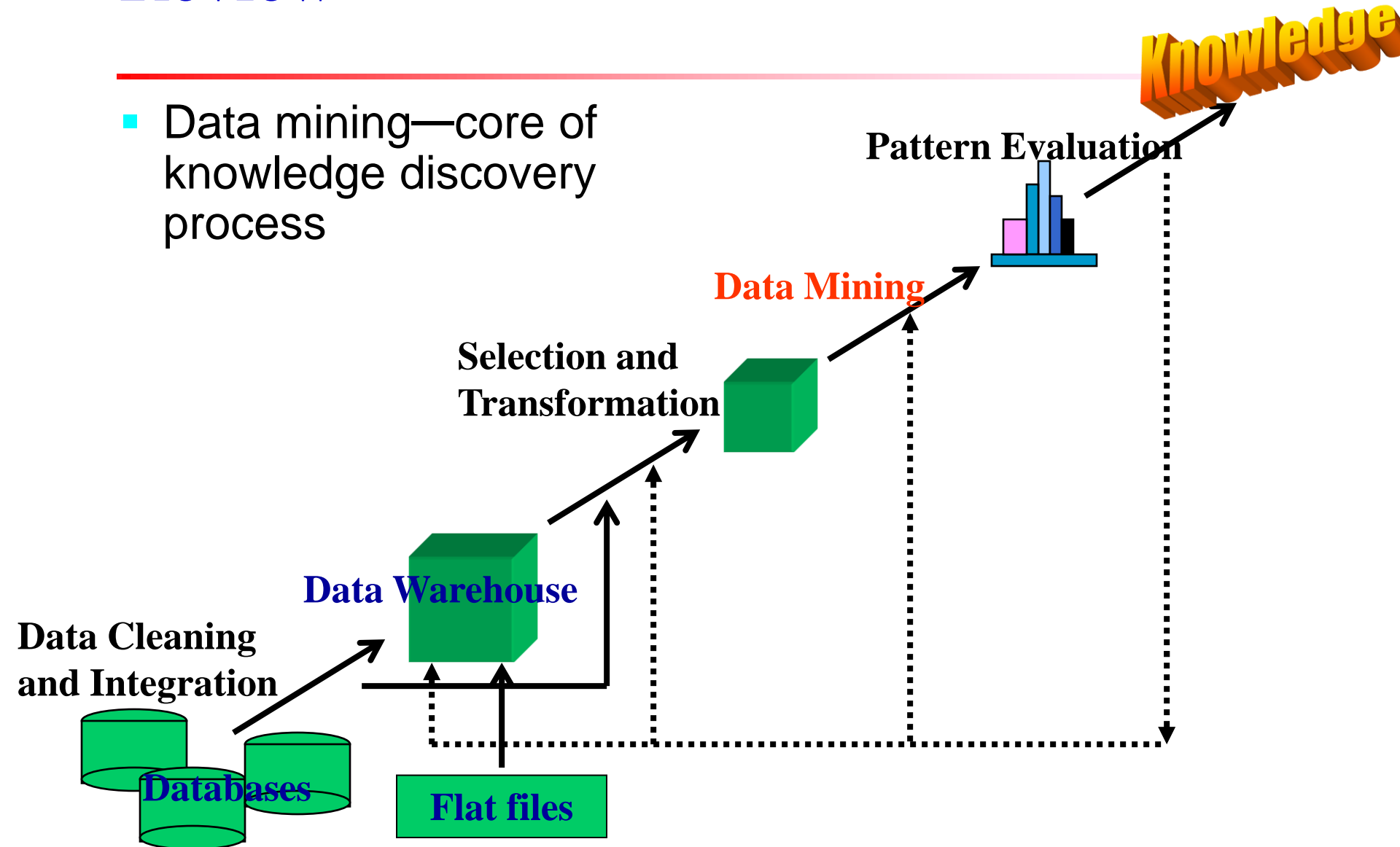
Data Mining

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Review

- Data mining—core of knowledge discovery process



Cluster Analysis

- What is Cluster Analysis?
- Types of Data in Cluster Analysis
- A Categorization of Major Clustering Methods
- Partitioning Methods
- Hierarchical Methods
- Density-Based Methods
- Grid-Based Methods
- Outlier Analysis
- Summary

What is Cluster Analysis?

- Cluster: a collection of data objects
 - Similar to one another within the same cluster
 - Dissimilar to the objects in other clusters
- Cluster analysis
 - Finding similarities between data according to the characteristics in the data and grouping similar data objects into clusters
- **Unsupervised learning**: no predefined classes
- Typical applications
 - As a **stand-alone tool** to get insight into data distribution
 - As a **preprocessing step** for other algorithms

Examples of Clustering Applications

- Marketing: Help marketers discover distinct groups according to their customer databases, and then use this knowledge to develop targeted marketing programs
- Land use: Identification of areas of similar land use in an earth observation database
- Insurance: Identifying groups of motor insurance policy holders with a high average claim cost
- City-planning: Identifying groups of houses according to their house type, value, and geographical location

Examples of Clustering Applications

- Earth-quake studies: Observed earth quake epicenters are clustered along continent faults
- Biology: categorize genes with similar functionality
- WWW
 - Document classification
 - Cluster Weblog data to discover groups of similar accessing patterns

Clustering: Rich Applications and Multidisciplinary Efforts

- Pattern Recognition
- GIS
 - Create thematic maps in GIS by clustering feature spaces
 - Detect spatial clusters or for other spatial mining tasks
- Image Processing
- Economic Science (especially marketing research)
- Software package
 - S-Plus, SPSS, SAS, R

What Is Good Clustering?

- A good clustering method will produce high quality clusters with
 - high intra-class similarity
 - low inter-class similarity
- The quality of a clustering result depends on both the similarity measure used by the method and its implementation
- The quality of a clustering method is also measured by its ability to discover some or all of the hidden patterns

Measure the Quality of Clustering

- **Dissimilarity/Similarity metric:** Similarity is expressed in terms of a distance function, typically metric: $d(i, j)$
- The definitions of **distance functions** are usually very different for interval-scaled, boolean, categorical, ordinal ratio, and vector variables
- Weights may be assigned to different variables based on applications and data semantics
- It is hard to define “similar enough” or “good enough”
 - The answer is typically highly subjective

Requirements of Clustering

- Scalability
- Ability to deal with different types of attributes
- Ability to handle dynamic data
- Discovery of clusters with arbitrary shape
- Minimal requirements for domain knowledge to determine input parameters
- Able to deal with noise and outliers
- Insensitive to order of input records
- High dimensionality
- Incorporation of user-specified constraints
- Interpretability and usability

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Data Structures

■ Data matrix

$$\begin{bmatrix} x_{11} & \dots & x_{1f} & \dots & x_{1p} \\ \dots & \dots & \dots & \dots & \dots \\ x_{i1} & \dots & x_{if} & \dots & x_{ip} \\ \dots & \dots & \dots & \dots & \dots \\ x_{n1} & \dots & x_{nf} & \dots & x_{np} \end{bmatrix}$$

■ Dissimilarity matrix

$$\begin{bmatrix} 0 & & & & \\ d(2,1) & 0 & & & \\ d(3,1) & d(3,2) & 0 & & \\ \vdots & \vdots & \vdots & & \\ d(n,1) & d(n,2) & \dots & \dots & 0 \end{bmatrix}$$

Type of Data in Clustering Analysis

- Interval-scaled variables
- Binary variables
- Nominal variables
- Ordinal variables
- Ratio-scaled variables
- Variables of mixed types

Interval-valued Variables

■ Standardize data

- Calculate the mean absolute deviation:

$$s_f = \frac{1}{n} (|x_{1f} - m_f| + |x_{2f} - m_f| + \dots + |x_{nf} - m_f|)$$

where $m_f = \frac{1}{n}(x_{1f} + x_{2f} + \dots + x_{nf})$.

- Calculate the standardized measurement (z-score)

$$z_{if} = \frac{x_{if} - m_f}{s_f}$$

- Using mean absolute deviation is more robust than using standard deviation

Similarity and Dissimilarity Between Objects

- Distances are normally used to measure the similarity or dissimilarity between two data objects
- Some popular ones include: *Minkowski distance*:

$$d(i, j) = \sqrt[q]{(|x_{i_1} - x_{j_1}|^q + |x_{i_2} - x_{j_2}|^q + \dots + |x_{i_p} - x_{j_p}|^q)}$$

where $i = (x_{i_1}, x_{i_2}, \dots, x_{i_p})$ and $j = (x_{j_1}, x_{j_2}, \dots, x_{j_p})$ are two p -dimensional data objects, and q is a positive integer

- If $q = 1$, d is Manhattan distance

$$d(i, j) = |x_{i_1} - x_{j_1}| + |x_{i_2} - x_{j_2}| + \dots + |x_{i_p} - x_{j_p}|$$

Similarity and Dissimilarity Between Objects

- If $q = 2$, d is Euclidean distance:

$$d(i, j) = \sqrt{(|x_{i_1} - x_{j_1}|^2 + |x_{i_2} - x_{j_2}|^2 + \dots + |x_{i_p} - x_{j_p}|^2)}$$

- Properties

- $d(i, j) \geq 0$
- $d(i, i) = 0$
- $d(i, j) = d(j, i)$
- $d(i, j) \leq d(i, k) + d(k, j)$

- Also, one can use weighted distance

Binary Variables

- A contingency table for binary data
- Distance measure for symmetric binary variables:
- Distance measure for asymmetric binary variables:

		Object <i>j</i>		
		1	0	<i>sum</i>
Object <i>i</i>	1	<i>a</i>	<i>b</i>	<i>a+b</i>
	0	<i>c</i>	<i>d</i>	<i>c+d</i>
<i>sum</i>		<i>a+c</i>	<i>b+d</i>	<i>p</i>

$$d(i, j) = \frac{b + c}{a + b + c + d}$$

$$d(i, j) = \frac{b + c}{a + b + c}$$

Dissimilarity between Binary Variables

■ Example

Name	Gender	Fever	Cough	Test-1	Test-2	Test-3	Test-4
Jack	M	Y	N	P	N	N	N
Mary	F	Y	N	P	N	P	N
Jim	M	Y	P	N	N	N	N

- gender is a symmetric attribute
- the remaining attributes are asymmetric binary
- let the values Y and P be set to 1, and the value N be set to 0

$$d(jack, mary) = \frac{0 + 1}{2 + 0 + 1} = 0.33$$

$$d(jack, jim) = \frac{1 + 1}{1 + 1 + 1} = 0.67$$

$$d(jim, mary) = \frac{1 + 2}{1 + 1 + 2} = 0.75$$

Nominal Variables

- A generalization of binary variable in that it can take more than 2 states, e.g., red, yellow, blue, green
- Method 1: Simple matching
 - m : # of matches, p : total # of nominal variables

$$d(i, j) = \frac{p - m}{p}$$

- Method 2: use a large number of binary variables
 - creating a new binary variable for each of the M nominal states

Ordinal Variables

- An ordinal variable can be discrete or continuous
- Order is important, e.g., rank
- Can be treated like interval-scaled
 - replace x_{if} by their rank $r_{if} \in \{1, \dots, M_f\}$
 - map the range of each variable onto $[0, 1]$ by replacing i -th object in the f -th variable by

$$z_{if} = \frac{r_{if} - 1}{M_f - 1}$$

- compute the dissimilarity using methods for interval-scaled variables

Ratio-Scaled Variables

- Ratio-scaled variable: a positive measurement on a nonlinear scale, approximately at exponential scale, such as Ae^{Bt} or Ae^{-Bt}
- Methods:
 - treat them like interval-scaled variables — *not a good choice!*
 - apply logarithmic transformation

$$y_{if} = \log(x_{if})$$

- treat them as continuous data and treat their rank as interval-scaled

Variables of Mixed Types

- A database may contain all the six types of variables
 - symmetric binary, asymmetric binary, nominal, ordinal, interval and ratio

- One may use a weighted formula to combine their effects

$$d(i, j) = \frac{\sum_{f=1}^p \delta_{ij}^{(f)} d_{ij}^{(f)}}{\sum_{f=1}^p \delta_{ij}^{(f)}}$$

- $\delta_{ij}^{(f)} = 0$ if x_{if} or x_{jf} is missing, or $x_{if} = x_{jf} = 0$ and f is asymmetric attribute; otherwise, $\delta_{ij}^{(f)} = 1$
- f is binary or nominal:
 - $d_{ij}^{(f)} = 0$ if $x_{if} = x_{jf}$, or $d_{ij}^{(f)} = 1$ otherwise
- f is interval-based: use the normalized distance
- f is ordinal
 - compute ranks r_{if} and treat z_{if} as interval-scaled
- f is ratio-scaled
 - Transform f , and treat f as interval-scaled. $y_{if} = \log(x_{if})$

$$z_{if} = \frac{r_{if} - 1}{M_f - 1}$$

Exercise

1. Please compute the dissimilarity matrix for the data set.

ID	Test-1 (categorical)	Test-2 (ordinal)	Test-3 (ratio-scaled)
1	A	excellent	445
2	B	fair	22
3	C	good	164
4	A	excellent	1,210

Solution

For test-1, use simple matching

0			
d(2,1)	0		
d(3,1)	d(3,2)	0	
d(4,1)	d(4,2)	d(4,3)	0

=

0			
1	0		
1	1	0	
0	1	1	0

For test-2

ID	Test-2 (ordinal)		Test-2 (ordinal)		Test-2 (ordinal)
1	excellent	➡	3	➡	1
2	fair		1		0
3	good		2		0.5
4	excellent		3		1

0			
1	0		
0.5	0.5	0	
0	1	0.5	0

Solution

For test-3, use log transformation

- Convert test-3 to 2.65, 1.34, 2.21, 3.08
- Normalize to 0.75, 0, 0.5, 1

0			
0.75	0		
0.25	0.5	0	
0.25	1	0.5	0

Dissimilarity matrix

0			
d(2,1)	0		
d(3,1)	d(3,2)	0	
d(4,1)	d(4,2)	d(4,3)	0

=

0			
0.92	0		
0.58	0.67	0	
0.08	1	0.67	0

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Major Clustering Approaches (I)

■ Partitioning approach:

- Construct various partitions and then evaluate them by some criterion, e.g., minimizing the sum of square errors
- Typical methods: k-means, k-medoids, CLARANS

■ Hierarchical approach:

- Create a hierarchical decomposition of the set of data (or objects) using some criterion
- Typical methods: Diana, Agnes, BIRCH, ROCK, CHAMELEON

■ Density-based approach:

- Based on connectivity and density functions
- Typical methods: DBSACN, OPTICS, DenClue

Major Clustering Approaches (II)

- Grid-based approach:
 - based on a multiple-level granularity structure
 - Typical methods: STING, WaveCluster, CLIQUE
- Probabilistic Model-based approach:
 - Typical methods: EM

Centroid, Radius and Diameter of a Cluster (for numerical data sets)

- Centroid: the “middle” of a cluster

$$C = \frac{\sum_{i=1}^N (t_i)}{N}$$

- Radius: square root of average distance from any point of the cluster to its centroid

$$R = \sqrt{\frac{\sum_{i=1}^N (t_i - c)^2}{N}}$$

- Diameter: square root of average mean squared distance between all pairs of points in the cluster

$$D = \sqrt{\frac{\sum_{i=1}^N \sum_{j=1}^N (t_i - t_j)^2}{N(N-1)}}$$

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Partitioning Algorithms: Basic Concept

- Partitioning method: Construct a partition of a database D of n objects into a set of k clusters, s.t., min sum of squared distance

$$\sum_{m=1}^k \sum_{t_{mi} \in K_m} (C_m - t_{mi})^2$$

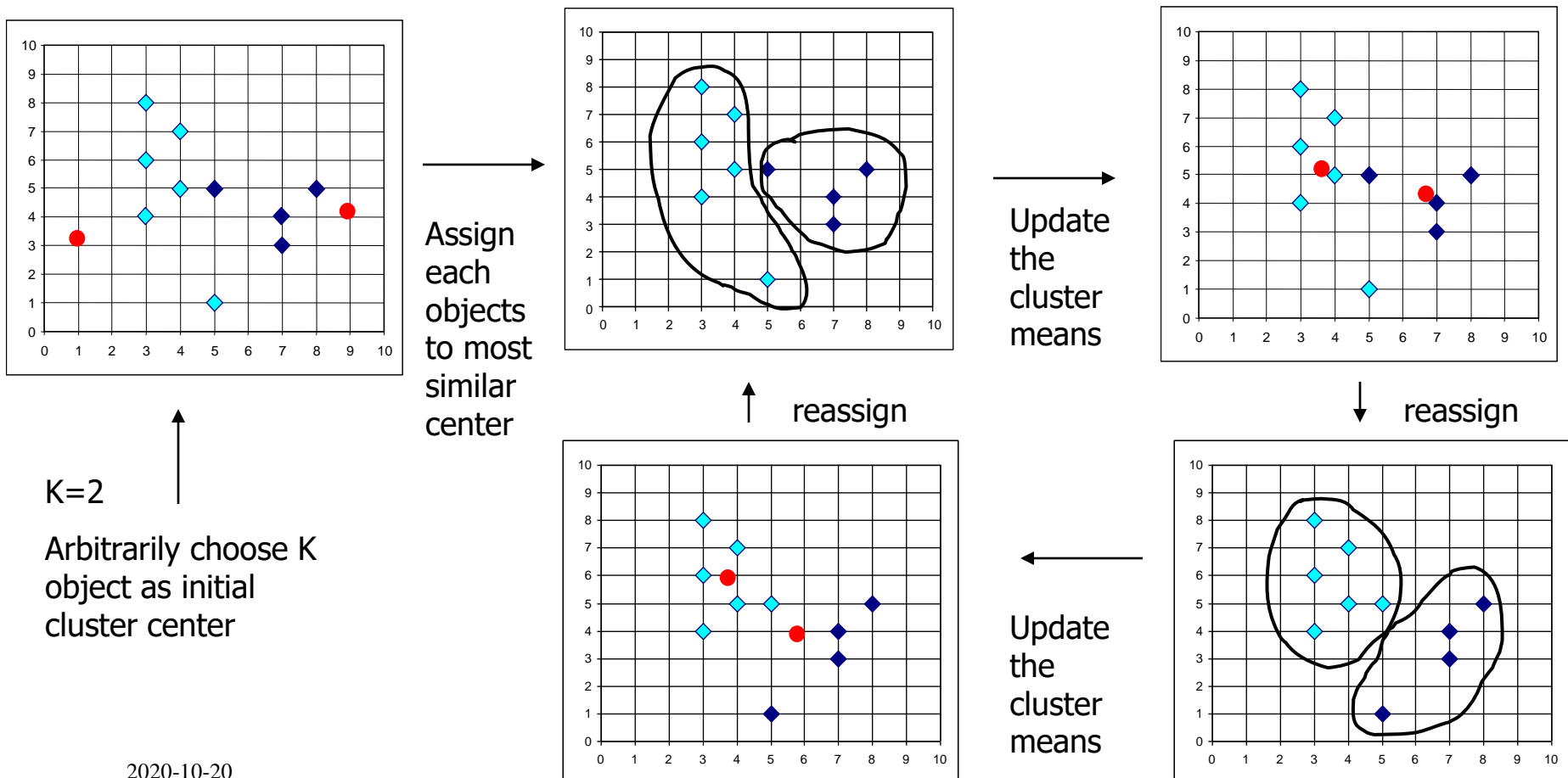
- Given a k , find a partition of k clusters that optimizes the chosen partitioning criterion
 - *k-means* (MacQueen'67): Each cluster is represented by the center of the cluster
 - *k-medoids* or PAM (Partition around medoids) (Kaufman & Rousseeuw'87): Each cluster is represented by one of the objects in the cluster

The *K-Means* Clustering Method

- Given a k , the *k-means* algorithm is implemented in four steps:
 - Give k random seeds as the initial centroids
 - Compute the centroid of each cluster of the current partition (the centroid is the center, i.e., *mean point*)
 - For each object, compute its distance to the centroids
 - Assign it to the cluster with the nearest centroid
 - Go back to Step 2, stop when no more new assignment

The *K-Means* Clustering Method

■ Example



Comments on the *K-Means* Method

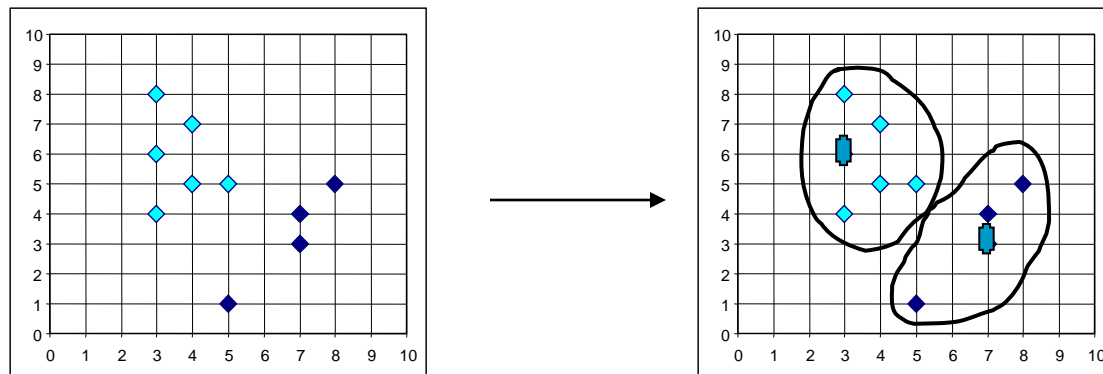
- Strength: Relatively efficient: $O(tkn)$, where n is # objects, k is # clusters, and t is # iterations. Normally, $k, t \ll n$
- Comment: Often terminates at a *local optimum*. The *global optimum* may be found using techniques such as: *deterministic annealing* and *genetic algorithms*
- Weakness
 - Applicable only when *mean* is defined, then what about categorical data?
 - Need to specify k , the number of clusters, in advance
 - Unable to handle noisy data and outliers
 - Not suitable to discover clusters with *non-convex shapes*

Variations of the *K-Means* Method

- Handling categorical data: *k-modes*
 - Replacing means of clusters with modes
 - Using new dissimilarity measures to deal with categorical objects
 - Using a frequency-based method to update modes of clusters
 - A mixture of categorical and numerical data: *k-prototype* method
- Expectation Maximization: an extension to k-means
 - Assign each object to a cluster according to a weight (prob.)
 - New means are computed based on weighted measures

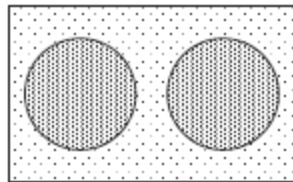
What Is the Problem of the K-Means Method?

- K-means algorithm is sensitive to outliers!
 - Since an object with an extremely large value may substantially distort the distribution of the data
- K-Medoids: Instead of taking the **mean** value of the objects in a cluster as a reference point, **medoids** can be used, which is the **most centrally located** object in a cluster



Exercise

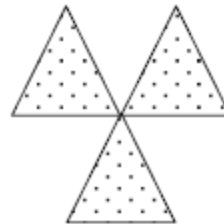
1. Identify the clusters using the K-means (using squared error as the objective function). Note that darkness or the number of dots indicates density.



(a)



(b)



(c)



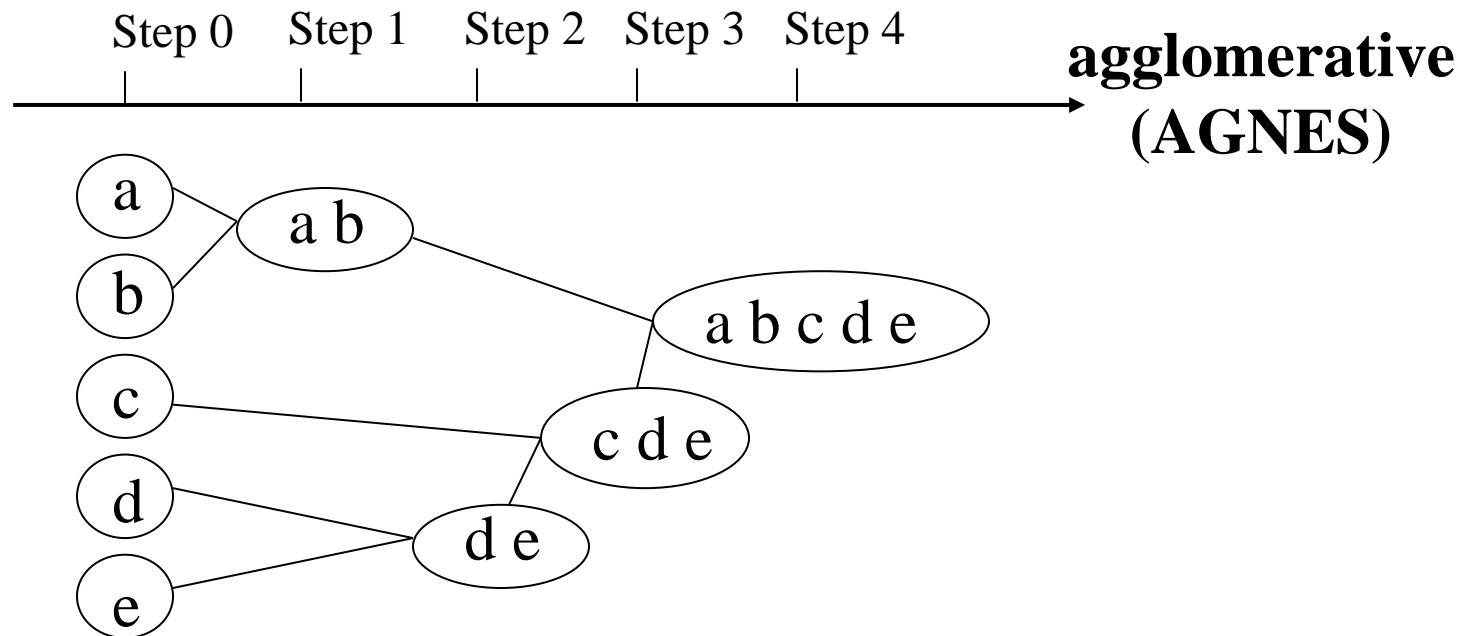
(d)

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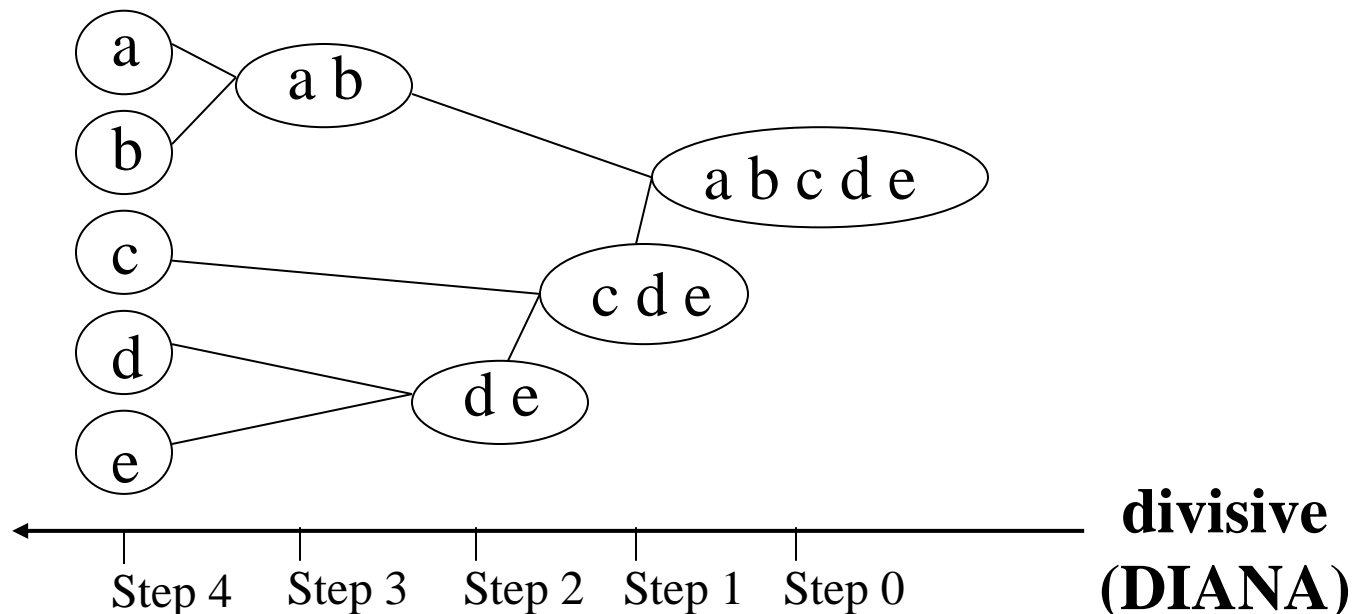
Hierarchical Clustering

- This method does not require the number of clusters k as an input, but needs a termination condition



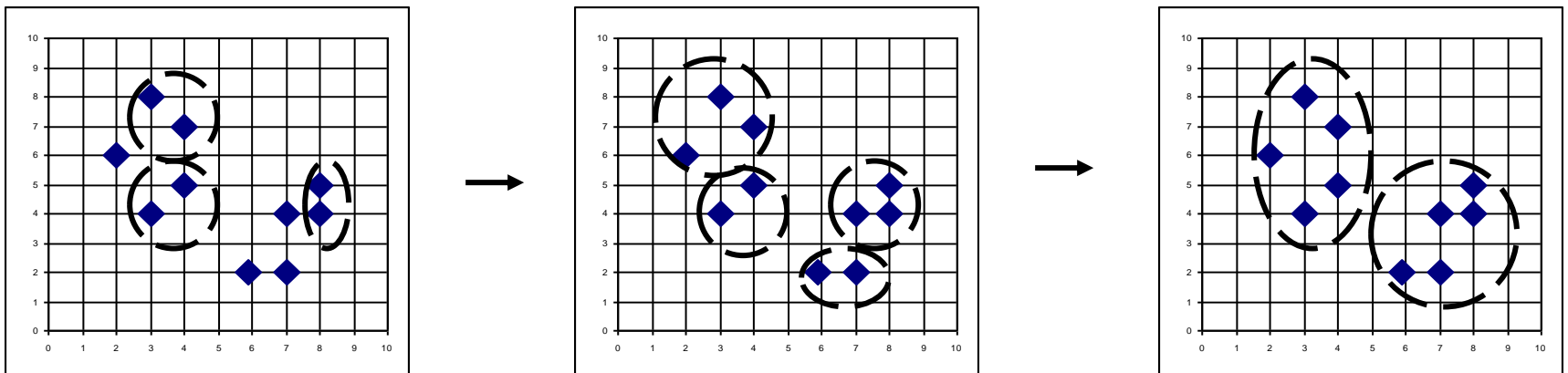
Hierarchical Clustering

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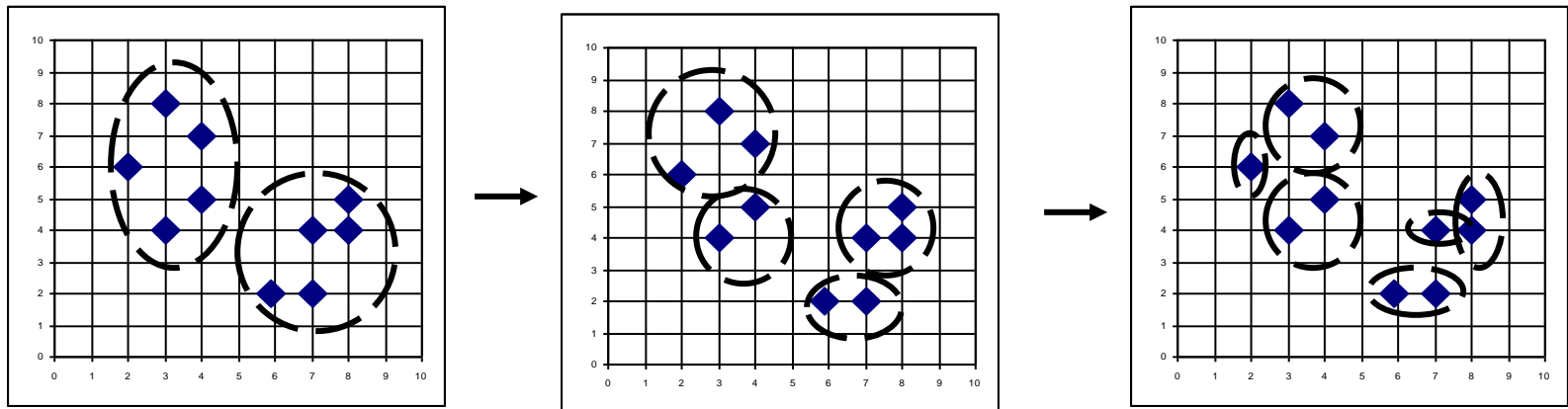
AGNES (Agglomerative Nesting)

- Introduced by Kaufmann and Rousseeuw (1990)
- Use the Single-Link method and the dissimilarity matrix
- Merge nodes that have the least dissimilarity
- Go on in a non-descending fashion
- Eventually all nodes belong to the same cluster



DIANA (Divisive Analysis)

- Introduced by Kaufmann and Rousseeuw (1990)
- Inverse order of AGNES
- Eventually each node forms a cluster on its own



Recent Hierarchical Clustering Methods

- Major weakness of hierarchical clustering methods
 - **Do not scale** well: time complexity of at least $O(n^2)$, where n is the number of total objects
 - can never undo what was done previously
- Integration of hierarchical with distance-based clustering
 - BIRCH (1996): uses CF-tree and incrementally adjusts the quality of sub-clusters
 - ROCK (1999): clustering categorical data by neighbor and link analysis
 - CHAMELEON (1999): hierarchical clustering using dynamic modeling

BIRCH (1996)

- BIRCH: integrated hierarchical clustering
- Clustering feature, Clustering feature tree
- Incrementally construct a CF (Clustering Feature) tree, a hierarchical data structure for multiphase clustering
 - Phase 1: scan DB to build an initial in-memory CF tree (a multi-level compression of the data that tries to preserve the inherent clustering structure of the data)
 - Phase 2: use a clustering algorithm to cluster the leaf nodes of the CF-tree

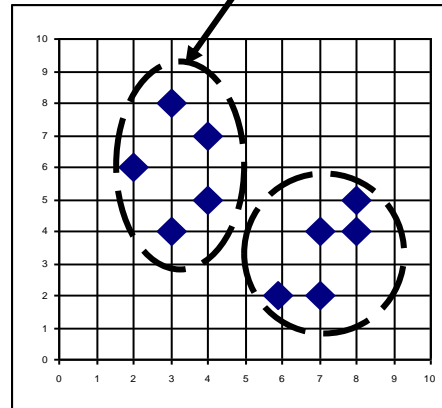
Clustering Feature Vector in BIRCH

Clustering Feature: $CF = (N, \overrightarrow{LS}, SS)$, summarize the cluster members

N : **Number of data points**

$$LS: \sum_{i=1}^N \overrightarrow{X_i}$$

$$SS: \sum_{i=1}^N \overrightarrow{X_i}^2$$



$$CF = (5, (16,30), (54,190))$$

(3,4)

(2,6)

(4,5)

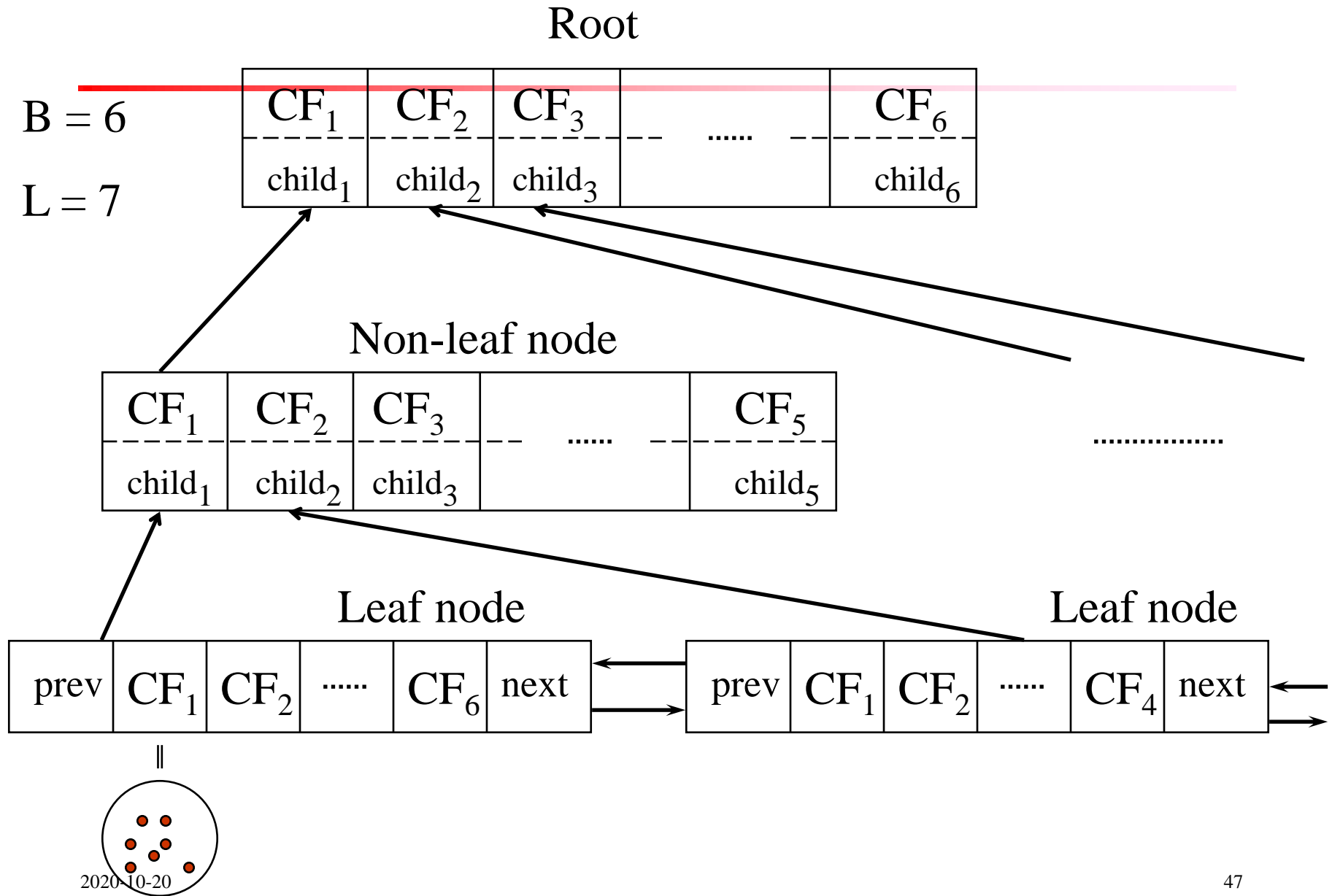
(4,7)

(3,8)

CF-Tree in BIRCH

- Clustering feature:
 - summary of the statistics for a given subcluster
 - registers crucial measurements for computing cluster and utilizes storage efficiently
- A CF tree is a height-balanced tree that stores the clustering features for a hierarchical clustering
 - A nonleaf node in a tree has descendants or “children”
 - The nonleaf nodes store sums of the CFs of their children
- A CF tree has two parameters
 - Branching factor: specify the maximum number of children
 - Threshold: max diameter of sub-clusters stored at the leaf nodes

The CF Tree Structure



BIRCH

■ Phase 1

- Insert each object to its closest leaf entry
- If the diameter of a leaf is larger than a threshold, the leaf will be split
- Update the CF and its ancestor's CF
- If the size of the CF tree is too big, re-build the tree from the leaf node, no re-scan the original objects
- Two parameters (branching factor, threshold), control the size of the tree

BIRCH

■ Scales linearly

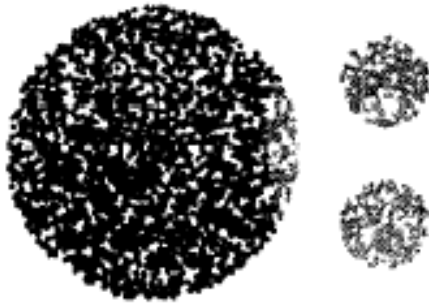
- Complexity: $O(n)$
- Scalable for large database
- Incremental clustering
- Finds a good clustering with a single scan, I/O cost small

■ Weakness

- Handles only numeric data, and sensitive to the order of the data record
- Not good at arbitrary shaped cluster

CURE: Clustering Using Representatives

Centroid-based clustering



All-points agglomerative clustering



CURE: middle ground between centroid-based clustering and all-points agglomerative clustering

CURE: Clustering Using Representatives

- Start with each individual point as a separate cluster
- Merge closest clusters till each cluster contains more than c points
- For each cluster, use c scattered points as representatives
- If more than k clusters
 - Clusters with the closest pair of representative points are merged
 - Update the representative points of merged clusters

CURE: Clustering Using Representatives

■ Choose representatives

- the point farthest from the mean of the cluster
- for 2 to c do
 - the point farthest from the previously chosen point
- Shrink the scattered points toward the mean by a fraction α
 - for each scattered point p do
 - representative = $p + \alpha * (\text{mean} - p)$

■ Merge

- Euclidian distance
- Closest clusters -- minimum distance between representative points from two clusters

$$\text{dist}(u, v) = \min_{p \in u.\text{rep}, q \in v.\text{rep}} \text{dist}(p, q)$$

CURE: Clustering Using Representatives

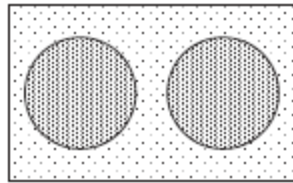
- Multiple representative points allow CURE to discover arbitrary shaped clusters
- Less sensitive to outliers
 - Shrink scattered points toward the mean, weaken the effects of outliers
- Time complexity $O(n^2 \log(n))$
- For large-scale database, do sampling and partitioning

CURE: Clustering Using Representatives

- Draw a random sampling S from original objects
- Cluster the sampled objects (basic *CURE*)
- Eliminate outliers
- Each unsampled original object is assigned to the cluster containing the closest representative point to it

Exercise

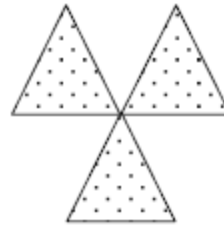
1. Identify the clusters using the Single-Link method. Note that darkness or the number of dots indicates density.



(a)



(b)



(c)



(d)

Cluster Analysis

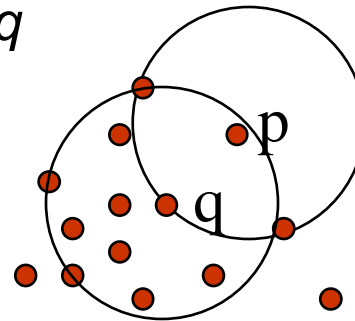
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Density-Based Clustering Methods

- Clustering based on density (local cluster criterion), such as density-connected points
- Major features:
 - Discover clusters of arbitrary shape
 - Handle noise
 - Need density parameters as termination condition
 - Complexity is $O(n^2)$

Density-Based Clustering: Basic Concepts

- Two parameters:
 - ε -neighborhood: neighborhood within a radius ε of a point
 - $MinPts$: Min number of points in ε -neighborhood of a point
- core object: If the number of points in ε -neighborhood of point p exceeds $MinPts$
- Directly density-reachable: A point p is directly density-reachable from a point q w.r.t. , ε , $MinPts$ if
 - p belongs to ε -neighborhood of q
 - q is core object



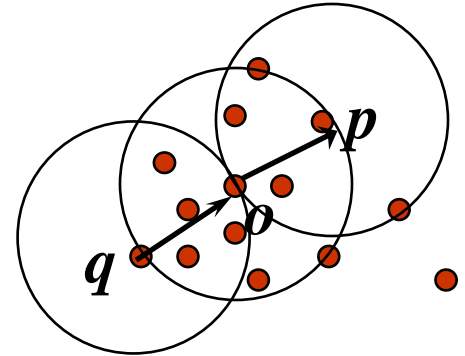
$MinPts = 5$

$\varepsilon = 1 \text{ cm}$

Density-Reachable and Density-Connected

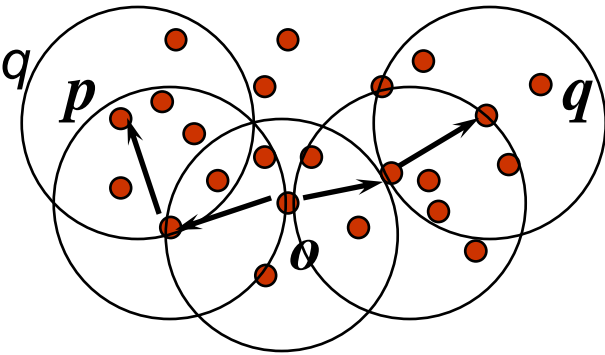
■ Density-reachable:

- A point p is **density-reachable** from a point q w.r.t. ε , $MinPts$ if there is a chain of points p_1, \dots, p_n , $p_1 = q$, $p_n = p$ such that p_{i+1} is directly density-reachable from p_i



■ Density-connected

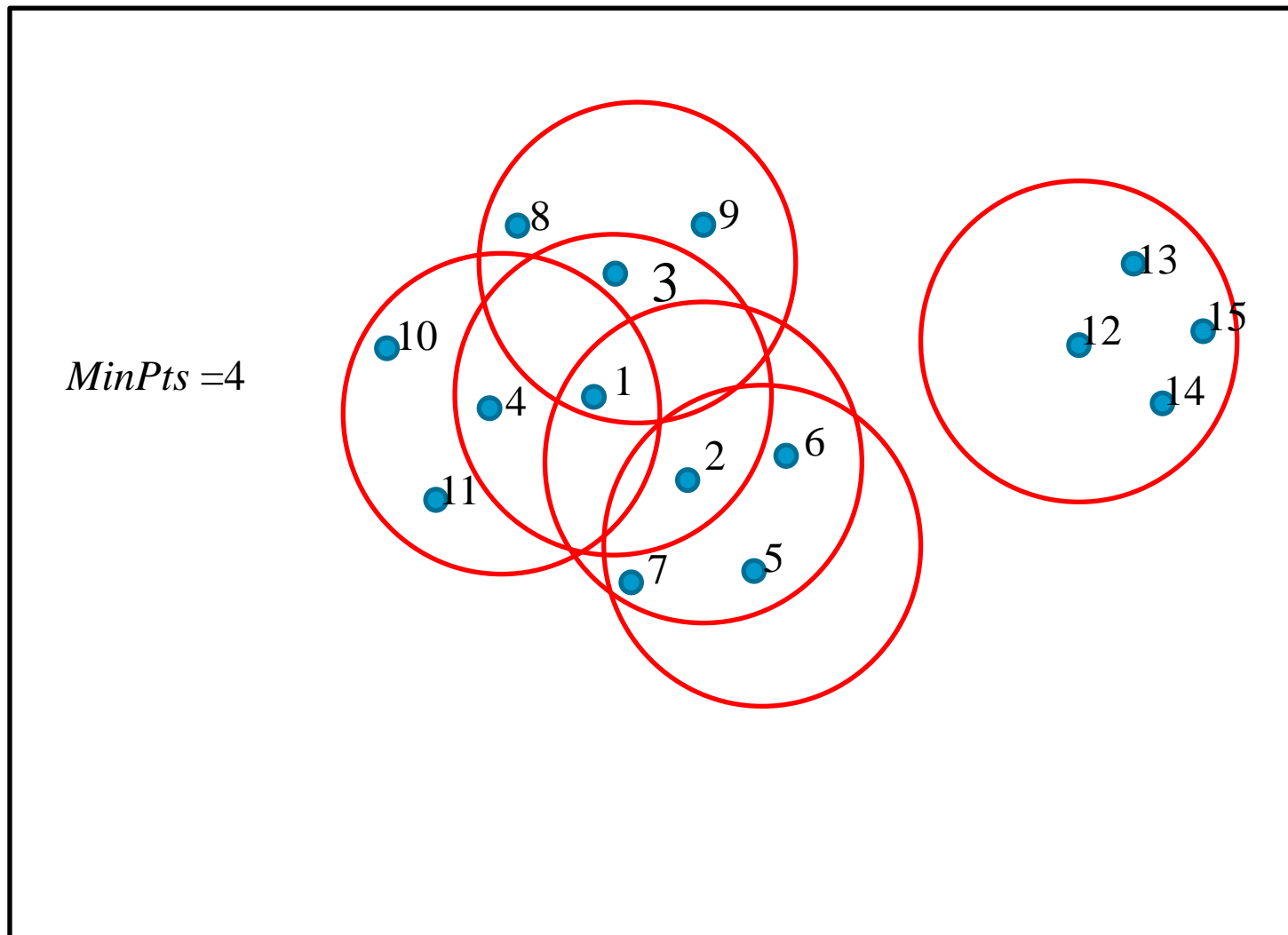
- A point p is **density-connected** to a point q w.r.t. ε , $MinPts$ if there is a point o such that both p and q are density-reachable from o w.r.t. ε and $MinPts$



DBSCAN: The Algorithm

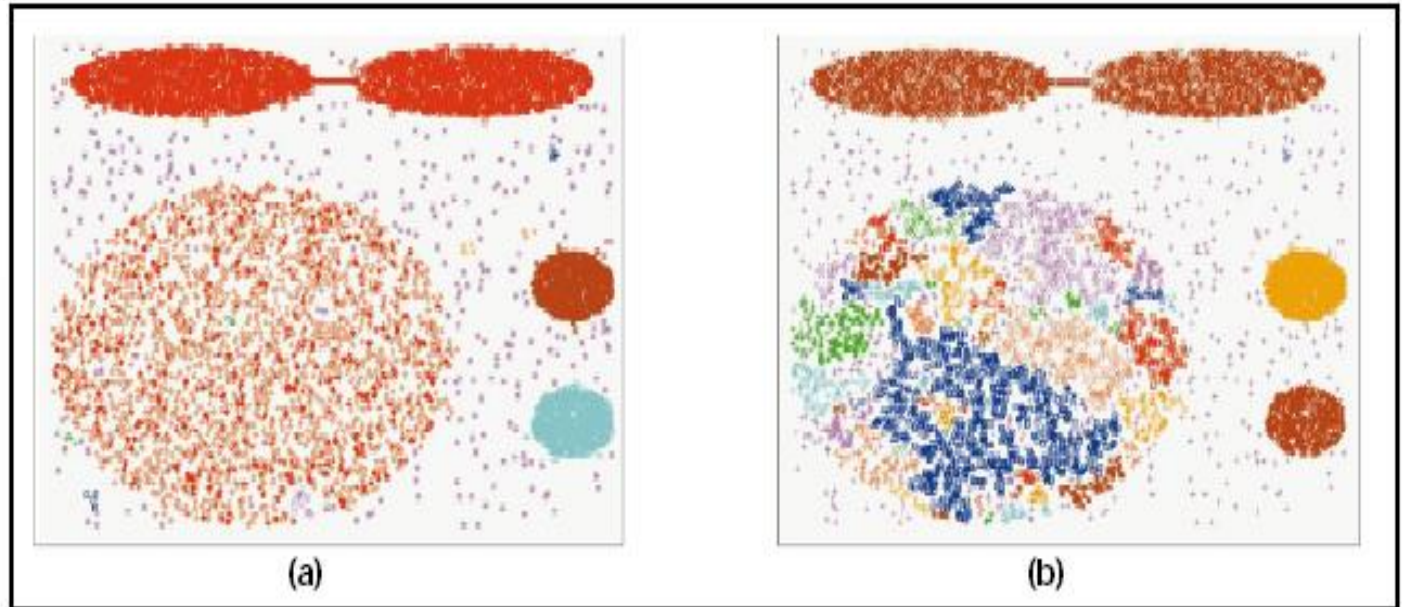
- (1) mark all the objects as ***unvisited***;
- (2) **do**
- (3) randomly select an unvisited object ***p***;
- (4) mark ***p*** as ***visited***;
- (5) **if** the ε -neighborhood of ***p*** has at least *MinPts* objects
- (6) create a new cluster ***C***, and add ***p*** to ***C***;
- (7) let *N* be the set of objects in the ε -neighborhood of ***p***;
- (8) **for** each point ***p'*** in *N*
- (9) **if** ***p'*** is ***unvisited***
- (10) mark ***p'*** as ***visited***;
- (11) **if** the ε -neighborhood of ***p'*** has at least *MinPts* points, add those points to *N*;
- (12) **if** ***p'*** is not yet a member of any cluster, add ***p'*** to *C*;
- (13) **end for**
- (14) output *C*;
- (15) **else** mark ***p*** as ***noise***;
- (16) **until** no object is ***unvisited***.

DBSCAN: The Algorithm

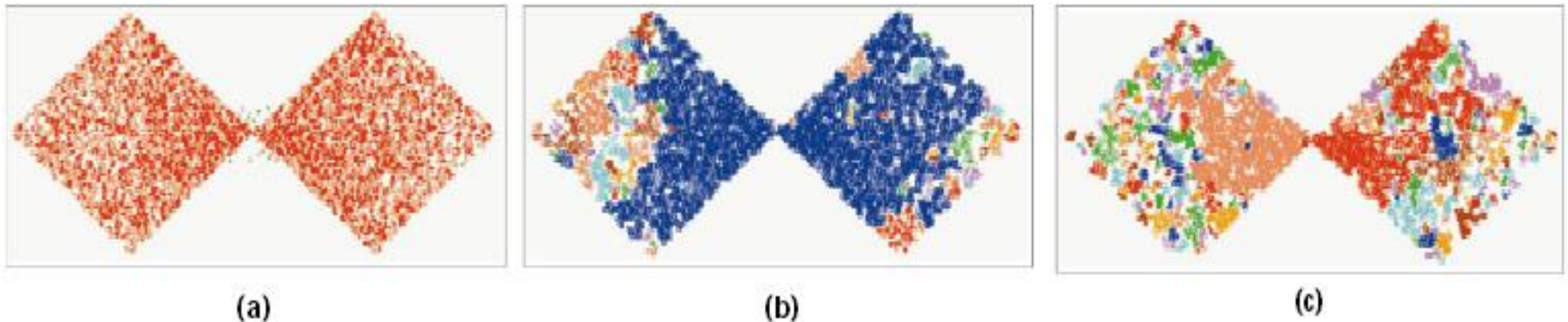


DBSCAN: Sensitive to Parameters

DBScan results
with MinPts = 4
and $\epsilon =$ (a) 0.5, (b)
0.4

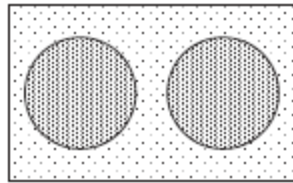


DBScan results
with MinPts = 4
and $\epsilon =$ (a) 5.0, (b)
4.0, (c) 3.0



Exercise

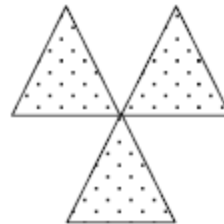
1. Identify the clusters using DBSCAN. Note that darkness or the number of dots indicates density.



(a)



(b)



(c)



(d)

Cluster Analysis

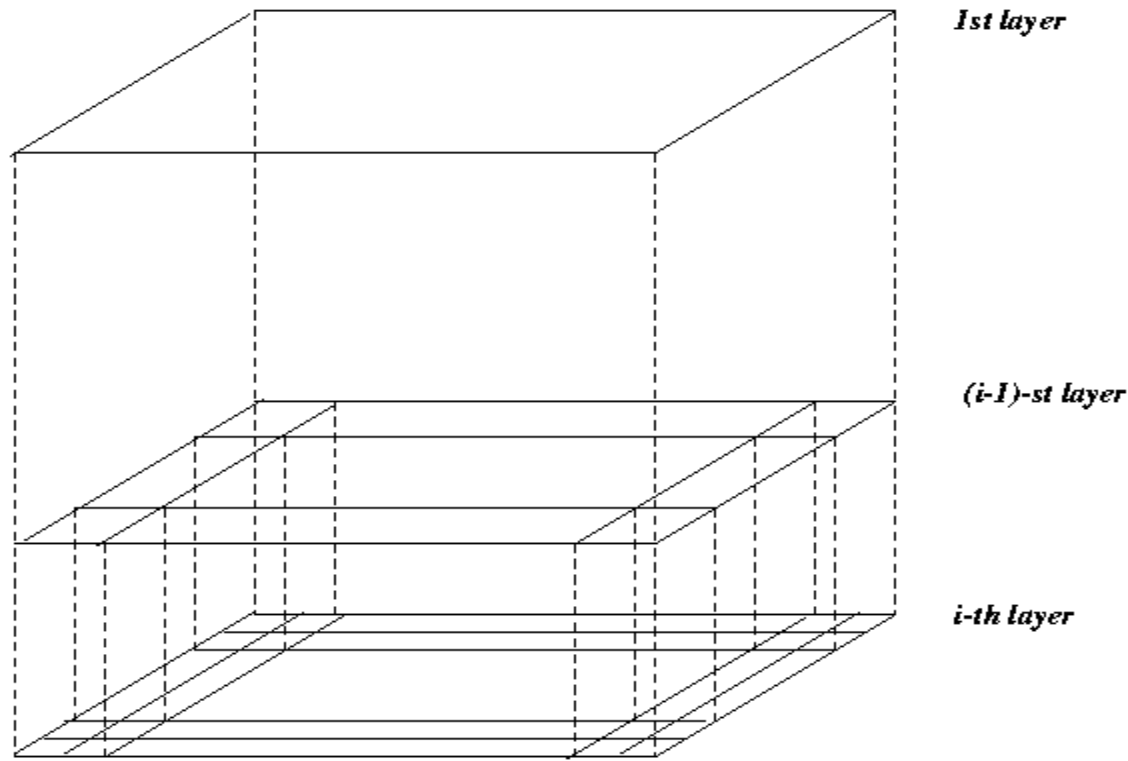
- What is Cluster Analysis?
- Types of Data in Cluster Analysis
- A Categorization of Major Clustering Methods
- Partitioning Methods
- Hierarchical Methods
- Density-Based Methods
- **Grid-Based Methods**
- Outlier Analysis
- Summary

Grid-Based Clustering Method

- Using multi-resolution grid data structure
- Several interesting methods
 - **STING** (a STatistical INformation Grid approach) by Wang, Yang and Muntz (1997)
 - **WaveCluster** by Sheikholeslami, Chatterjee, and Zhang (VLDB'98)
 - A multi-resolution clustering approach using wavelet method
 - **CLIQUE**: Agrawal, et al. (SIGMOD'98)
 - On high-dimensional data

STING: A Statistical Information Grid Approach

- The spatial area is divided into rectangular cells
- There are several levels of cells corresponding to different levels of resolution
- Each cell at a high level is partitioned into a number of smaller cells in the next lower level



The STING Clustering Method

- Statistical info of each cell is calculated and stored beforehand and is used to answer queries
 - *count, mean, s, min, max*
 - type of distribution—normal, uniform, NONE, etc.
- Parameters of higher level cells can be easily calculated from parameters of lower level cells
- Clusters are identified based on *count, cell size, etc.*

$$n = \sum_i n_i$$
$$m = \frac{\sum_i m_i n_i}{n}$$
$$s = \sqrt{\frac{\sum_i (s_i^2 + m_i^2) n_i}{n} - m^2}$$
$$\min = \min_i (\min_i)$$
$$\max = \max_i (\max_i)$$

The STING Query Method

- Use a top-down approach to answer spatial data queries
- Start from a pre-selected layer — typically with a small number of cells
- For each cell in the current level compute the confidence interval
- Remove the irrelevant cells from further consideration
- When finish examining the current layer, proceed to the next lower level of the relevant cells
- Repeat this process until the bottom layer is reached

Exercise

1. Please give some comments on STING in the following aspects:
 - (1) cluster shape
 - (2) computational complexity
 - (3) cluster quality
 - (4) incremental clustering

Comments on STING Clustering

■ Advantages:

- Query-independent
- incremental update
- $O(K)$ for query, where K is the number of grid cells at the lowest level
- $O(n)$ for generating clusters

■ Disadvantages:

- All the cluster boundaries are either horizontal or vertical, and no diagonal boundary is detected
- Processing time depends on the size of each grid

Cluster Analysis

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What Is Outlier Discovery?

- What are outliers?
 - The set of objects are considerably dissimilar from the remaining of the data
 - Caused by
 - Measurement or execution errors
 - Result of inherent variability
- Mining outliers is valuable
- Applications:
 - Credit card fraud detection
 - Customer segmentation
 - Medical analysis

Outlier Detection

■ Visualization

- Weak in data with categorical data, high dimensional data
- Good at numerical data of 2 or 3 dimensions

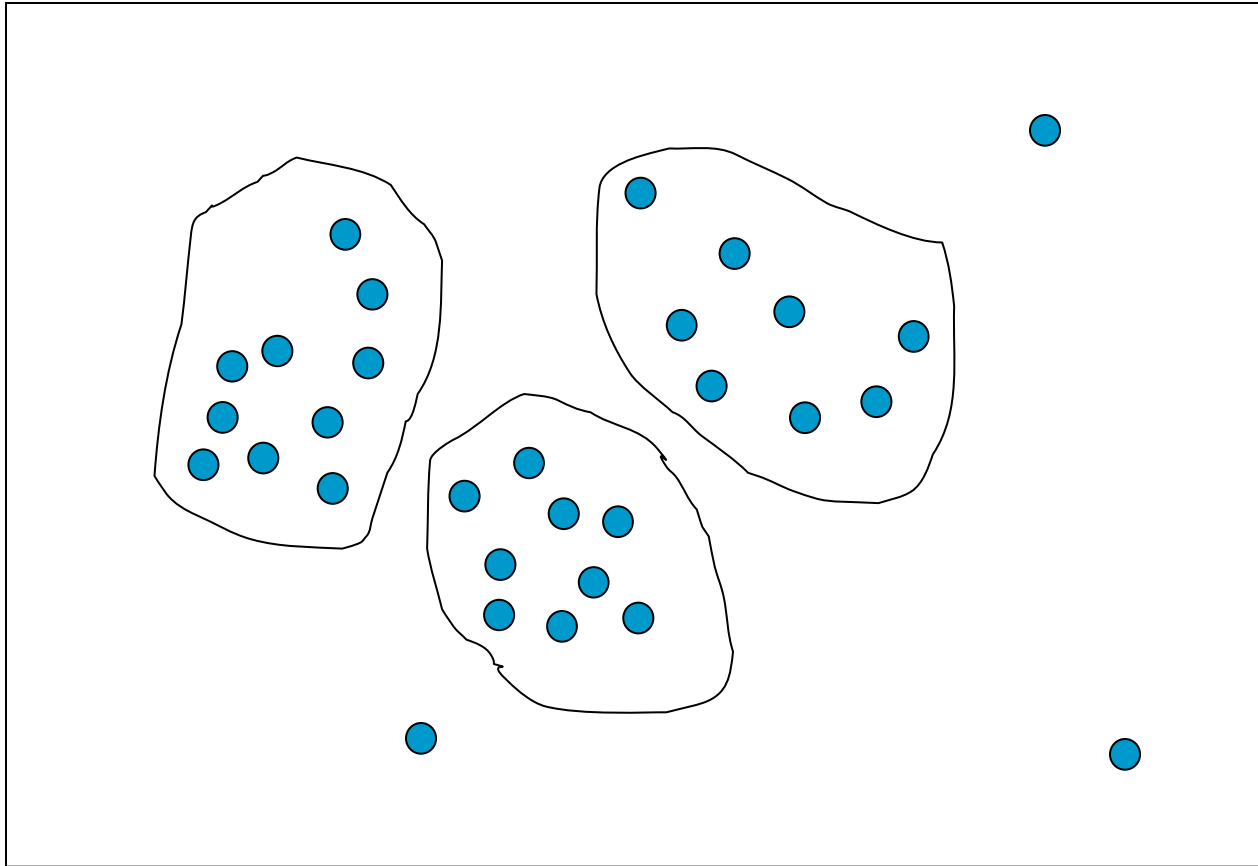
■ Clustering

- Byproduct of clustering may be outliers

■ Computer-based methods

- Statistical-based outlier detection
- Distance-based outlier detection
- Deviation-based outlier detection

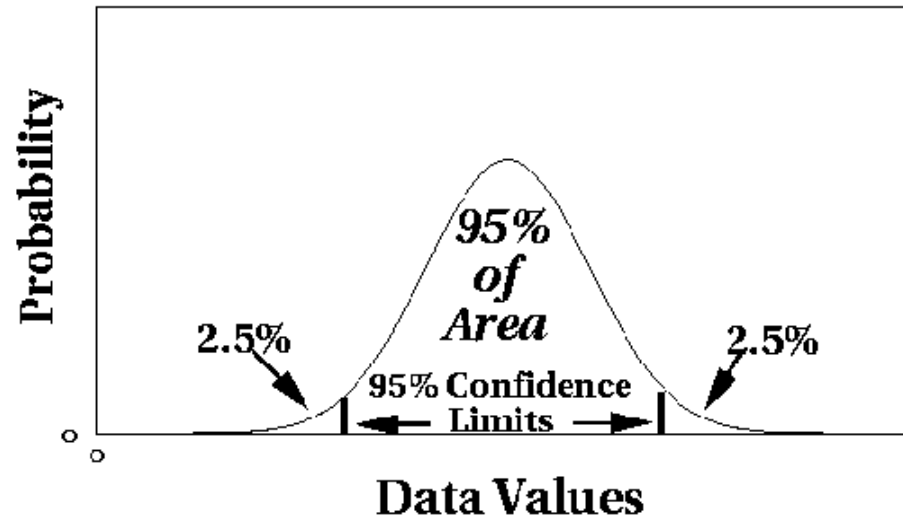
Outlier Detection: Visualization



Outlier Detection: Statistical Approaches

- Assume a distribution (e.g. normal distribution) for the data set and then use discordancy test to find outliers
- Discordancy tests depends on knowledge
 - data distribution
 - two hypothesis
 - distribution parameter (e.g., mean, variance)
 - number of expected outliers

Outlier Detection: Statistical Approaches

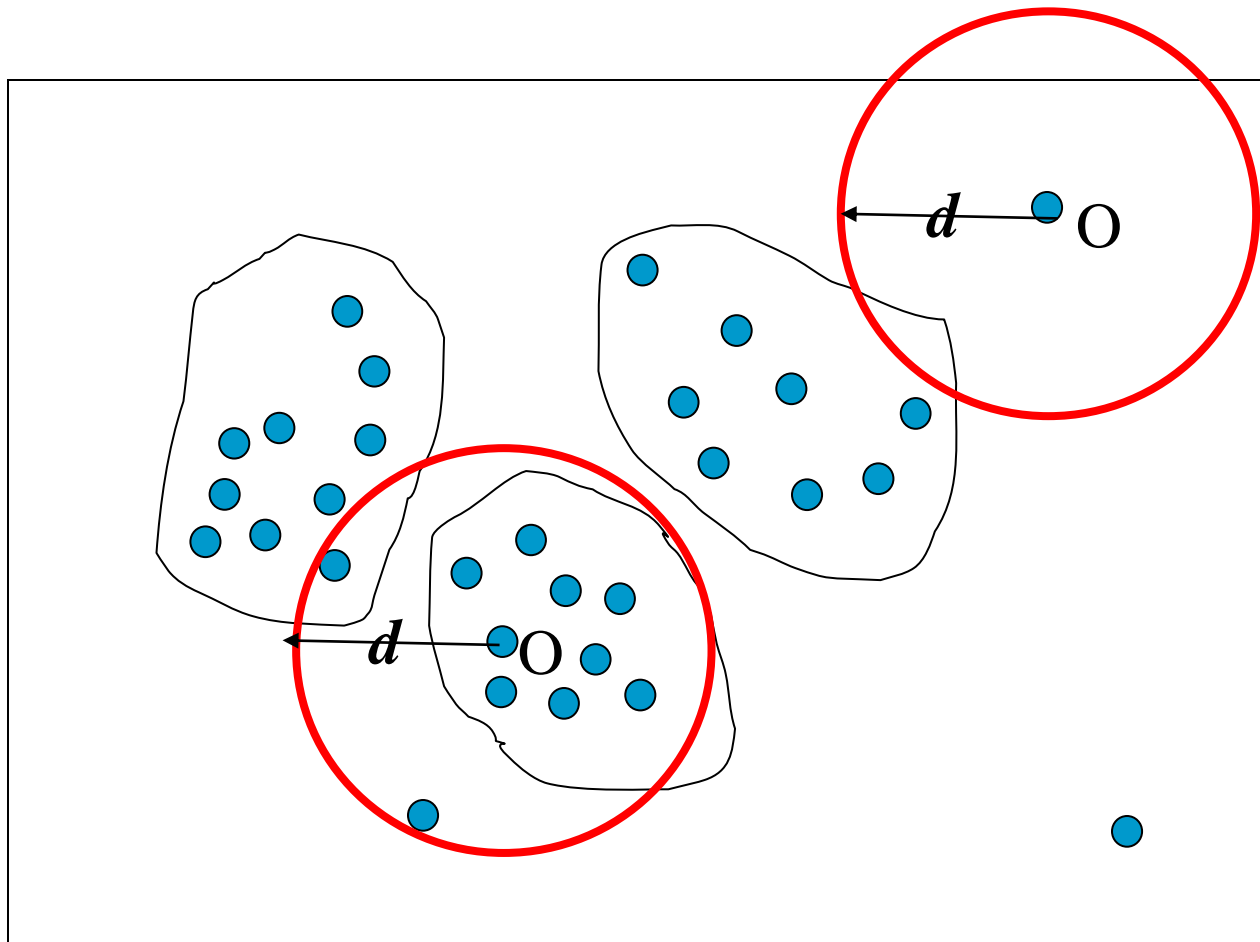


■ Drawbacks

- Most tests are for single attribute
- In many cases, data distribution may not be known
- Require input parameters

Outlier Detection: Distance-Based Approach

- Introduced to overcome the main limitations imposed by statistical methods
 - We need multi-dimensional analysis without knowing data distribution, no statistical test
- Distance-based outlier: A $DB(p, d)$ -outlier is an object O in a dataset T such that at least a fraction p of the objects in T lies at a distance greater than d from O
- Algorithms for mining distance-based outliers
 - Index-based algorithm
 - Cell-based algorithm



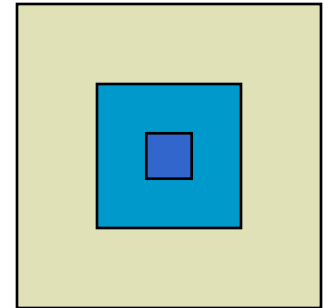
Index-based Algorithm

- Search for neighbors of each object O within radius d around the object
- Multi-dimensional index structure, e.g. kd tree
- Max number of objects within d -neighborhood of each outlier
- The worst case $O(kn^2)$
 k dimensionality, n number of objects
- Drawbacks:
 - Tree building is computational intensive

Cell-based Algorithm

■ Cell partition

- Partition data space into cells, side length $d/2k^{1/2}$
- Each cell has two layers around it
 - First layer one cell thick
 - Second layer $(2k^{1/2} - 1)$ cells thick

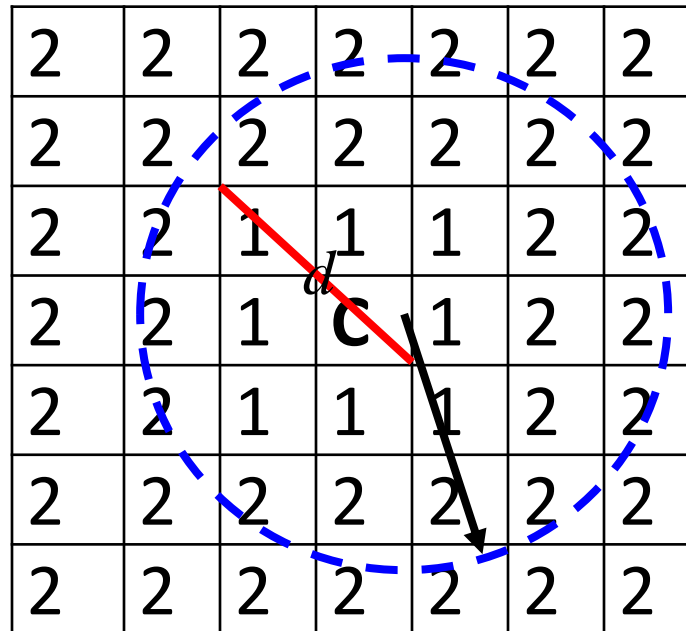


■ Outlier detection

- If count of the first layer $>M$, no outlier in this cell
- If count of the second layer $\leq M$, all objects are outliers
- Otherwise, examine every object in the cell

■ Good for large-scale data set

Cell-based Algorithm



side width = $d/2\sqrt{2}$

- $k=2$, k dimensionality
- Layer-1 property: given any point x in cell C , and any point y in layer-1 cell, $\text{dist}(x,y) \leq d$
- Layer-2 property: given any point x in cell C , and any point y outside layer-2 cell, $\text{dist}(x,y) > d$

Outlier Detection: Deviation-Based Approach

- Identifies outliers by examining the main characteristics of objects in a group
- Objects that “deviate” from this description are considered outliers
- Sequential exception technique
 - Simulates the way in which humans can distinguish unusual objects from among a series of supposedly like objects
 - A sequence of subsets, $\{S_1, S_2, \dots, S_m\}$, $S_{j-1} \subset S_j$
 - Calculate the dissimilarity difference between the current subset with the proceeding subset in the sequence

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Summary

- **Cluster analysis** groups objects based on their **similarity** and has wide applications
- Measure of similarity can be computed for **various types of data**
- Clustering algorithms can be **categorized** into partitioning methods, hierarchical methods, density-based methods, grid-based methods
- **Outlier detection** and analysis are very useful for fraud detection, etc. and can be performed by statistical, distance-based or deviation-based approaches

Summary

- Considerable progress has been made in scalable clustering methods
 - Partitioning: k-means, k-medoids, CLARANS
 - Hierarchical: BIRCH, ROCK, CHAMELEON
 - Density-based: DBSCAN, OPTICS, DenClue
 - Grid-based: STING, WaveCluster, CLIQUE
 - Model-based: EM, Fuzzy K-Means
 - Frequent pattern-based: pCluster
 - Constraint-based: COD, constrained-clustering