On Pilot Design for Wideband Sparse MIMO Channels

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February 12, 2016

1 Channel Model

Consider the wideband MIMO channel characterized by impulse response $\{\boldsymbol{H}[l]\}_{l=0}^{L-1}$, where $\boldsymbol{H} \in \mathbb{C}^{N_{\mathrm{r}} \times N_{\mathrm{t}}}$ and where $N_{\mathrm{t}}, N_{\mathrm{r}}, L$ denote the number of transmit antennas, receive antennas, and taps, respectively. If $\boldsymbol{t}[n] \in \mathbb{C}^{N_{\mathrm{t}}}$ is transmitted over the channel, then the receiver sees $\boldsymbol{y}[n] = \boldsymbol{z}[n] + \boldsymbol{w}[n]$ with

$$\boldsymbol{z}[n] = \sum_{l=0}^{L-1} \boldsymbol{H}[l]\boldsymbol{t}[n-l] \tag{1}$$

and AWGN $\boldsymbol{w}[n]$. Likewise, if the N-symbol sequence $\boldsymbol{T} \in \mathbb{C}^{N_{r} \times N}$ is transmitted, the receiver sees $\boldsymbol{Y} = \boldsymbol{Z} + \boldsymbol{W}$ with

$$Z = \begin{bmatrix} \boldsymbol{H}[0] & \boldsymbol{H}[1] & \cdots & \boldsymbol{H}[L-1] \end{bmatrix} \begin{bmatrix} \boldsymbol{T}\boldsymbol{J}_0 \\ \boldsymbol{T}\boldsymbol{J}_1 \\ \vdots \\ \boldsymbol{T}\boldsymbol{J}_{L-1} \end{bmatrix}$$
(2)

and AWGN W, where right multiplication by J_l circularly shifts the columns right by l places. Let us now define the virtual channel coefficients

$$X[l] \triangleq B_{N_{\rm r}}^* H[l] B_{N_{\rm t}}, \tag{3}$$

where

$$\boldsymbol{B}_{N} \triangleq \boldsymbol{F}_{\sqrt{N}} \otimes \boldsymbol{F}_{\sqrt{N}}, \tag{4}$$

is the steering vector matrix for an N-antenna uniform square array and F_N is the unitary N-DFT matrix. Note that B_N is symmetric and unitary, so that

$$\boldsymbol{H}[l] \triangleq \boldsymbol{B}_{N_{r}} \boldsymbol{X}[l] \boldsymbol{B}_{N_{t}}^{*}, \tag{5}$$

The virtual channel coefficients $\{X[l]\}$ are expected to be sparse, which can be exploited in channel estimation. Thus, we rewrite (2) in terms of $\{X[l]\}$ as

$$Z = B_{N_{t}} [X[0] \ X[1] \cdots X[L-1]] \begin{bmatrix} B_{N_{r}}^{*} & & \\ & B_{N_{r}}^{*} & \\ & & \ddots & \\ & & B_{N_{r}}^{*} \end{bmatrix} \begin{bmatrix} TJ_{0} \\ TJ_{1} \\ \vdots \\ TJ_{L-1} \end{bmatrix}.$$

$$= I_{L} \otimes B_{N_{r}}^{*} \qquad \triangleq \widetilde{T}$$

$$(6)$$

2 Pilot Design

We are interested in a pilot sequence T for which:

- 1. \tilde{T} is well conditioned,
- 2. there is a fast way of computing Z from a given X.

Towards this aim, we propose to construct ${\pmb T}$ such that $[{\pmb T}]_{n,m} = t[\langle nL + N_{{\pmb N}/{\pmb N}} \rangle],$

$$[T]_{n,m} = t[\langle nL + M_{NN} \rangle], \tag{7}$$

where $N, \sqrt{N_t}, \sqrt{N_r}$ are all powers of two, and where $\{t[n]\}_{n=0}^{N-1}$ is one of several possibilities:

- a) random BPSK,
- b) Chu sequence, i.e., $t[n] = \exp(j\pi n(n+1)/N)$ for n = 0...N-1,
- c) all-pass sequence, i.e., $t = F_N a$ for any a with $|a_n| = 1$.

The reasoning behind (7) is that the rows of \widetilde{T} will consist of the first $N_{\rm t}L$ circular shifts of the sequence $t \triangleq [t[0] \dots t[N-1]]$, and thus multiplication by \widetilde{T} can be accomplished using fast convolution (i.e., two N-FFTs). Similarly, the operations involving $B_{N_{\rm t}}$ and $B_{N_{\rm r}}$ can also be accomplished using FFTs.

Figure 1 plots the singular values for one realization of \tilde{T} under several choices of t. For reference, it also shows the singular values for one realization of \tilde{T} with i.i.d. Gaussian entries (i.e., no convolution structure). The figure shows that the convolution matrix \tilde{T} constructed using random BPSK t has a similar spectrum to the i.i.d. Gaussian \tilde{T} , which is widely considered as an "isometry" in the field of compressive sensing. The figure also shows that the spectrum resulting from all-pass t has a flat singular-value spectrum, as expected. The practical disadvantage of the all-pass sequence is that the elements of t are far from constant modulus, which implies a high peak-to-average power ratio. Finally, the figure shows that the Chu sequence has a singular value spectrum close to the allpass sequence, with the advantage of constant modulus t[n].

3 Fast Implementation



We now provide some details on the fast implementation of (6). Recall that, due to the construction (7), the first N_t rows in \widetilde{T} contain the $\{0, L, 2L, ..., (N_t - 1)L\}$ shifts of t. Likewise, the next N_t rows in \widetilde{T} contain the $\{1, L + 1, 2L + 1, ..., (N_t - 1)L + 1\}$ shifts of t, and the last N_t rows in \widetilde{T} contain the $\{L - 1, 2L - 1, 3L - 1, ..., N_tL - 1\}$ shifts of t. Altogether, the rows of $\widetilde{T} \in \mathbb{C}^{N_tL \times N}$ contain the $\{0, 1, 2, ..., N_tL\}$ shifts of t. We can thus re-order the rows in \widetilde{T} to make \widetilde{T} a Toeplitz matrix, which we will denote by \overline{T} in the sequel. Doing so yields

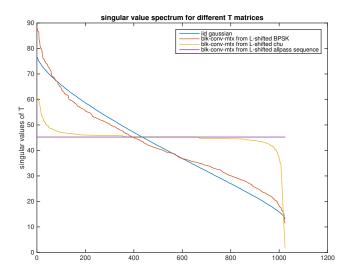


Figure 1: Singular values of \widetilde{T} for various constructions of t.

where \boldsymbol{b}_i is the *i*th column of $\boldsymbol{B}_{N_r}^{\mathsf{T}}*$ and $\boldsymbol{x}_i[l]$ is the *i*th column of $\boldsymbol{X}[l]$. For the last equality above, we exploited the fact $(\boldsymbol{A}\otimes\boldsymbol{B})^{\mathsf{T}}=\boldsymbol{A}^{\mathsf{T}}\otimes\boldsymbol{B}^{\mathsf{T}}$ and the symmetry of $\boldsymbol{B}_{N_r}^*$.

The fast implementation of (10) is now visible. First, for any $\mathbf{v} \in \mathbb{C}^{LN_t}$, notice that

$$(\boldsymbol{B}_{N_{t}}^{*} \otimes \boldsymbol{I}_{L})\boldsymbol{v} = \operatorname{vec}(\boldsymbol{V}\boldsymbol{B}_{N_{t}}^{*}) = \operatorname{vec}([\boldsymbol{B}_{N_{t}}\boldsymbol{V}^{\mathsf{H}}]^{\mathsf{H}}), \tag{11}$$

where $V \in \mathbb{C}^{L \times N_t}$ is the column-wise matricization of v. Furthermore, for any $u \in \mathbb{C}^{N_t}$, notice that

$$\boldsymbol{B}_{N_{\mathrm{t}}}\boldsymbol{u} = (\boldsymbol{F}_{\sqrt{N_{\mathrm{t}}}} \otimes \boldsymbol{F}_{\sqrt{N_{\mathrm{t}}}})\boldsymbol{u} = \operatorname{vec}(\boldsymbol{F}_{\sqrt{N_{\mathrm{t}}}}\boldsymbol{U}\boldsymbol{F}_{\sqrt{N_{\mathrm{t}}}}),$$
(12)

where $U \in \mathbb{C}^{\sqrt{N_{\mathrm{t}}} \times \sqrt{N_{\mathrm{t}}}}$ is the column-wise matricization of u. Thus the multiplication $(B_{N_{\mathrm{t}}}^* \otimes I_L)\overline{X}$ in (10) can be accomplished using $\sqrt{N_{\mathrm{t}}}$ -point FFTs. The result of that multiplication is then left-multiplied by $\overline{T}^{\mathsf{T}}$, which can be performed via fast convolution using N-point FFTs. And the result of that multiplication is then left-multiplied by $B_{N_{\mathrm{t}}}$, which can be performed as in (12) using $\sqrt{N_{\mathrm{t}}}$ -point FFTs. [Should count how many total FFTs of each length.]

If the above complexity is still too high, it can be reduced by choosing $\mathbf{t} = [1, 0, 0, ..., 0]$, which turns $\overline{\mathbf{T}}$ into an $N_{\rm t}L \times N$ identity matrix. The cost is a drastic reduction in SNR. Still, it may be worth investigating as an option.