Cheatsheet Probability and Statistics

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Mathematical framework

Probability space

Def. 1.1. The set Ω is called the sample space. An element $\omega \in \Omega$ is called an outcome or elementary experiment.

Ex. 1.1. Throw of a die : $\Omega = \{1, 2, 3, 4, 5, 6\}$

Def. 1.2. A sigma-algebra is a subset $\mathcal{F} \subset \mathcal{P}(\Omega)$ satisfying the following properties:

P1. $\Omega \in \mathcal{F}$

P2. $A \in \mathcal{F} \Rightarrow A^c \in \mathcal{F}$: If A is an event, "not A" is also an event.

P3. $A_1, A_2, \ldots \in \mathcal{F} \Rightarrow \bigcup_{i=1}^{\infty} A_i \in \mathcal{F} : \text{if } A_1, A_2, \ldots \text{ are events,}$ then " A_1 or A_2 or ..." is an event

Ex. 1.2. Examples of sigma-algebras for $\Omega = \{1, 2, 3, 4, 5, 6\}$

• $\mathcal{F} = \{\emptyset, \{1, 2, 3, 4, 5, 6\}\}$

• $\mathcal{F} = \mathcal{P}(\Omega)$

• $\mathcal{F} = \{\emptyset, \{1, 2\}, \{3, 4, 5, 6\}, \{1, 2, 3, 4, 5, 6\}\}$

Non examples of sigma-algebras for $\Omega = \{1, 2, 3, 4, 5, 6\}$:

• $\mathcal{F} = \{\{1, 2, 3, 4, 5, 6\}\}\ : P2 \text{ is not satisfied}$

• $\mathcal{F} = \{\emptyset, \{1, 2, 3\}, \{4, 5, 6\}, \{1\}, \{2, 3, 4, 5, 6\}, \Omega\} : \mathbf{P3} \text{ is}$ not satisfied

Def. 1.3. Let Ω a sample space and \mathcal{F} a sigma-algebra. A | 1.3 Properties of Events **probability measure** on (Ω, \mathcal{F}) is a map

$$\mathbb{P}: \mathcal{F} \to [0,1], \quad A \mapsto \mathbb{P}[A]$$

that satisfies the properties

P1. $\mathbb{P}[\Omega] = 1$

P2. (countable additivity) $\mathbb{P}[A] = \sum_{i=1}^{\infty} \mathbb{P}[A_i]$ if A = $\bigcup_{i=1}^{\infty} A_i \text{ (disjoint union)}$

Int. A probability measure is a map that associates to each event a number in [0, 1]

Ex. 1.3. For $\Omega = \{1, 2, 3, 4, 5, 6\}$ and $\mathcal{F} = \mathcal{P}(\Omega)$, the mapping $\mathbb{P}: \mathcal{F} \to [0,1]$ defined by

$$\forall A \in \mathcal{F} \quad \mathbb{P}[A] = \frac{|A|}{6}$$

is a probability measure on (Ω, \mathcal{F}) .

Def. 1.4. Let Ω a sample space, \mathcal{F} a sigma-algebra and \mathbb{P} a probability measure. The triple $(\Omega, \mathcal{F}, \mathbb{P})$ is called a **proba**bility space.

Int. To construct a probabilistic model, we give

- a sample space Ω : all the possible outcomes of the experiment
- a sigma-algebra $\mathcal{F} \subset \mathcal{P}(\Omega)$: the set of events
- a probability measure \mathbb{P} : gives a number in [0,1] to every event

Def. 1.5. Let $\omega \in \Omega$ (a possible outcome). Let A be an event. We say the event A occurs (does not occur) (for ω) if $\omega \in A \ (\omega \notin A)$.

Examples of probability spaces

Def. 1.6. Let Ω be a finite sample space. The Laplace **model** on Ω is the triple $(\Omega, \mathcal{F}, \mathbb{P})$, where $\mathcal{F} = \mathcal{P}(\Omega)$ and $\mathbb{P}: \mathcal{F} \to [0,1]$ is defined by

$$\forall A \in \mathcal{F} \quad P[A] = \frac{|A|}{|\Omega|}$$

Prop 1.1. (Consequences of definition 1.2). Let \mathcal{F} be a sigma-algebra on Ω . We have

P4. $\emptyset \in \mathcal{F}$

P5. $A_1, A_2, \ldots \in \mathcal{F} \Rightarrow \bigcap_{i=1}^{\infty} A_i \in \mathcal{F}$

P6. $A, B \in \mathcal{F} \Rightarrow A \cup B \in \mathcal{F}$

P7. $A, B \in \mathcal{F} \Rightarrow A \cap B \in \mathcal{F}$

Event	Graphical representation	Probab. interpretation
A^c	A^{c} A	A does not occur
$A \cap B$	$\stackrel{A}{\bigoplus}$	$A \ {f and} \ B \ {f occur}$
$A \cup B$	AB	$A ext{ or } B ext{ occurs}$
$A\Delta B$	$\stackrel{A}{\bigoplus}$	one and only one of A or B occurs

Figure 1: Representation of set operations

Relation	Graphical representation	Probab. interpretation
$A \subset B$	A B	If A occurs, then B occurs
$A \cap B = \emptyset$		A and B cannot occur at the same time
$\Omega = A_1 \cup A_2 \cup A_3 \text{ with }$ $A_1, A_2, A_3 \text{ pairwise disjoint }$	Ω A_1 A_3 A_2	for each outcome ω , one and only one of the events A_1 , A_2 , A_3 is satisfied.

Figure 2: Representation of set relations

1.4 Properties of probability measures

Prop 1.2. (Consequences of definition 1.3). Let \mathbb{P} be a probability measure on (Ω, \mathcal{F}) .

P3. We have $\mathbb{P}[\emptyset] = 0$

P4. (additivity) Let $k \geq 1$, let A_1, \ldots, A_k be k pairwise disjoint events, then

$$\mathbb{P}\left[A_1 \cup \ldots \cup A_k\right] = \mathbb{P}\left[A_1\right] + \ldots + \mathbb{P}\left[A_k\right]$$

P5. Let A be an event, then

$$\mathbb{P}\left[A^c\right] = 1 - \mathbb{P}\left[A\right]$$

P6. If A and B are two events (not necessarily disjoint), then

$$\mathbb{P}\left[A \cup B\right] = \mathbb{P}\left[A\right] + \mathbb{P}\left[B\right] - \mathbb{P}\left[A \ capB\right]$$

Prop 1.3. (Monotonicity). Let $A, B \in \mathcal{F}$, then

$$A \subset B \Rightarrow \mathbb{P}[A] \leq \mathbb{P}[B]$$

Prop 1.4. (Union bound).Let $A_1, A_2, ...$ be a sequence of events (not necessarily disjoint), then we have

$$\mathbb{P}\left[\bigcup_{i=1}^{\infty}A_{i}\right]\leq\sum_{i=1}^{\infty}\mathbb{P}\left[A_{i}\right]$$

Union bound also applies to a finite collection of events.

Prop 1.5. Let (A_n) be an increasing sequence of events (i.e. $\forall n \ A_n \subset A_{n+1}$). Then

$$\lim_{n\to\infty} \mathbb{P}[A_n] = \mathbb{P}\left[\bigcup_{n=1}^{\infty} \infty A_n\right]$$
. increasing limit

Let (B_n) be a decreasing sequence of events (i.e. $\forall n \ B_n \supset B_{n+1}$). Then

$$\lim_{n\to\infty} \mathbb{P}[B_n] = \mathbb{P}\left[\bigcap_{n=1}^{\infty} \infty B_n\right]$$
. decreasing limit

1.5 Conditional probabilities

Def. 1.7. Let $(\Omega, \mathcal{F}, \mathbb{P})$ be some probability space. Let A, B be two events with $\mathbb{P}[B] > 0$. The **conditional probability of** A **given** B is defined by

$$\mathbb{P}\left[A|B\right] = \frac{A \cap B}{B}$$

Ex. 1.4. We consider the probability space $(\Omega, \mathcal{F}, \mathbb{P})$ corresponding to the throw of one die. Let $A = \{1, 2, 3\}$ and $B = \{2, 4, 6\}$. Then

$$\mathbb{P}[A|B] = \frac{\mathbb{P}[A \cap B]}{\mathbb{P}[B]} = \frac{\frac{1}{6}}{\frac{1}{2}} = \frac{1}{3}$$

Prop 1.6. Let $(\Omega, \mathcal{F}, \mathbb{P})$ be some probability space. Let B be an event with positive probability. Then $\mathbb{P}[\cdot, B]$ is a probability measure on Ω .

Prop 1.7. (Formula of total probability). Let B_1, \ldots, B_n be a partition¹ of the sample space Ω with $\mathbb{P}[B_i] > 0$ for every $i \leq i \leq n$. Then one has

$$\forall A \in \mathcal{F} \quad \mathbb{P}[A] = \sum_{i=1}^{n} \mathbb{P}[A|B_i] \, \mathbb{P}[B_i]$$

Prop 1.8. (Bayes formula). Let $B_1, \ldots, B_n \in \mathcal{F}$ be a partition of Ω with $\mathbb{P}[B_i] > 0 \ \forall i$. For every event A with $\mathbb{P}[A] > 0$ we have

$$\forall i = 1, \dots, n \quad \mathbb{P}\left[B_i | A\right] = \frac{\mathbb{P}\left[A | B_i\right] \mathbb{P}\left[B_i\right]}{\sum_{j=1}^n \mathbb{P}\left[A | B_j\right] \mathbb{P}\left[B_j\right]}$$

¹i.e. $\Omega = B_1 \cup \ldots \cup B_n$ and the events are pairwise disjoint.