

Table 1: Performance of the planners* in task (stack ?table ?pile), in the *stripped tower* domain.

Problem	Total time (s)			Memory (MB)			Developed states			Plan length		
	Mp	FF	SBP	Mp	FF	SBP	Mp	FF	SBP	Mp	FF	SBP
p10	0.4	0.0	0.2	27.6	5.4	6.9	95	106	71	39	39	39
p12	0.8	0.0	0.3	37.8	6.2	9.3	196	140	88	48	49	48
p14	0.1	0.0	0.5	47.1	6.7	12.6	407	177	103	56	57	55
p16	0.2	0.1	0.8	61.8	7.7	17.0	766	217	120	63	63	64
p18	0.4	0.1	1.2	79.6	8.5	23.4	1107	263	136	72	73	72
p20	0.7	0.1	1.4	102.1	9.6	22.9	1418	310	152	80	80	80
p22	1.0	0.2	1.9	120.4	10.6	27.5	1160	364	168	87	87	88
p24	1.5	0.4	2.6	151.8	11.7	30.5	1428	422	183	96	97	95
p26	2.2	0.3	3.2	196.2	13.0	36.7	2026	483	199	104	105	103
p28	3.2	0.7	4.2	255.5	14.6	40.5	2832	548	215	112	113	111
p30	4.2	0.6	5.5	278.6	15.9	48.7	2355	616	232	119	119	120
p32	6.2	0.8	6.9	351.6	17.5	54.7	4009	690	248	128	129	128
p34	8.2	0.1	8.9	433.5	19.1	65.3	4575	766	263	135	135	135
p36	11.1	0.1	11.8	534.1	21.0	76.6	5884	847	280	143	143	144
p38	14.9	0.1	15.1	653.7	22.8	85.8	7288	932	295	151	151	151
p40	19.6	0.1	20.0	785.8	24.7	98.6	9276	1020	311	160	160	159
p42	23.8	0.2	26.5	867.3	26.8	117.4	8054	1113	328	168	168	168
p44	30.8	0.2	34.2	1.0k	28.9	137.1	9922	1210	344	176	176	176
p46	39.8	0.3	45.1	1.2k	31.0	152.4	12124	1311	360	184	184	184
p48	48.5	0.3	60.1	1.4k	33.4	177.6	12589	1416	376	192	192	192
p50	59.9	0.4	79.2	1.5k	35.8	198.2	13106	1526	392	199	199	200

* Mp (MADAGASCAR), FF (Fast-Forward), SBP (Schema-Based Planner). The outperformed results in terms of the developed nodes are shown in bold.