

Table 1: Performance of the planners* in task (clear ?table ?bin), in the *robotic_arm* domain.

Problem	Total time (s)			Memory (MB)			Developed states			Plan length		
	Mp	FF	SBP	Mp	FF	SBP	Mp	FF	SBP	Mp	FF	SBP
p10	0.00	0.00	0.84	24.4	3.8	2.0	806	129	62	41	43	41
p11	0.01	0.00	0.92	24.6	3.8	2.2	827	145	68	45	47	45
p12	0.01	0.00	0.11	24.6	3.8	2.2	691	95	72	48	48	48
p13	0.00	0.00	0.10	26.9	3.8	2.6	1204	103	78	52	52	52
p14	0.01	0.00	0.11	27.2	3.8	2.9	1243	111	84	56	56	56
p15	0.02	0.00	0.12	29.8	4.0	3.3	1847	201	92	61	63	61
p16	0.02	0.00	0.15	29.8	4.0	3.6	1727	213	98	65	67	65
p17	0.03	0.00	0.16	30.0	4.0	3.9	1796	227	104	69	71	69
p18	0.03	0.00	0.16	34.6	4.0	4.2	2395	243	110	73	75	73
p19	0.04	0.00	0.18	34.6	4.0	4.2	2456	255	116	77	79	77
p20	0.04	0.00	0.18	37.5	4.0	4.6	3125	269	122	81	83	81
p21	0.05	0.00	0.21	35.7	4.0	5.0	3259	285	128	85	87	85
p22	0.05	0.00	0.22	38.0	4.0	5.2	3295	175	132	88	88	88
p23	0.07	0.00	0.24	40.8	4.3	5.7	3962	313	140	93	95	93
p24	0.06	0.00	0.25	41.4	4.3	6.1	3977	325	146	97	99	97
p25	0.09	0.00	0.27	44.5	4.3	6.4	5150	199	150	100	100	100
p26	0.09	0.00	0.30	43.7	4.3	6.9	5356	353	158	105	107	105
p27	0.10	0.00	0.31	46.2	4.3	7.5	5186	215	162	108	108	108
p28	0.13	0.00	0.34	47.8	4.3	7.3	6253	383	170	113	115	113
p29	0.12	0.00	0.37	47.0	4.3	7.8	6228	397	176	117	119	117

* Mp (MADAGASCAR), FF (Fast-Forward), SBP (Schema-Based Planner). The outperformed results in terms of the developed nodes are shown in bold.