# Final Project Report: Parallel SSSP Update Using MPI, OpenMP, and METIS

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Paper: A Parallel Algorithm Template for Updating Single-Source Shortest Paths in Large-Scale Dynamic Networks

#### 1. Introduction

This project is based on the paper titled "A Parallel Algorithm Template for Updating Single-Source Shortest Paths in Large-Scale Dynamic Networks". The paper proposes a highly parallel template for updating SSSP paths efficiently after dynamic changes in the network, enabling scalable, real-time updates in large graphs.

The selected paper proposes a framework that combines work-efficient, theoretically optimal techniques with practical considerations to deliver scalable performance. Our implementation leverages this template using MPI for inter-node communication, OpenMP for intra-node shared-memory parallelism, and METIS for efficient graph partitioning.

#### 2. Tools and Technologies

- MPI (Message Passing Interface): For inter-node communication across a distributed memory system.
- OpenMP (Open Multi-Processing): For parallelism within individual nodes.
- METIS: For graph partitioning to optimize load distribution across MPI processes.
- **Dataset Used:** mdual.graph a real-world graph used to test performance and scalability.

# 3. Problem Statement

The goal is to efficiently update the shortest paths from a source node in a large-scale graph upon dynamic changes (e.g., edge insertions or deletions). Sequential algorithms often re-compute the SSSP from scratch, which is inefficient. This project addresses the need for an incremental and scalable parallel approach.

# 4. Parallelization Strategy

- Graph Partitioning (METIS): The graph was partitioned using METIS to distribute subgraphs across MPI processes. This reduced inter-process communication and ensured load balance.
- Inter-node Parallelism (MPI): Each MPI process handled updates on a partition of the graph, communicating frontier changes with neighboring processes.
- Intra-node Parallelism (OpenMP): Within each MPI process, OpenMP was used to parallelize relaxations and updates of vertex distances.

# 5. Implementation Overview

- Read the partitioned graph using METIS.
- Each MPI process loads its subgraph and initializes local SSSP data structures.
- Upon an edge update, only affected nodes are propagated using a frontier-based model.
- OpenMP parallelizes the inner loop of vertex relaxations.
- Frontier updates are communicated via MPI.

### 6. Experimental Setup

- Cluster: 4-node MPI cluster with shared memory support.
- **Graph**: mdual.graph
- Metrics: Execution time, speedup, scalability (weak and strong), partition balance.

#### 7. Challenges and Solutions

- Challenge: Communication overhead among MPI processes.
  - Solution: Optimized graph partitioning and minimized inter-process frontier exchanges.
- Challenge: Synchronization between MPI and OpenMP regions.

• Solution: Carefully structured parallel regions and used barriers where necessary.

## 8. GitHub Repository

The project code, presentation, datasets, and documentation are maintained at: **GitHub:** https://github.com/molarmuaz/PDC\_PROJECT

#### Features:

- Source code for MPI, OpenMP, METIS integration.
- Experimental data and plots.
- Slides and report documentation.

#### 9. Conclusion

We successfully implemented and demonstrated a parallel algorithm for updating SSSP paths using MPI, OpenMP, and METIS. The approach is scalable, efficient, and adaptable to real-time dynamic graphs. This project validates the paper's claim that theoretically efficient parallel graph algorithms can be practical and scalable in real-world settings.