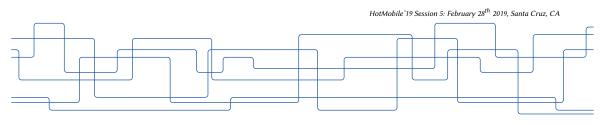


# **EdgeDroid**

An Experimental Approach to Benchmarking Human-in-the-Loop Applications

M. Olguín Muñoz<sup>†</sup>, J. Wang<sup>‡</sup>, M. Satyanarayanan<sup>‡</sup> and J. Gross<sup>†</sup>

Sweden





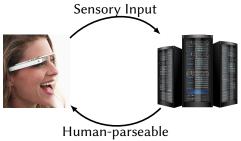
















Feedback

Need to understand and optimize these applications:

- ► How do they interact with each other?
- ► How do they interact with infrastructure?
- ► How do they scale?

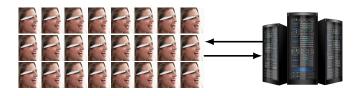
With which methodology can we study these behaviors?



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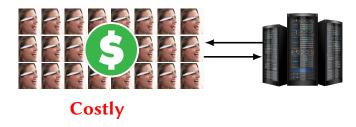
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With which methodology can we study these behaviors?



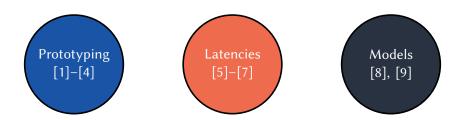
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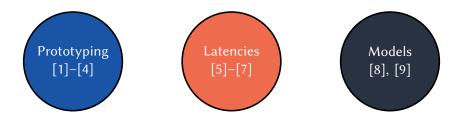
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With which methodology can we study these behaviors?



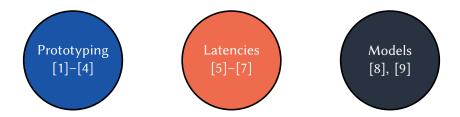
Costly, poor repeatability





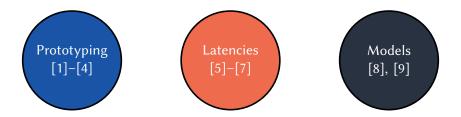
### **Our Contributions**

► A methodology for benchmarking human-in-the-loop applications.



#### **Our Contributions**

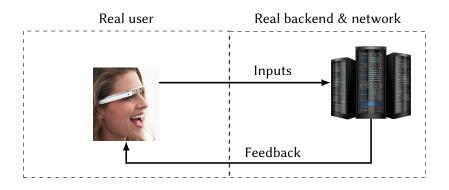
- ► A methodology for benchmarking human-in-the-loop applications.
- ► EdgeDroid: A benchmarking tool-suite.



#### **Our Contributions**

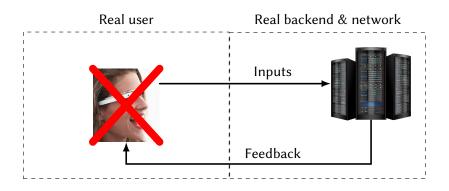
- ► A methodology for benchmarking human-in-the-loop applications.
- ► EdgeDroid: A benchmarking tool-suite.
- Experiments and measurements which show the effectiveness of the approach.

# Approach



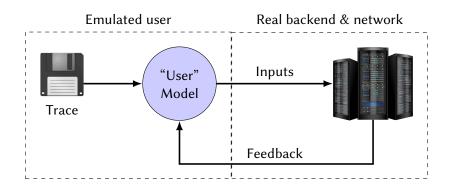
Benchmarking human-in-the-loop applications is  $\mathsf{HARD}$ 

# Approach



What if we could do away with the human users?

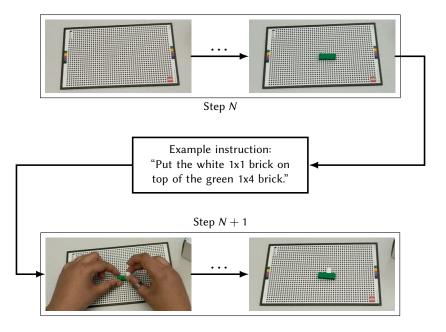
# Approach



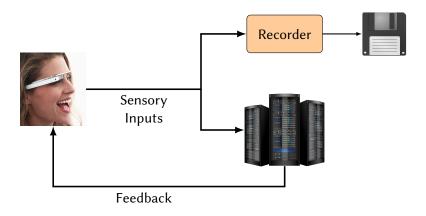
What if we could do away with the human users?

Repeatable, scalable!

# Example: Task Guidance Wearable Cognitive Assitance, LEGO [1]



# Tracing





# Trace Replay

### Non-trivial Challenge

- ► Changes in system responsiveness require adapting trace.
- System delays affect user behavior as well.

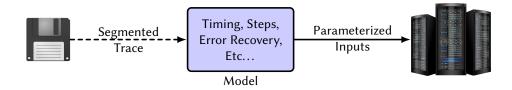
## Trace Replay

### Non-trivial Challenge

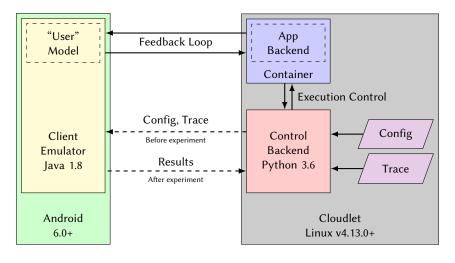
- Changes in system responsiveness require adapting trace.
- System delays affect user behavior as well.

### Our Approach

- Segment trace into logical "steps".
- Controlled replay of steps.



# Implementation: EdgeDroid



https://github.com/molguin92/EdgeDroid

### **Evaluation**

# **Key purpose:**

Demonstrate utility of EdgeDroid.

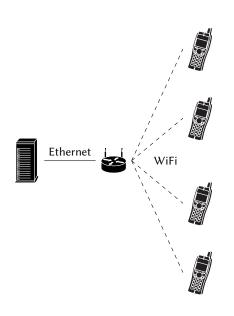
# **Evaluation: Setup**

### **Application & Scenarios**



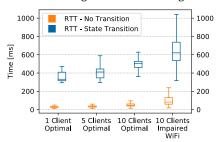
**LEGO Assistant** 

- ► Three *optimal* scenarios with 1, 5 and 10 devices.
- Weakened wireless link with 10 devices.
- ► KPI: Round-Trip Time (RTT).

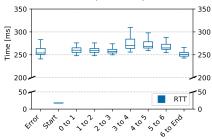


### **Use Cases**

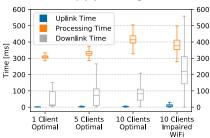
State change vs. no state change.



RTT by task step.



#### Times by pipeline segments.



### Conclusions

#### **Future Work**

- ► User Model.
- ► Other types of Applications.

### Summary

- ▶ Need to study the scaling of Human-in-the-Loop applications.
  - Difficult due to human users.
- ► Methodology + tool suite for benchmarking:
  - EdgeDroid
  - ► Trace based.
  - Model of human behavior.
- Results which show the utility of EdgeDroid.



## Thank you.

#### Contact

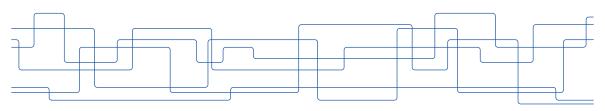
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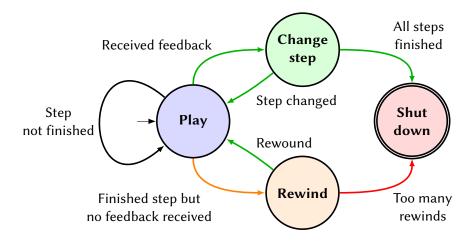


## Requirements

- Generate realistic, high-dimensional, real-time inputs.
- Correctly and realistically react to feedback.
- ► KPI: Delays.

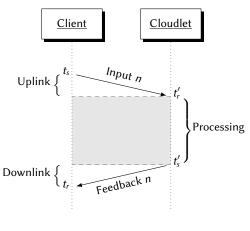
Trace of pre-recorded inputs & a model of user behavior

### User Model



Future work: more elaborate models.

## Timestamping



Clocks are synchronized previous to the experiment.

Timestamps at key points to obtain:

$$\Delta T_{\rm up} = t_r' - t_s \tag{1}$$

$$\Delta T_{\text{proc}} = t_s' - t_r' \tag{2}$$

$$\Delta T_{\text{down}} = t_r - t_s' \tag{3}$$

$$\Delta T_{\text{total}} = \Delta T_{\text{up}} + \Delta T_{\text{proc}} + \Delta T_{\text{down}} = t_r - t_s \tag{4}$$

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