

Active Learning in the Predict-then-Optimize Framework: A Margin-Based Approach

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Build a prediction model to predict unknown parameters

Prediction



Decision

Customers' preference



Product recommendation

Demand



Inventory level

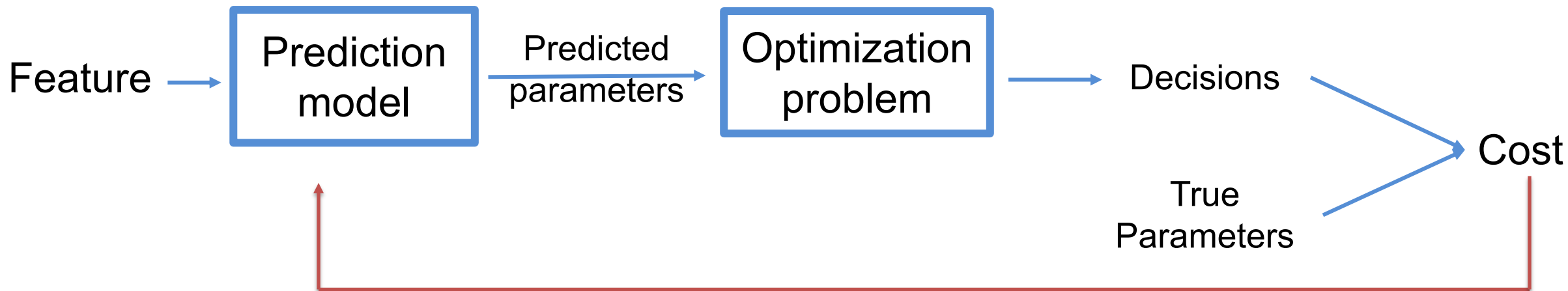
Price elasticity



Optimal prices

Predict-then-optimize framework

- Consider a stochastic optimization problem with unknown parameters:



Higher prediction accuracy $\xrightarrow{?}$ Lower cost

Data collection in predict-then-optimize framework

Realization of one sample: feature + parameters (**labels** of the samples)



Acquiring the labels for one sample could be very expensive.

In a personalized pricing problem, to realize the purchase probability under all prices:

- Customer investigation
 - Price trials
-
- How can we minimize the number of labels acquired while learning an effective prediction model?
 - Select **representative** samples to acquire their labels
-
- Active learning + predict-then-optimize framework

Agenda

- Information gathering process for predict-then-optimize framework
- **Smart predict-then-optimize loss (SPO) and preliminaries**
- Theoretical motivation for margin-based algorithm
- Algorithm
- Analysis
- Numerical Experiments

Predict-then-optimize framework

- Optimization problem:

$$\min_{w \in S} \mathbb{E}_{c \sim D_X} [c^T w | x] = \min_{w \in S} \mathbb{E}_{c \sim D_X} [c^T | x] w$$

- Suppose we have access to the optimization oracle:

$$w^*(c) = \arg \min_{w \in S} c^T w$$

- SPO (Smart Predict-then-optimize) loss function:

$$\ell_{SPO}(\hat{c}, c) := c^T w^*(\hat{c}) - c^T w^*(c)$$

- Predictor $h \in \mathcal{H}$

- SPO Risk:

$$R_{SPO}(h) = \mathbb{E}_{x, c \sim D} [\ell_{SPO}(h(x), c)]$$

- Best predictor:

$$h^* := \arg \min_{h \in \mathcal{H}} R_{SPO}(h)$$

Constructing the training set

- During the data collection process:
 - Feature x_i is readily available
 - Cost vector c_i is expensive
 - Large label cost
 - Time-consuming label process
- How can we minimize the number of labels acquired while achieving a small SPO risk?

Active learning

From iteration 1 to T , at each iteration t :

- Given one unlabeled sample with feature x_t from some unknown distribution
- Decide whether to acquire the label c_t of this sample x_t

– Goal: Use a small number of inquiries to achieve good performance

min: Number of acquired labels after T iterations

subject to: The final prediction model after T iterations has a good performance

- **Label complexity:** The minimum number of inquiries we need to make to attain performance at a given level

Goal of active learning

- Traditionally, active learning focuses on minimizing the prediction error
- In the predict-then-optimize framework:

Can we select samples to minimize the **SPO loss** directly, instead of the **prediction error**?
After T iterations, the prediction model h_T is obtained by using the selected training set

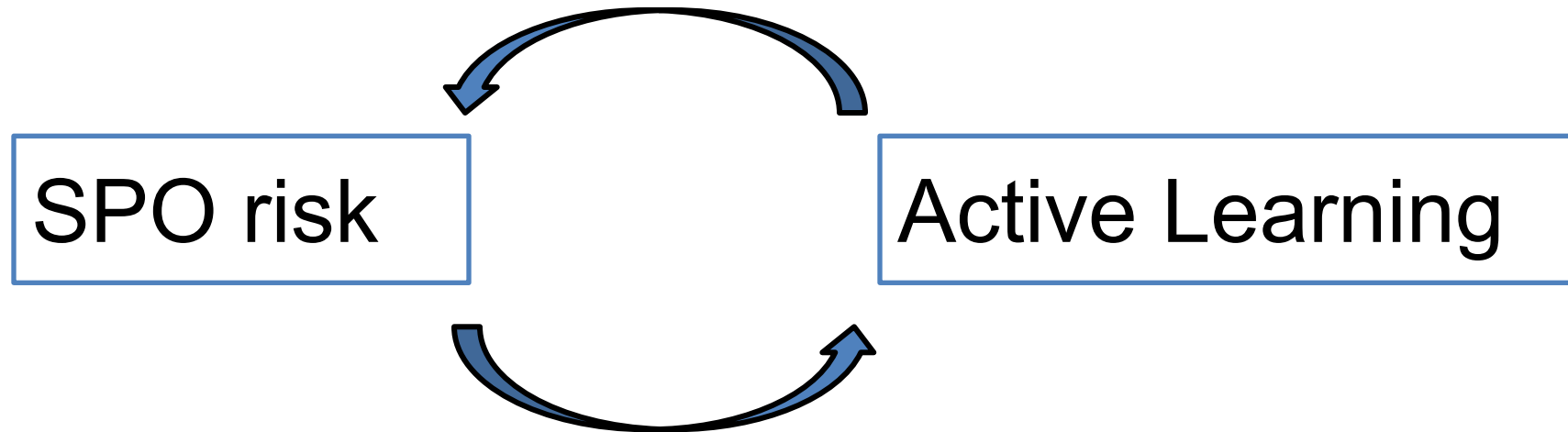
$$\begin{aligned} \text{min: } & \text{Number of acquired labels after } T \text{ iterations} \\ \text{subject to: } & R_{SPO}(h_T) - R_{SPO}(h^*) \leq \epsilon \end{aligned}$$

Agenda

- Information gathering process for predict-then-optimize framework
- Smart predict-then-optimize loss (SPO) and preliminaries
- **Theoretical motivation for margin-based algorithm**
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Motivation in theory

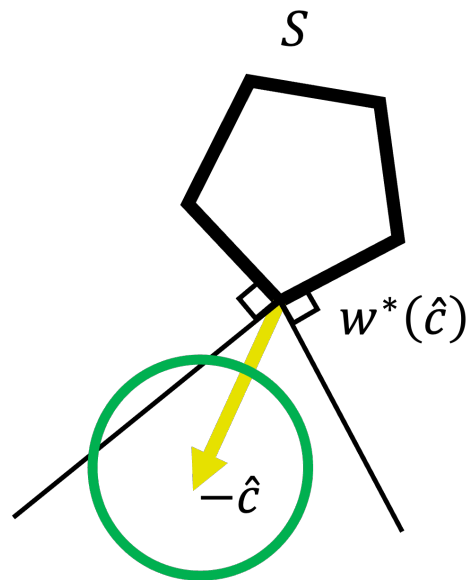
Active learning can help to minimize SPO loss



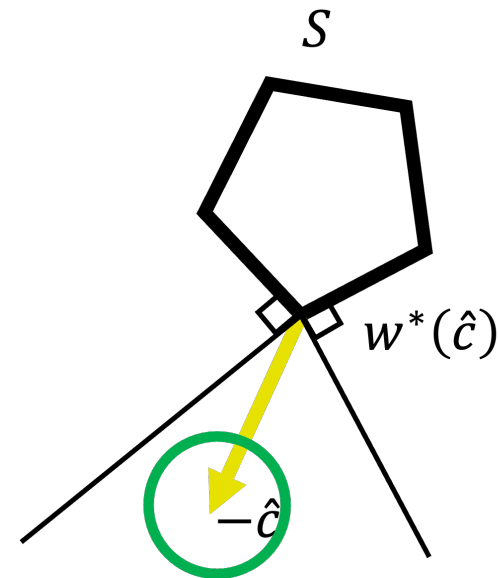
SPO loss can help to select samples for active learning

Motivation

- **Vector \hat{c}** is the prediction from $\hat{h}(x)$
- **Green circle** is the “confidence region” of \hat{c}



Size of training set: 5

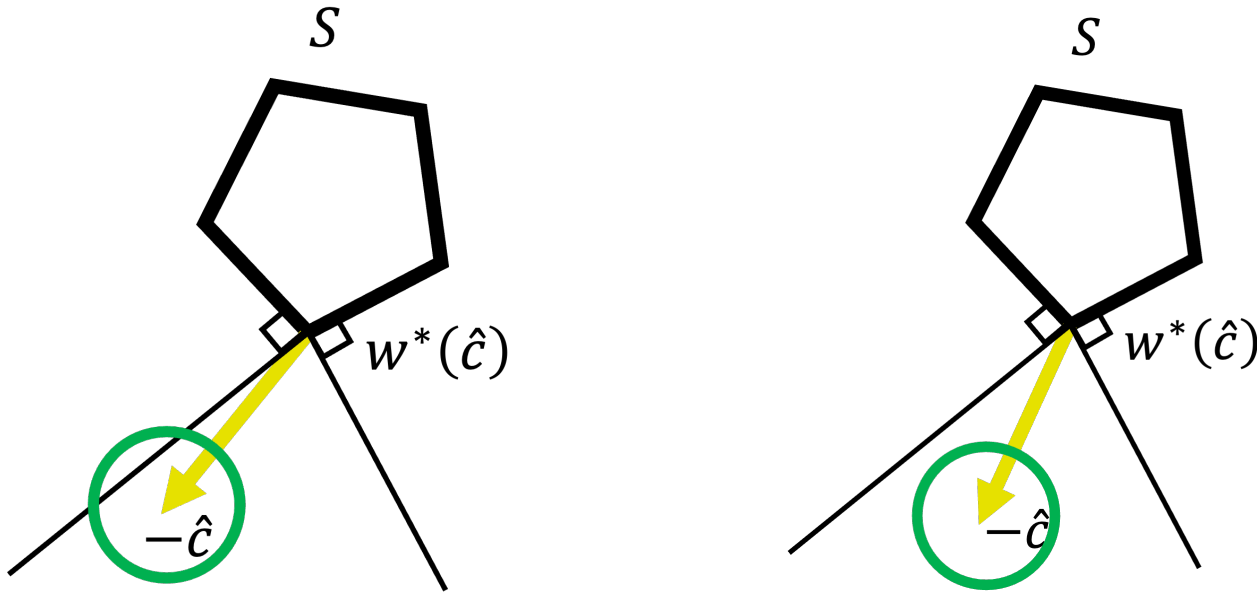


Size of training set: 5,000

- Active learning help identify critical samples to minimize SPO

Motivation

- Green circle has the same radius but different locations



- SPO can make active learning more selective

Agenda

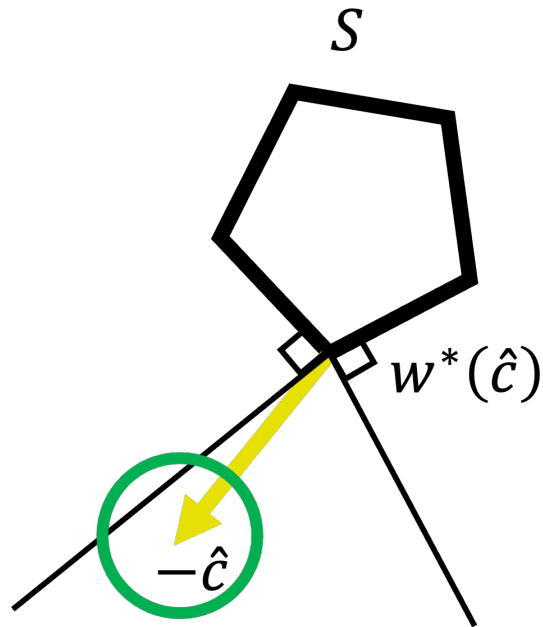
- Information gathering process for predict-then-optimize framework
- Smart predict-then-optimize loss (SPO) and preliminaries
- Theoretical motivation for margin-based algorithm

➤ **Algorithm**

- Analysis
- Numerical Experiments

Margin-based algorithm

- Idea: If the **green circle** (confidence region) intersects the boundary of the cone, then we acquire the label of that sample



Margin-based algorithm

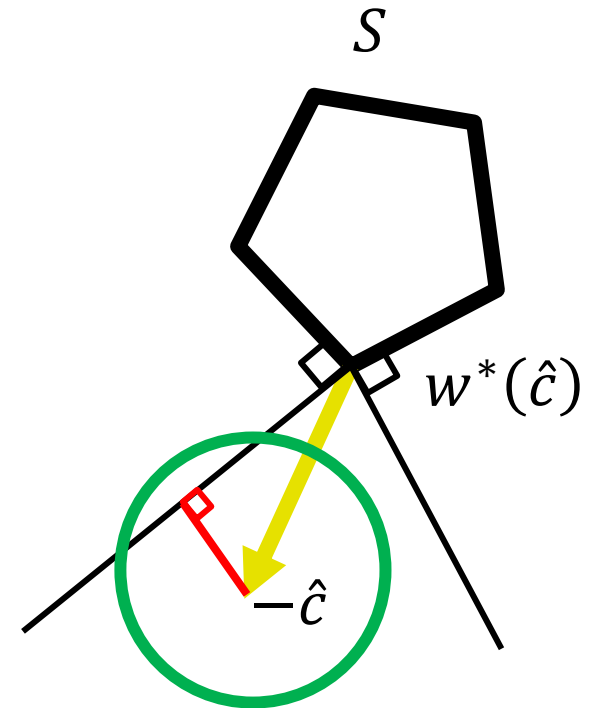
- Suppose \mathcal{C}^0 is the set of cost vectors that have multiple optimal decisions

- Distance to degeneracy:

$$v_S(\hat{c}) := \inf_{c \in \mathcal{C}^0} \{\|c - \hat{c}\|\}$$

- If $v_S(h_{t-1}(x_t)) < b_{t-1}$:

Acquire the label of this sample x_t



Model training in the prediction-then-optimize framework

- After constructing a training set, how to obtain the predictor h_T ?
- Minimize empirical loss in the selected training set
 - Squared loss
 - SPO+ loss
 - A specialized training loss that considering the downstream optimization:
 - Proposed in *Elmachtoub and Grigas (2022)*:

$$\ell_{\text{SPO}+}(\hat{c}, c) := \max_{w \in S} \{ (c - 2\hat{c})^T w \} + 2\hat{c}^T w^*(c) - c^T w^*(c)$$

- There is some benefit when using the SPO+ loss

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➤ **Analysis**

- Numerical Experiments

Theoretical guarantees for MBAL-SPO

- Label complexity vs. Sample complexity



Without any assumptions about the noise distribution:

- The label complexity is the **same** as the sample complexity in the supervised learning
(*Kääriäinen M (2006)*)

- We need some additional noise conditions

Label complexity from the low noise conditions

- Near-degeneracy function Ψ : the **CDF** of the **distance to degeneracy**
 - Difficulty in distinguishing the optimal decisions from the sub-optimal decisions

Low-noise condition: $\Psi(b) \leq b_0 \cdot b^\kappa$, $b < 1$, for some $\kappa > 0$

- κ gets larger $\rightarrow \Psi(b)$ gets smaller \rightarrow easier to find the optimal decisions
- Low-noise condition is closely related to Hu et al. 2022 and Tsybakov's noise condition

Assumption:

When the excess surrogate risk is at most $\Delta \rightarrow$ The prediction error for $\hat{h}(x)$ is at most $\mathcal{O}(\sqrt{\Delta})$

Overview of the results

- After T iterations:

	Active learning	Supervised learning
Excess surrogate risk	$\mathcal{O}(T^{-1/2})$	$\mathcal{O}(T^{-1/2})$
Excess SPO risk	$\Psi\left(\mathcal{O}\left(T^{-\frac{\kappa}{4}}\right)\right)$	$\Psi\left(\mathcal{O}\left(T^{-\frac{\kappa}{4}}\right)\right)$
Number of labels	$\sum_{t=1}^T \Psi\left(\mathcal{O}\left(t^{-\frac{\kappa}{4}}\right)\right)$	T

Overview of the results

- After T iterations with low-noise conditions:

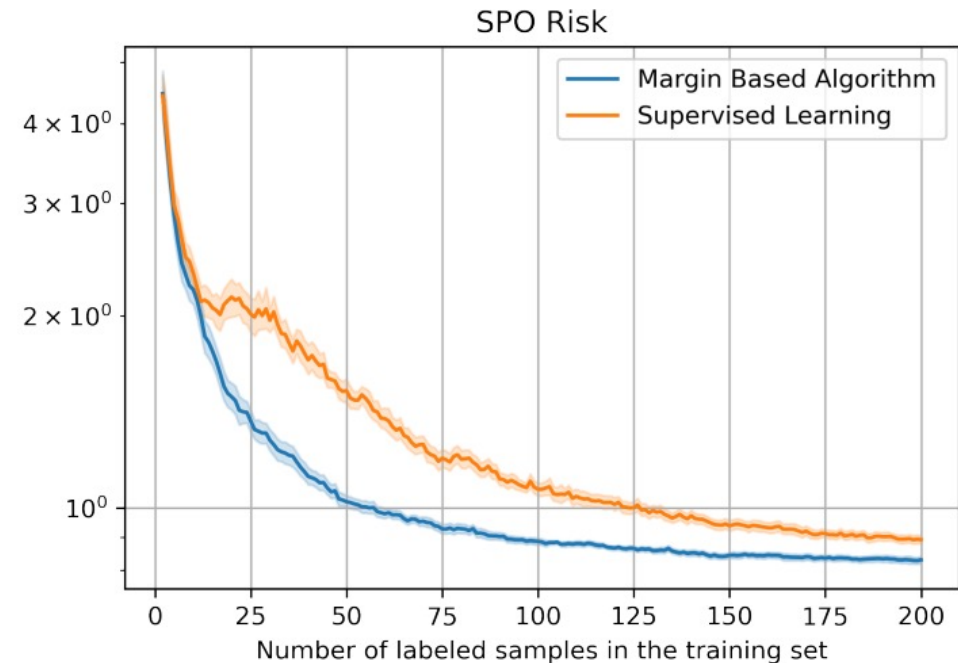
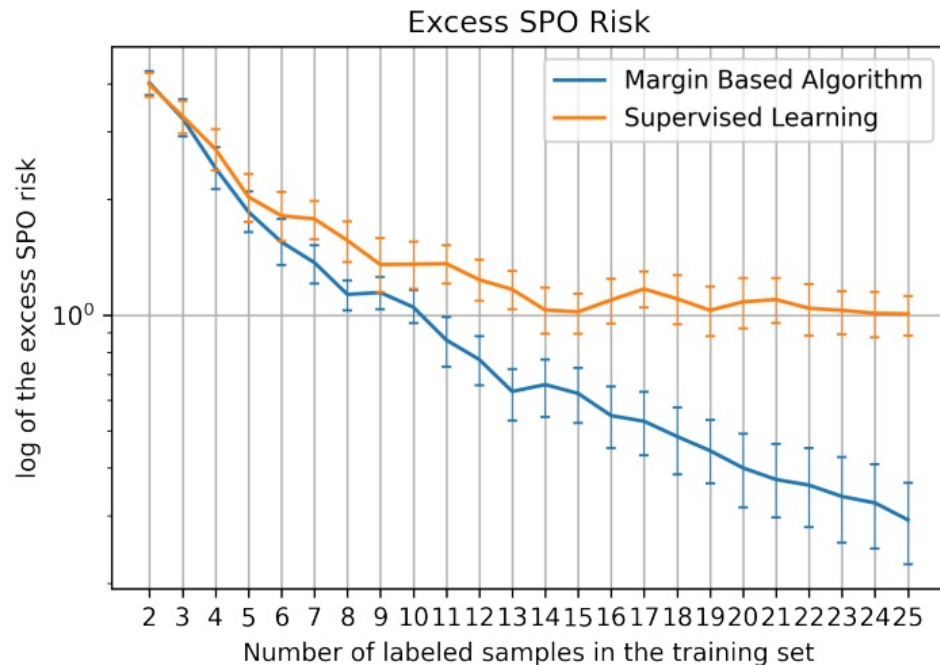
	Active learning	Supervised learning
Excess surrogate risk	$\mathcal{O}(T^{-1/2})$	$\mathcal{O}(T^{-1/2})$
Excess SPO risk	$\mathcal{O}(T^{-\kappa/4})$	$\mathcal{O}(T^{-\kappa/4})$
Number of labels	$\mathcal{O}(T^{1-\kappa/4})$	T

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Numerical experiments: shortest path problem

- Shortest path problem on 3×3 and 5×5 grid networks
- Predict the traveling time of each edge based on some features
- Using the SPO+ as the surrogate training loss



Numerical experiments: personalized pricing problem

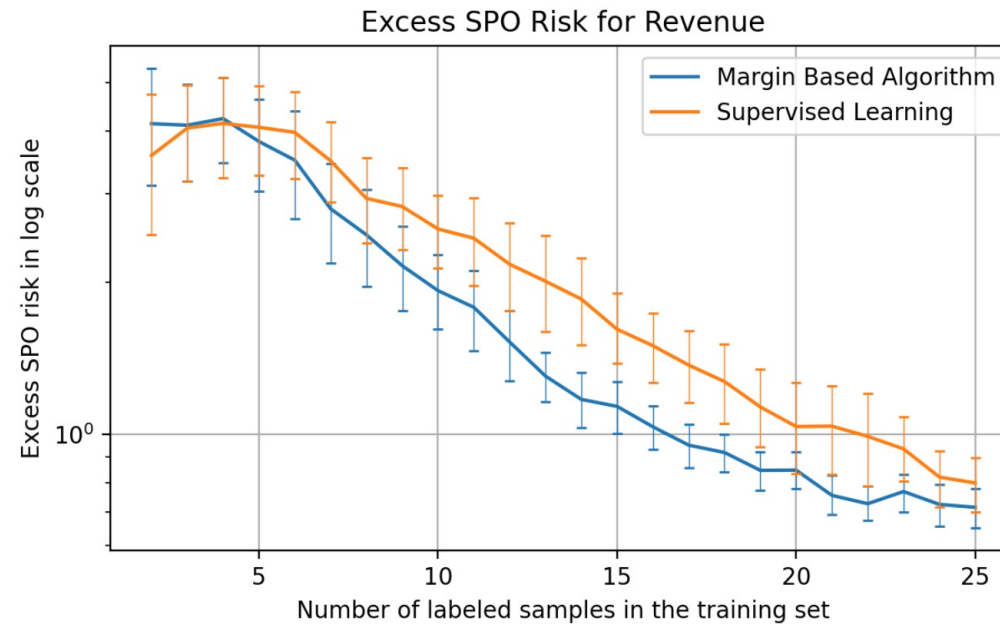
- Unknown function: $d_j(p^i) \in [0,1]$
 - Purchase probability of product j under price p^i
 - $d_j(p^i)$ depends on customer feature x
- Decisions: $w_{i,j} \in \{0,1\}$, whether the price of product j is set as p^i

$$\begin{aligned} \max_{\mathbf{w}} : \quad & \mathbb{E} \left[\sum_{j=1}^{\mathfrak{J}} \sum_{i=1}^{\mathcal{I}} d_j(p_i) p_i w_{i,j} | x \right] \\ & \sum_{i=1}^{\mathcal{I}} w_{i,j} = 1, \forall j = 1, 2, \dots, \mathfrak{J} \\ & \mathbf{A} \mathbf{w} \leq b \\ & w_{i,j} \in \{0, 1\}, \quad i = 1, 2, \dots, \mathcal{I}, j = 1, 2, \dots, \mathfrak{J}. \end{aligned}$$

- SPO loss: Revenue loss of the personalized prices based on the prediction for $d_j(p^i)$

Numerical experiments: personalized pricing problem

- Personalized pricing problem for three products
- The hypothesis class is mis-specified (The true model is exponential while the hypothesis class is linear.)



Thank you
<https://arxiv.org/pdf/2305.06584.pdf>

Variations of the algorithm

- If the noise does not satisfy the separable conditions or we use general surrogate loss:
- We have two variations:
- **Variation 1:**
 - Construct a confidence set of the optimal predictor at each iteration
 - $h_t \in H_t \subset H_{t-1} \subset \dots \subset H_0$
 - Minimize the training loss within the confidence set
- **Variation 2:**
 - At each iteration, when $v_S(h_{t-1}(x_t)) > b_{t-1}$, reject samples with some probability smaller than 1

Overview of the results

- After T iterations under separability condition:

	Active learning	Supervised learning
Excess surrogate risk	$\mathcal{O}(T^{-1/2})$	$\mathcal{O}(T^{-1/2})$
Excess SPO risk	$\mathcal{O}(\min\{T^{-\kappa/4}, T^{-1/2}\})$	$\mathcal{O}(T^{-\kappa/4})$
Number of labels	$\mathcal{O}(1)$	T

Property of SPO+ loss

- SPO+ loss in *Elmachtoub and Grigas (2022)*:

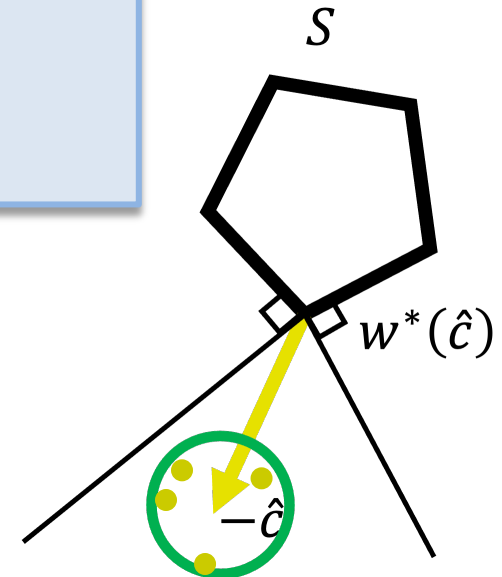
$$\ell_{\text{SPO}+}(\hat{c}, c) := \max_{w \in S} \{ (c - 2\hat{c})^T w \} + 2\hat{c}^T w^*(c) - c^T w^*(c)$$

Separability condition: for some $\varrho \in (0,1)$:

$$\|h^*(x) - c\| \leq \varrho v_S(h^*(x))$$

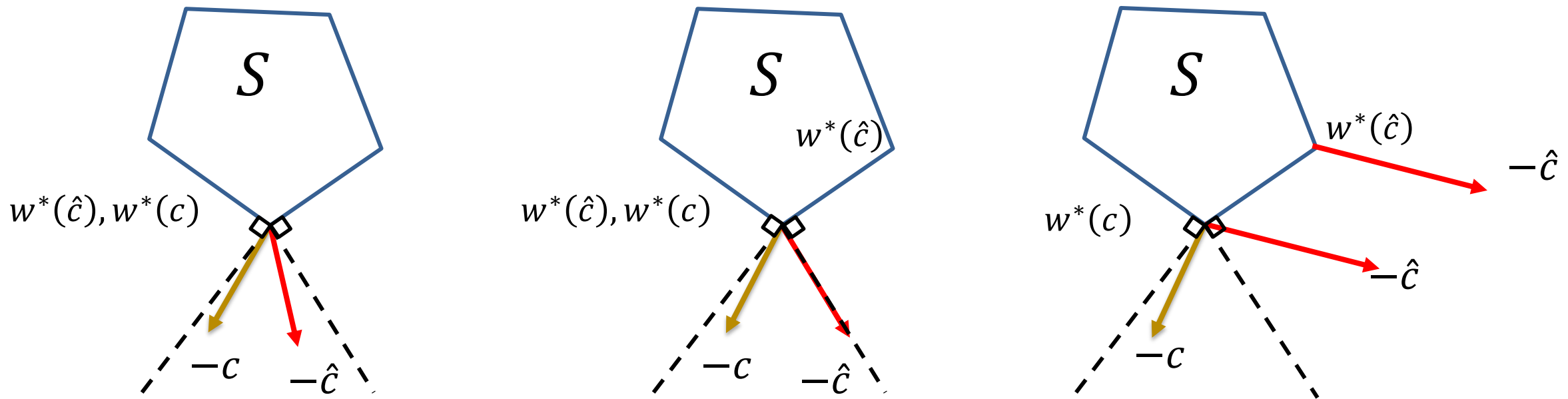
Separability condition implies:

- The minimum SPO+ risk and SPO risk are both **zero**.



Geometric Interpretation

- $\ell_{SPO}(\hat{c}, c) := c^T w^*(\hat{c}) - c^T w^*(c)$



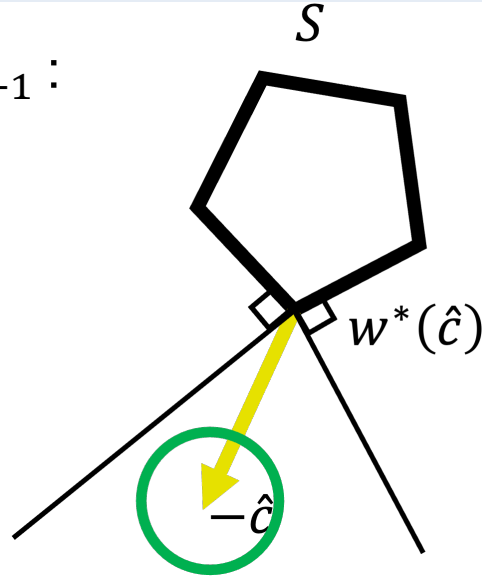
- SPO loss is discontinuous and nonconvex.
- Convex surrogate loss function: SPO+, squared loss, ...

Summary: Three versions of MBAL-SPO

- Given a sequence b_t , and \tilde{p} (If $\tilde{p} > 0$: soft-rejection; Otherwise, hard-rejection.)
- At each iteration t :
- Observe x_t
- If $v_S(h_{t-1}(x_t)) \geq b_{t-1}$:
 - Flip a coin with heads-up probability \tilde{p}
 - If the coin gets heads-up:
 - Acquire its label and update the training set
 - Else:
 - Reject x_t .
- Else:
 - Acquire its label and update the training set
- Update the predictor h_t by minimizing the empirical risk within the confidence set H_t
- Update a confidence set of predictor H_t if using general surrogate loss under hard-rejection.

Margin-Based Algorithm

- What if $v_S(h_{t-1}(x_t)) \geq b_{t-1}$:



- Reject it directly?
- The SPO loss of this sample is zero, so rejecting it **does not change the total SPO loss**.

$$\boxed{\ell_{SPO}(h_{t-1}(x_t), c_t)} + \sum_{i=1}^{t-1} \ell_{SPO}(h_{t-1}(x_i), c_i)$$

0

- 😞 We are minimizing the **surrogate loss**, instead of SPO loss.
- 😞 Although SPO loss is zero, **the surrogate loss is possibly nonzero**.

Margin-Based Algorithm

- When rejecting the sample directly:

😞 Empirical surrogate loss  Surrogate risk.

Soft rejection	Hard rejection with SPO+ surrogate	Hard rejection with general surrogate function
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Soft rejection Algorithm

- If $v_S(h_{t-1}(x_t)) \geq b_{t-1}$ (Green circle does not intersect with the boundary):
 - Acquire the label **with probability $\tilde{p} > 0$** . (**soft-rejection**)
 - If this sample eventually gets labeled, the **weight** of this sample is $\frac{1}{\tilde{p}}$
 - The expectation of re-weighted empirical surrogate loss equals the surrogate risk.
- 😞 The expected number of labels up to time T is at least $O(\tilde{p}T)$

Proof Sketch

1. Convergence for the surrogate risk:

$$\begin{aligned} R_\ell(h) - R_\ell(h^*) = & \text{average excess risk for hard rejected samples} \\ & + \text{uniform convergence rate for the reweighted risk} \\ & + \text{average empirical excess risk of } h \end{aligned}$$

Proof Sketch

1. Convergence for the surrogate risk:

$R_\ell(h) - R_\ell(h^*) =$ average excess risk for hard rejected samples (Holder's property)
+ uniform convergence rate for the reweighted risk (Sequential complexity)
+ average empirical excess risk of h (h^* is within H_t)

Proof Sketch

1. Convergence for the surrogate risk:

$R_\ell(h) - R_\ell(h^*) =$ average excess risk for hard rejected samples (Holder's property)
+ uniform convergence rate for the reweighted risk (Sequential complexity)
+ average empirical excess risk of h (h^* is within H_t)

2. From surrogate risk to the SPO risk: near-degeneracy function.

3. Label complexity: Bound for the label probability at each step

4. For the soft-rejection, optimize \tilde{p} as a function of T to achieve a small label complexity.

Examples of operations management problems

Unknown parameters

Decision

Customers' preference

Product recommendation

Demand

Inventory level

Price elasticity

Optimal prices