

## Objective

This example demonstrates UART communication and blinks an LED using a TCPWM Component, on the PSoC® 6 MCU, using ModusToolbox IDE.

## Requirements

**Tool:** [ModusToolbox™ 1.0](#); Cypress SDK

**Programming Language:** C

**Associated Parts:** All [PSoC 6 MCU](#) parts

**Related Hardware:** [PSoC 6 WiFi-BT Pioneer Kit](#)

## Overview

This example uses the TCPWM in PWM mode to blink a green LED once per second. The UART resource prints a “Hello World! This is PSoC 6 MCU.” message.

## Hardware Setup

This example uses the kit's default configuration. Refer to the kit guide to ensure the kit is configured correctly.

## Software Setup

This example uses a terminal emulator. Install one if you don't have one. The instructions use [Tera Term](#).

## Operation

1. Open your terminal software and select the KitProg3 COM port. Set the serial port parameters to 8N1 and 115,200 baud.
2. Connect the Pioneer board to your PC using the provided USB cable through the USB connector.
3. Import the project into a new workspace.
4. Build the project. For a multi-core device, choose **Project > Build All**.
5. Program the PSoC 6 MCU device. Choose **Run > Run Configurations**. Expand **GDB OpenOCD Debugging**. Select the **<project> Program OpenOCD** item. Then click **Run**.
6. Observe the “Hello World! This is PSoC 6 MCU.” message on the UART terminal, and the green LED toggles every 500 milliseconds.

## Design and Implementation

This example configures a TCPWM resource in PWM mode to blink the green LED at 1 Hz, and a UART resource to print “Hello World! This is PSoC 6 MCU.” message.

The TCPWM resource is connected to a clock operating at 1 kHz, with a compare value of 500. It outputs a signal to pin P1[1], which drives the green LED on the kit. The Serial Communication Block resource is configured as a UART at 115200 baud, 8N1. It is connected to a clock operating at approximately 926 kHz to generate the correct baud rate. The RX is on pin P5[0] and TX is on P5[1], to match the pin usage on the kit.

All code runs on the CM4 processor.

To see all the settings, review the *design.modus* file in the project.

## Resources and Settings

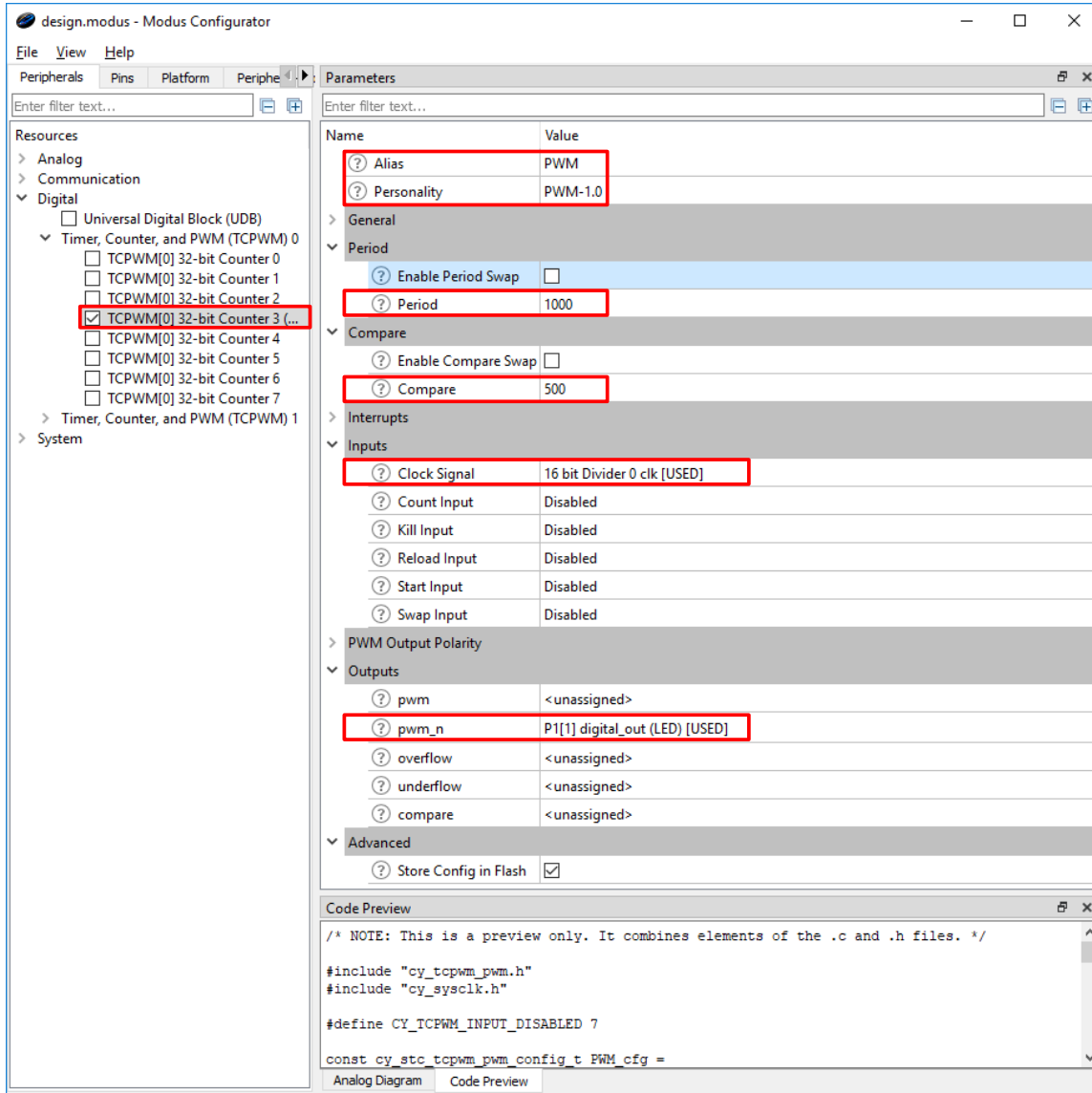
Table 1 lists the ModusToolbox resources used in this example, and how they are used in the design.

Table 1: ModusToolbox Resources

Resource	Alias	Purpose
Timer Counter (TCPWM)	PWM	Drives the green LED
SCB	UART	Prints a message to a terminal window
Digital Output Pin	LED	Provide visual feedback
	UART_TX	Used for UART transmit (Tx)
Digital Input Pin	UART_RX	Used for UART receive (Rx)

Figure 1 to Figure 4 show non-default configuration settings for the Resources.

Figure 1. PWM Configuration



The screenshot shows the Modus Configurator interface for configuring a PWM peripheral. The left pane shows the resource tree with 'TCPWM[0] 32-bit Counter 3' selected. The right pane shows the configuration parameters for this counter.

Name	Value
Alias	PWM
Personality	PWM-1.0
<b>General</b>	
Enable Period Swap	<input type="checkbox"/>
Period	1000
<b>Compare</b>	
Enable Compare Swap	<input type="checkbox"/>
Compare	500
<b>Interrupts</b>	
<b>Inputs</b>	
Clock Signal	16 bit Divider 0 clk [USED]
Count Input	Disabled
Kill Input	Disabled
Reload Input	Disabled
Start Input	Disabled
Swap Input	Disabled
<b>PWM Output Polarity</b>	
<b>Outputs</b>	
pwm	<unassigned>
pwm_n	P1[1] digital_out (LED) [USED]
overflow	<unassigned>
underflow	<unassigned>
compare	<unassigned>
<b>Advanced</b>	
Store Config in Flash	<input checked="" type="checkbox"/>

**Code Preview**

```

/* NOTE: This is a preview only. It combines elements of the .c and .h files. */

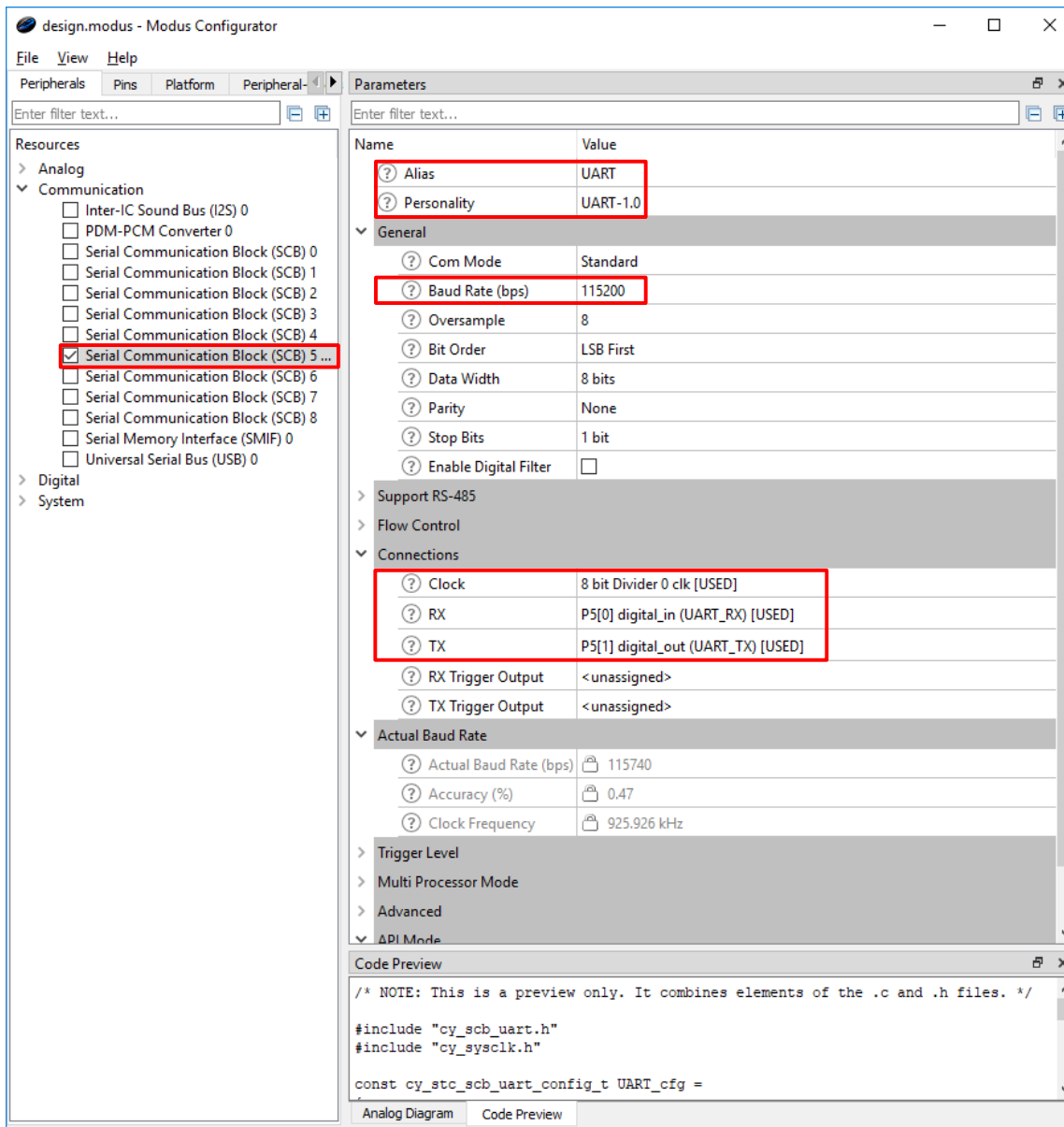
#include "cy_tcpwm_pwm.h"
#include "cy_sysclk.h"

#define CY_TCPWM_INPUT_DISABLED 7

const cy_stc_tcpwm_pwm_config_t PWM_cfg =

```

Figure 2. UART Configuration



The screenshot shows the Modus Configurator interface for a PSoC 6 MCU. The left pane displays the 'Resources' tree with 'Serial Communication Block (SCB) 5' selected. The right pane shows the 'Parameters' table for this block.

Name	Value
Alias	UART
Personality	UART-1.0
<b>General</b>	
Com Mode	Standard
Baud Rate (bps)	115200
Oversample	8
Bit Order	LSB First
Data Width	8 bits
Parity	None
Stop Bits	1 bit
Enable Digital Filter	<input type="checkbox"/>
<b>Support RS-485</b>	
<b>Flow Control</b>	
<b>Connections</b>	
Clock	8 bit Divider 0 clk [USED]
RX	P5[0] digital_in (UART_RX) [USED]
TX	P5[1] digital_out (UART_TX) [USED]
RX Trigger Output	<unassigned>
TX Trigger Output	<unassigned>
<b>Actual Baud Rate</b>	
Actual Baud Rate (bps)	115740
Accuracy (%)	0.47
Clock Frequency	925.926 kHz
<b>Trigger Level</b>	
<b>Multi Processor Mode</b>	
<b>Advanced</b>	
<b>ADI Mode</b>	

The bottom pane shows the 'Code Preview' for the selected block, displaying the following code:

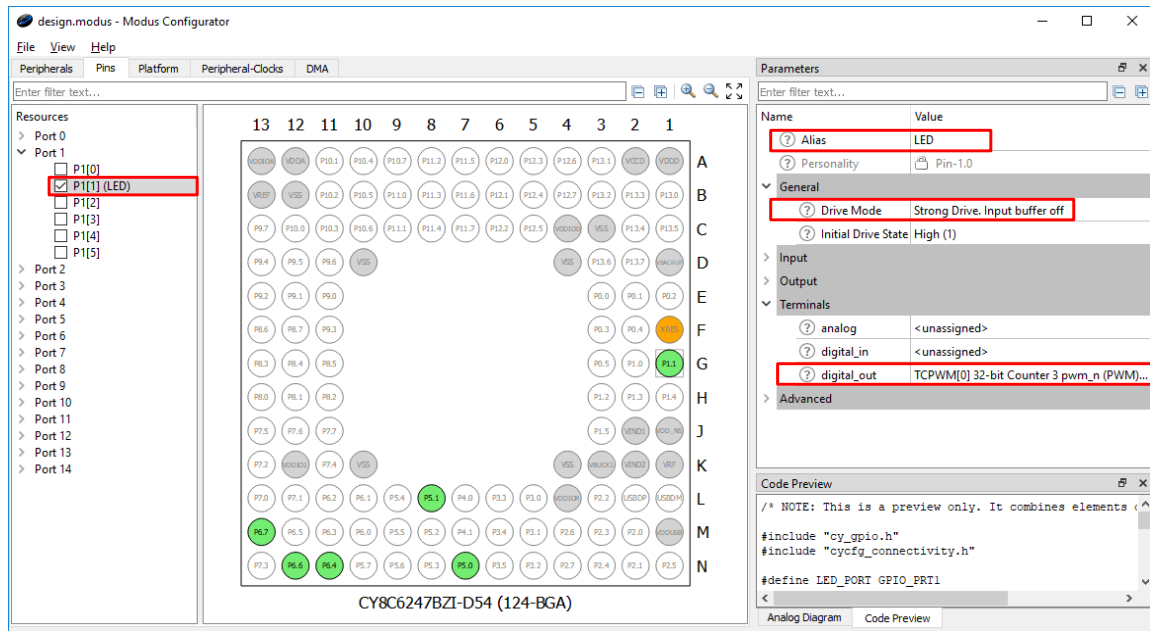
```

/* NOTE: This is a preview only. It combines elements of the .c and .h files. */

#include "cy_scb_uart.h"
#include "cy_sysclk.h"

const cy_stc_scb_uart_config_t UART_cfg =
  
```

Figure 3. GPIO Pin configuration for LED



design.modus - Modus Configurator

File View Help

Peripherals Pins Platform Peripheral-Clocks DMA

Enter filter text...

Resources

- Port 0
- Port 1
  - ☒ P1[0]
  - ☒ P1[1] (LED)
  - ☐ P1[2]
  - ☐ P1[3]
  - ☐ P1[4]
  - ☐ P1[5]
- Port 2
- Port 3
- Port 4
- Port 5
- Port 6
- Port 7
- Port 8
- Port 9
- Port 10
- Port 11
- Port 12
- Port 13
- Port 14

Pin Matrix (CY8C6247BZI-D54 (124-BGA))

Parameters

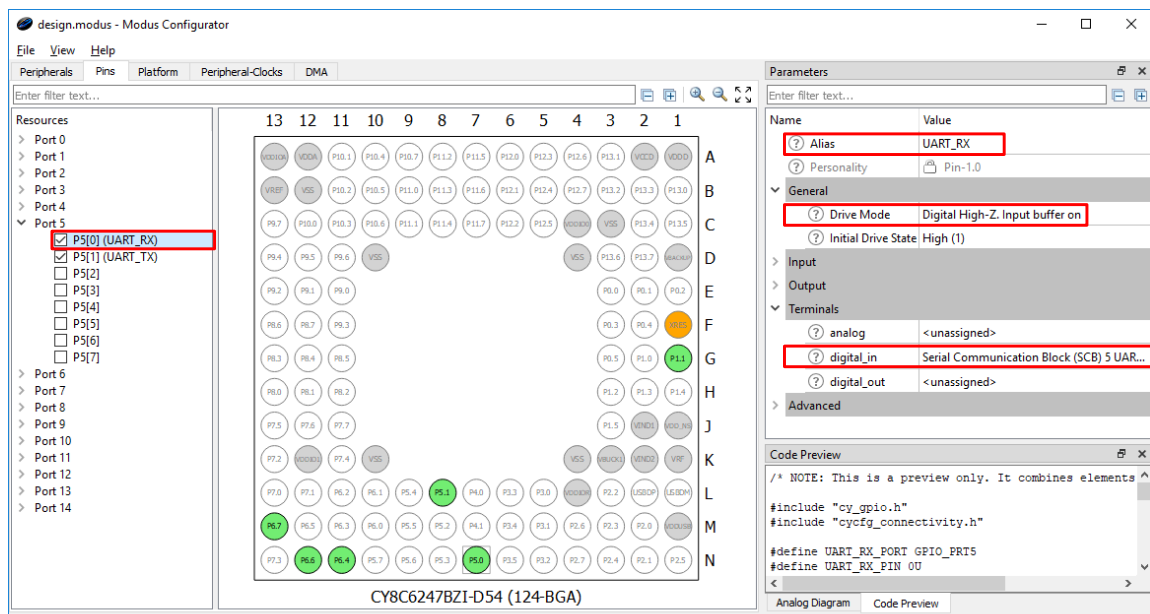
Name	Value
Alias	LED
Personality	Pin-1.0
General	
Drive Mode	Strong Drive, Input buffer off
Initial Drive State	High (1)
Input	
Output	
Terminals	
analog	<unassigned>
digital_in	<unassigned>
digital_out	TCPWM[0] 32-bit Counter 3 pwm_n (PWM)...
Advanced	

Code Preview

```

/* NOTE: This is a preview only. It combines elements
#include "cy_gpio.h"
#include "cy_cfg_connectivity.h"
#define LED_PORT GPIO_PRT1
  
```

Figure 4. GPIO Pin Configuration for UART Rx



design.modus - Modus Configurator

File View Help

Peripherals Pins Platform Peripheral-Clocks DMA

Enter filter text...

Resources

- Port 0
- Port 1
- Port 2
- Port 3
- Port 4
- Port 5
  - ☒ P5[0] (UART\_RX)
  - ☒ P5[1] (UART\_TX)
  - ☐ P5[2]
  - ☐ P5[3]
  - ☐ P5[4]
  - ☐ P5[5]
  - ☐ P5[6]
  - ☐ P5[7]
- Port 6
- Port 7
- Port 8
- Port 9
- Port 10
- Port 11
- Port 12
- Port 13
- Port 14

Pin Matrix (CY8C6247BZI-D54 (124-BGA))

Parameters

Name	Value
Alias	UART_RX
Personality	Pin-1.0
General	
Drive Mode	Digital High-Z, Input buffer on
Initial Drive State	High (1)
Input	
Output	
Terminals	
analog	<unassigned>
digital_in	Serial Communication Block (SCB) 5 UAR...
digital_out	<unassigned>
Advanced	

Code Preview

```

/* NOTE: This is a preview only. It combines elements
#include "cy_gpio.h"
#include "cy_cfg_connectivity.h"
#define UART_RX_PORT GPIO_PRT5
#define UART_RX_PIN 0U
  
```

Figure 5. GPIO Pin Configuration for UART Tx

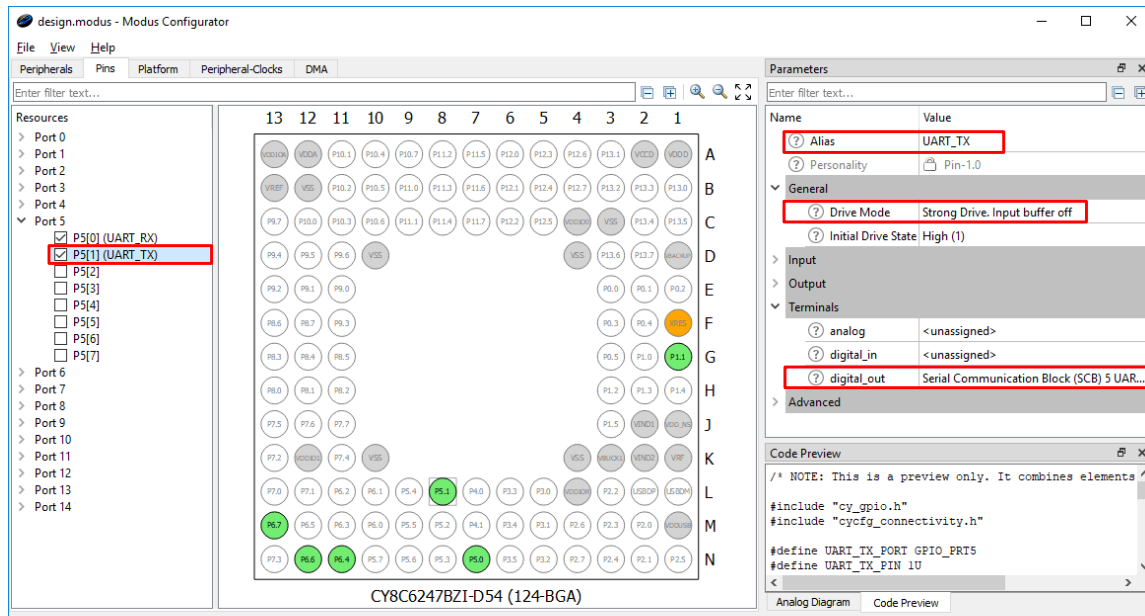


Figure 6 and Figure 7 shows the Peripheral-Clock configuration for UART and TCPWM resources respectively.

Figure 6. Peripheral-Clock Configuration for UART

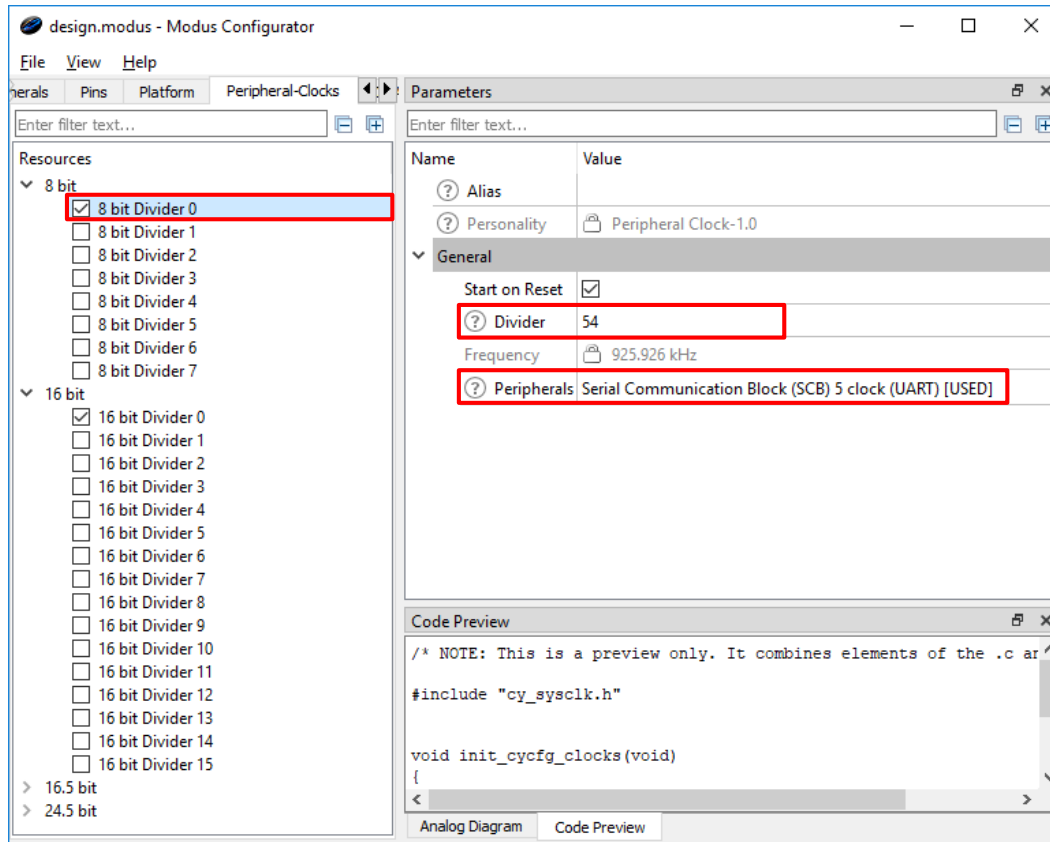


Figure 7. Peripheral-Clock Configuration for PWM

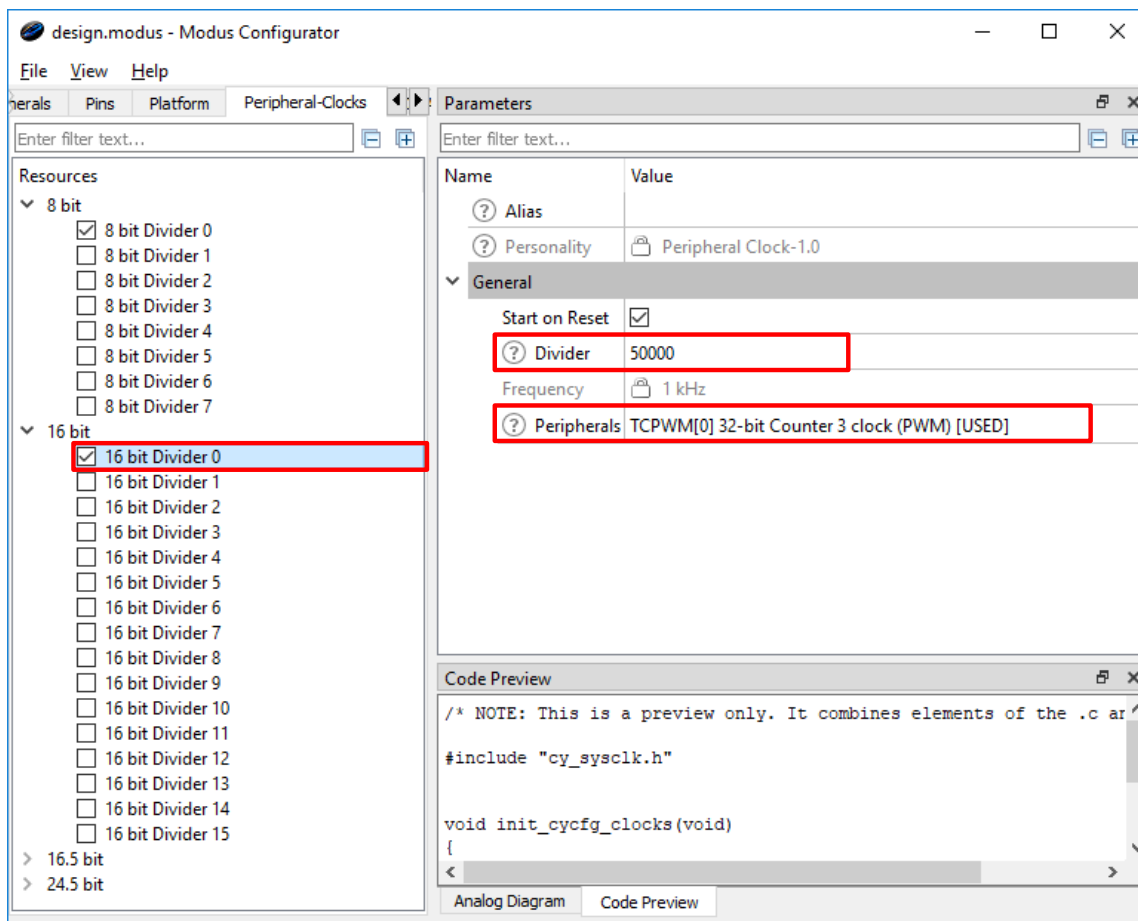


Table 2 shows the pin assignments for the project.

Table 2. Pin Assignments

Name	Port
LED	P1[1]
UART_RX	P5[0]
UART_TX	P5[1]

## Debugging

You can debug the example to step through the code. If you are unfamiliar with how to start a debug session on the PSoC 6 MCU with Modus IDE, see KBA224621 in the Cypress community.

## Reusing This Example

This example is designed for the [PSoC 6-WIFI-BT Pioneer Kit](#).

In some cases, a resource used by a code example (for example, an IP block) is not supported on another device. In that case the example will not work. If you build the code targeted at such a device, you will get errors. See the device datasheet for information on which resources the device supports.

## Related Documents

For a comprehensive list of PSoC 6 MCU resources, see [KBA223067](#) in the Cypress community.

Application Notes	
<a href="#">AN210781</a> – Getting Started with PSoC 6 MCU with Bluetooth Low Energy (BLE) Connectivity	Describes PSoC 6 MCU with BLE Connectivity devices and how to build your first PSoC Creator project
<a href="#">AN215656</a> – PSoC 6 MCU: Dual-CPU System Design	Describes the dual-CPU architecture in PSoC 6 MCU, and shows how to build a simple dual-CPU design
Code Examples	
<a href="#">CE212736</a> – PSoC 6 MCU BLE Find Me	<a href="#">CE218133</a> – PSoC 6 MCU E-Ink Display with CapSense
Device Documentation	
<a href="#">PSoC 6 MCU: PSoC 63 with BLE Datasheet</a>	<a href="#">PSoC 6 MCU: PSoC 63 with BLE Architecture Technical Reference Manual</a>
Development Kit Documentation	
<a href="#">CY8CKIT-062-BLE PSoC 6 BLE Pioneer Kit</a>	
<a href="#">CY8CKIT-062-WiFi-BT PSoC 6 WiFi-BT Pioneer Kit</a>	
Tool Documentation	
<a href="#">ModusToolbox</a>	Join the Early Access Program for links to the latest tools
Cypress SDK	Installed with ModusToolbox



## Cypress Resources

Cypress provides a wealth of data at [www.cypress.com](http://www.cypress.com) to help you to select the right device, and quickly and effectively integrate the device into your design.

For the PSoC 6 MCU devices, see [KBA223067](#) in the Cypress community for a comprehensive list of PSoC 6 MCU resources.

## Document History

Document Title: CE223541 – PSoC 6 MCU: Hello World using ModusToolbox

Document Number: 002-23541

Revision	ECN	Orig. of Change	Submission Date	Description of Change
**	nnnnnnnn	SNVN	07/19/2018	New code example

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