

# Covariance Structure Analysis: Introduction

Y645  
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# Nice Resources

- David Kenny's [website](#)
  - <http://davidakenny.net/cm/causalm.htm>
- Kristopher Preacher's website:
  - <https://www.quantpsy.org/medn.htm>
- Jason Newsom's website:
  - <https://web.pdx.edu/~newsomj/semclass/>
- For R
  - <http://lavaan.ugent.be/>
  - UCLA IDRE ([stats.idre.ucla.edu/r/seminars/rsem/](http://stats.idre.ucla.edu/r/seminars/rsem/))
  - R Google group
  - lavaan Google group
- Supplementary text:
  - Beaujean, A.A. (2014). *Latent variable modeling using R*. New York: Routledge.

# SEM – A rose by *many* names

- Structural equation modeling
  - Covariance structure analysis
  - Structural modeling
  - LISREL (linear structural relations) modeling
  - Latent variable modeling
- 
- In this class, we'll primarily use SEM

# What is SEM?

- Very broadly – it is a modeling method used by social and natural scientists to uncover relationships in data.
- Interesting features:
  - Accounts for measurement error
  - Can build rich models involving *latent constructs*
  - Explicit test of model fit
  - Models are fit to covariance/correlation matrices
- You can cast almost any model in an SEM framework: regression, multilevel models, IRT, etc.

# Latent construct

- Typically, a theoretical or hypothetical construct.
- Normally unobservable
- Examples:
  - Proficiency (math, language, athletic)
  - Attitudes (toward learning, crime, spending)
  - Perceptions (of others, of behavior, of laws)
  - *Many* others

# What is SEM?

- An analytical approach that allows a researcher to build an elegant and parsimonious model of the processes that give rise to the observed data (Little, 2013)

# SEM

- We usually focus on cases or individual observations
  - Subjects in a study
  - Students taking a test
- We try to model these observations
- In SEM, our focus is different
  - First, let's briefly review OLS regression

# Review of OLS Regression

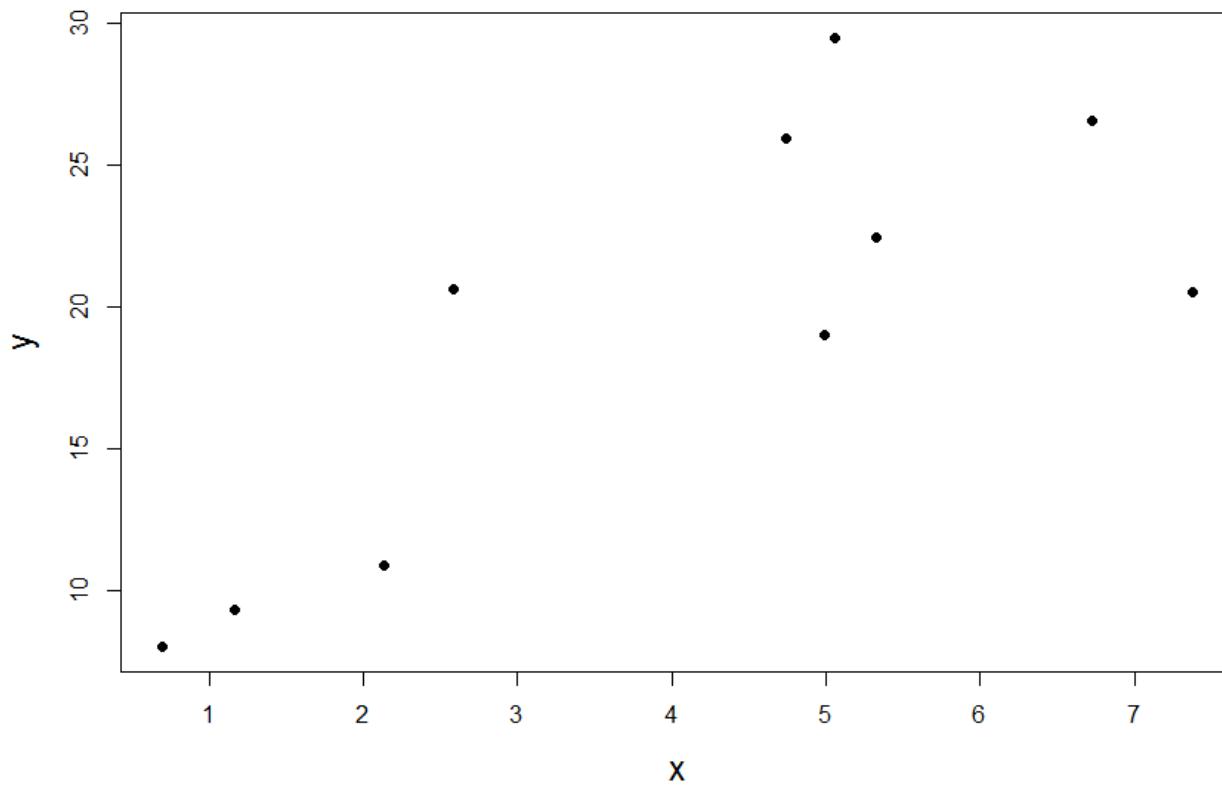
- We hope to describe relationships on a straight line
- We collect observations on many units
- Usually: 1 variable acts as a response/outcome and 1 variable acts as a predictor
- We view outcome ( $Y$ ) as  $f(X)$

- In particular

$$f(x_i) = \beta_0 + \beta_1 x_i + e_i$$

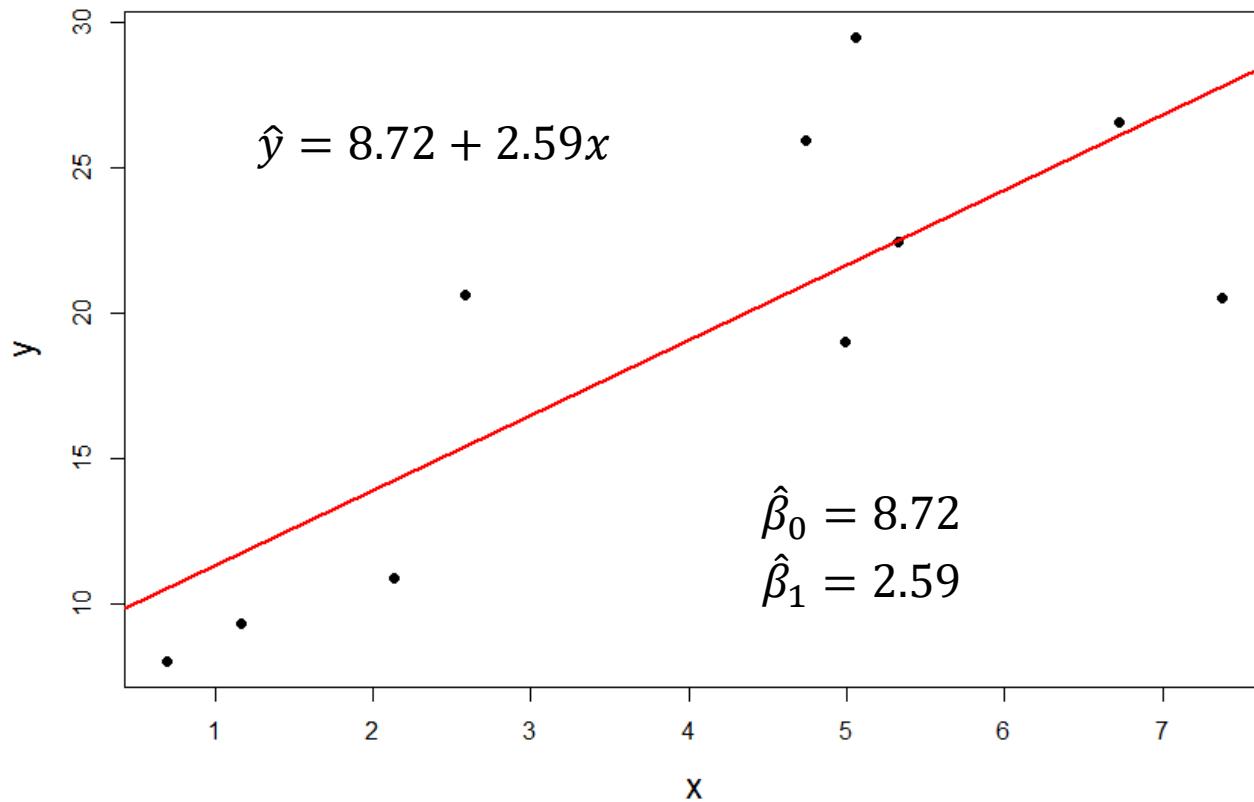
- The hypothesized model is such that the predictor,  $x_i$ , is set or known by data collector and  $Y_i$  is a  $f(x_i)$ .
- The hypothesized model specifies, except for some unknown parameters, the response behavior for given  $x$  values
- Model also characterizes failure to provide exact fit through error terms.
- Then we use the data to estimate unknown parameters

- We observe:



- Notation:
  - $X, Y$  are random variables
  - $x_i, y_i$  are observed values for the  $i^{\text{th}}$  case
- Equation of a line:  $Y = \beta_0 + \beta_1 X$ 
  - Parameters
    - $\beta_0$  – intercept or value of  $Y$  when  $X$  is 0.
    - $\beta_1$  – rate of change in  $Y$  for 1 unit change in  $X$ .

# Then we have...



# OLS Regression: Errors

- Real data don't fall on a straight line
- Instead, there are statistical errors
- Random errors
  - Measurement error (in  $Y$ )
  - Omitted variables
  - Natural variability
- $e_i$  – statistical error for  $i^{\text{th}}$  case ( $i = 1, \dots, n$ )

# OLS Assumptions

- $E(e_i) = 0$  for  $i = 1, \dots, n$
- $\text{cov}(e_i, e_j) = 0$  for all  $i \neq j$ 
  - Errors are mutually independent and uncorrelated
- $\text{var}(e_i) = \sigma^2$ 
  - Common though usually unknown variance
- Then  $e_1 \sim N(0, \sigma^2), i = 1, \dots, n$

# Simple regression model

- The model is given by:

$$y_i = \beta_0 + \beta_1 x_i + e_i, i = 1, \dots, n$$

$$\text{E}(e_i) = 0$$

$$\text{var}(e_i) = \sigma^2$$

$$\text{cov}(e_i, e_j) = 0 \quad i \neq j$$

- How many unknowns?

- 3:  $\beta_0, \beta_1$ , &  $\sigma^2$

- $e_i$  are unobservable quantities to account for failure of observed values to fall on a straight line.  
Only  $x_i$  and  $y_i$  are observed

# Notation

- Parameters:  $\alpha, \beta, \gamma, \sigma$
- Estimators:  $\hat{\alpha}, \hat{\beta}, \hat{\gamma}, \hat{\sigma}$

# Fitting Errors vs. Statistical Errors

- While  $e_i$ s are not parameters, we use  $\hat{e}_i$  to describe “observed fitting errors” or residuals:

$$\hat{e}_i = y_i - (\hat{\beta}_0 + \hat{\beta}_1 x_i) \quad i = 1, 2, \dots, n$$

- Statistical error (not observable):

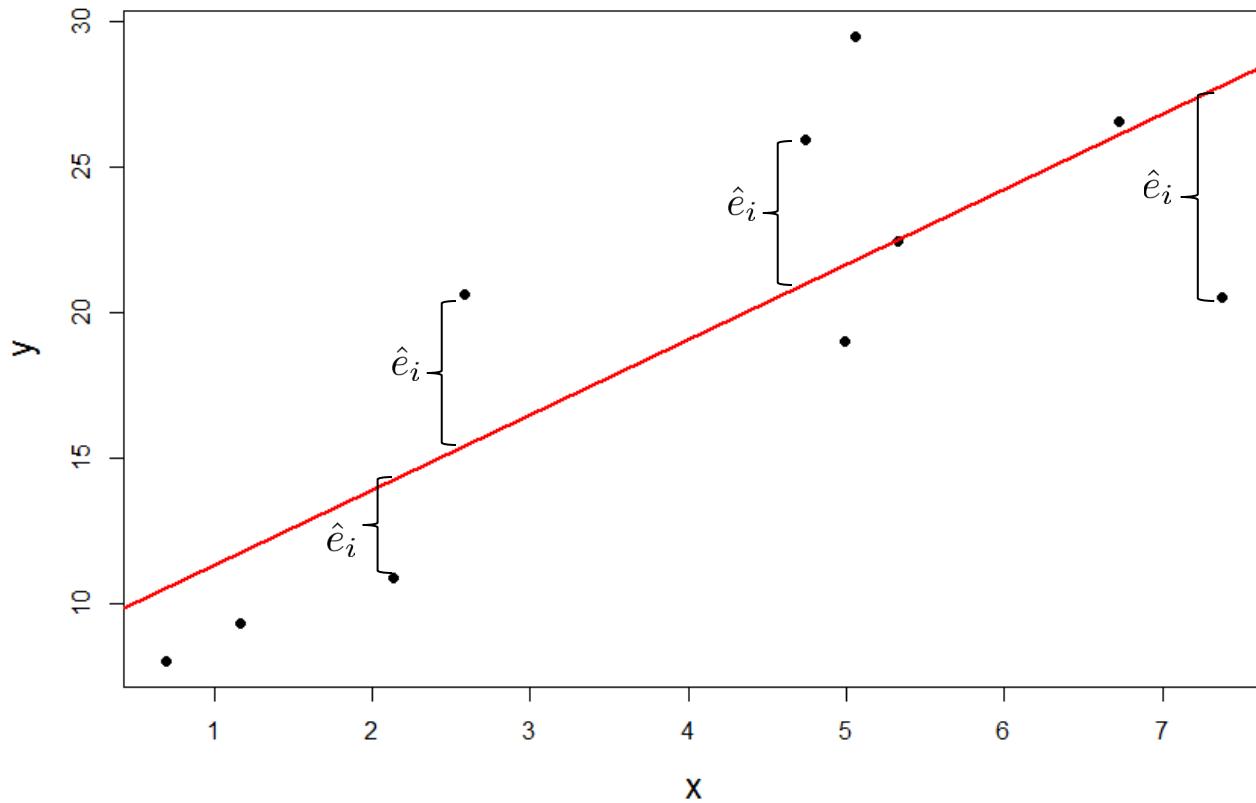
$$e_i = y_i - (\beta_0 + \beta_1 x_i) \quad i = 1, 2, \dots, n$$

# Fitted Values

$$\hat{y}_i = \hat{\beta}_0 + \hat{\beta}_1 x_i \quad i = 1, 2, \dots, n$$

- Notice:  $\hat{e}_i = y_i - (\hat{\beta}_0 + \hat{\beta}_1 x_i)$   
 $\hat{y}_i = \hat{\beta}_0 + \hat{\beta}_1 x_i$
- Then:  $\hat{e}_i = y_i - \hat{y}_i$

# Errors



# LS Estimators

- Those values:  $\hat{\beta}_0$  of  $\beta_0$  and  $\hat{\beta}_1$  of  $\beta_1$
- That minimize:  $RSS(\beta_0, \beta_1) = \sum [y_i - (\beta_0 + \beta_1 x_i)]^2$

$$\hat{\beta}_1 = \frac{SXY}{SXX} = r_{xy} \frac{SD_y}{SD_x} = r_{xy} \left( \frac{SYY}{SXX} \right)^{\frac{1}{2}}$$

$$\hat{\beta}_0 = \bar{y} - \hat{\beta}_1 \bar{x}$$

and

$$\hat{\sigma}^2 = \frac{RSS}{n-2} \text{ where } RSS = SYY - \frac{(SXY)^2}{SXX} = SYY - \hat{\beta}_1^2 SXX$$

# Matrix Notation

$\boldsymbol{x}, \boldsymbol{e}, \boldsymbol{\beta}$        $\leftarrow$  Vectors and matrices

$x_{ij}, e_i, \beta_j$        $\leftarrow$  Elements of a vector or matrix

# Multiple Predictors & Matrix Notation

$$\mathbf{Y} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix} \quad \mathbf{e} = \begin{bmatrix} e_1 \\ e_2 \\ \vdots \\ e_n \end{bmatrix} \quad \boldsymbol{\beta} = \begin{bmatrix} \beta_0 \\ \beta_1 \\ \vdots \\ \beta_p \end{bmatrix}$$

$\mathbf{Y}$  and  $\mathbf{e}$  are  $n \times 1$  vectors

$\boldsymbol{\beta}$  is  $(p + 1) \times 1$

$$\mathbf{X} = \begin{bmatrix} 1 & x_{11} & x_{12} & \dots & x_{1p} \\ 1 & x_{21} & x_{22} & \dots & x_{2p} \\ 1 & x_{31} & x_{32} & \dots & x_{3p} \\ \vdots & \vdots & & & \\ 1 & x_{n1} & x_{n2} & \dots & x_{np} \end{bmatrix}$$

and  $p'$  = no. columns in  $\mathbf{X}$

$\mathbf{X}$  is  $n \times (p + 1)$ :

# OLS Regression

- Then we have

$$\begin{matrix} \mathbf{Y} \\ n \times 1 \end{matrix} = \begin{matrix} \mathbf{X} \\ n \times p' \end{matrix} \begin{matrix} \boldsymbol{\beta} \\ p' \times 1 \end{matrix} + \begin{matrix} \mathbf{e} \\ n \times 1 \end{matrix}$$

$$\boldsymbol{e} \sim N(\mathbf{0}, \sigma^2 \mathbf{I}_n)$$

where  $\mathbf{0}$  is  $n \times 1$  and  $I$  is an  $n \times n$  identity matrix

$$E(\boldsymbol{e}) = \mathbf{0}$$

$$\text{var}(\boldsymbol{e}) = \sigma^2 \mathbf{I}n$$

Then the estimator  $\hat{\boldsymbol{\beta}} = \left( \begin{matrix} \mathbf{X}^T & \mathbf{X} \\ p' \times n & n \times p' \end{matrix} \right)^{-1} \begin{matrix} \mathbf{X}^T & \mathbf{Y} \\ p' \times n & n \times 1 \end{matrix}$

minimizes  $RSS(\boldsymbol{\beta}) = \sum (y_i - \mathbf{x}_i^T \boldsymbol{\beta})^2 = (\mathbf{Y} - \mathbf{X}\boldsymbol{\beta})^T (\mathbf{Y} - \mathbf{X}\boldsymbol{\beta})$

The important thing to note here is that the estimator deals with *cases / observations*

# A change in focus: Covariance instead of cases

- Instead of minimizing  $RSS(\beta)$  we want to minimize difference between sample covariance and model predicted covariance

$$\text{obs covar} - \widehat{\text{covar}} = \text{residuals}$$

- $H_0$ : Observed covariance is a function of a set of parameters if model is correct and parameters are known, then residuals = 0

$\Sigma = \Sigma(\theta)$  – Fundamental Equation

$\Sigma$  - population covariance matrix of observed variables

$\theta$  - vector of model parameters

$\Sigma(\theta)$  - population covariance matrix as a function of model parameters

I cannot stress enough how important this equation is.  
We will return to it again and again and again.

## Simple regression:

$y = \gamma x + \zeta$  where  $y$ ,  $x$ , and  $\zeta$  are random variables and  $E(\zeta)=0$

Then:  $\Sigma = \Sigma(\theta)$

$$\begin{bmatrix} \text{VAR}(y) & \\ \text{COV}(x, y) & \text{VAR}(x) \end{bmatrix} = \begin{bmatrix} \gamma^2 \text{VAR}(x) + \text{VAR}(\zeta) & \\ \gamma \text{VAR}(x) & \text{VAR}(x) \end{bmatrix}$$

where:  $\text{VAR}(y) = \gamma^2 \text{VAR}(x) + \text{VAR}(\zeta)$  because  $\text{VAR}(\gamma x) = \gamma^2 \text{VAR}(x)$

and:  $\text{COV}(x, y) = \gamma \text{VAR}(x)$  because  $\gamma = \frac{SXY}{SXX}$  and  $\text{VAR}(x) = \frac{SXX}{n-1}$

Then:  $\frac{SXY}{SXX} * \frac{SXX}{n-1} = \frac{SXY}{n-1} = \text{COV}(x, y)$

Here,  $\theta$  has 3 parameters:  $\gamma$ ,  $\text{VAR}(x)$ , and  $\text{VAR}(\zeta)$

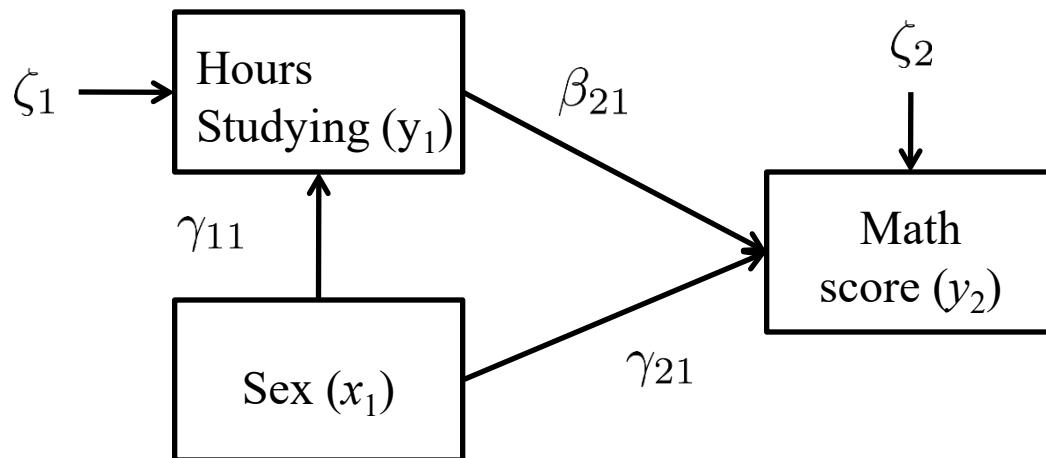
# Types of SEMs

1. Path analysis models
  - Usually involves only observed variables

# Path analysis

(Wright, 1918, 1921, 1934, 1960)

## 1) Path Diagram



**One way** “causal” influences  
from variable at base to point

# Path Analysis cont.

2) Equations     $y_1 = \gamma_{11}x_1 + \zeta_1$

$$y_2 = \gamma_{21}x_1 + \beta_{21}y_1 + \zeta_2$$

# Path Analysis continued

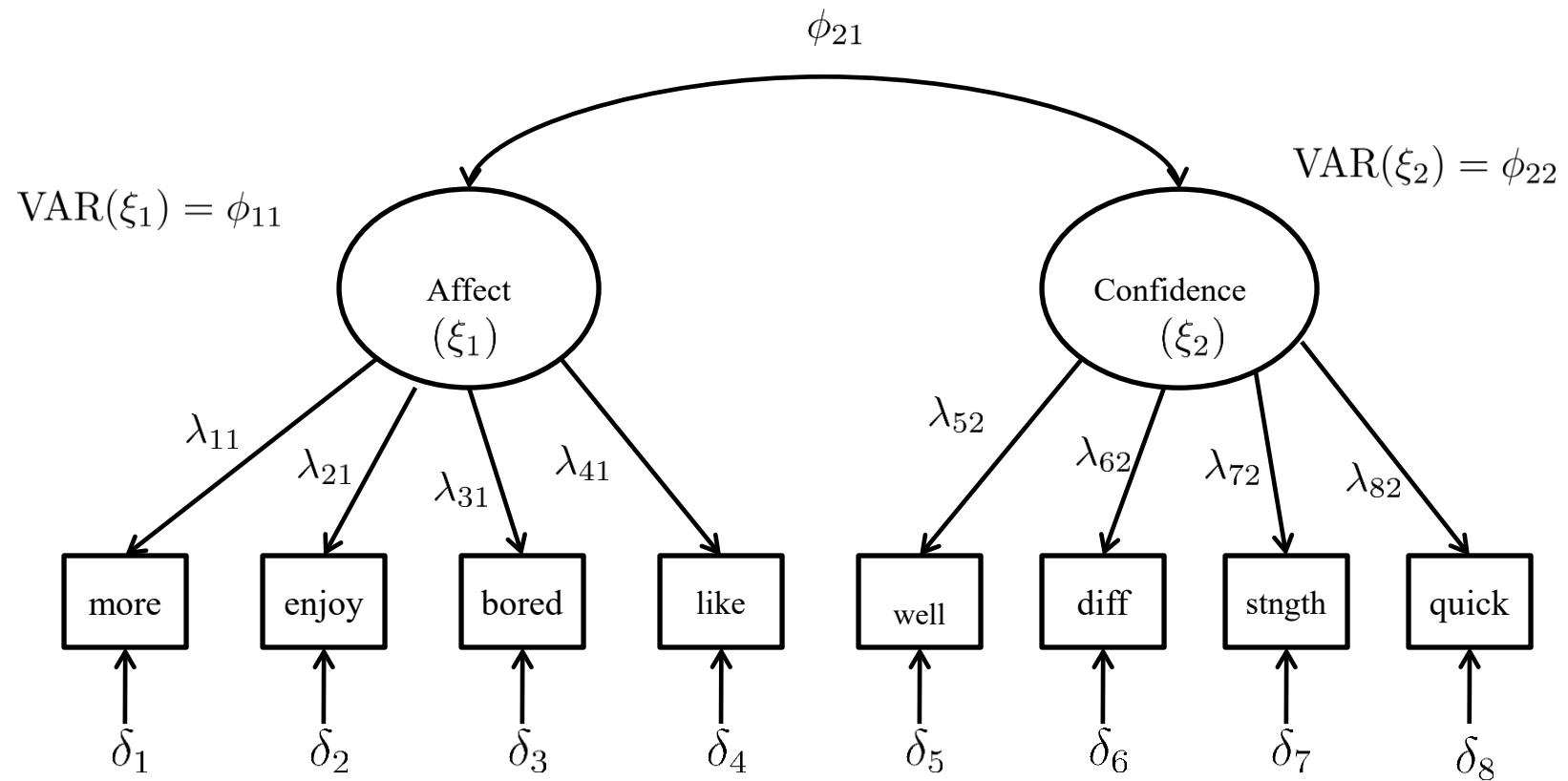
- 3) Can distinguish      direct  
                        indirect    } effects  
                        total

# Types of SEMS

2. Confirmatory factor analysis / measurement model
  1. Involves one or more latent variables and the way in which they relate to manifest/observed variables
  2. No specified relationship between latent variables
  3. Useful for scale development

# Confirmatory factor analysis

- Two factors:



# Confirmatory Factor Analysis

- Describes structure of data in terms of relationships with latent variables
- Lots of assumptions underlying – we'll discuss in a few weeks.

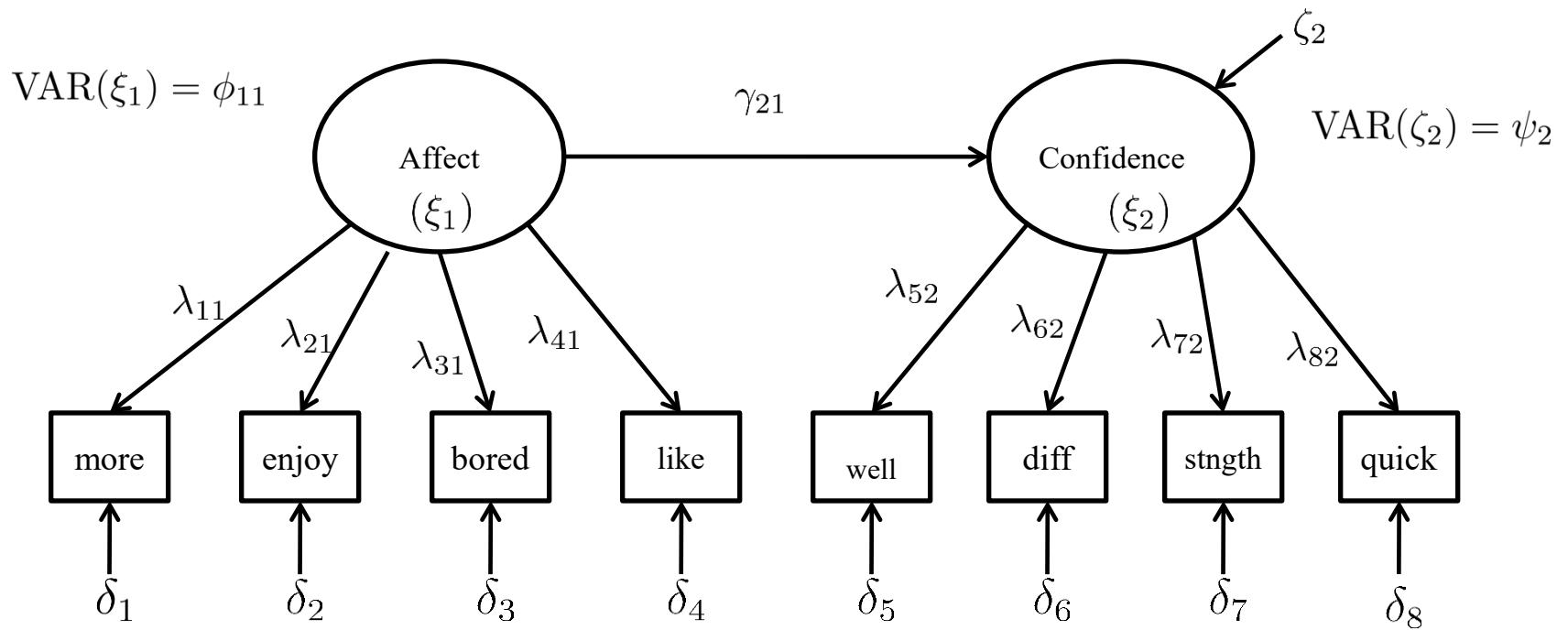
# Types of SEMS

## 3. Structural models

- Somewhat similar to measurement models except relationships between latent variables are also postulated.
- Particularly well suited for testing hypotheses about relationships among latent variables.

# Structural model

- Two factors: *Affect* predicts *Confidence*

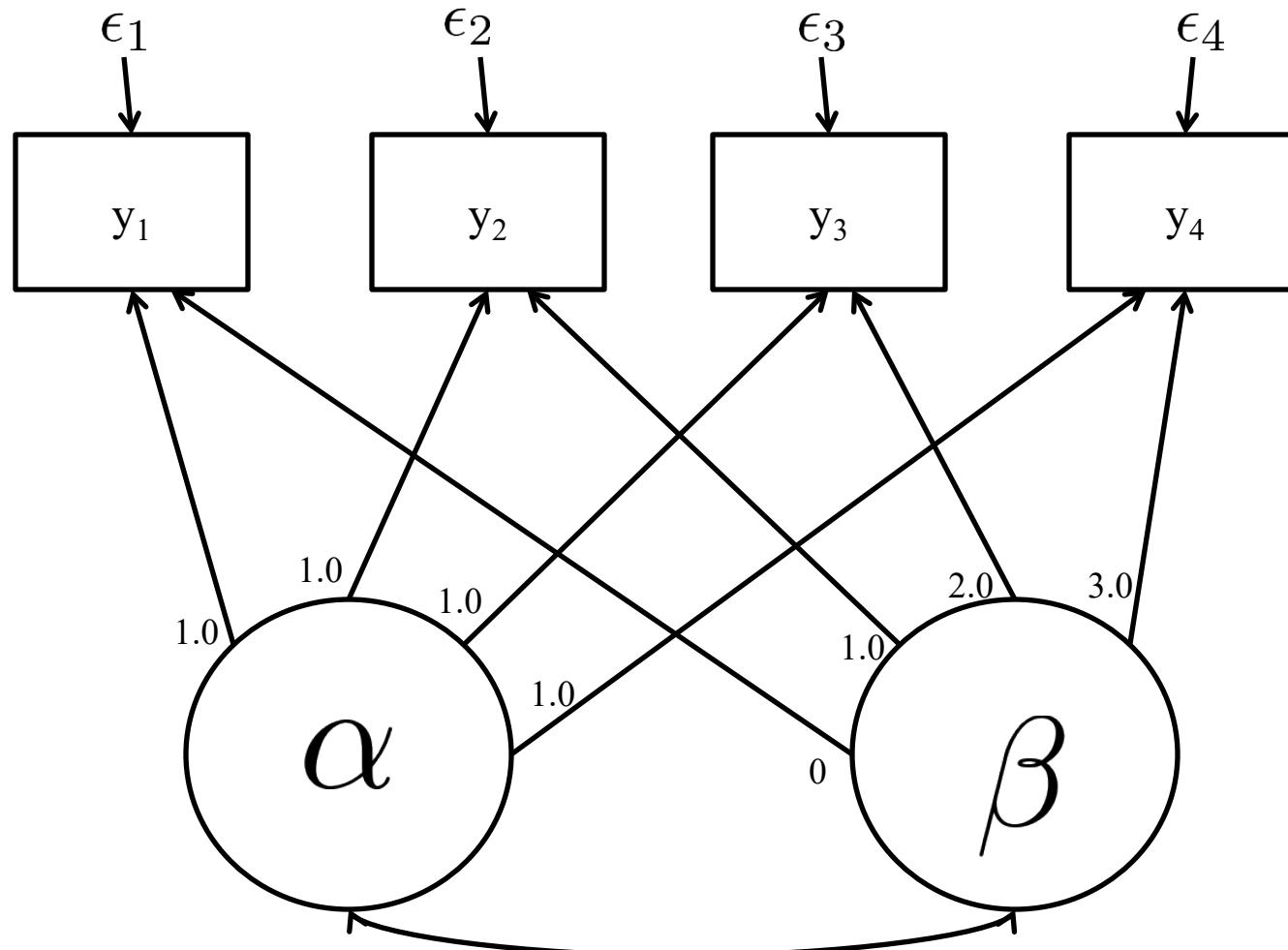


# Types of SEMs

## 4. Latent growth/change models

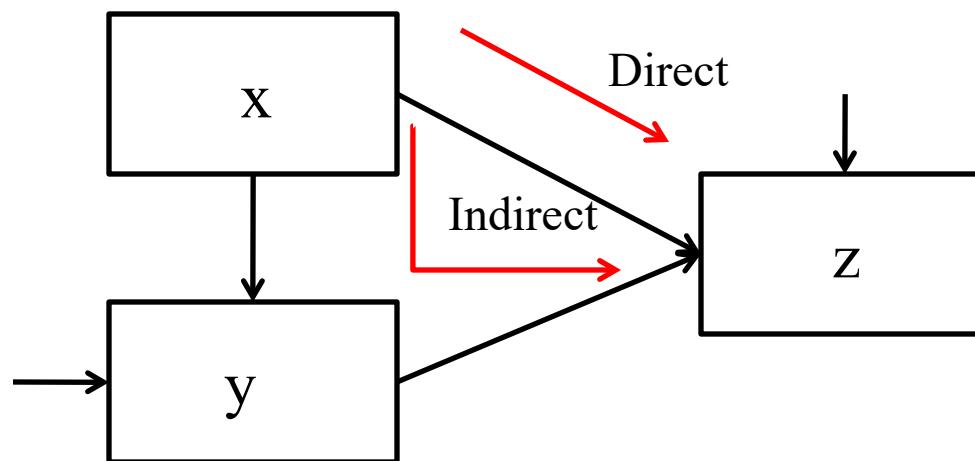
- Intended to study change over time

# Growth model



# When are SEMs useful?

- To test theories about phenomena
- To validate measures
- Theory development (exploratory)
- For studying direct & indirect effects



# Systems of Linear Equations

- Linear in the observed, latent, and disturbance variables
- Not necessarily linear in the covariance structure equations

# Evolution

- From path analysis to LISREL model
  - LISREL: linear structural relations (Jöreskog)
- We use “LISREL” notation
- There are others:
  - Bentler & Weeks (1980)
  - McArdle & McDonald (1984)

# On your own time

- Review of matrix algebra. Be sure to have a look at:
  - Bollen Appendix A
  - Your old Y604 notes on linear algebra
- For a general orientation:
  - MacCallum, R. & Austin, J. (2000). Applications of structural equation modeling in psychological research. *Annual review of Psychology*, 51(1), 201-227.
  - Weston, R. & Gore, P. (2006). A brief introduction to structural equation modeling. *The Counseling Psychologist*, 34(5), 719-751.

# 1<sup>st</sup> Exercise

- Matrix/linear algebra exercise
  - Details are on Canvas
  - You are free to work with one partner, but **please only turn in one joint submission** on Canvas.

# Next: Notation & Path Analysis

- Model notation
  - Get friendly with the Greek alphabet!
  - There is a Greek alphabet saved in the Class 2 folder on Canvas.
- See the syllabus for upcoming readings