

Finite State Machine, state charts

model checking?



Finite State Machine, state charts and implementations

V&V



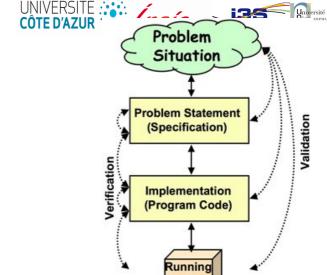
V&V?



- Disclaimer:
 - on ne verra ici qu'une introduction aux notions et problèmes de V&V. Beaucoup de raccourcis sont fait mais cela devrait être suffisant pour vous donner l'intuition derrière ces notions et vous permettre de les approfondir par vous même si besoin.

- Verification and Validation
 - Verification: Construisons-nous le système correctement ?
 - Est-ce que le système est implémenté de manière correcte ? (sans erreur, avec les bonnes performances, sans fuites mémoires, rafinement correct, etc)
 - Validation:





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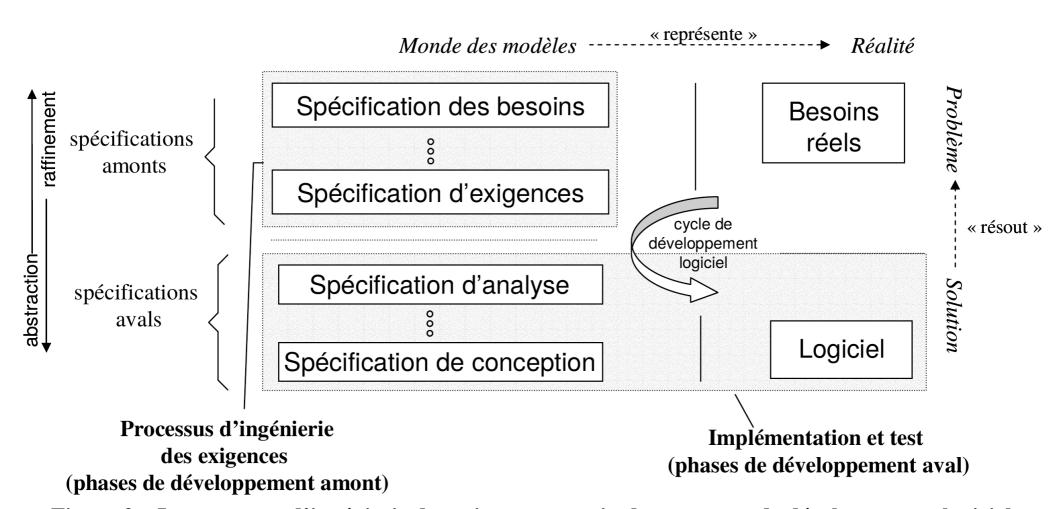
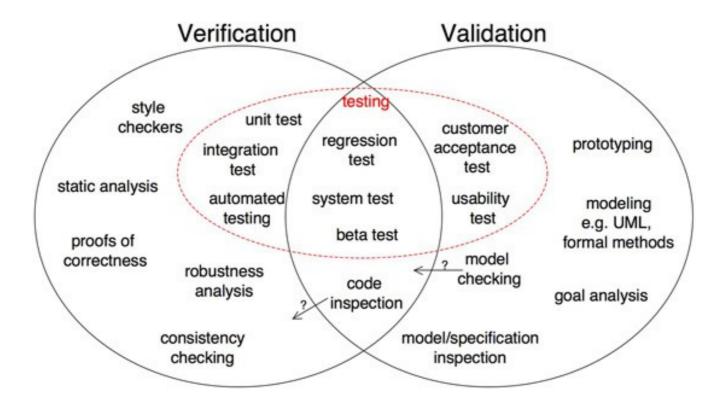


Figure 2 – Le processus d'ingénierie des exigences au sein du processus de développement logiciel.

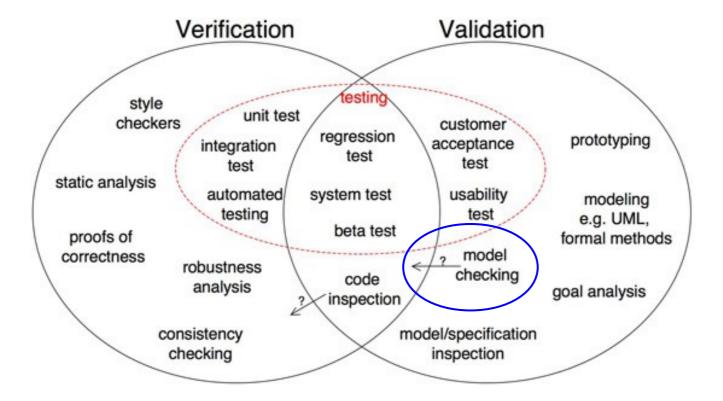
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 - Est-ce que le système que nous développons est celui que le client voulait / qui répond au problème initial?
- → Dans les deux cas on "pose des questions au système".



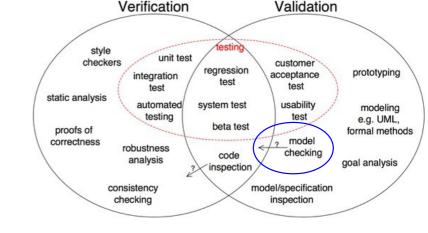
Verification and Validation



Verification and Validation



V&V?

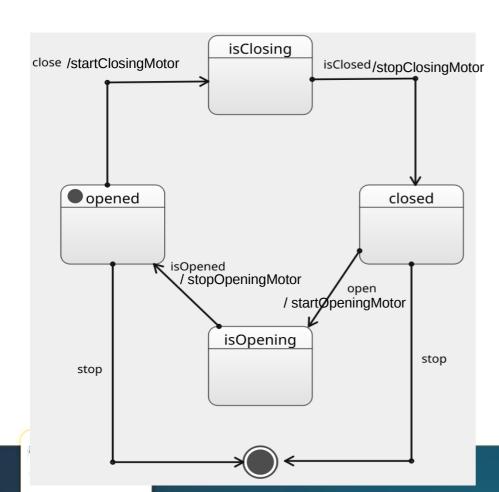


- Testing or model checking? (intuition)
 - <u>testing</u>: regarder si certains chemins d'exécutions donnent le résultat attendu. On pose autant de questions que nécessaires pour vérifier une propriété du système.
 - → taux de couverture ? Nombre de tests ?
 - model checking: regarder si tous les chemins d'exécution donnent le résultat attendu. On exprime une propriété sous la forme d'une expression
 - → ensemble de chemins d'exécutions finis ? Quel type de propriétés ?



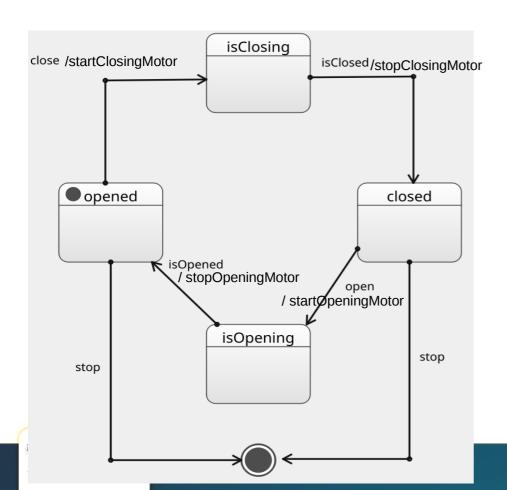


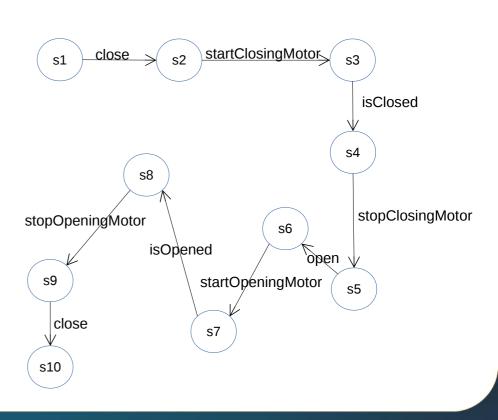
- Each test or run of a program creates a trace.
- Speaking automata, a trace is a, possibly infinite, sequence of states and transitions. It is a word accepted by the automata.





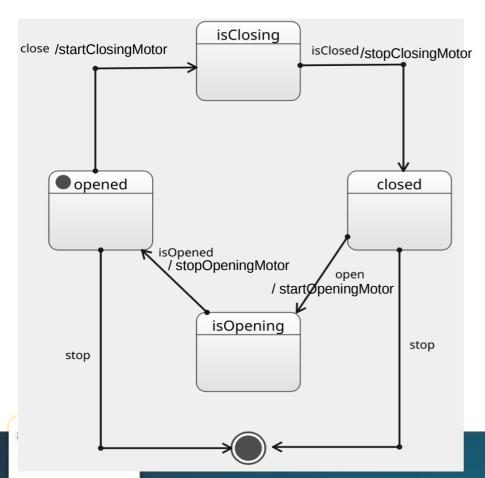
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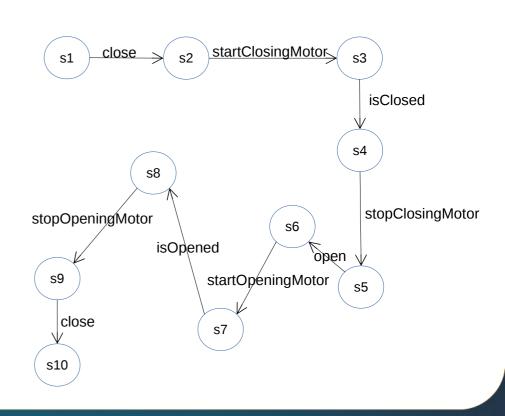






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- Speaking code, a trace is a, possibly sequence of states and

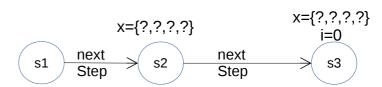
```
transitions:)
 1 #include <stdio.h>
 2 #include <assert.h>
                                                               next
Step
   void foo( int *array ) {
       for ( int i = 0; i <= 4; ++i ) {
           printf( "writing at index %d\n", i );
           array[i] = 42;
  int main() {
       int x[4];
       foo(x);
       assert( x[3] == 42 );
15 }
```



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```
transitions:)
#include <stdio.h>
    #include <assert.h>
                                                                                                            x=\{?,?,?,?\}
                                                                                      x=\{?,?,?,?\}
                                                                                                                i=0
    void foo( int *array ) {
                                                                                                   next
                                                                                 next
                                                                                                                s3
                                                                                 Step
                                                                                                   Step
         for ( int i = 0; i <= 4; ++i ) {
                                                                                                                  next
               printf( "writing at index %d\n", i );
                                                                                                                  Step
               array[i] = 42;
                                                                                                                     x=\{42,?,?,?\}
                                                                             x = \{42, 42, 42, 42\}, 42
                                                                                                  x=\{42,42,42,?\}
                                                                                     s8
                                                                                                                   next
                                                                             next
                                                                                                                   Step
                                                                             Step/
                                                                                                        s6
    int main() {
                                                                                       next
                                                       x=\{42,42,42,42\},42
         int x[4];
12
                                                                                                next
                                                                                       Step
                                                                                                          next
                                                                                                Step
                                                                                                                     x={42,42,?,?}
         foo(x);
                                                                                                          Step
                                                         resAssert = true
         assert( x[3] == 42 );
                                                                       next
15 }
                                                                       Step
                                                                                               s7
```

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trace (run), state space and real life

- Each test or run of a program creates a trace.
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- Speaking code, a trace is a, possibly sequence of states and transitions:)

```
$ divine verify program.c
                                                        DIVINE will now compile your program and run the verifier on the compiled code. After a short while, it
 1 #include <stdio.h>
                                                        will produce the following output:
 2 #include <assert.h>
                                                        compiling program.c
 4 void foo( int *array ) {
                                                        loading bitcode ... LART ... RR ... constants ... done
        for ( int i = 0; i <= 4; ++i ) {
                                                        booting ... done
             printf( "writing at index %d\n", i ); found 83 states in 0:00,
             array[i] = 42;
11 int main() {
        int x[4];
        foo(x);
13
        assert( x[3] == 42 );
14
```



15 **}**

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DIVINE will now compile you will produce the following of will produce the following of will produce the following of compiling program.c loading bitcode ... LART ... booting ... done found 83 states in 0:00, array[i] = 42;

}

printf( "writing at index %d\n", i );

array[i] = 42;

printf( "writing at index %d\n", i );

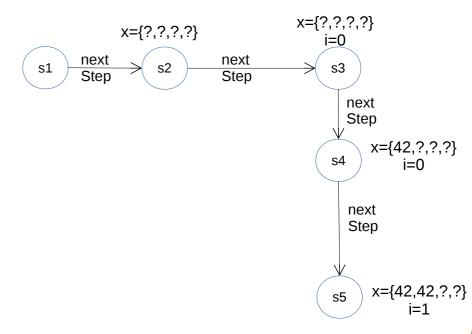
int main() {
   int x[4];
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PIVINE will now compile you will produce the following of compiling program.c loading bitcode ... LART ... booting ... done
found 83 states in 0:00,

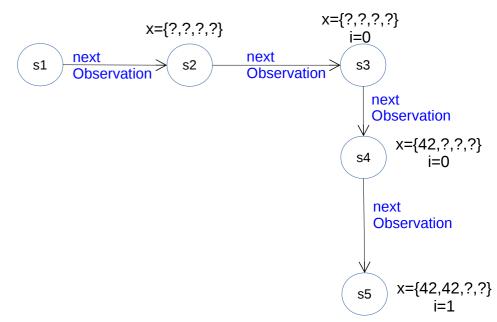
error found: yes
error trace: |
   [0] writing at inde
   [0] writing at inde
   [0] writing at inde
   FAULT: access of si
   [0] Fault in usersp
   [0] Backtrace:
```

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will produce the following output:
compiling program.c
loading bitcode ... LART ... RR ... constants ... done
booting ... done
error found: yes
error trace:
  [0] writing at index 0
  [0] writing at index 1
  [0] writing at index 2
  [0] writing at index 3
  [0] writing at index 4
  FAULT: access of size 4 at [heap* 53e6ba2a 10 ddp] is 4 bytes out of bounds
  [0] Fault in userspace: memory
  [0] Backtrace:
  [0]
         1: foo
  [0]
         2: main
  [0]
         3: start
```

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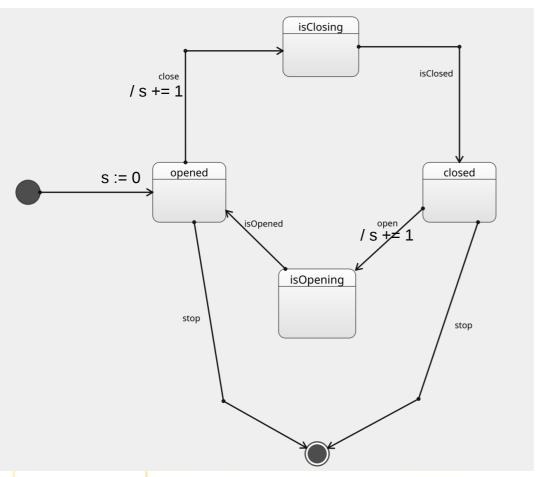
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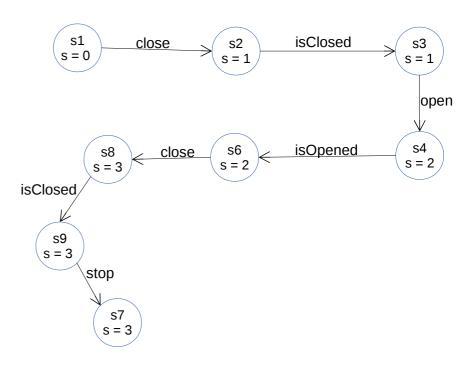




To obtain traces:

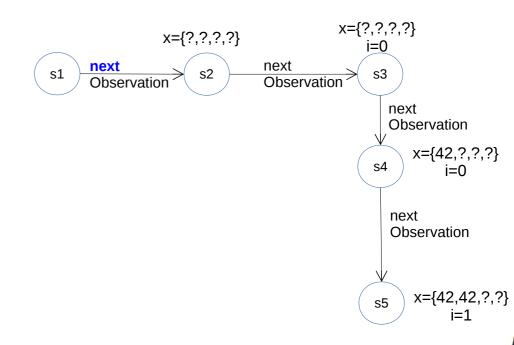
- Take your favorite programming/modeling language
- Equip it with discrete transition semantics (e.g., S.O.S)
- Determine what should be observable events / conditions / execution states







• All traces are dealing with time



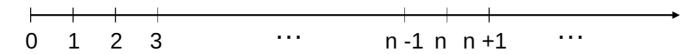
Time

All traces are dealing with time

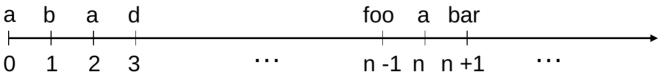
Time is discrete

Starts at 0

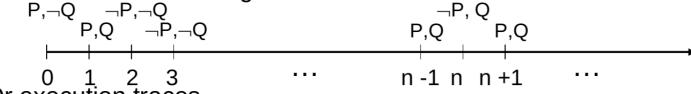
Goes on forever



Time points decorated by events



Or conditions/truth assignments/valuations



Or execution traces





- Specifying properties over time.
- Two types of properties:
 - Safety property: asserts that nothing bad happens.

• Liveness property: asserts that something good eventually happens.





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Safety properties violation can be determinate over finite execution while liveness properties cannot (something good can always happen latter)





Logiques temporelles

- Elles rajoutent une notion de temporalité au dessus de la logique Booleénne.
- Deux classes principales: *Linear Temporal Logic* (LTL) et *Computational Tree Logic* (CTL)



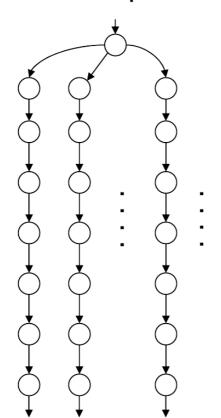
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trace (run), state space and real life

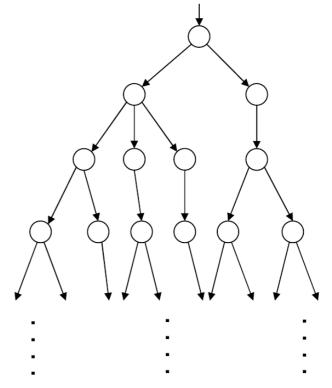
All traces are speaking about time

Branching Time Logic

Sets of paths?



Or computation tree?



Taken from Mads Dam Theoretical Computer Science KTH, 2009

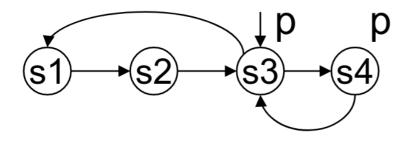


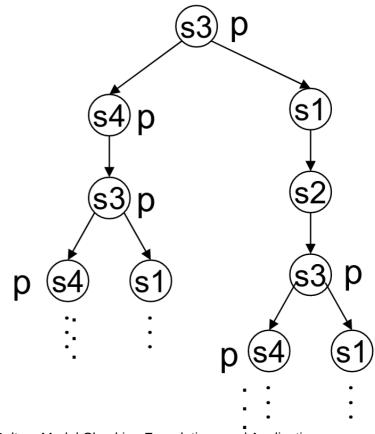


- All traces are speaking about time.
- When possible, a state space (also named transition system)
 represents in a finite way an infinite (set of) traces

Computation Tree

Transition System





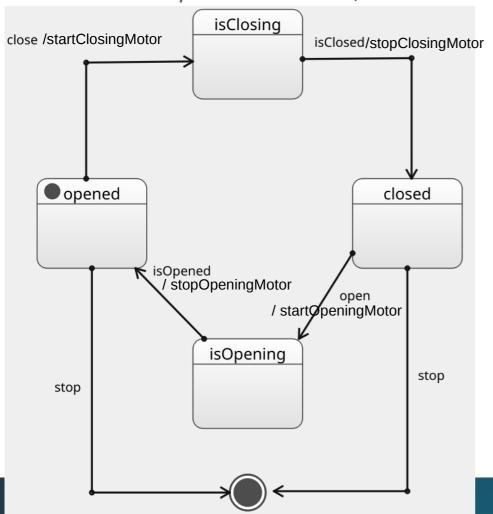
Taken from Tevfik Bultan, Model Checking Foundations and Applications







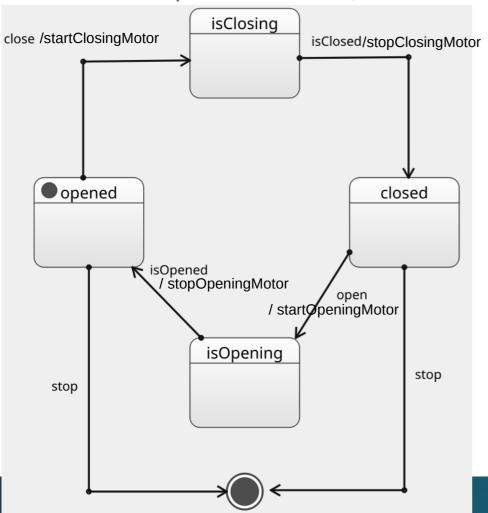
- ensemble de chemins d'exécutions finis?
 - Énumération de l'espace d'état (habituellement un graphe orienté d'une forme particulière : *Labelled Transition system* or *Kripke structure*)

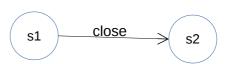


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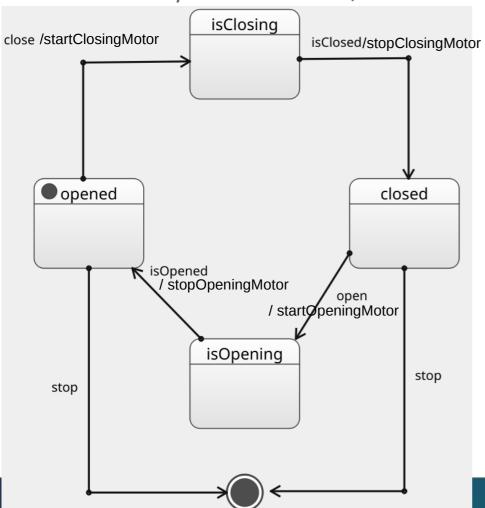
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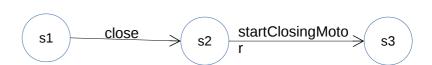




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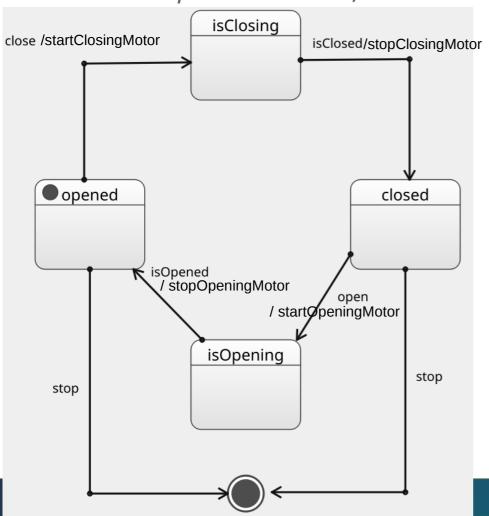
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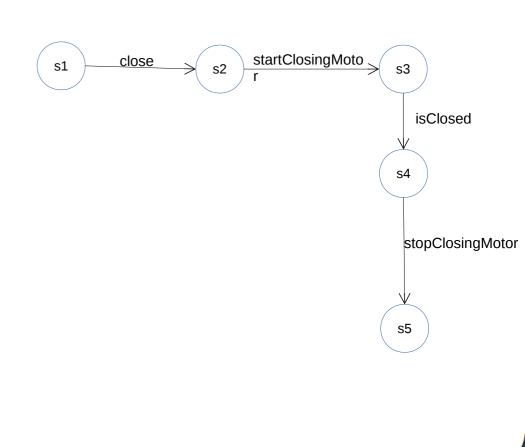




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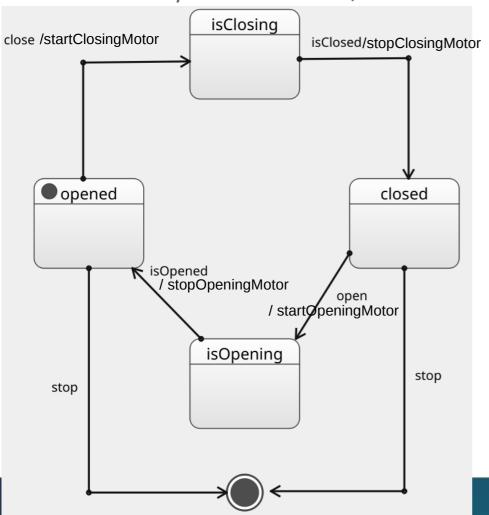


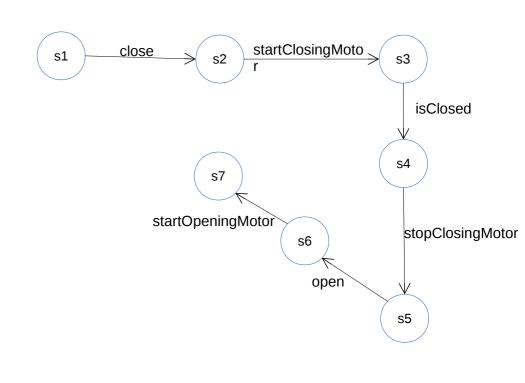


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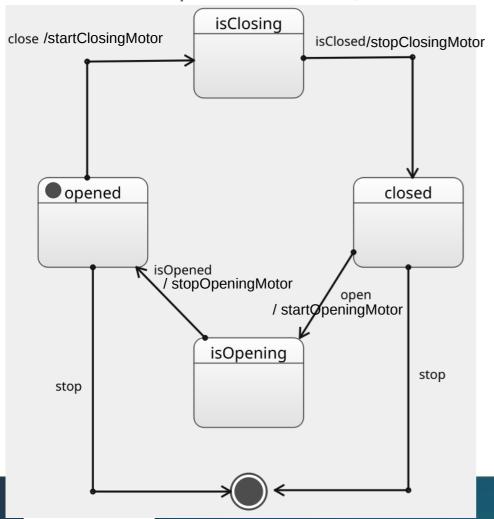
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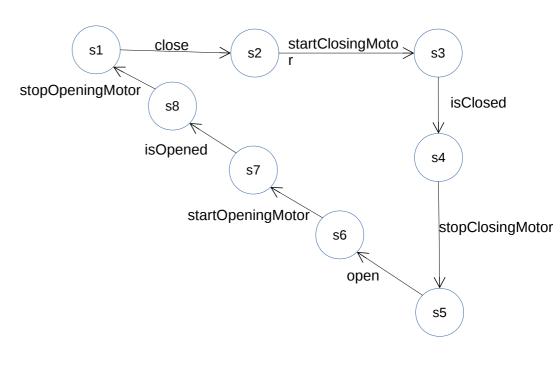




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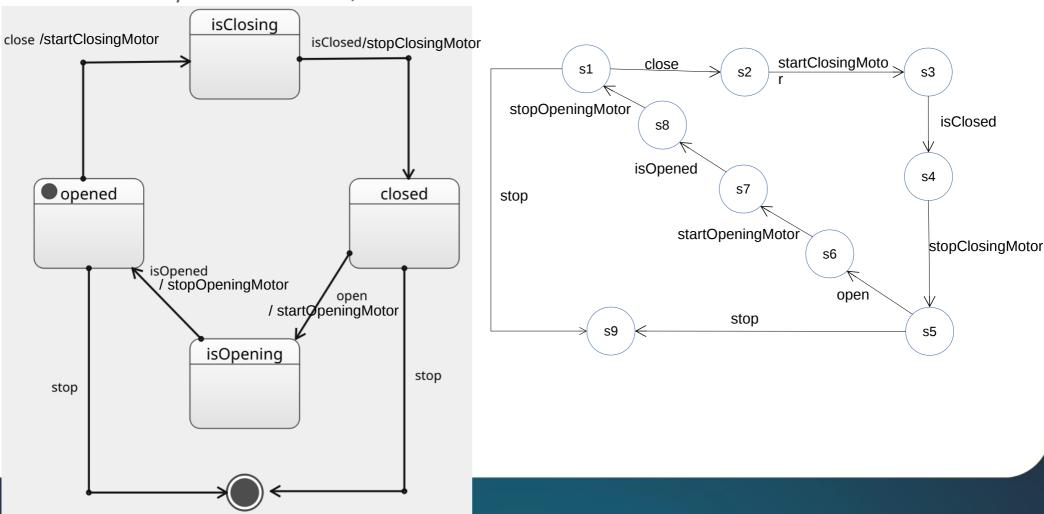
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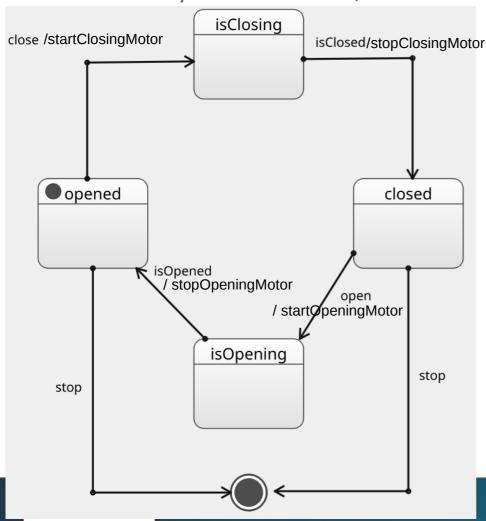
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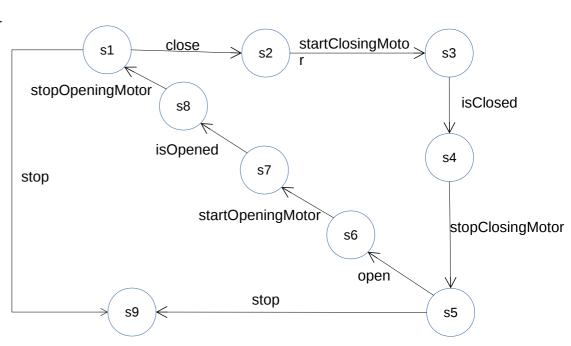
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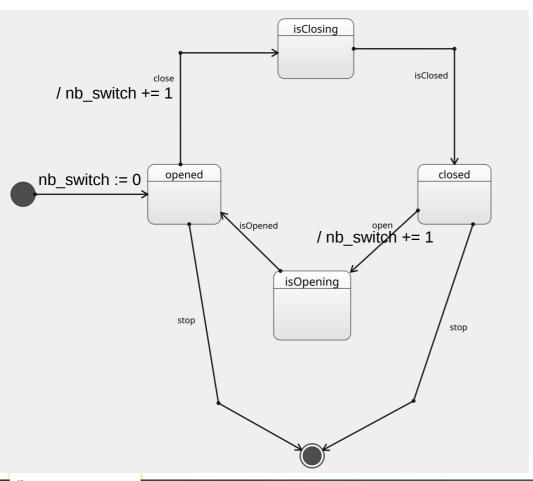
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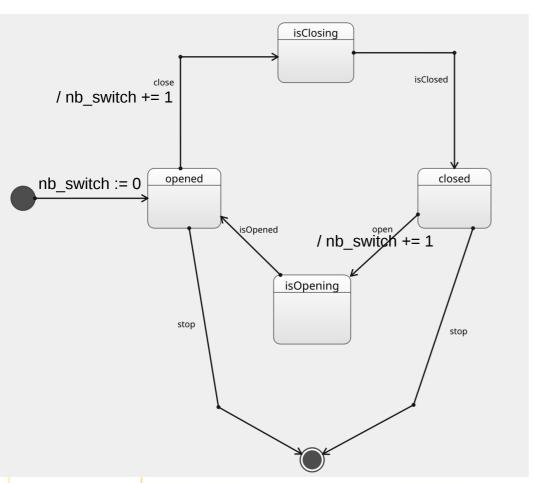


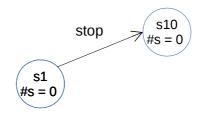


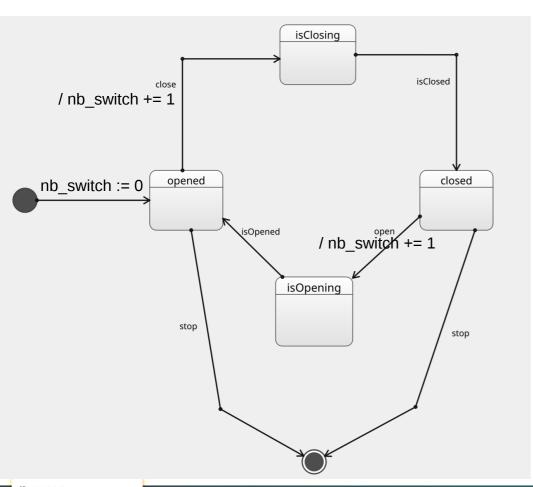
Plus les actions on Enter et on Exit!

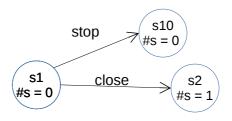


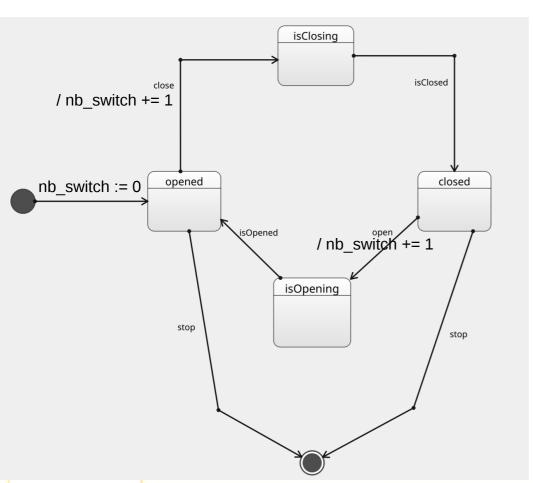


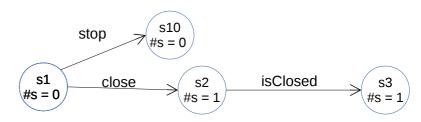


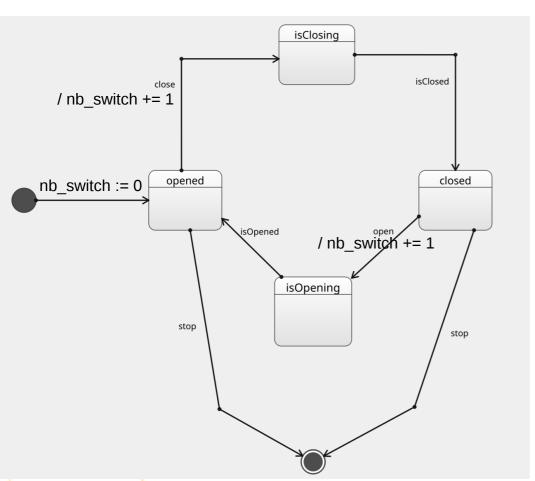


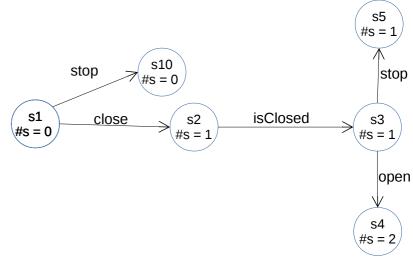


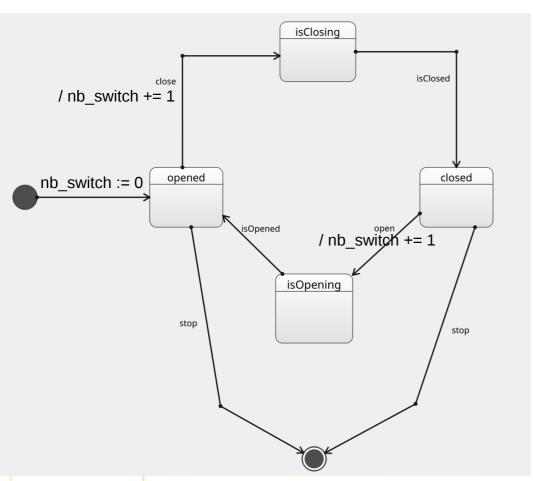


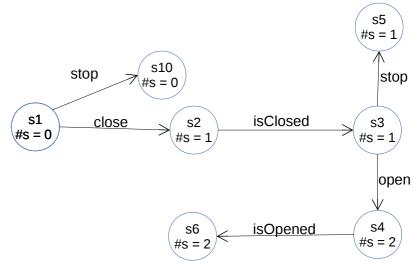


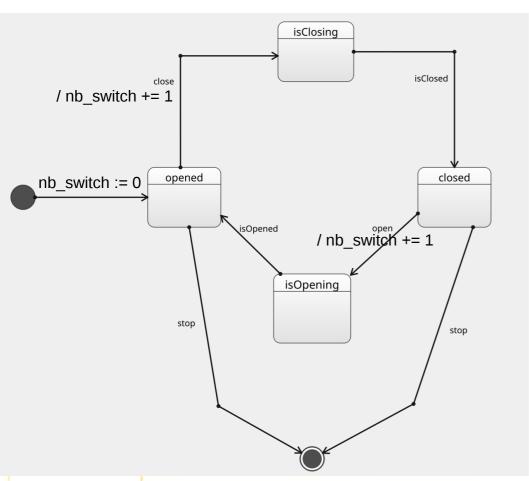


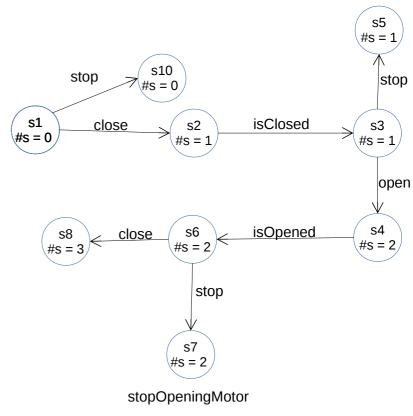


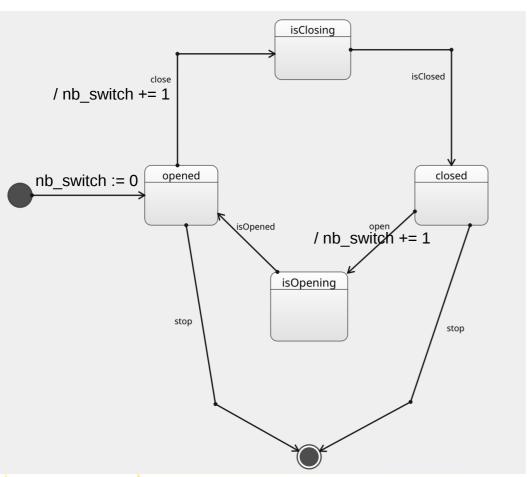


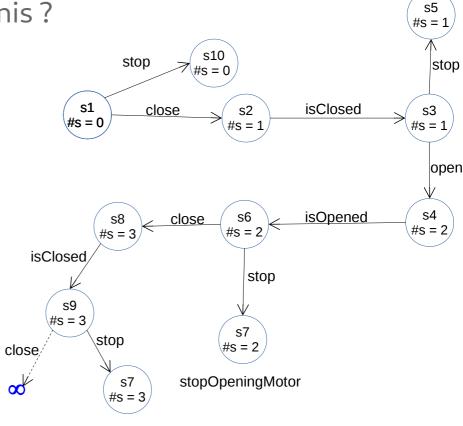






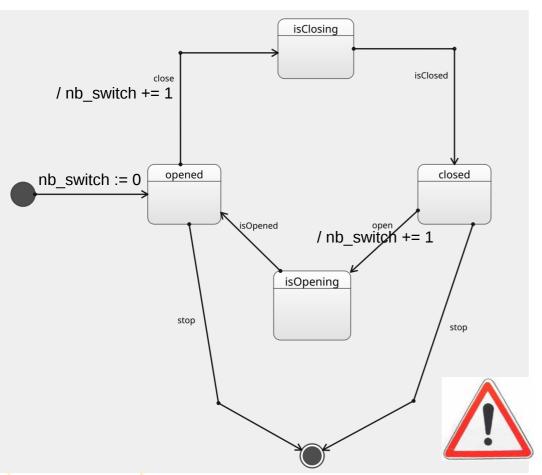


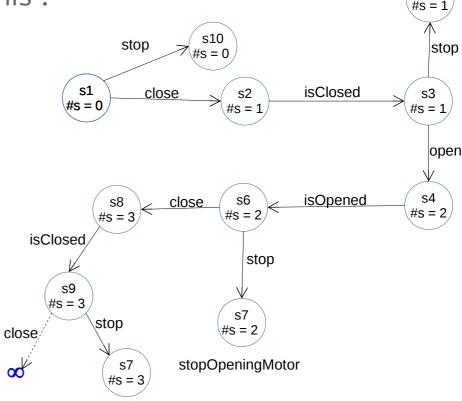




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• ensemble de chemins d'exécutions finis ?



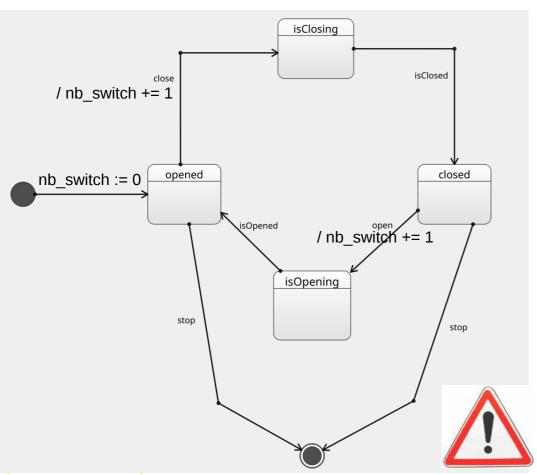


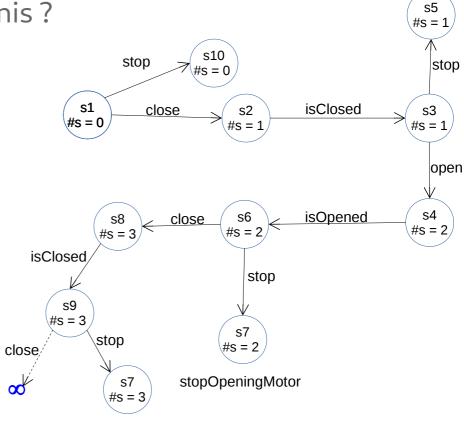
Tout ce qui est dans la state machine est considéré dans la construction de l'espace d'état.

Tout ce qui n'est pas dans la state machine ne peut pas être utilisé pour "poser des questions"



• ensemble de chemins d'exécutions finis ?





 Determine what should be observable events / conditions / execution states





Logiques temporelles

- Elles rajoutent une notion de temporalité au dessus de la logique Booleénne.
- Deux classes principales: *Linear Temporal Logic* (LTL) et *Computational Tree Logic* (CTL)

Textual	Symbolict						
Unary operators:							
X ϕ	$\bigcirc \phi$	ne X t: ϕ ł					
G ϕ	$\Box \phi$	G lobally:					
F ϕ	$\Diamond \phi$	Finally: q					
Binary operators:							
ψ U ϕ	$\psi\mathcal{U}\phi$	Until: ψ					
ψ R ϕ	$\psi\mathcal{R}\phi$	Relea					





Textual	Symbolict	Explanation		Diagram				
Unary or	perators:							
$\mathbf{X}\phi$	$\bigcirc \phi$	ne X t: ϕ has to hold at the next state.		→• φ	- - • •	→・	>	
G ϕ	$\Box \phi$	G lobally: ϕ has to hold on the entire subsequent path.	$\dot{\phi}$	ϕ	-→• φ	\rightarrow_{ϕ}	> φ	
F ϕ	$\Diamond \phi$	Finally: ϕ eventually has to hold (somewhere on the subsequent path).	•	→•	-→• φ	→•	>	
Binary o	Binary operators:							
ψ U ϕ	$\psi\mathcal{U}\phi$	U ntil: ψ has to hold <i>at least</i> until ϕ , which holds at the current or a future position.	$\dot{\psi}$	$\dot{\psi}$	- , . ψ	$\overrightarrow{\phi}$	>	
ψ R ϕ	$\psi\mathcal{R}\phi$	R elease: ϕ has to be true until and including the point where ψ first becomes true; if ψ never becomes true, ϕ must remain true forever.	ϕ	ϕ	- → • —	$\overrightarrow{\phi}, \overrightarrow{\psi}$	>	
	Ψ	Release. φ has to be true until and including the point where φ more becomes true, if ψ have becomes true, φ must remain true forever.	$\dot{\phi}$	ϕ	- → • φ	ϕ	› φ	

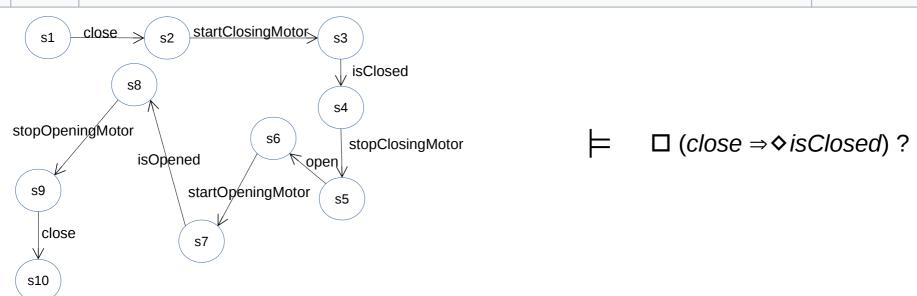
Model checking problem:

Given a model M and an LTL formula $\phi,$ all traces of M must satisfy ϕ Given a transition system T and an LTL property, determine if T is a model for p



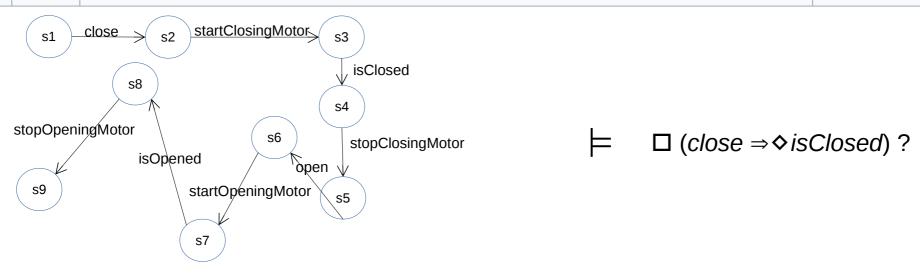


Textual	Symbolict	Explanation		Diagram				
Unary op	perators:							
$X\phi$	$\bigcirc \phi$	ne X t: ϕ has to hold at the next state.		→• φ	- → • —	→・	>	
G ϕ	$\Box \phi$	G lobally: ϕ has to hold on the entire subsequent path.	$\dot{\phi}$	→• φ	- , φ	ϕ	> φ	
F ϕ	$\Diamond \phi$	Finally: ϕ eventually has to hold (somewhere on the subsequent path).		→•	• φ	→•	>	
Binary o	Binary operators:							
ψ U ϕ	$\psi\mathcal{U}\phi$	U ntil: ψ has to hold <i>at least</i> until ϕ , which holds at the current or a future position.	$\dot{\psi}$	$\dot{\psi}$	$\dot{\psi}$	ϕ	>	
ψ R ϕ	$\psi \mathcal{R} \phi$	Release: ϕ has to be true until and including the point where ψ first becomes true; if ψ never becomes true, ϕ must remain true forever.	$\dot{\phi}$	→• φ	• φ	$\overrightarrow{\phi}, \overrightarrow{\psi}$	>	
	Ψ		$\dot{\phi}$	→ • · · · · · · · · · · · · · · · · ·	• φ	$\overrightarrow{\phi}$	φ	



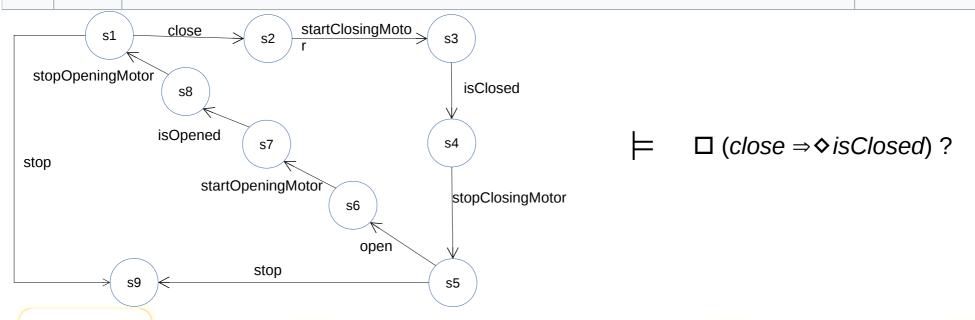


Textual	Symbolict	Explanation		Diagram				
Unary or	perators:							
$X\phi$	$\bigcirc \phi$	ne X t: ϕ has to hold at the next state.	•	•• φ	- → • —	→・	->	
G ϕ	$\Box \phi$	G lobally: ϕ has to hold on the entire subsequent path.	$\dot{\phi}$	•• φ	•• φ	ϕ	- > φ	
F ϕ	$\Diamond \phi$	Finally: ϕ eventually has to hold (somewhere on the subsequent path).	·	→ • – – ·	• φ	→•	->	
Binary o	Binary operators:							
ψ U ϕ	$\psi\mathcal{U}\phi$	U ntil: ψ has to hold <i>at least</i> until ϕ , which holds at the current or a future position.	$\dot{\psi}$	ψ	$\dot{\psi}$	ϕ	->	
ψ R ϕ ψ π	$\psi \mathcal{R} \phi$	ϕ R elease: ϕ has to be true until and including the point where ψ first becomes true; if ψ never becomes true, ϕ must remain true forever.	$\dot{\phi}$	••· φ	• φ	$\overrightarrow{\phi}, \overrightarrow{\psi}$	->	
			ϕ	•• φ	• φ	ϕ	- > φ	





Textual	Symbolict	bolic† Explanation		Diagram				
Unary of	perators:							
$\mathbf{X}\phi$	$\bigcirc \phi$	ne X t: ϕ has to hold at the next state.	•	→• φ	· · ·	→•	>	
G ϕ	$\Box \phi$	G lobally: ϕ has to hold on the entire subsequent path.	$\dot{\phi}$	ϕ	φ	ϕ	- , φ	
F ϕ	$\Diamond \phi$	Finally: ϕ eventually has to hold (somewhere on the subsequent path).		→•	• φ	→・	>	
Binary o	perators:							
ψ U ϕ	$\psi\mathcal{U}\phi$	U ntil: ψ has to hold <i>at least</i> until ϕ , which holds at the current or a future position.	$\dot{\psi}$	$\dot{\psi}$	ψ	ϕ	>	
ψ R ϕ	$\psi \mathcal{R} \phi$	$\mathcal{R}\phi$ R elease: ϕ has to be true until and including the point where ψ first becomes true; if ψ never becomes true, ϕ must remain true forever.	$\dot{\phi}$	$\overrightarrow{\phi}$	• φ	$\overrightarrow{\phi}, \overrightarrow{\psi}$	>	
ΨΚΨΨ	Release. ϕ has to be true until and including the point where ϕ hist becomes true, if ϕ here becomes true, ϕ hids tremain true follower.	$\dot{\phi}$	$\overrightarrow{\phi}$	•• φ	ϕ	φ		

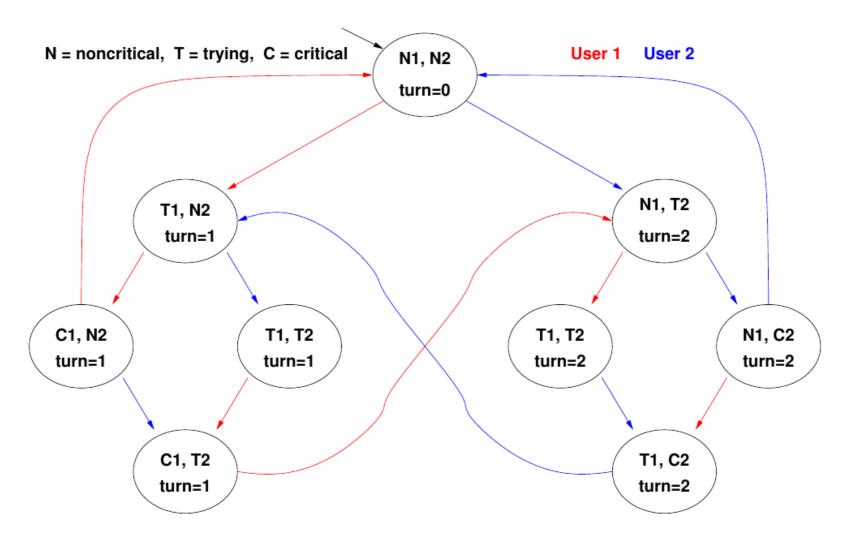


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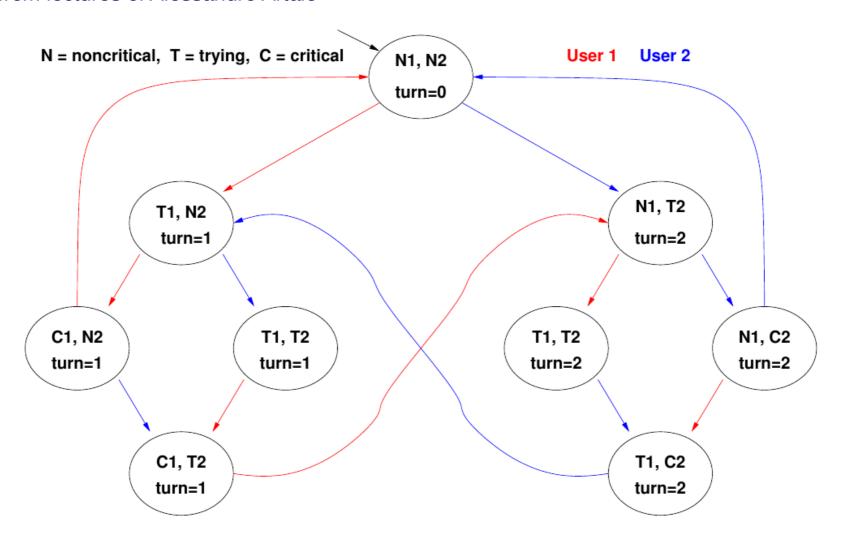




Mutual exclusion system

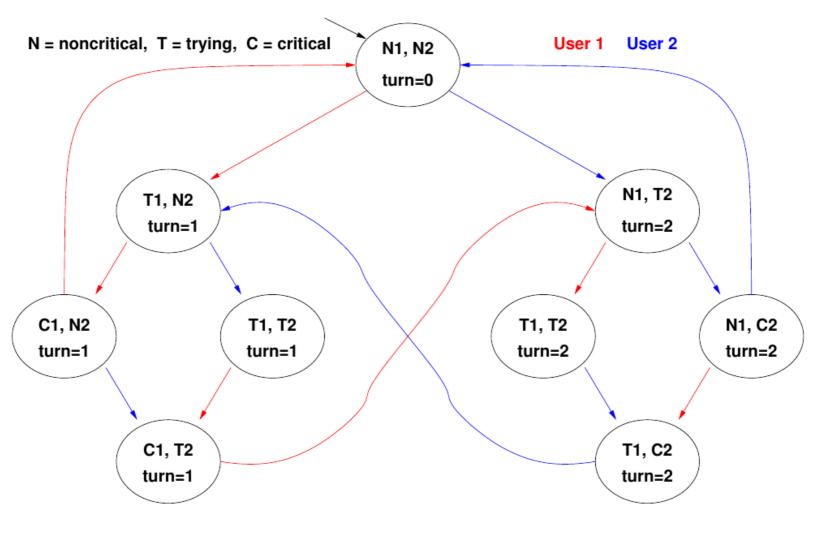






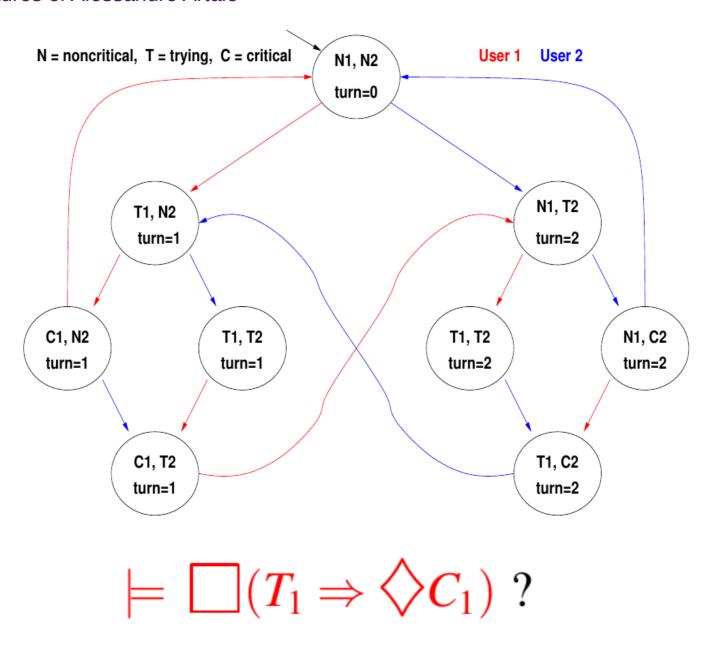
$$\models \Box \neg (C_1 \land C_2) ?$$







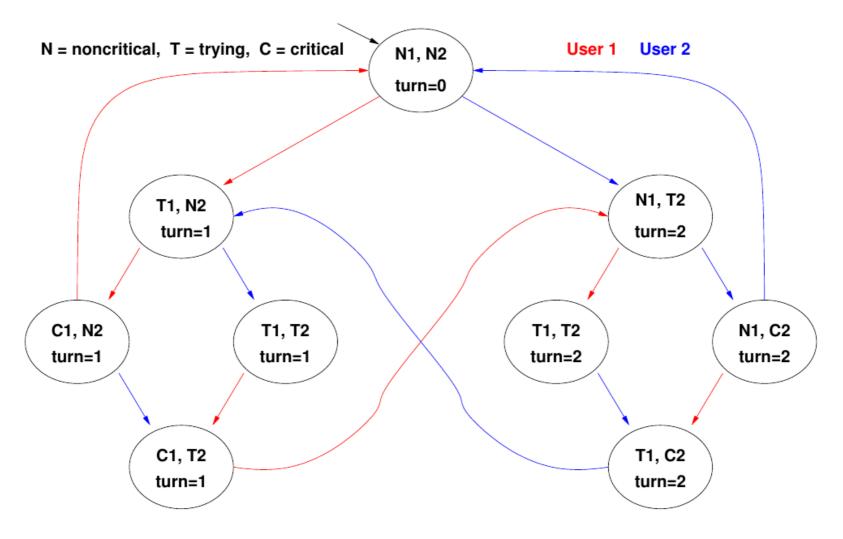








taken from lectures of Alessandro Artale



Il existe de nombreuse forme en langage naturel contraint des logiques temporelles (pattern de Dwyer, de Cheng, de Dhaussy)

