

# A (Basic) C++ Course

12 - lambda expressions and concurrency in C++11 and C++17, and C++20

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A unnamed function (which is a std::function)

• Usable in many place like algorithms, thread, ...

```
[capture] (parameters) ->return-type {body}
```

- [] → putting objects in the scope of the lambda's body
  - [] Capture nothing
  - [&] Capture any referenced variable by reference
  - [=] Capture any referenced variable by making a copy
  - [=, &foo] Capture any referenced variable by making a copy, but capture variable foo by reference
  - [bar] Capture bar by making a copy; don't copy anything else
  - [this] Capture the this pointer of the enclosing class



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```

```
vector<int> v;

//...
for_each( v.begin(), v.end(), [] (int val)
{
    cout << val;
});</pre>
```



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```
vector<int> v;
ofstream f("toto.truc");
//...
for_each( v.begin(), v.end(), [&f] (int
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{
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});</pre>
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vector<int> v;
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//...
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{
    f << val;
    return f; //non-useful here...
});</pre>
```



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ofstream f("toto.truc");
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{
    f << val;
    return f; //non-useful here...
});</pre>
```

Lambda's type: std::function<ostream& (int)>



### Function pointer and Lambda expressions

```
#include <functional>
#include <string>
class Delegator{
public:
    std::function<void (const std::string&)> handler func;
    void process(const string& message) {
        if (handler func) {
            handler func (message); //call to a function pointer
    Delegator(std::function<void (const std::string&) > hf): handler func(hf)
    {}
};
Delegator d1{[&] ("blablabla") {dosomething usefull}};
Delegator d2{[]("/home/toto/toto.truc"){dosomething else}};
```



### Concurrency in C++

- Only from C++11, still evolving
- Well adapted to the STL
  - Thread management
  - Shared data protection
  - Thread synchronization
  - •
- Different abstraction level
- Based on the boost library
- Platform independent

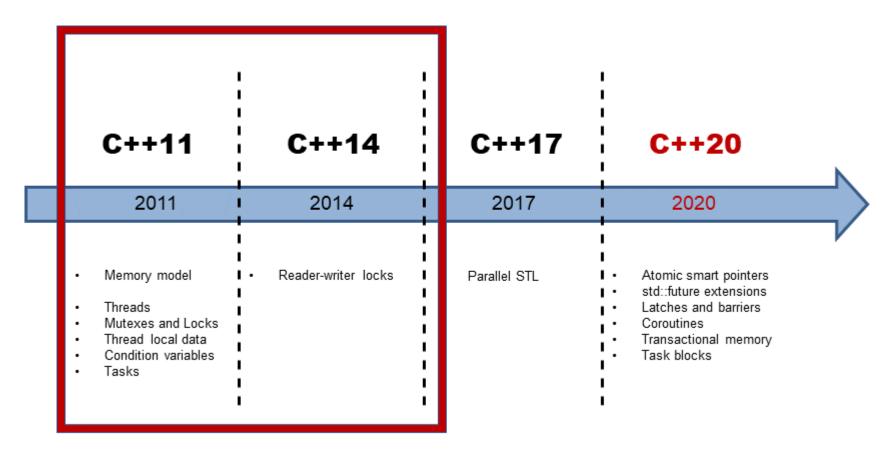








### Concurrency in C++



https://www.modernescpp.com/index.php/c-core-guidelines-rules-for-concurrency-and-parallelism





```
#include <iostream>
#include <thread>
void hello() {
       std::cout << "Hello Concurrent World \n";
int main() {
       std::thread t(hello); //create and start a thread
       t.join(); //wait the end of the thread execution
return 0 :
```





```
#include <iostream>
#include <thread>
class Myfunctor{
public:
void operator();
};
int main() {
       MyFunctor m;
       std::thread t(m); //create and start a thread
       t.join(); //wait the end of the thread execution
return 0 :
```





```
#include <iostream>
#include <thread>
class Myfunctor{
public:
 void operator();
};
int main() {
       std::thread t(MyFunctor()); //create and start a thread
       t.join(); //wait the end of the thread execution
return 0 :
```



```
--hread>
        Is not understood as expected by the compiler
        add parenthesis or use the bracket initialization syntax
std::thread t(MyFunctor());
```

Every thread has to have an initial function, which is where the new

```
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        add parenthesis or use the bracket initialization syntax
std::thread t{MyFunctor()};
```

Every thread has to have an *initial function*, which is where the new

```
Is not understood as expected by the compiler
                                                                                                                                      ightharpoonup and a set of the distribution and a set of the bracket initialization syntax is a set of the bracket
                                       std::thread t{MyFunctor()};
https://stackoverflow.com/questions/18222926/why-is-list-initialization-using-curly-braces-better-than-the-alternatives
```

Every thread has to have an initial function, which is where the new



```
#include <iostream>
#include <thread>
class Myfunctor{
 Xxxx someAttribute
public:
 MyFunctor(Xxxx someParam);
void operator();
};
int main() {
       std::thread t{MyFunctor(xxx)}; //create and start a thread
       t.join(); //wait the end of the thread execution
return 0:
```









For any versions, add <a href="#">-pthread</a> to the linker flags





The destructor of std::thread calls std::terminate()

→ you may choose to detach or join





### Joining a thread

```
t.join();
```

thread::join() cleans up the storage associated with the thread. After join () returned, t is not associated with a thread anymore t.joinable() returns false hoose to detach or join

→ thread::join() can be called only once per thread object

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### Thread object life duration

The destructor of std::thread calls std::terminate()
→ you may choose to detach or join



The notion of Object life duration is to take into account carefully!



### Detaching and object life duration

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```
#include <iostream>
#include <thread>

doSomething(int intcopy, string s);

int main() {
    int anInt = 0;
    std::thread t{doSomething, anInt, string("a string !")};
    t.join();
return 0;
}
```

Explicit call to string constructor to avoid conversion from const char \* to int in doSomething...





```
#include <iostream>
#include <thread>

doSomething(int intcopy, string s);

int main() {
    int anInt = 0;
    string s = "a string !";
    std::thread t{doSomething, anInt, s};
    t.join();
return 0;
}
```

Explicit call to string constructor to avoid conversion from const char \* to int in doSomething...



```
#include <iostream>
#include <thread>

doSomething(string& s) { s+="!"}

int main() {
   int anInt = 0;
   std::thread t{doSomething, std::string("a string !")};
   t.join();
return 0;
}
```

Explicit call to string constructor to avoid conversion from const char \* to string *inside* doSomething...

Thread constructor is unaware of reference passing and will copy first :-/
→ need to make the reference explicit



```
#include <iostream>
#include <thread>

doSomething(string& s) { s+="!"}

int main() {
    int anInt = 0;
    std::thread t{doSomething, std::ref(std::string("a string !"))};
    t.join();
return 0;
}
```

Explicit call to string constructor to avoid conversion from const char \* to string *inside* doSomething...

Thread constructor is unaware of reference passing and will copy first :-/
→ need to make the reference explicit





```
#include <iostream>
#include <thread>
class X{
public: doSomething(int);
};
int main() {
    int anInt = 0;
    X myX;
    std::thread t{&X::doSomething, myX, 3}; //myX.doSomething(3);
    t.join();
return 0 ;
```

Calling a member function: remember the hidden parameter!





### Passing a thread as parameter

```
void f(std::thread t);

void g()
{
  void some_function();
  f(std::thread(some_function));
  std::thread t(some_function);
  f(std::move(t));

//here 't' is empty...
}
```



Warning, a thread cannot be copied! Only "moved" (see move semantics for more details)



```
#include <list>
#include <mutex>
#include <algorithm>
std::list<int> aList;
std::mutex aListMutex;
void add to list(int new value) {
  aListMutex.lock();
  aList.push back(new value);
  aListMutex.unlock();
bool list contains (int value to find) {
  aListMutex.lock();
 bool res = std::find(
       aList.begin(),
       aList.end(),
       value to find
        != aList.end();
  aListMutex.unlock();
  return res;
```

Classical mutex...



```
#include <list>
#include <mutex>
#include <algorithm>
std::list<int> aList;
std::mutex aListMutex;
void add to list(int new value) {
  std::lock_guard<std::mutex> guard(aListMutex);
  aList.push back(new value);
bool list contains (int value to find) {
  std::lock guard<std::mutex> guard(aListMutex);
  return std::find(
       aList.begin(),
       aList.end(),
       value to find
        != aList.end();
```

Mutex is taken until guard is destroyed!



```
#include <list>
#include <mutex>
#include <algorithm>
std::list<int> aList;
std::mutex aListMutex:
void recursive add to list(int new value) {
  if (new value <= 0) return;
  aListMutex.lock();
  aList.push_back(new_value);
  aListMutex.unlock();
  recursive add to list(newValue--)
```

Warning to correctly free the mutex before the recursion

→ but non atomic





```
#include <list>
#include <mutex>
#include <algorithm>
std::list<int> aList;
std::recursive mutex aListMutex;
void recursive add to list(int new value) {
  if (new value <= 0) return;
  aListMutex.lock();
  aList.push back(new value);
  recursive add to list(newValue --);
  aListMutex.unlock();
```

recursive\_mutex can be locked several time by the same thread!

Need to be unlocked as many as locked!

→ atomic





#### Condition variable

```
std::mutex mut;
                                //shared variables
int anInt;
std::condition variable anInt cond;
void f() {
 while(true) {
  std::lock_guard<std::mutex> guard(mut);
  anInt = computeNewInt();
  anInt_cond.notify_one();
                   Condition false → mutex unlocked and thread "blocked"
                   Condition true → control and thread given to thread
void g() {
 while(true) {
  std::unique lock<std::mutex> guard(mut);
  anInt_cond.wait(guard,[]{return anInt == somethingSpecial;});
  //Do whatever to do
  quard.unlock();
  //continue doing something or not...
```



```
#include<future>
#include<iostream>
int solving ltuae();
void do other stuff();
int main()
  std::future<int> the answer=std::async(solving ltuae);
  do other stuff();
  std::cout << "The answer is " << the answer.get() << std::endl;
return 0;
```

async runs a function and eventually returns a future
get() is blocking if the future is not ready, yet.



```
#include<future>
#include<iostream>
int solving ltuae(int);
void do other stuff();
int main()
  std::future<int> the answer=std::async(solving ltuae, 42);
  do other stuff();
  std::cout<<"The answer is "<<the answer.get()<<std::endl;
return 0;
```

async runs a function and eventually returns a future
get() is blocking if the future is not ready, yet.



## promise and Futures

```
#include<future>
#include<iostream>
int solving ltuae(std::promise<int>);
// at some point the function does: promiseObj.set_value(42);
void do other stuff();
int main()
  std::promise<int> promiseObj;
  std::future<int> futureObj = promiseObj.get_future();
  Thread t(solving_ltuae, promiseObj);
  do other stuff();
  std::cout << "The answer is " << future Obj.get() << std::endl;
return 0:
```





```
#include<future>
#include<iostream>
int solving ltuae(int);
void do other stuff();
int main()
  std::future<int> the answer=std::async(solving ltuae, 42);
  future<string> f2 = the answer.then([](future<int> f) {
  return to string(f.get());
  });
  do other stuff();
  std::cout << "The answer is " << f2.get() << std::endl;
return 0;
```

async runs a function and eventually returns a future get() is blocking if the future is not ready, yet.

C++20 adds a nice way to compose futures





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```
#include<future>
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int solving ltuae(int);
void do other stuff();
int main()
  std::future<int> the answer=std::async(solving ltuae, 42);
  future<string> f2 = the answer.then([](future<int> f) {
  return to string(f.get());
                                     when_any
  });
                                             → still experimental
                                     When all
  do other stuff();
  std::cout << "The answer is " << f2.get() << std::endl;
return 0;
```

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The algorithm is used in sequence...





#### All algorithms

69 of the algorithms of the STL support a parallel or a parallel and vectorized execution. Here they are.

Standard library alg	orithms for which parallelized versions	are provided Collaps
• std::adjacent difference	• std::is_heap_until	• std::replace_copy_if
• std::adjacent_find	<ul><li>std::is_partitioned</li></ul>	<ul><li>std::replace_if</li></ul>
std::all_of	<ul><li>std::is_sorted</li></ul>	• std::reverse
std::any_of	<ul><li>std::is_sorted_until</li></ul>	<ul><li>std::reverse_copy</li></ul>
• std::copy	<ul><li>std::lexicographical_compare</li></ul>	• std::rotate
std::copy_if	<ul><li>std::max_element</li></ul>	<ul><li>std::rotate_copy</li></ul>
std::copy n	• std::merge	• std::search
std::count	<ul><li>std::min_element</li></ul>	<ul><li>std::search_n</li></ul>
std::count if	<ul><li>std::minmax_element</li></ul>	<ul><li>std::set_difference</li></ul>
std::equal	• std::mismatch	<ul><li>std::set_intersection</li></ul>
• std::fill	• std::move	<ul><li>std::set_symmetric_differen</li></ul>
• std::fill n	• std::none_of	<ul><li>std::set_union</li></ul>
std::find	<ul><li>std::nth_element</li></ul>	• std::sort
std::find_end	<ul><li>std::partial_sort</li></ul>	<ul><li>std::stable_partition</li></ul>
std::find first of	<ul><li>std::partial_sort_copy</li></ul>	<ul><li>std::stable_sort</li></ul>
std::find_if	<ul><li>std::partition</li></ul>	<ul><li>std::swap_ranges</li></ul>
std::find if not	<ul><li>std::partition_copy</li></ul>	• std::transform
std::generate	• std::remove	<ul><li>std::uninitialized_copy</li></ul>
std::generate n	• std::remove_copy	<ul><li>std::uninitialized_copy_n</li></ul>
std::includes	<ul><li>std::remove_copy_if</li></ul>	<ul><li>std::uninitialized_fill</li></ul>
std::inner_product	• std::remove_if	<ul><li>std::uninitialized_fill_n</li></ul>
• std::inplace_merge	• std::replace	• std::unique
• std::is_heap	<ul><li>std::replace_copy</li></ul>	<ul><li>std::unique_copy</li></ul>

https://www.modernescpp.com/index.php/parallel-algorithm-of-the-standard-template-library

In addition, we get 8 new algorithms.



The algorithm is used in parallel in different threads... but it's your responsibility to avoid race conditions



The algorithm is used in parallel in different threads and potentially makes used of Vectorization...

but it's your responsibility to avoid race conditions



Vectorization means that the compiler detects that your independent instructions can be executed as one <a href="SIMD">SIMD</a> instruction. Usual example is that if you do something like

```
for(i=0; i<N; i++){
  a[i] = a[i] + b[i];
}</pre>
```

It will be vectorized as (using vector notation)

```
for (i=0; i<(N-N%VF); i+=VF){
   a[i:i+VF] = a[i:i+VF] + b[i:i+VF];
}</pre>
```

Basically the compiler picks one operation that can be done on VF elements of the array at the same time and does this N/VF times instead of doing the single operation N times.

It increases performance, but puts more requirement on the architecture.









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but it's your responsibility to avoid race conditions





Historically, accelerating your C++ code with GPUs has not been possible in Standard C++ without using language extensions or additional libraries:

- CUDA C++ requires the use of \_\_host\_\_ and \_\_device\_\_ attributes on functions and the triple-chevron syntax for GPU kernel launches.
- OpenACC uses #pragmas to control GPU acceleration.
- Thrust lets you express parallelism portably but uses language extensions internally and only supports a limited number of CPU and GPU backends. The portability of the application is limited by the portability of the library.



In many cases, the results of these ports are worth the effort. But what if you could get the same effect without that cost? What if you could take your Standard C++ code and accelerate on a GPU?

Now you can! NVIDIA recently announced NVC++, the NVIDIA HPC SDK C++ compiler. This is the first compiler to support GPU-accelerated Standard C++ with no language extensions, pragmas, directives, or non-standard libraries. You can write Standard C++, which is portable to other compilers and systems, and use NVC++ to automatically accelerate it with high-performance NVIDIA GPUs. We built it so that you can spend less time porting and more time on what really matters—solving the world's problems with computational science.

https://developer.nvidia.com/blog/accelerating-standard-c-with-gpus-using-stdpar/





Many more but not addressed here...

