Label-efficient Deep Learning in Remote Sensing

Michael Mommert, University of St. Gallen

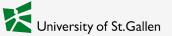
Resources: github.com/mommermi/iadfschool2023_efficientlearning





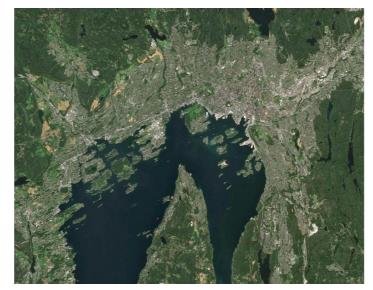
Input data (x) Output (y) $f(\mathbf{x};\theta) = \mathbf{y}$ training training unseen unseen X

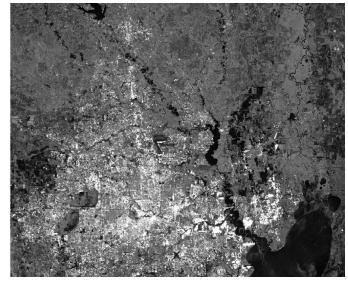
Introduction

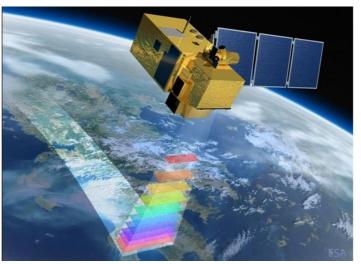




Earth observation data are highly complex (unstructured, multi-modal).



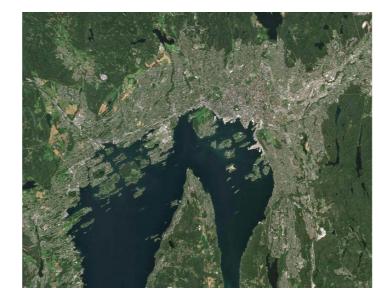




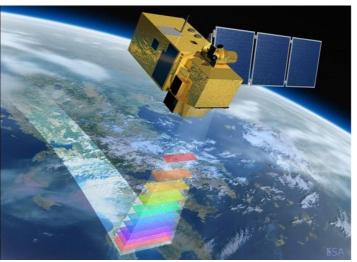


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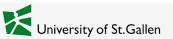
How can we analyze these vast amounts of data?







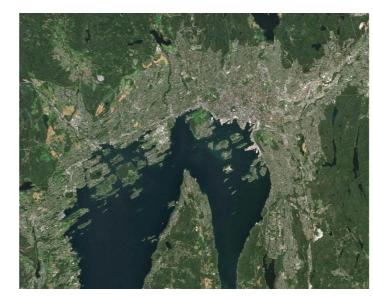


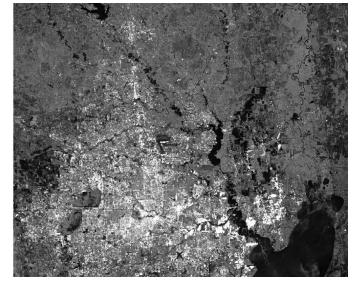


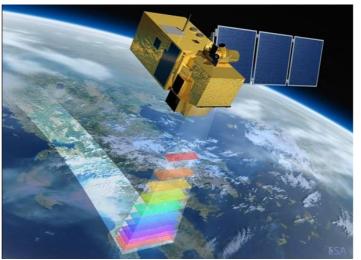
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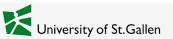
Deep Learning offers the **scalability** to analyze large amounts of data.









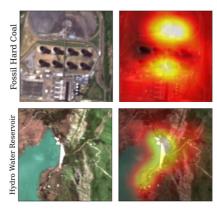


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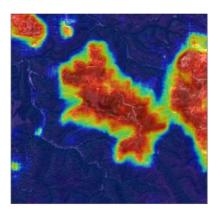
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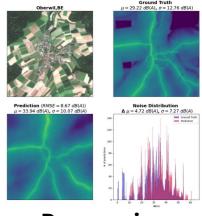
Deep Learning also offers the **flexibility** to deal with a range of different tasks.



Classification



Segmentation



Regression



Object Detection



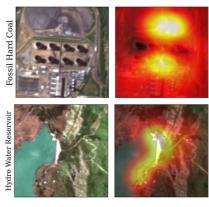
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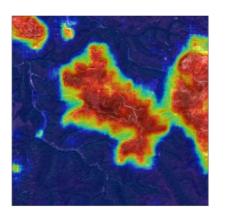
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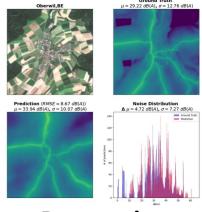
How does it work?



Classification



Segmentation

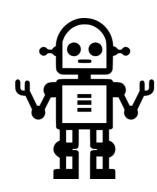


Regression

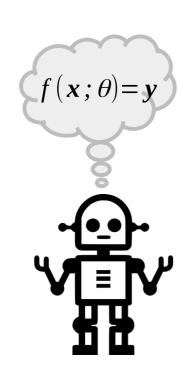


Object Detection



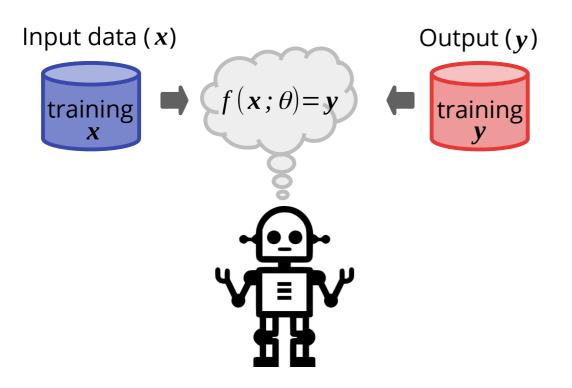




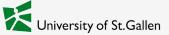


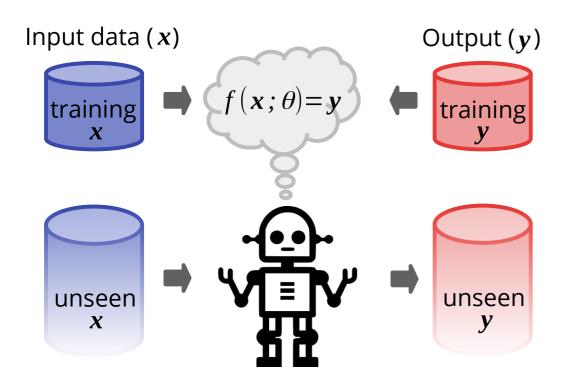
A machine learns a task from **annotated examples**.



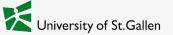


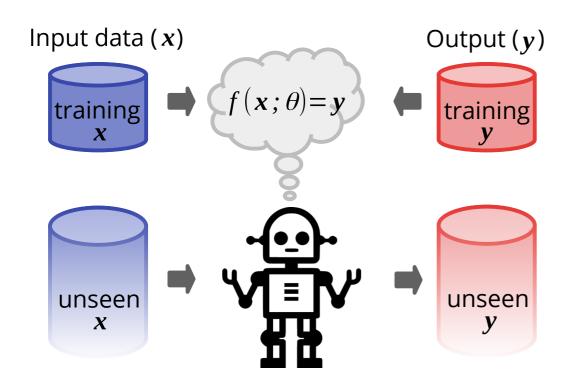
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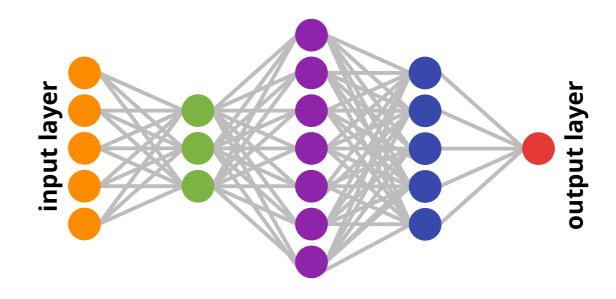




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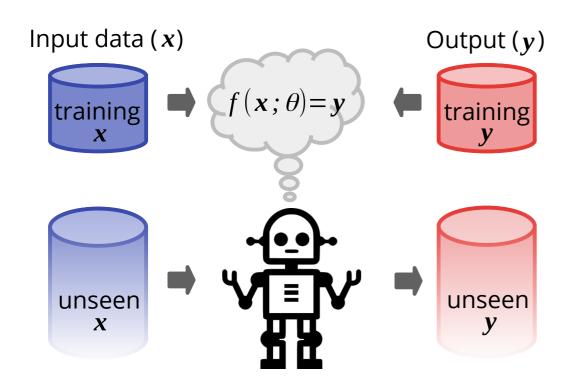


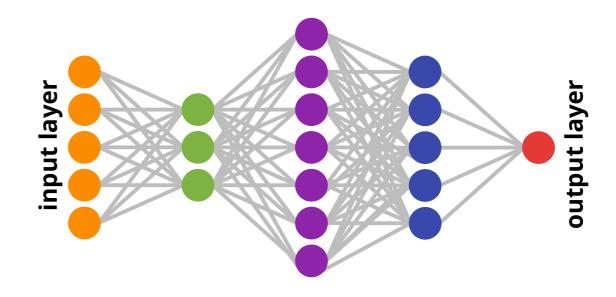


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Mathematically, it learns a function, f, that maps input data, x, to the output, y.

A Neural Network is a cascade of mathematical functions; each neuron contains learnable weights that represent the learned knowledge.



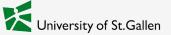


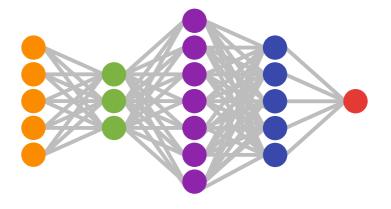
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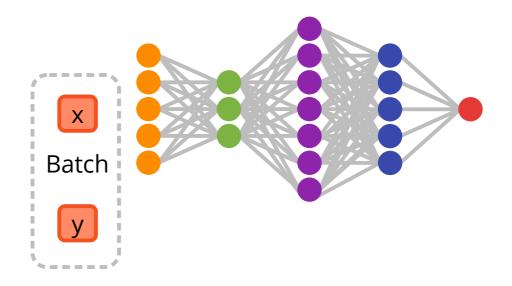
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How does the model learn?

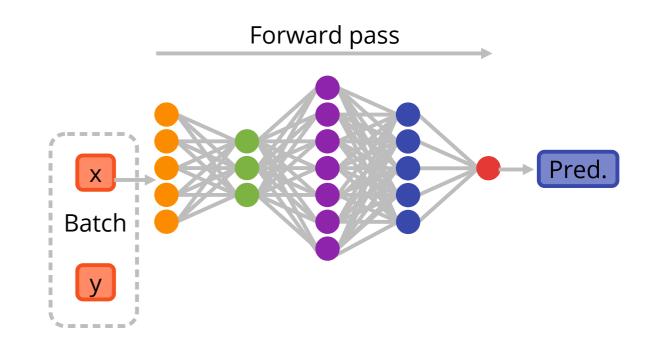




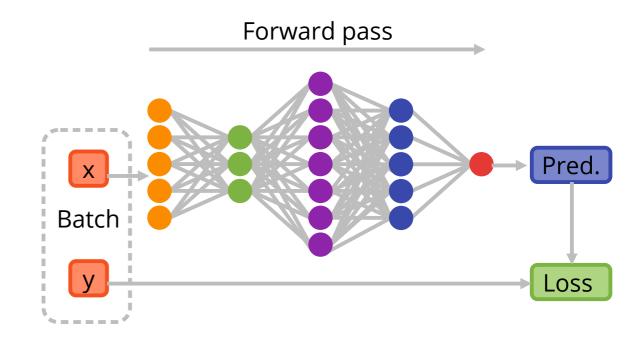
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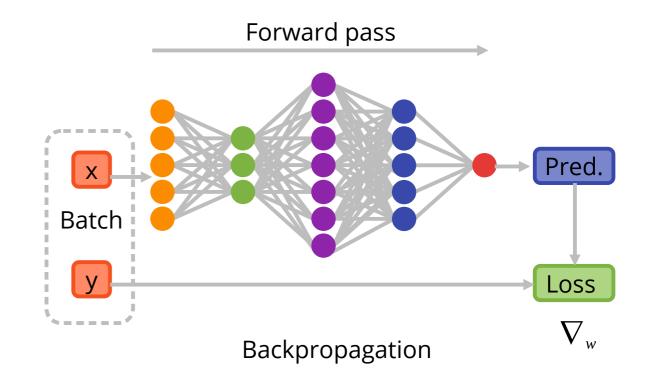


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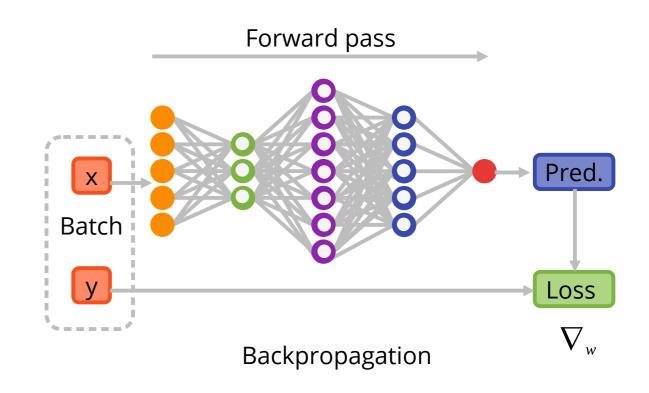


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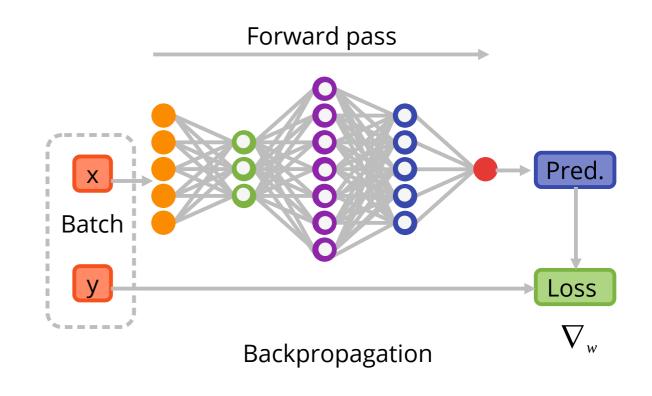


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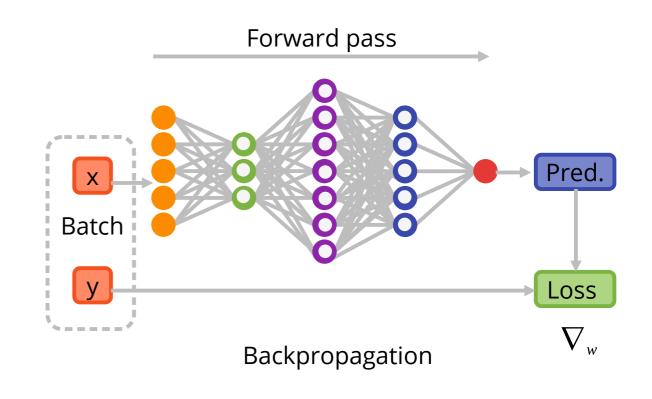




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 - Repeat for all batches



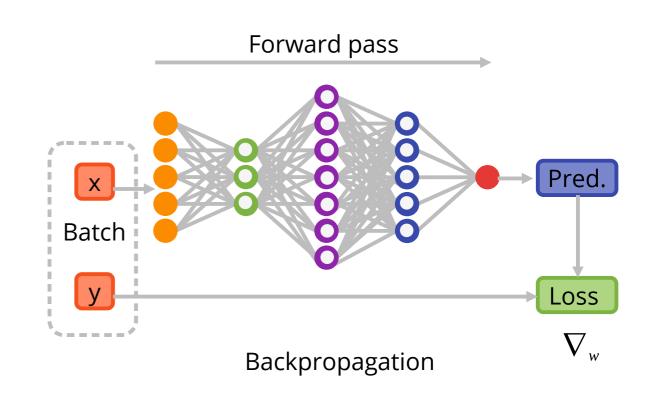
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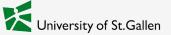




1 epoch

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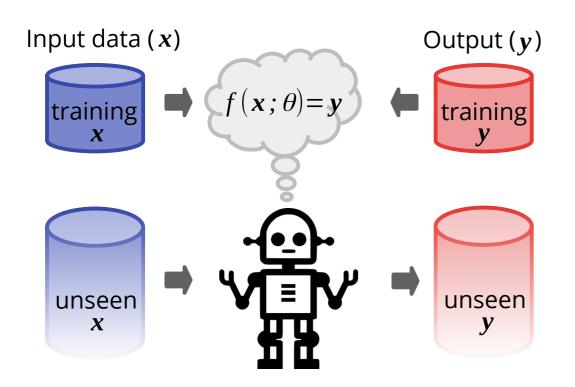


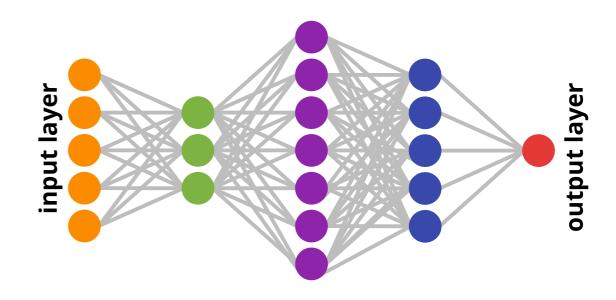
1 epoch

Let's implement a fully supervised learning pipeline with PyTorch and PyTorch Lightning!

Please go to:

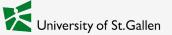
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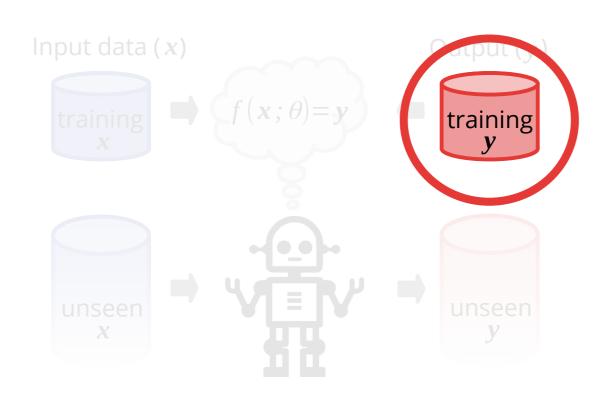




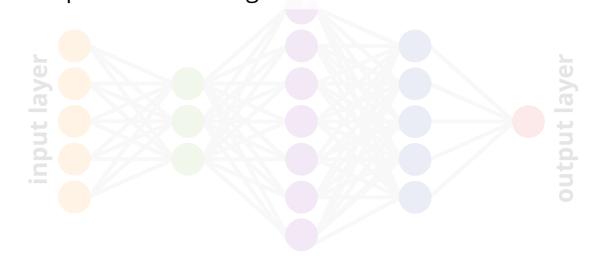
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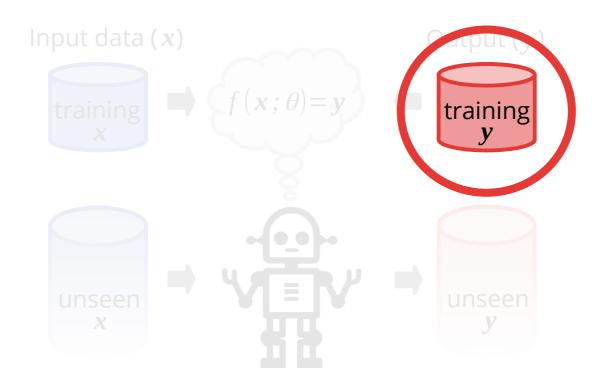
The availability of annotations typically represents the most important **bottleneck** in supervised learning.



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The availability of annotations typically represents the most important **bottleneck** in supervised learning.

Can we force the model to use the available annotations more **efficiently**?

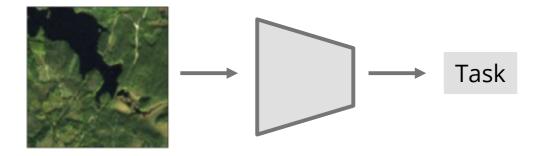
Can we take advantage of the vast amounts of **unannotated data**?

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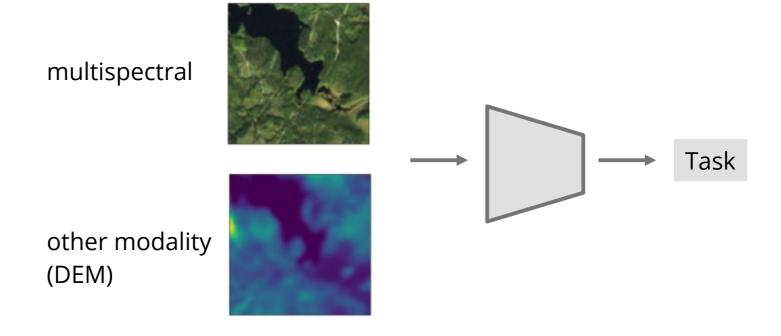
• Data augmentations



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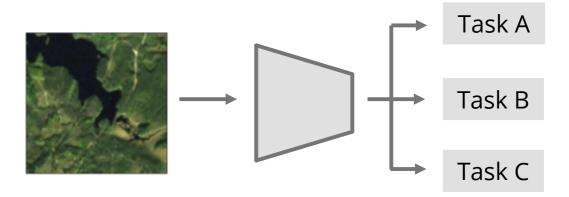


- Data augmentations
- Data Fusion

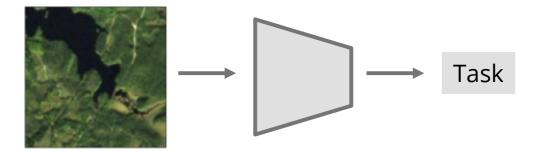




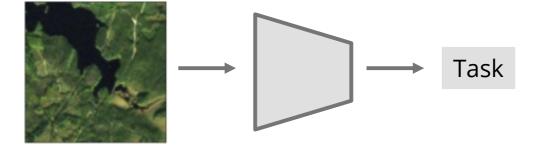
- Data augmentations
- Data Fusion
- Multi-task Learning

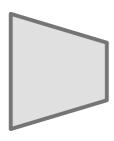


- Data augmentations
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- Transfer Learning



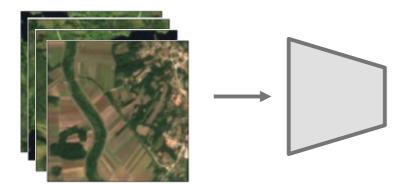
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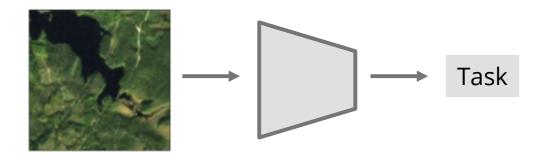


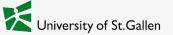


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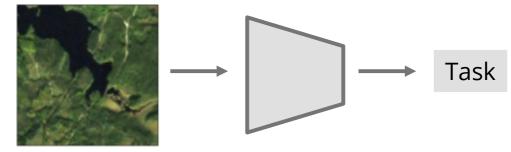
other dataset



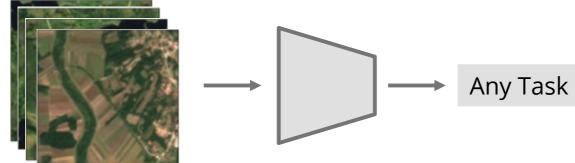




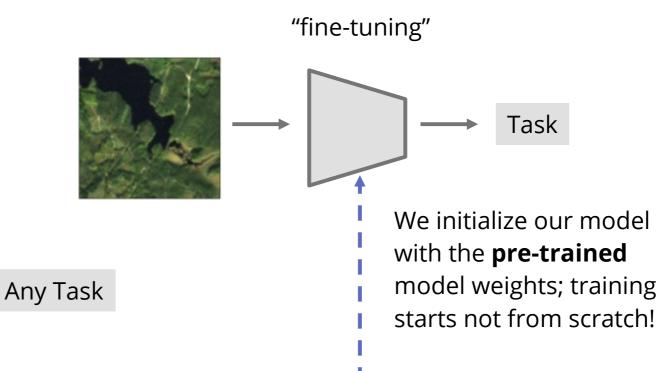
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other dataset



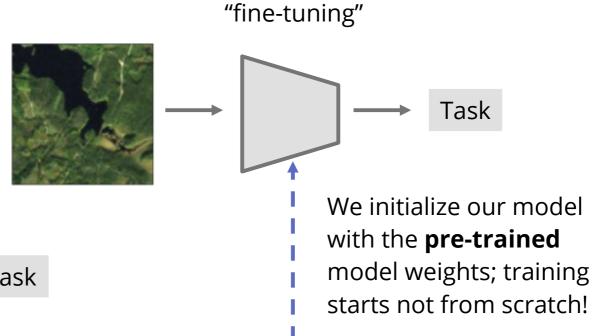
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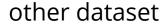




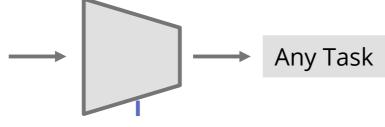
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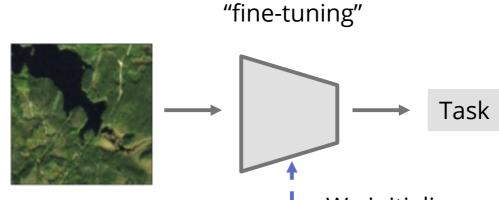




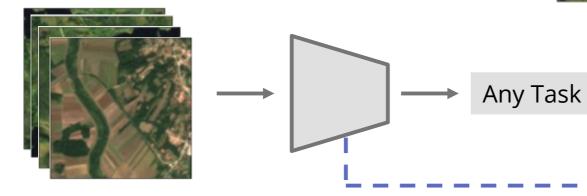


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Can we pretrain a model from unannotated data?

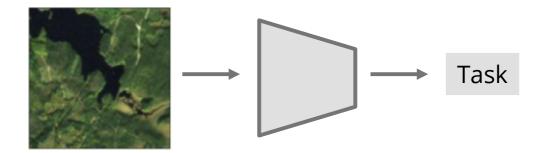


other dataset

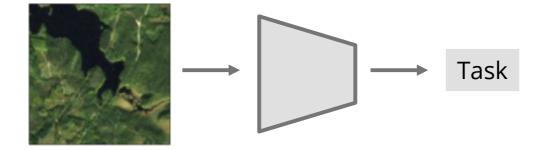


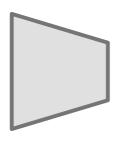
We initialize our model with the **pre-trained** model weights; training starts not from scratch!

- Data augmentations
- Data Fusion
- Multi-task Learning
- Transfer Learning
- Self-supervised Learning



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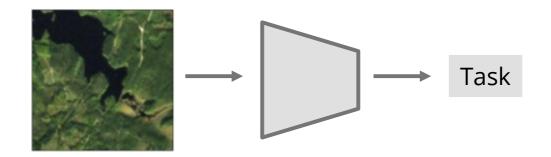




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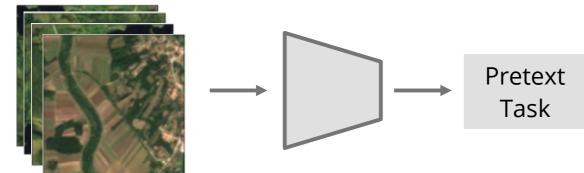


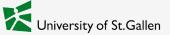


- Data augmentations
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→ Task

other dataset

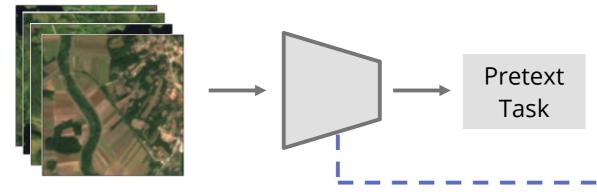




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Task

other dataset



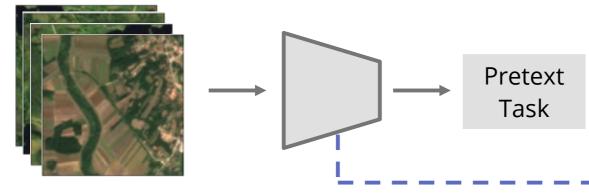
In SSL, we pretrain our model in a **self-supervised way** (no labels required) and then apply transfer learning to learn our actual task more efficiently.



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We will introduce these methods in the following and implement some them using PyTorch after the coffee break.

Data **Augmentations**







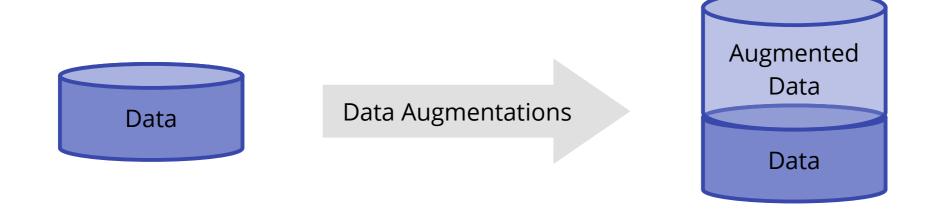






Data Augmentations

Data augmentations are a means to synthetically "increase the size" of your dataset. Augmentations are **transformations** that affect input data but not the corresponding labels; as a result, models trained with data augmentations tend to be **more robust** and **less prone to overfitting**.







Original







Flip







Flip



Image Enhancements



Original



Flip



Image Enhancements



Color distortions



Original



Flip



Image Enhancements



Color distortions



Crop



Original



Flip



Image Enhancements



Color distortions



Crop





Original



Flip



Image Enhancements



Color distortions



Crop







Original



Flip



Image Enhancements



Color distortions

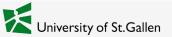


Crop











Original



Flip



Image Enhancements



Color distortions

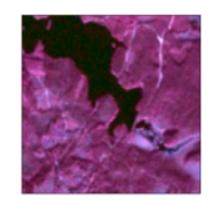


Crop











Original



Flip



Image Enhancements



Color distortions

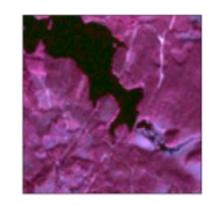


Crop













Original



Flip



Image Enhancements



Color distortions



Crop

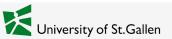














Original



Flip



Image Enhancements



Color distortions



Crop















Original



Flip



Image **Enhancements**



Color distortions



Crop





+ Rotations!









Data augmentations are a powerful method, but they have to be used with care: some transformations might be unphysical and harm/confuse the model.

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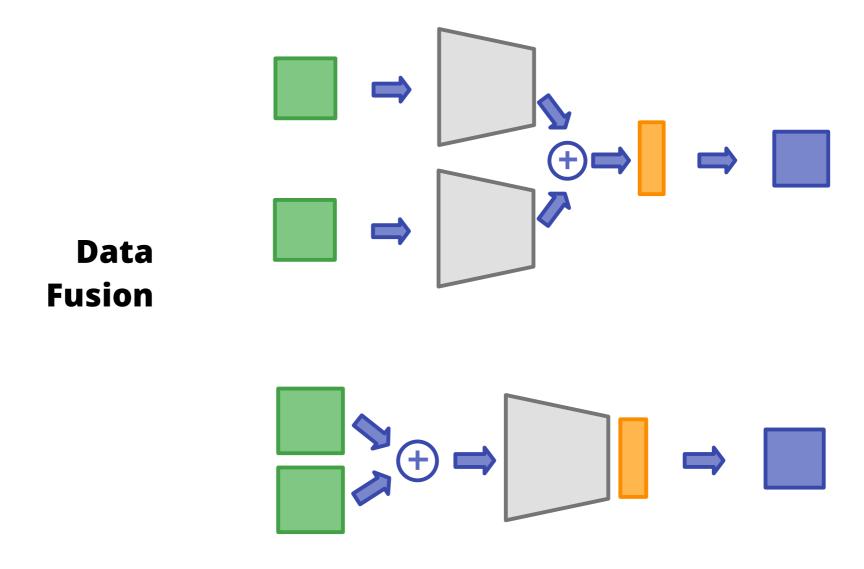
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Data augmentations are generally easy to implement, which is why we will not look at them in more detail...









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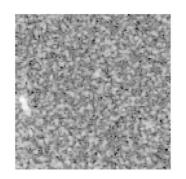


Multispectral (e.g., Sentinel-2, Landsat)

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Multispectral (e.g., Sentinel-2, Landsat)

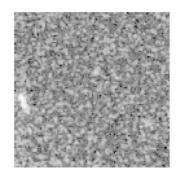


SAR (e.g., Sentinel-1, ICEye)

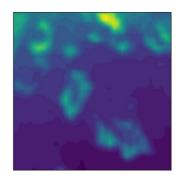
Data Fusion is a technique in which different data modalities are combined ("fused"). The goal of data fusion is to better perform a task by combining relevant data.



Multispectral (e.g., Sentinel-2, Landsat)



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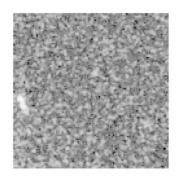


DEM (e.g., Copernicus DEM)

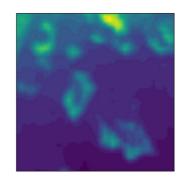
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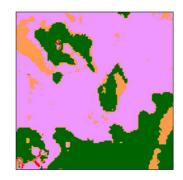
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LU/LC (e.g., Corine, Esa WorldCover)

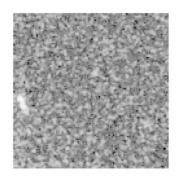
Data Fusion

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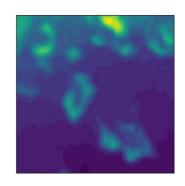
Earth observation is predestined for Data Fusion, as EO sensors collect data across many different data modalities:



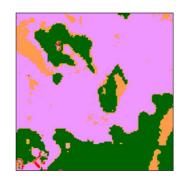
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Meta Data (e.g., weather data, observation circumstances)

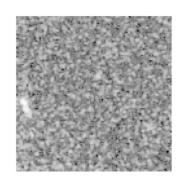
Data Fusion

Paolo Gamba Will Presel Data Fusion for change detection in urban areas Data Fusion is a technique in which different data modalities are combined ("fused" fusion is to better perform a task by combining relevant data.

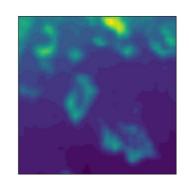
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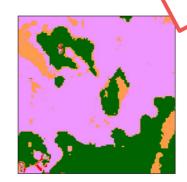
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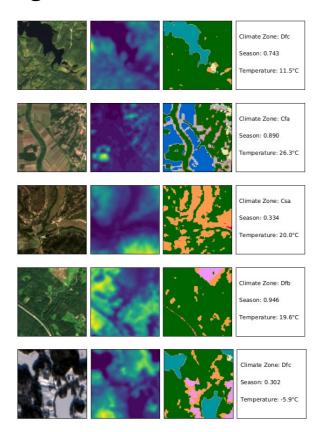


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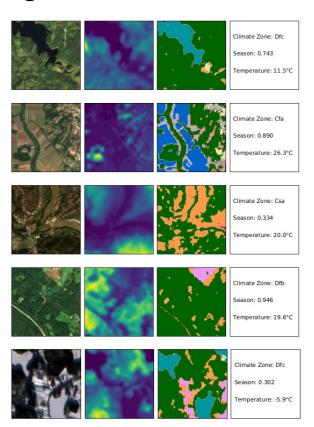


To explore the use of multimodal for Data Fusion (and other methods), we will use a specifically designed dataset:

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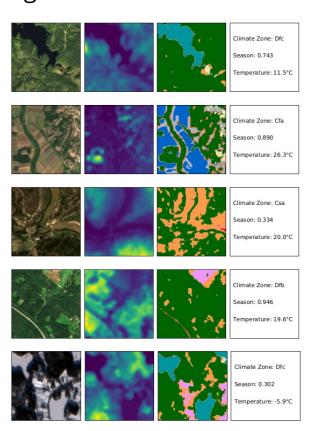


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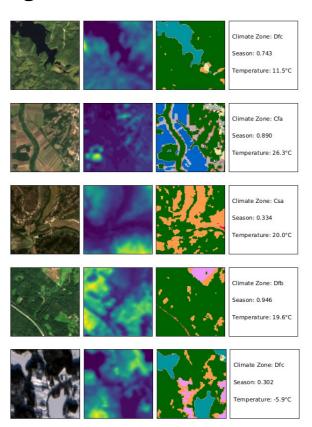
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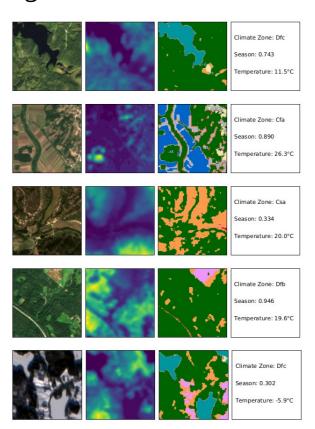


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ben-ge extends BigEarthNet by the following data modalities:

Elevation data (Copernicus DEM GLO-30)

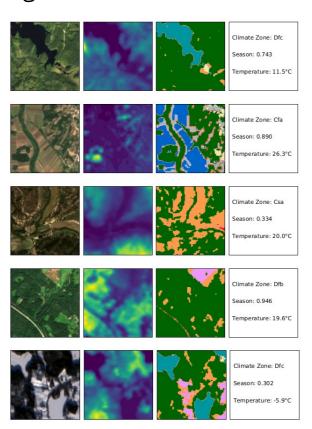
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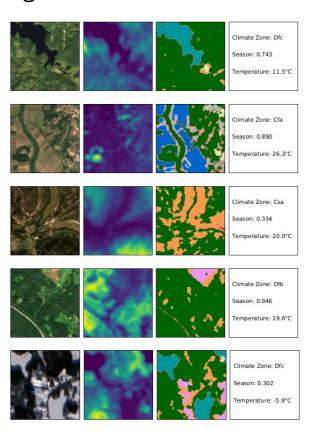
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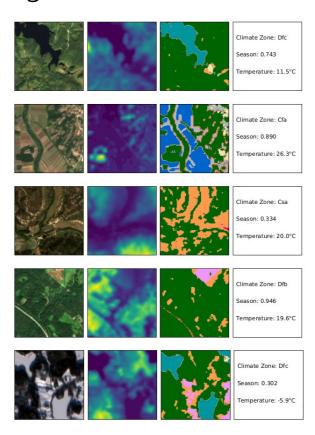


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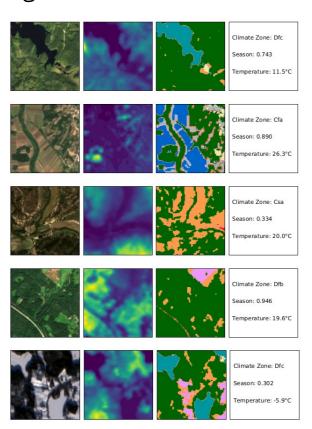
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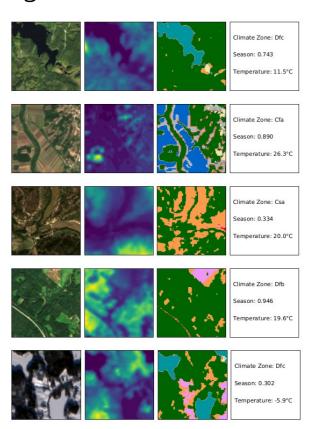
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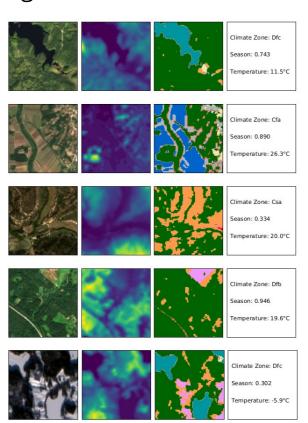
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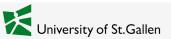
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We will use a subset of ben-ge, ben-ge-800, in this tutorial.



What data modalities are available in ben-ge?

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Sentinel-2 Multispectral

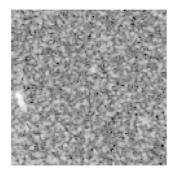
12 bands Level-2A

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Sentinel-2 Multispectral

12 bands Level-2A

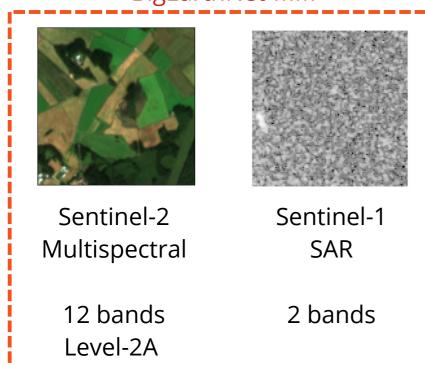


Sentinel-1 SAR

2 bands

What data modalities are available in ben-ge?

BigEarthNet-MM



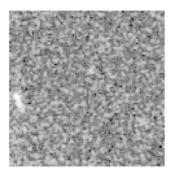
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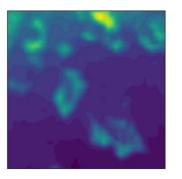
Sentinel-2 Multispectral

12 bands Level-2A



Sentinel-1 SAR

2 bands



Copernicus DEM (GLO-30, resampled)



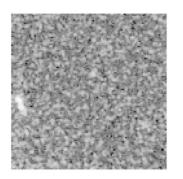
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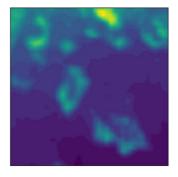
Sentinel-2 Multispectral

12 bands Level-2A

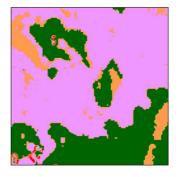


Sentinel-1 SAR

2 bands



Copernicus DEM (GLO-30, resampled)



ESA WorldCover LU/LC

8/11 classes

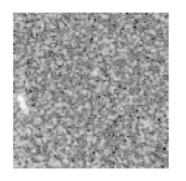
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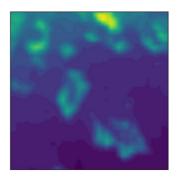
Sentinel-2 Multispectral

12 bands Level-2A

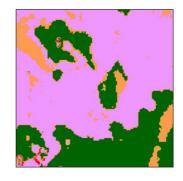


Sentinel-1 SAR

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Meta Data

ERA-5 weather Climate zones Seasonality



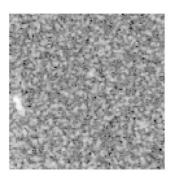
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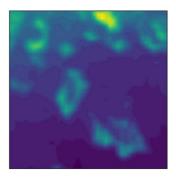
Sentinel-2 Multispectral

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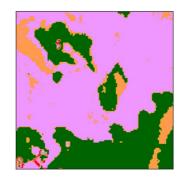


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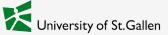
10m resolution

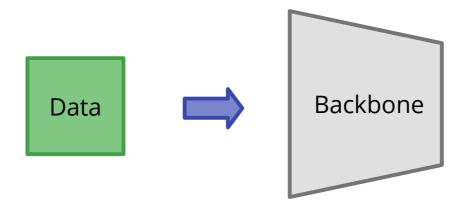
Data Fusion for Deep Learning

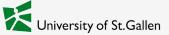
How can we leverage Data Fusion in Deep Learning?

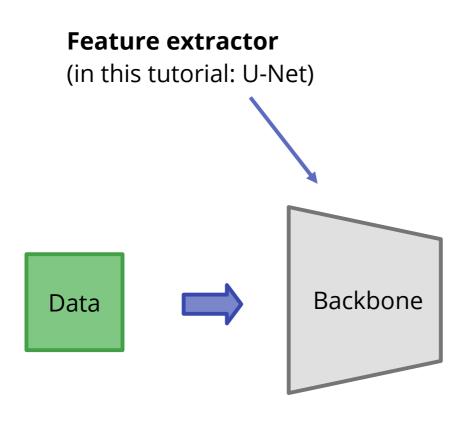


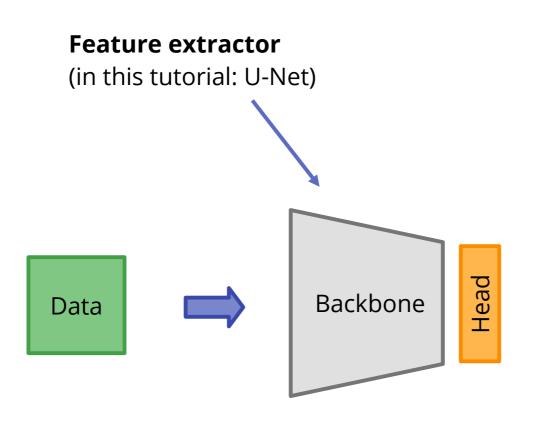


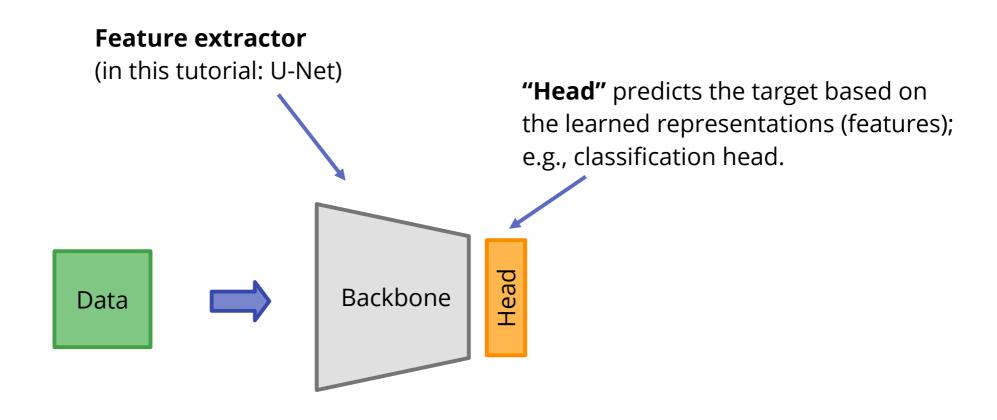


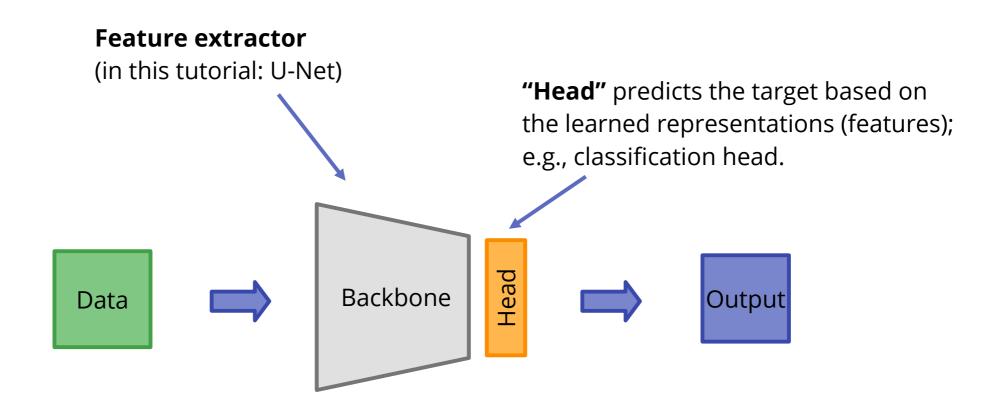












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Data 1

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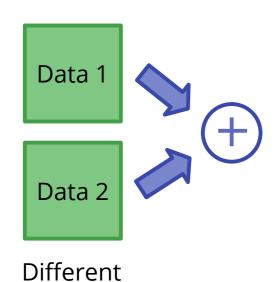
Data 1

Data 2

Different data modalities

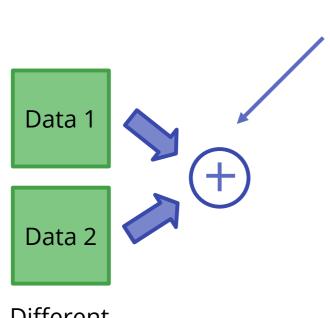


In Early Fusion, two (or more) data modalities are combined before they enter the backbone:



data modalities

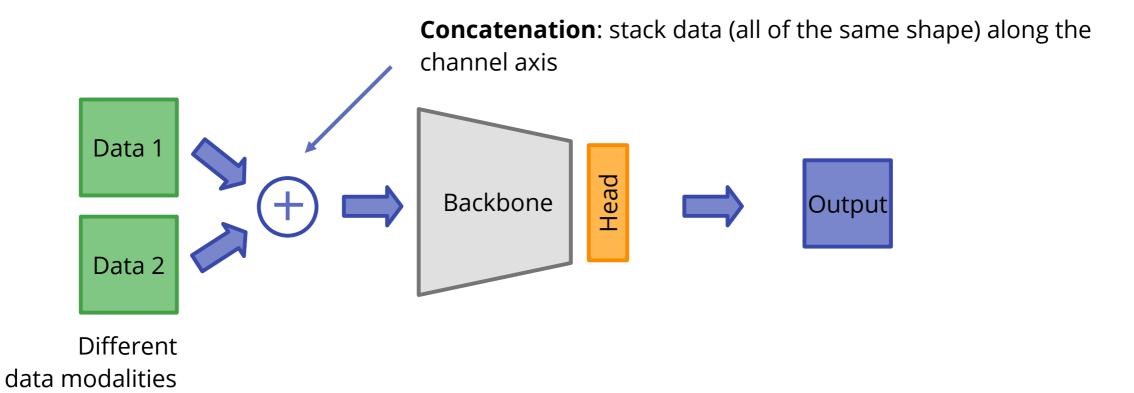
In Early Fusion, two (or more) data modalities are combined before they enter the backbone:



Concatenation: stack data (all of the same shape) along the channel axis

Different data modalities

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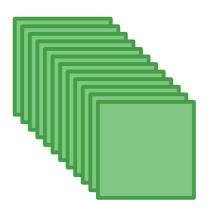




Early Fusion is simple if the data modalities to be combined have the same shape (e.g., map-like features with the same extent).

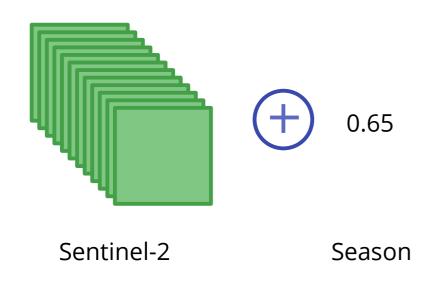
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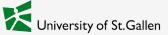
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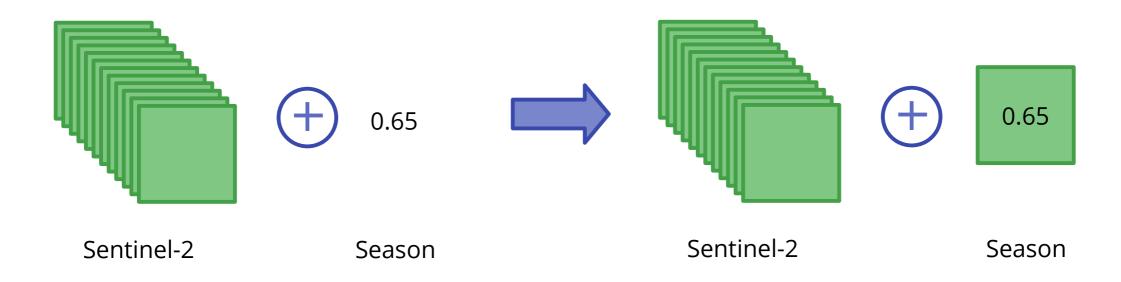
Sentinel-2

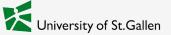
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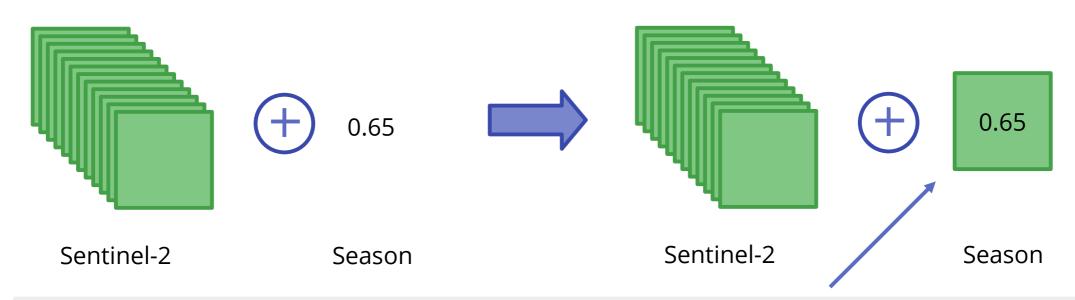
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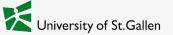


Early Fusion is simple if the data modalities to be combined have the same shape (e.g., map-like features with the same extent).

But: how to combine Sentinel-2 data (12 channels x 120 px x 120 px) with patch-global seasonality (scalar value in the range [0, 1]) data?

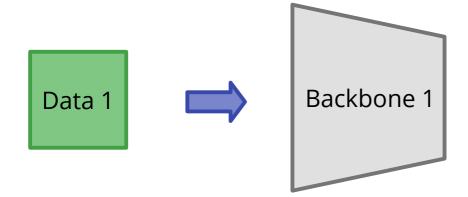


Blow-up patch: same height and width as Sentinel-2; each "pixel" equals the global value (0.65)

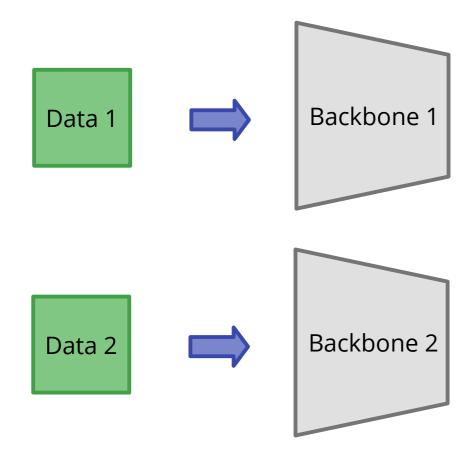


In Late Fusion, two (or more) data modalities are combined after passing through separate backbones:

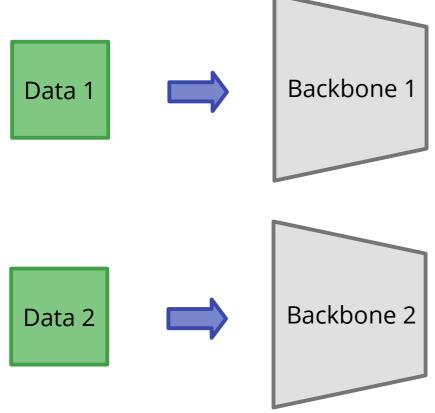
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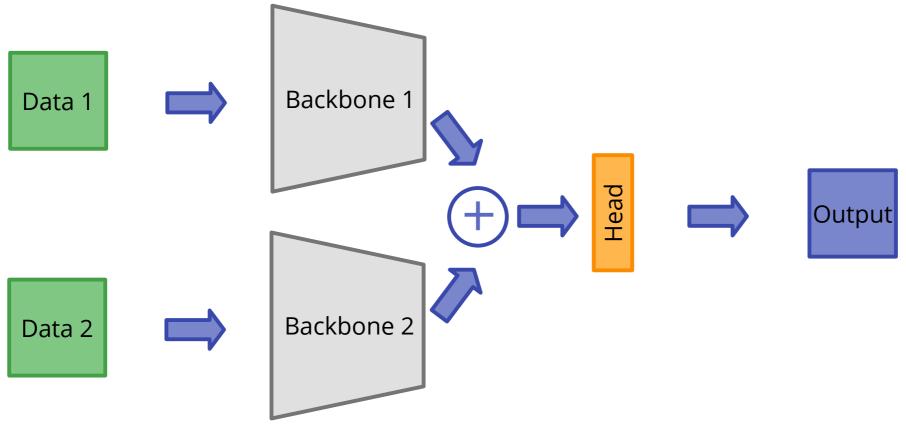


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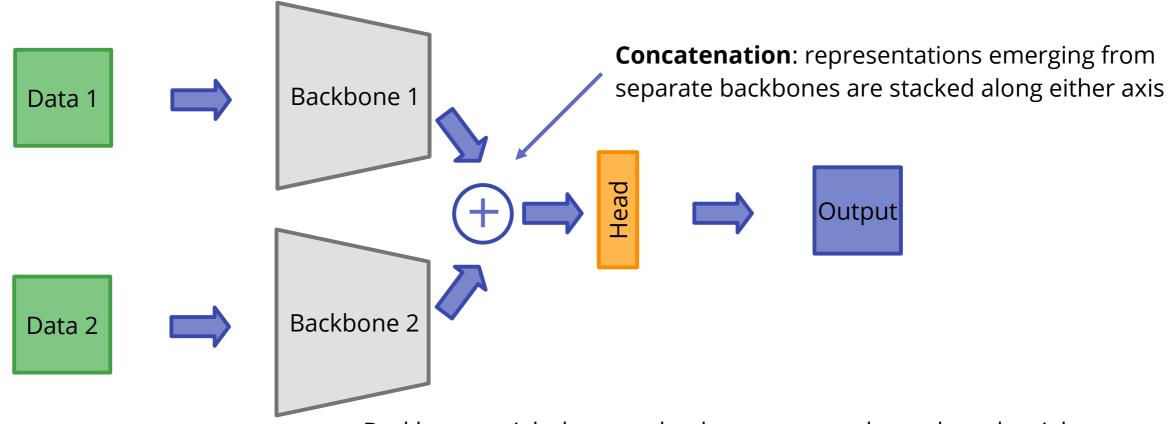
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Let's implement some Data Fusion techniques into our model!

Data Fusion: An example

Which data modalities make sense to combine? (Mommert et al. 2023)

N	Sen-2	Sen-1	Climate	DEM	Weather	Season	Classification [%]		Segmentation [%]	
							F1-score	Accuracy	IoU	Accuracy
	✓						77.12 ±0.64	96.21 ± 0.08	39.17 ±0.09	87.57±0.05
		\checkmark					73.09 ± 0.24	95.60 ± 0.05	31.70±0.17	82.65 ± 0.05
1			\checkmark				70.50 ± 0.34	94.69 ± 0.03	14.70 ± 0.32	60.65 ± 1.35
1				\checkmark			55.96 ± 1.00	93.53 ± 0.15	26.25 ± 0.48	76.92 ± 0.63
					\checkmark		46.15 ± 0.68	91.60 ± 0.02	6.30 ± 0.05	45.20 ± 0.08
						\checkmark	39.15 ± 0.74	91.75 ± 0.05	6.01 ± 0.34	43.89 ± 0.51
2	√	√					82.81 ±0.29	97.03 ± 0.04	39.67 ±0.16	87.98 ± 0.07
	\checkmark					\checkmark	78.61 ± 0.67	96.42 ± 0.08	38.92 ± 0.21	87.37 ± 0.10
	√	√	√				85.12 ±0.34	97.39 ± 0.05	39.63 ± 0.23	87.94 ± 0.12
3	\checkmark	\checkmark		\checkmark			83.30 ± 0.43	97.10 ± 0.08	39.71 ±0.21	88.05 ± 0.11
	\checkmark	✓				✓			39.61±0.19	87.93 ± 0.12



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	√	√	√				85.12 ±0.34	97.39 ± 0.05	39.63±0.23	87.94 ± 0.12
3	\checkmark	\checkmark		\checkmark			83.30 ± 0.43	97.10 ± 0.08	39.71 ±0.21	88.05 ± 0.11
	✓	✓				✓	<u> </u>	<u> </u>	39.61±0.19	87.93 ± 0.12

... it depends on the downstream task and the data...

Data Fusion: An example

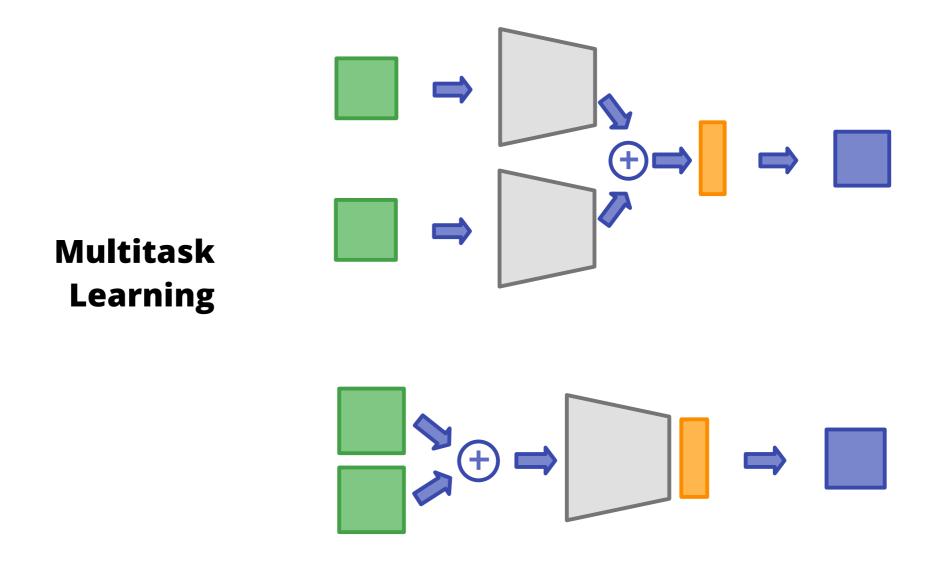
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	✓						77.12 ±0.64	96.21 ± 0.08	39.17 ±0.09	87.57±0.05
		\checkmark					73.09 ± 0.24	95.60 ± 0.05	31.70±0.17	82.65 ± 0.05
1			\checkmark				70.50 ± 0.34	94.69 ± 0.03	14.70 ± 0.32	60.65 ± 1.35
				\checkmark			55.96 ± 1.00	93.53 ± 0.15	26.25 ± 0.48	76.92 ± 0.63
					\checkmark		46.15 ± 0.68	91.60 ± 0.02	6.30 ± 0.05	45.20 ± 0.08
						\checkmark	39.15 ± 0.74	91.75 ± 0.05	6.01 ± 0.34	43.89 ± 0.51
2	√	√					82.81 ±0.29	97.03 ± 0.04	39.67 ±0.16	87.98 ± 0.07
2	\checkmark					\checkmark	78.61 ± 0.67	96.42 ± 0.08	38.92 ± 0.21	87.37 ± 0.10
	√	√	√				85.12 ±0.34	97.39 ± 0.05	39.63±0.23	87.94 ± 0.12
3	\checkmark	\checkmark		\checkmark			83.30 ± 0.43	97.10 ± 0.08	39.71 ±0.21	88.05 ± 0.11
	✓	✓				✓	<u> </u>	<u> </u>	39.61±0.19	87.93 ± 0.12

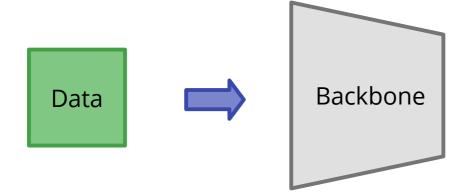
... it depends on the downstream task and the data...

Which method is better: in most cases, late fusion seems to be more beneficial (might be a fallacy).

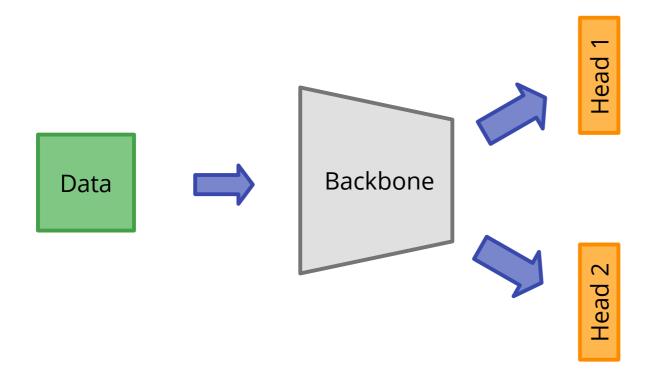




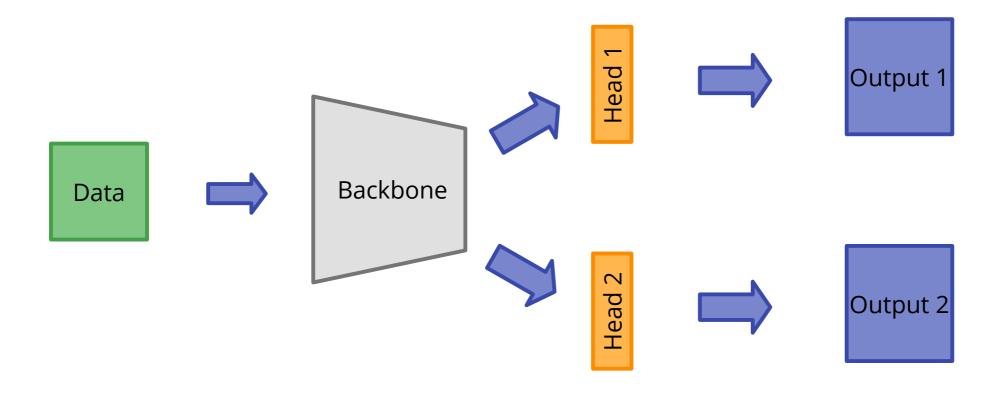
Multitask Learning

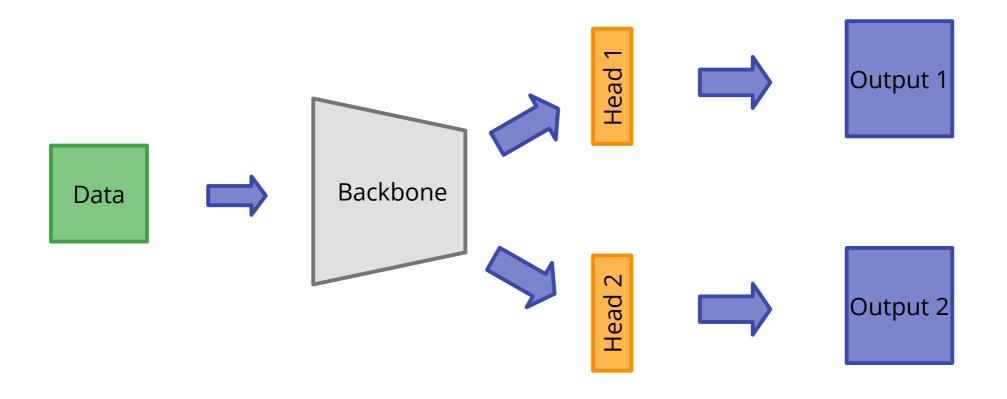


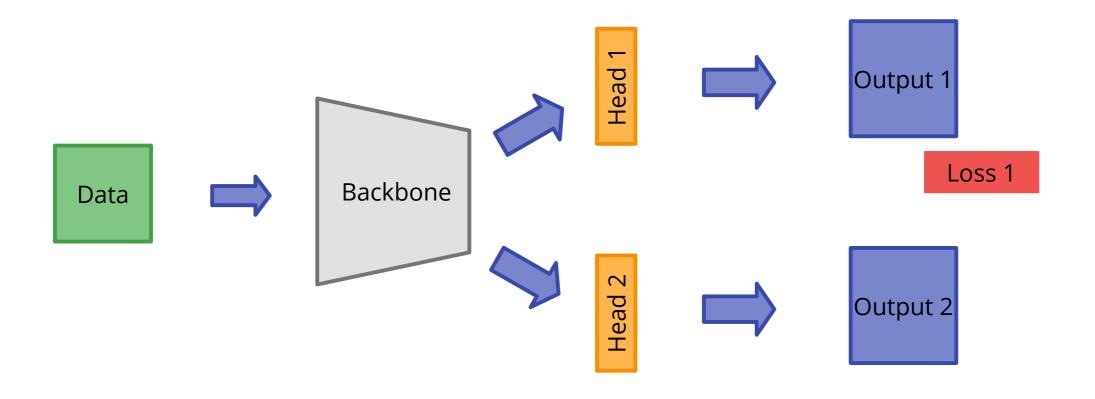
Multitask Learning

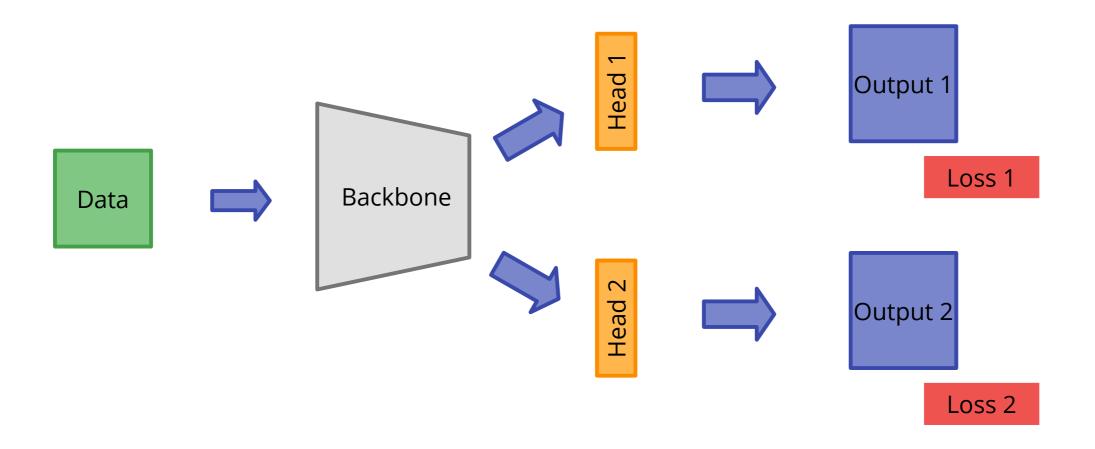


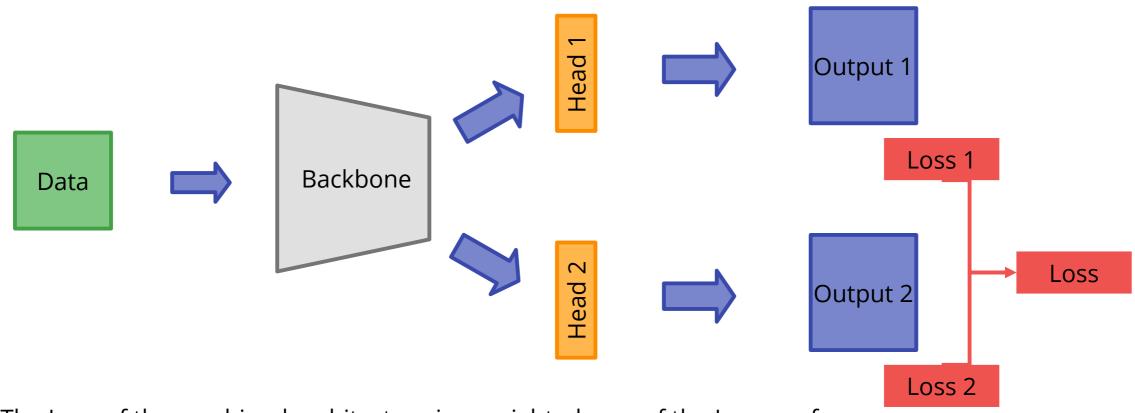
Multitask Learning











The Loss of the combined architecture is a weighted sum of the Losses of the individual downstream tasks. Let's implement some Multitask Learning techniques based on our model!

Idea: Can we train a neural network to estimate power and CO2 output of power plants?

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~3000 observations of

~150 power plants

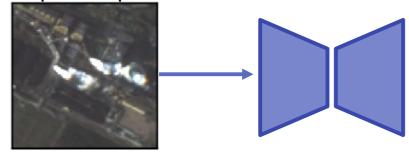


Sentinel-2 12 Bands

Idea: Can we train a neural network to estimate power and CO2 output of power plants?

~3000 observations of

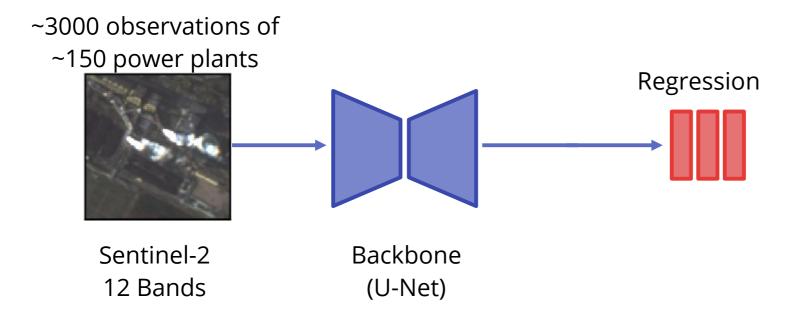




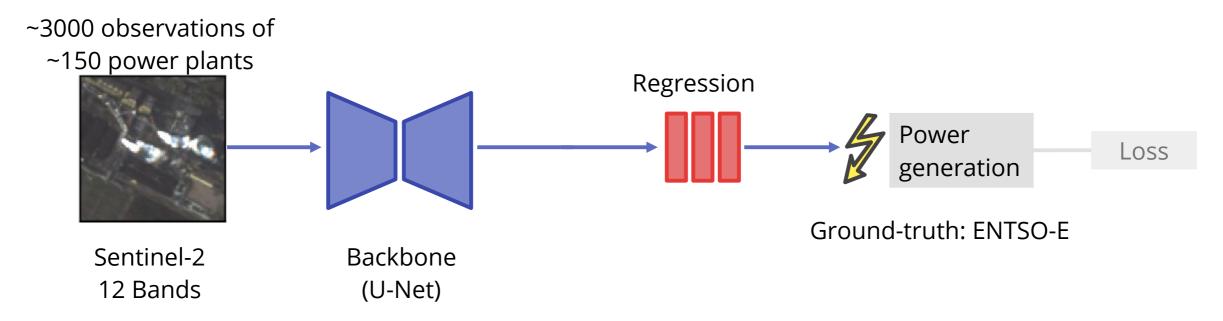
Sentinel-2 12 Bands

Backbone (U-Net)

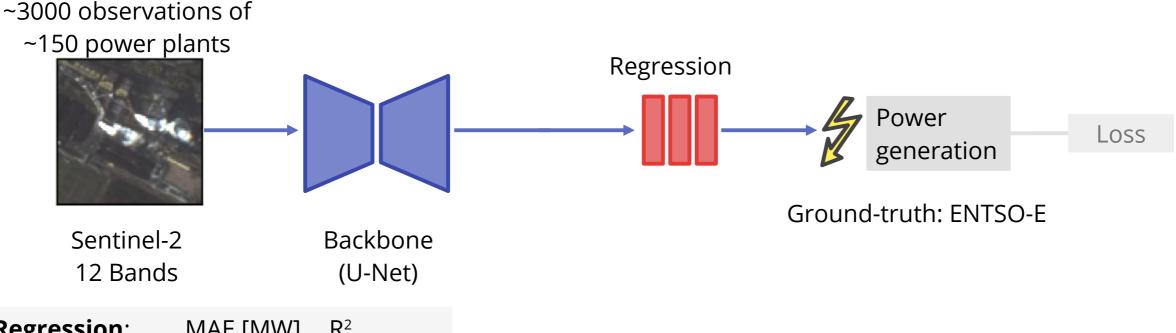
Idea: Can we train a neural network to estimate power and CO2 output of power plants?



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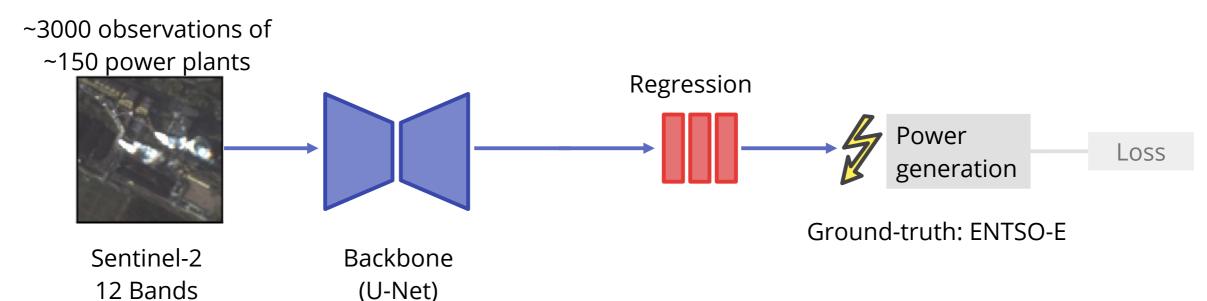
Idea: Can we train a neural network to estimate power and CO2 output of power plants?



Regression: MAE [MW] R^2

Baseline: 202±20 65±5

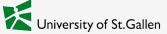
Idea: Can we train a neural network to estimate power and CO2 output of power plants?

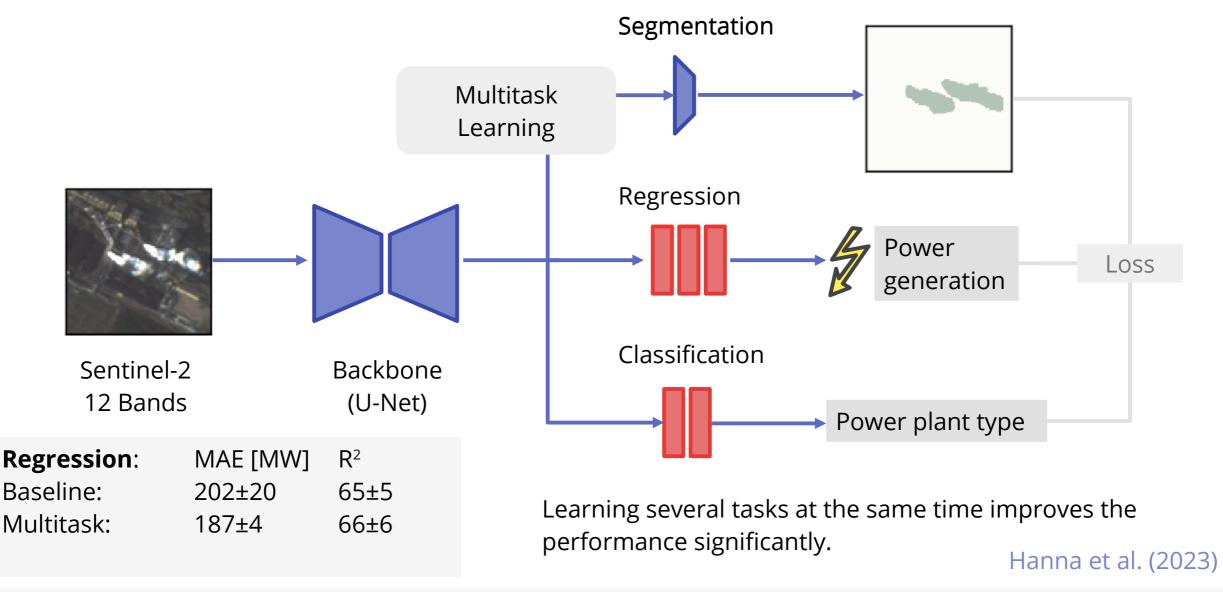


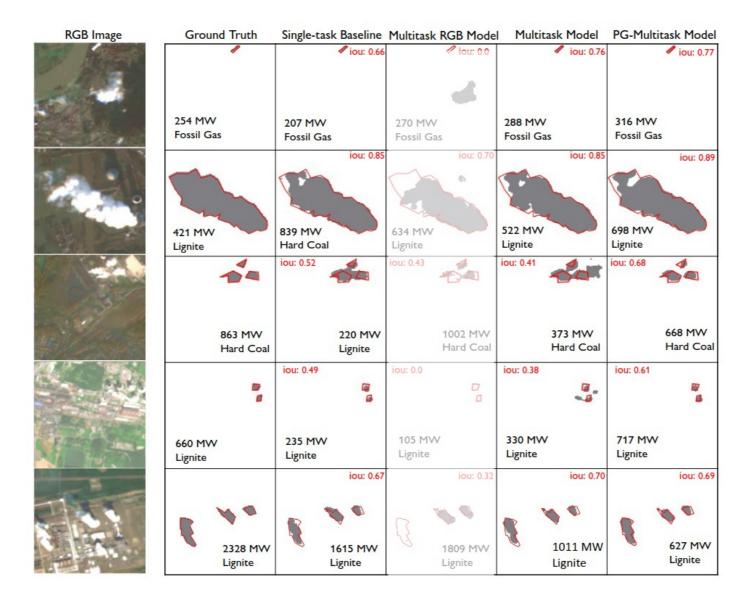
Regression: MAE [MW] R²

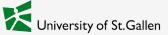
Baseline: 202±20 65±5

Estimating power generation is possible. But can we improve it with Multitask learning?

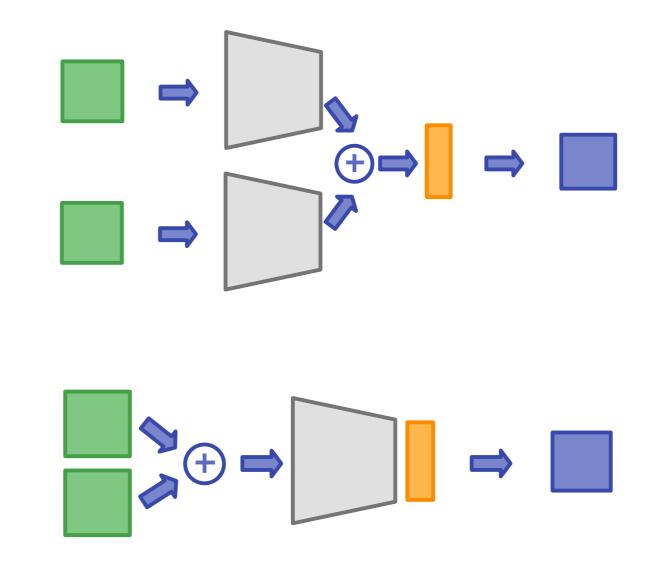




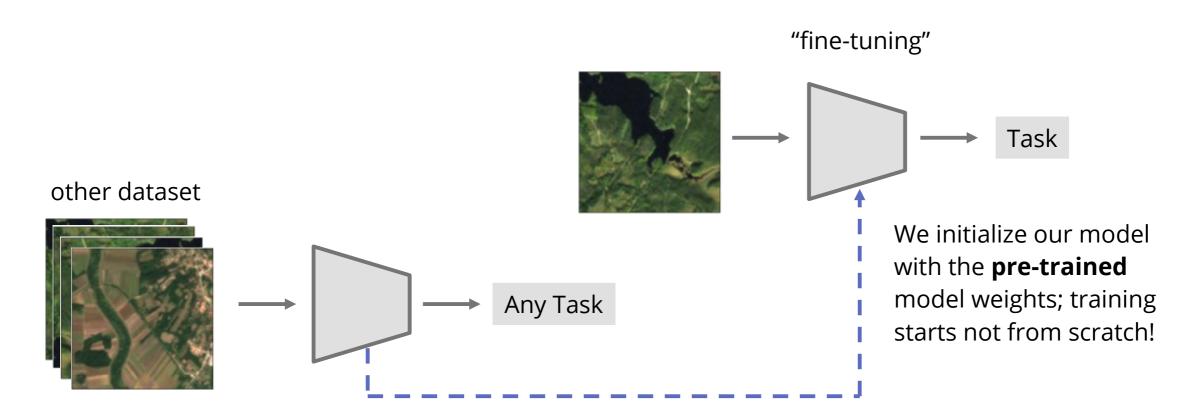




Transfer
Learning
and
Self-supervised
Learning



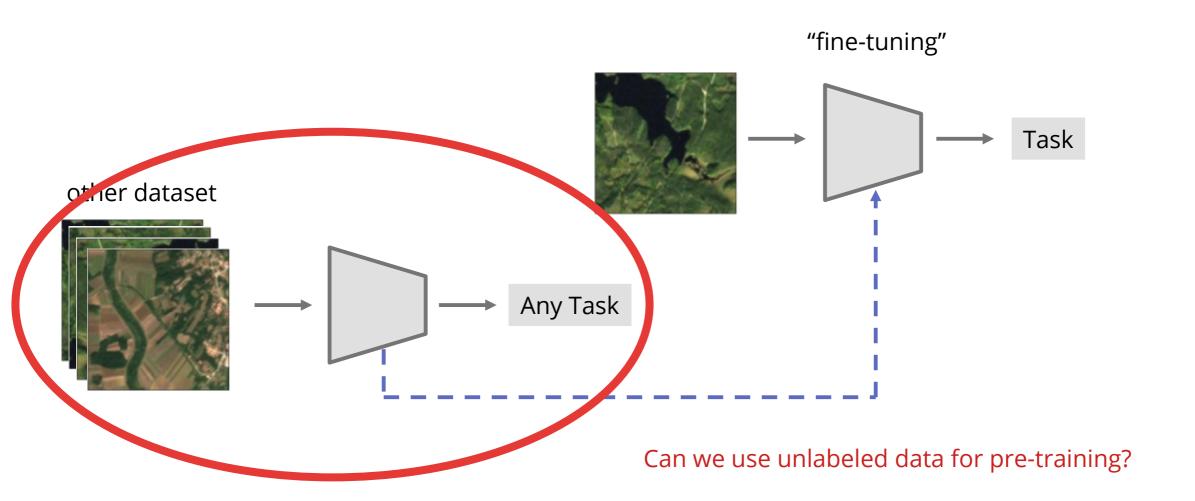
Transfer Learning



In the end, transfer learning simply means that your model has previously been trained: you load a model checkpoint and resume training on your data and for your downstream task.

Implementing Transfer Learning is simple. Let's do it!

Transfer Learning still needs labels





Self-Supervised Learning (SSL) and Transfer Learning



Self-Supervised Learning (SSL) and Transfer Learning



Self-supervised learning: learn "to see", differentiate between image features (edges, colors) without supervision

Self-Supervised Learning (SSL) and Transfer Learning



Self-supervised learning: learn "to see", differentiate between image features (edges, colors) without supervision



Transfer learning: use the learned features to solve a task by providing "few labels"

Contrastive learning setup (following SimCLR):

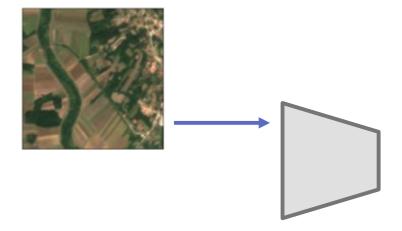


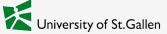
Contrastive learning setup (following SimCLR):



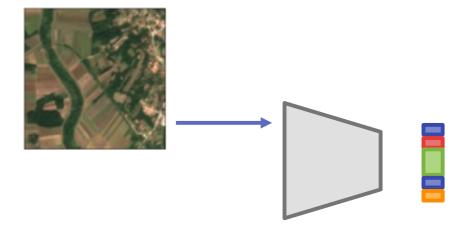


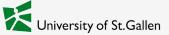
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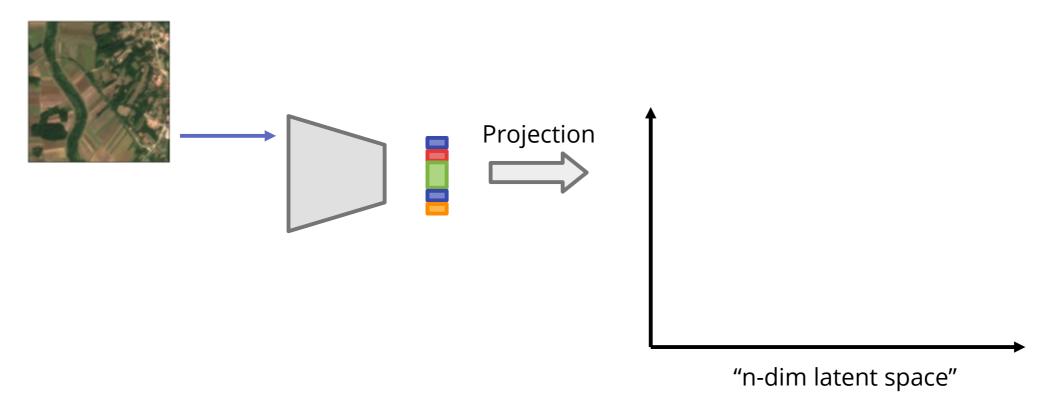


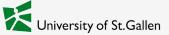
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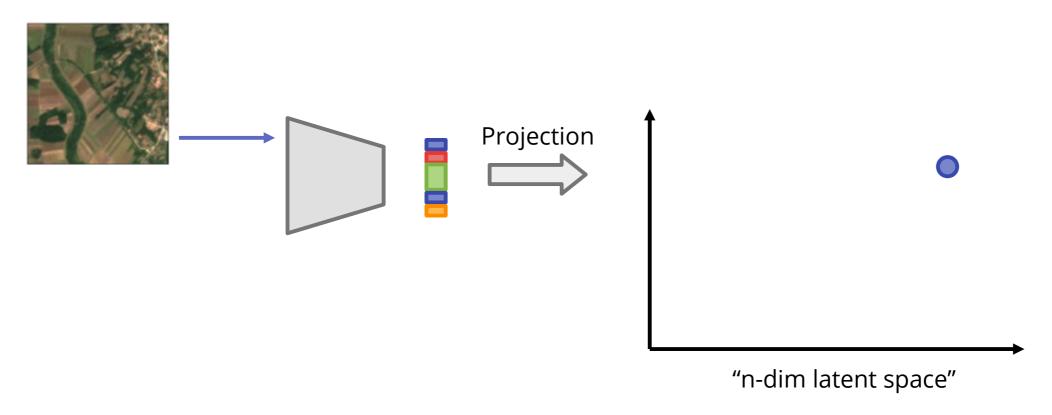


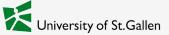
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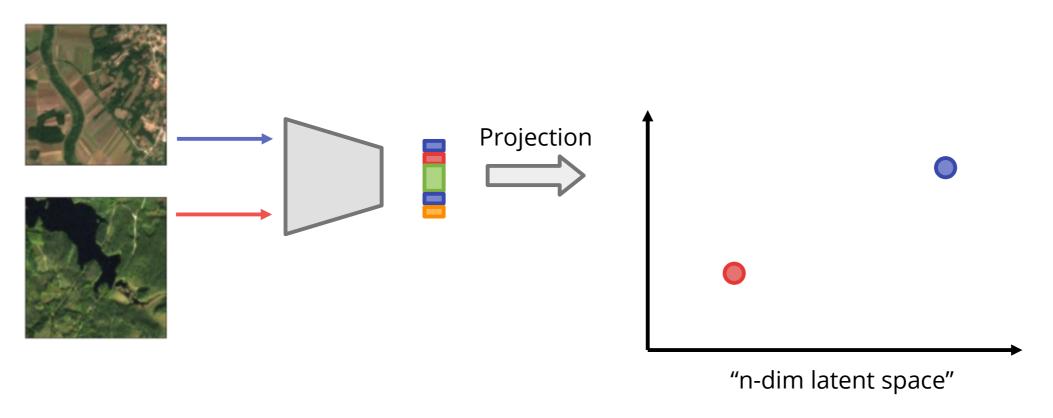


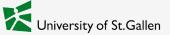
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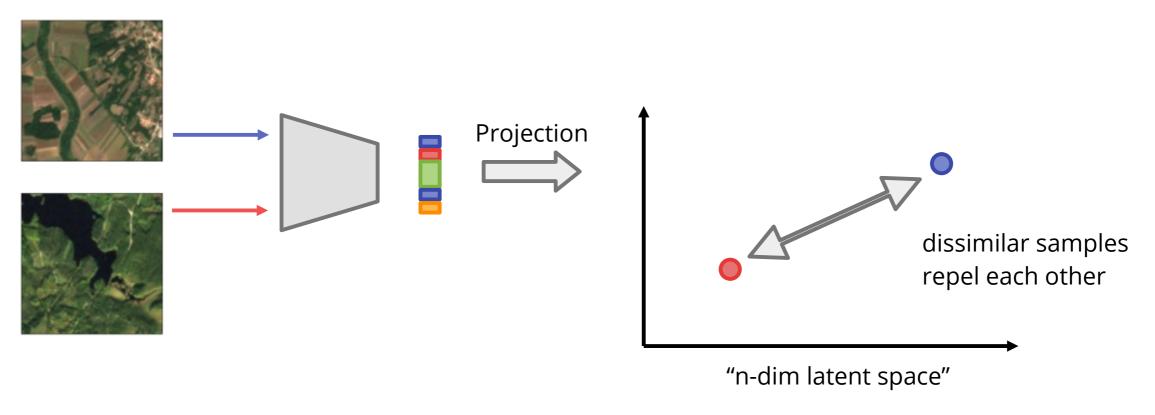


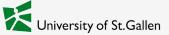
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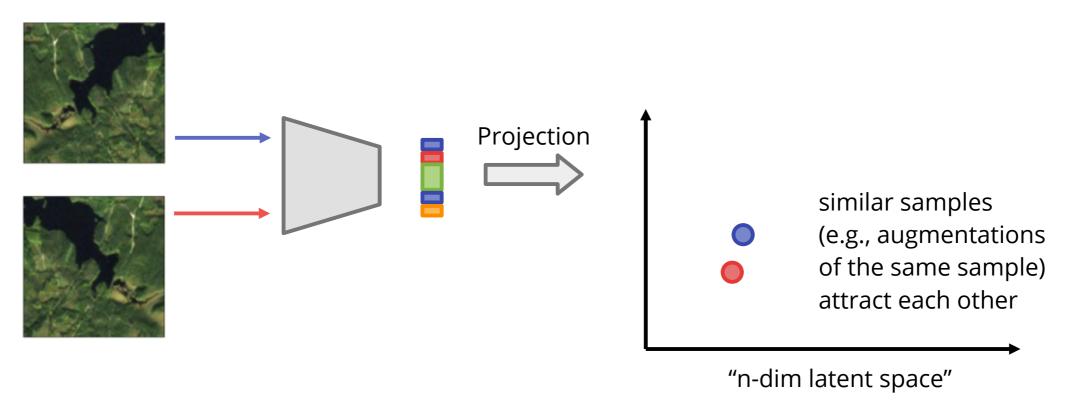
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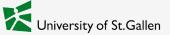




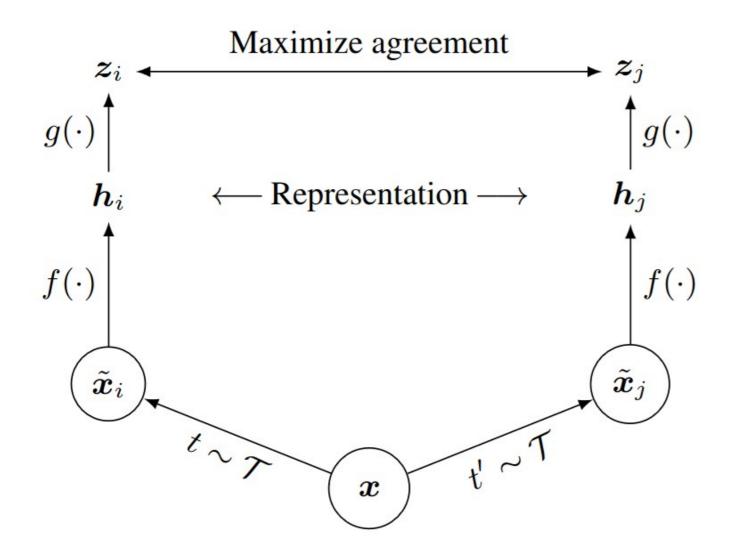
Yes we can! SSL is able to learn **rich representations** from large amounts of unannotated data.

Contrastive learning setup (following SimCLR):



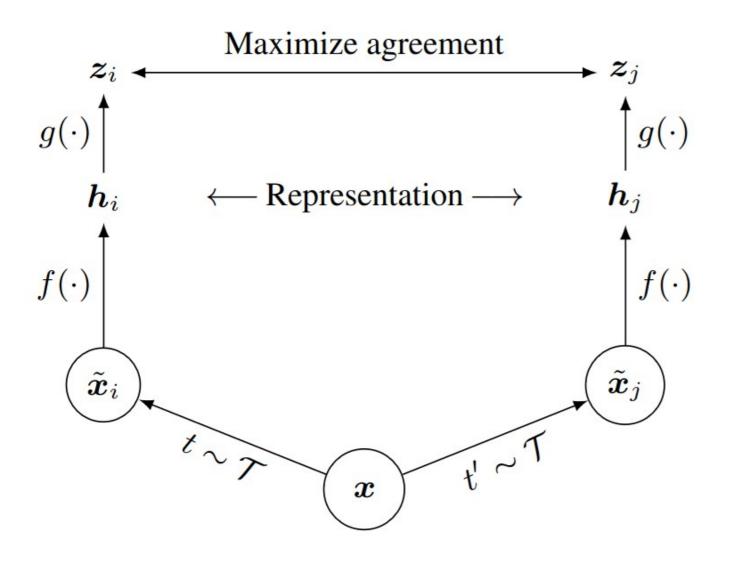


SimCLR: A Simple Framework for Contrastive Learning of Visual Representations



Chen et al. (2020)

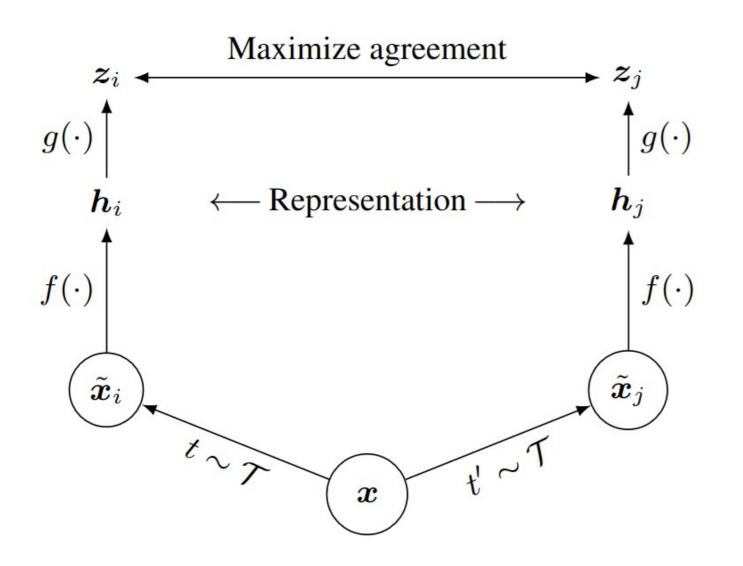
SimCLR: A Simple Framework for Contrastive Learning of Visual Representations



Data augmentations (Transformations) are key for SimCLR to work.

Chen et al. (2020)

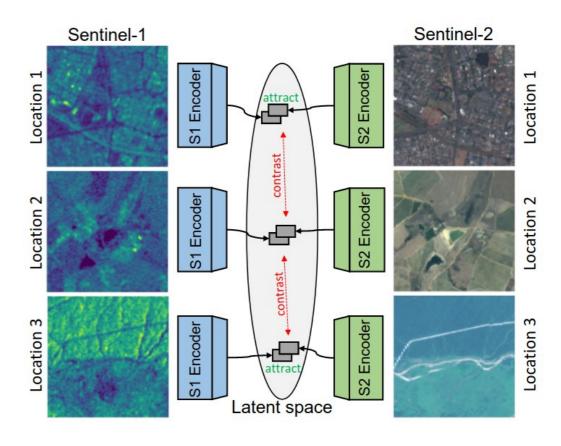
SimCLR: A Simple Framework for Contrastive Learning of Visual Representations



Data augmentations (Transformations) are key for SimCLR to work.

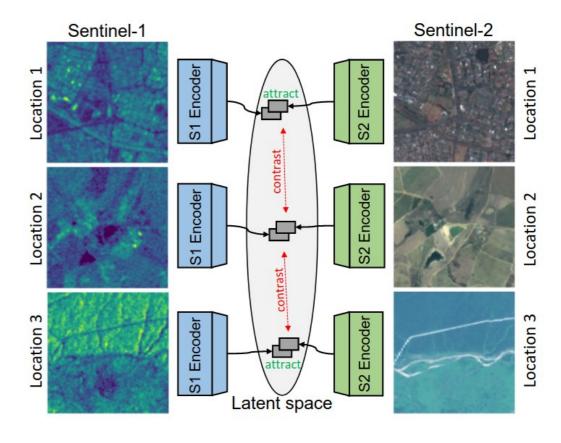
In remote sensing, we naturally have different views of the same scence (different times, different data modalities, etc.) We can leverage these views...

Chen et al. (2020)





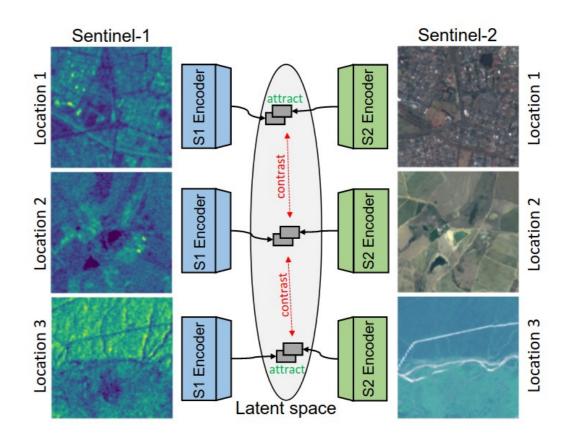
Pre-training





Pre-training

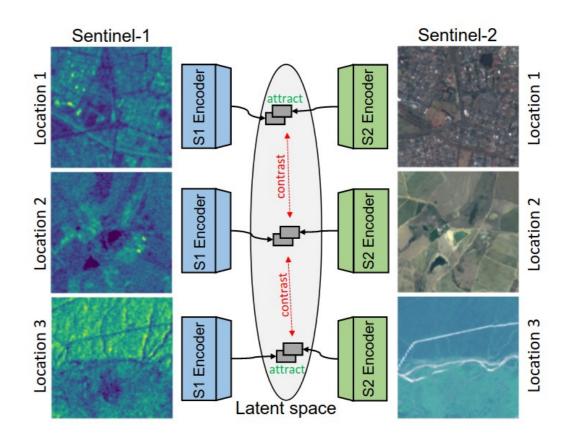
Multimodal dataset (SEN12MS, ~181k
 Sentinel-1/2 patch pairs)





Pre-training

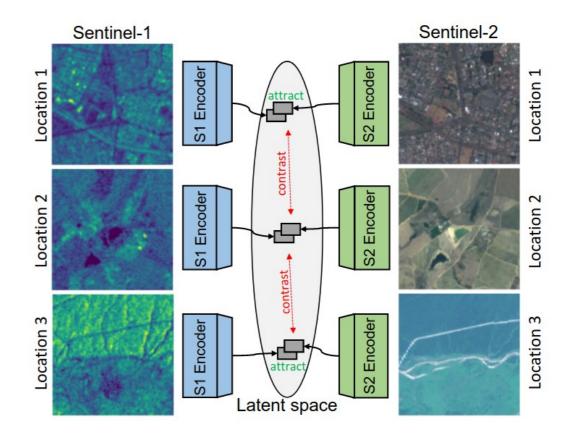
- Multimodal dataset (SEN12MS, ~181k
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- Separate backbones for each modality





Pre-training

- Multimodal dataset (SEN12MS, ~181k
 Sentinel-1/2 patch pairs)
- Separate backbones for each modality
- Augmentation-free, contrastive setup





Let's see how we can build this architecture...





Fine-tuning on classification task



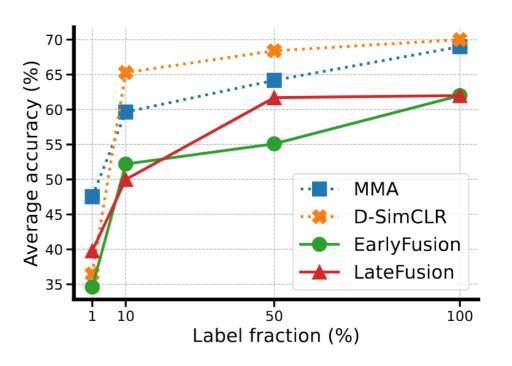
Fine-tuning on classification task

 Annotations from DFC2020 high-res (10m) land use/land cover maps, ~5k patches, 8 classes



Fine-tuning on classification task

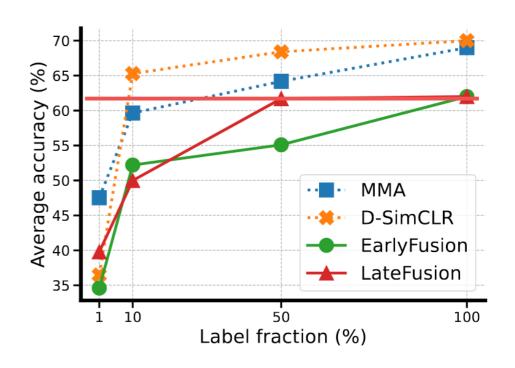
 Annotations from DFC2020 high-res (10m) land use/land cover maps, ~5k patches, 8 classes





Fine-tuning on classification task

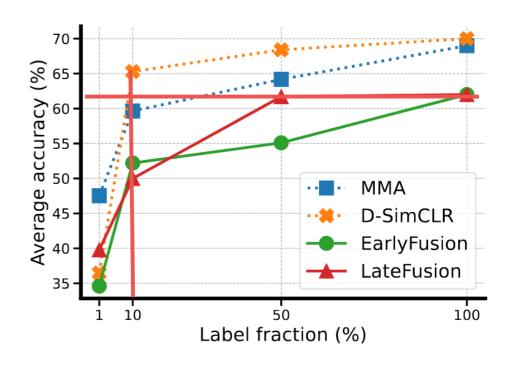
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Fine-tuning on classification task

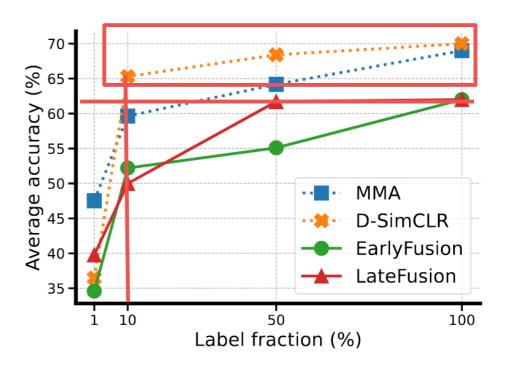
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Fine-tuning on classification task

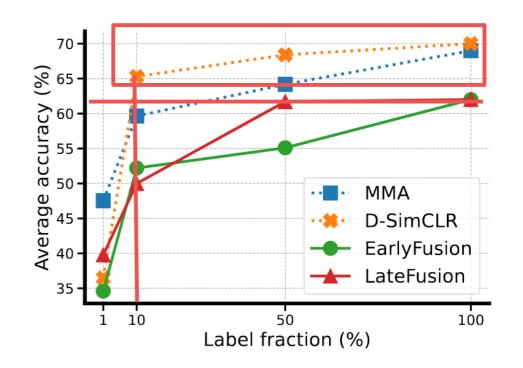
 Annotations from DFC2020 high-res (10m) land use/land cover maps, ~5k patches, 8 classes





Fine-tuning on classification task

- Annotations from DFC2020 high-res (10m) land use/land cover maps, ~5k patches, 8 classes
- Main result: pretrained models outperform supervised baselines with only 10% of training data





This is it!



Summary

We introduced a number of methods to make more efficient use of labels (or use no labels at all):

- Data augmentations
- Data Fusion
- Multi-task Learning
- Transfer Learning
- Self-supervised Learning

Now go out into the world and use the code that we discussed for your own research!

