

view\_frames Result

Recorded at time: 222.610

map

Broadcaster: /amcl  
Average rate: 40.202 Hz  
Most recent transform: 222.659 ( -0.049 sec old)  
Buffer length: 4.950 sec

odom

Broadcaster: /gazebo  
Average rate: 50.201 Hz  
Most recent transform: 222.599 ( 0.011 sec old)  
Buffer length: 4.980 sec

base\_footprint

Broadcaster: /my\_robo/robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 222.610 sec old)  
Buffer length: 0.000 sec

base\_link

Broadcaster: /my\_robo/robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 222.610 sec old)  
Buffer length: 0.000 sec

caster\_link

Broadcaster: /my\_robo/robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 222.610 sec old)  
Buffer length: 0.000 sec

hokuyo\_link

Broadcaster: /my\_robo/robot\_state\_publisher  
Average rate: 50.201 Hz  
Most recent transform: 222.599 ( 0.011 sec old)  
Buffer length: 4.980 sec

left\_wheel\_link

Broadcaster: /my\_robo/robot\_state\_publisher  
Average rate: 50.201 Hz  
Most recent transform: 222.599 ( 0.011 sec old)  
Buffer length: 4.980 sec

right\_wheel\_link