

Introduction to Satisfiability Modulo Theories

Combinatorial Problem Solving (CPS)

Albert Oliveras Enric Rodríguez-Carbonell

May 31, 2019

Satisfiability Modulo Theories

- Some problems are more naturally expressed in other logics than propositional logic, e.g:
 - ◆ Software verification needs reasoning about equality, arithmetic, data structures, ...
- SMT consists in deciding the satisfiability of a (quantifier-free) first-order formula with respect to a background theory
- Example (Equality with Uninterpreted Functions – EUF):

$$g(a)=c \quad \wedge \quad \left(f(g(a)) \neq f(c) \vee g(a)=d \right) \quad \wedge \quad c \neq d$$

- SMT is widely applied in hardware/software verification
Theories of interest here:
EUF, arithmetic, arrays, bit vectors, combinations of these
- With these and other theories,
SMT methods can also be used to solve combinatorial problems

Lazy Approach to SMT

Methodology:

Example: consider EUF and

$$\underbrace{g(a)=c}_1 \wedge \left(\underbrace{f(g(a)) \neq f(c)}_{\bar{2}} \vee \underbrace{g(a)=d}_3 \right) \wedge \underbrace{c \neq d}_{\bar{4}}$$

Lazy Approach to SMT

Methodology:

Example: consider EUF and

$$\underbrace{g(a)=c}_1 \wedge \underbrace{(f(g(a)) \neq f(c) \vee g(a)=d)}_{\bar{2}} \wedge \underbrace{c \neq d}_{\bar{4}}$$

- Send $\{1, \bar{2} \vee 3, \bar{4}\}$ to SAT solver
SAT solver returns model $[1, \bar{2}, \bar{4}]$
Theory solver says *T*-inconsistent

Lazy Approach to SMT

Methodology:

Example: consider **EU**F and

$$\underbrace{g(a)=c}_1 \wedge \underbrace{(f(g(a)) \neq f(c)) \vee g(a)=d}_{\bar{2}} \wedge \underbrace{c \neq d}_{\bar{4}}$$

- Send $\{1, \bar{2} \vee 3, \bar{4}\}$ to **SAT solver**
SAT solver returns model $[1, \bar{2}, \bar{4}]$
Theory solver says **T-inconsistent**
- Send $\{1, \bar{2} \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4\}$ to **SAT solver**
SAT solver returns model $[1, 2, 3, \bar{4}]$
Theory solver says **T-inconsistent**

Lazy Approach to SMT

Methodology:

Example: consider **EU**F and

$$\underbrace{g(a)=c}_1 \wedge \underbrace{(f(g(a)) \neq f(c))}_{\bar{2}} \vee \underbrace{g(a)=d}_3 \wedge \underbrace{c \neq d}_{\bar{4}}$$

- Send $\{1, \bar{2} \vee 3, \bar{4}\}$ to **SAT solver**
SAT solver returns model $[1, \bar{2}, \bar{4}]$
Theory solver says **T-inconsistent**
- Send $\{1, \bar{2} \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4\}$ to **SAT solver**
SAT solver returns model $[1, 2, 3, \bar{4}]$
Theory solver says **T-inconsistent**
- Send $\{1, \bar{2} \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4, \bar{1} \vee \bar{2} \vee \bar{3} \vee 4\}$ to **SAT solver**
SAT solver says **UNSATISFIABLE**

Lazy Approach to SMT

■ Why “lazy”?

Theory information used lazily when checking T -consistency of propositional models (cf. eagerly encoding into SAT upfront)

■ Characteristics:

- + Modular and flexible
- Theory information does not guide the search

■ (Early) Tools:

- | | |
|--|--|
| ◆ Barcelogic (UPC) | ◆ MathSAT (Univ. Trento) |
| ◆ CVC (Uni. NY + Iowa) | ◆ Yices (SRI) |
| ◆ DPT (Intel) | ◆ Z3 (Microsoft) |
| | ◆ ... |

Optimizations

Several optimizations for enhancing efficiency:

- Check T -consistency only of full propositional models

Optimizations

Several optimizations for enhancing efficiency:

- ~~Check T -consistency only of full propositional models~~
- Check T -consistency of partial assignment while being built

Optimizations

Several optimizations for enhancing efficiency:

- ~~Check T -consistency only of full propositional models~~
- Check T -consistency of **partial** assignment while being built
- Given a T -inconsistent assignment M , add $\neg M$ as a clause

Optimizations

Several optimizations for enhancing efficiency:

- ~~Check T -consistency only of full propositional models~~
- Check T -consistency of **partial** assignment while being built
- ~~Given a T -inconsistent assignment M , add $\neg M$ as a clause~~
- Given a T -inconsistent assignment M ,
identify a T -inconsistent **subset** $M_0 \subseteq M$ and add $\neg M_0$ as a clause

Optimizations

Several optimizations for enhancing efficiency:

- ~~Check T -consistency only of full propositional models~~
- Check T -consistency of **partial** assignment while being built
- ~~Given a T -inconsistent assignment M , add $\neg M$ as a clause~~
- Given a T -inconsistent assignment M ,
identify a T -inconsistent **subset** $M_0 \subseteq M$ and add $\neg M_0$ as a clause
- Upon a T -inconsistency, add clause and restart

Optimizations

Several optimizations for enhancing efficiency:

- ~~Check T -consistency only of full propositional models~~
- Check T -consistency of **partial** assignment while being built

- ~~Given a T -inconsistent assignment M , add $\neg M$ as a clause~~
- Given a T -inconsistent assignment M ,
identify a T -inconsistent **subset** $M_0 \subseteq M$ and add $\neg M_0$ as a clause

- ~~Upon a T -inconsistency, add clause and restart~~
- Upon a T -inconsistency, do **conflict analysis** and **backjump**

Important Points

Advantages of the lazy approach:

- Everyone **does** what it is **good at**:
 - ◆ **SAT solver** takes care of **Boolean information**
 - ◆ **Theory solver** takes care of **theory information**
- Theory solver **only** receives **conjunctions** of literals
- Modular approach:
 - ◆ SAT solver and T -solver **communicate** via a **simple API**
 - ◆ SMT for a **new theory** only requires **new T -solver**
 - ◆ **SAT solver** can be **extended** to a lazy SMT system with very few new lines of code (40?)

Theory propagation

- As pointed out, the lazy approach has a drawback:

- ◆ Theory information does not guide the search

- How can we improve that? Theory propagation

T-Propagate

$$M \parallel F \quad \Rightarrow \quad M \parallel F \text{ if } \left\{ \begin{array}{l} M \models_T l \\ l \text{ or } \neg l \text{ occurs in } F \text{ and not in } M \end{array} \right.$$

- Search guided by T-Solver by finding T-consequences, instead of only validating it as in basic lazy approach.
- Naive implementation: Add $\neg l$. If T-inconsistent then infer l . But for efficient T-Propagate we need specialized T-Solvers
- This approach has been named DPLL(T)

Example

Consider again EUF and the formula:

$$\underbrace{g(a)=c}_1 \wedge \left(\underbrace{f(g(a)) \neq f(c)}_{\bar{2}} \vee \underbrace{g(a)=d}_3 \right) \wedge \underbrace{c \neq d}_{\bar{4}}$$

Example

Consider again **EU**F and the formula:

$$\underbrace{g(a)=c}_1 \wedge \left(\underbrace{f(g(a)) \neq f(c)}_{\bar{2}} \vee \underbrace{g(a)=d}_3 \right) \wedge \underbrace{c \neq d}_{\bar{4}}$$

$$\emptyset \parallel 1, \bar{2} \vee 3, \bar{4} \Rightarrow (\text{UnitPropagate})$$

Example

Consider again **EU****F** and the formula:

$$\underbrace{g(a)=c}_1 \wedge \left(\underbrace{f(g(a)) \neq f(c)}_{\bar{2}} \vee \underbrace{g(a)=d}_3 \right) \wedge \underbrace{c \neq d}_{\bar{4}}$$

$$\emptyset \parallel \textcolor{green}{1}, \bar{2} \vee 3, \bar{4} \Rightarrow (\text{UnitPropagate})$$

$$\textcolor{blue}{1} \parallel 1, \bar{2} \vee 3, \bar{4} \Rightarrow (\text{T-Propagate})$$

Example

Consider again **EU****F** and the formula:

$$\underbrace{g(a)=c}_1 \wedge \left(\underbrace{f(g(a)) \neq f(c)}_{\bar{2}} \vee \underbrace{g(a)=d}_3 \right) \wedge \underbrace{c \neq d}_{\bar{4}}$$

$$\emptyset \parallel 1, \bar{2} \vee 3, \bar{4} \Rightarrow (\text{UnitPropagate})$$

$$1 \parallel 1, \bar{2} \vee 3, \bar{4} \Rightarrow (\text{T-Propagate})$$

$$1\ 2 \parallel 1, \bar{2} \vee 3, \bar{4} \Rightarrow (\text{UnitPropagate})$$

Example

Consider again **EU****F** and the formula:

$$\underbrace{g(a)=c}_1 \wedge \left(\underbrace{f(g(a)) \neq f(c)}_{\bar{2}} \vee \underbrace{g(a)=d}_3 \right) \wedge \underbrace{c \neq d}_{\bar{4}}$$

$$\emptyset \parallel 1, \bar{2} \vee 3, \bar{4} \Rightarrow (\text{UnitPropagate})$$

$$1 \parallel 1, \bar{2} \vee 3, \bar{4} \Rightarrow (\text{T-Propagate})$$

$$1\ 2 \parallel 1, \bar{2} \vee 3, \bar{4} \Rightarrow (\text{UnitPropagate})$$

$$1\ 2\ 3 \parallel 1, \bar{2} \vee 3, \bar{4} \Rightarrow (\text{T-Propagate})$$

Example

Consider again **EU**F and the formula:

$$\underbrace{g(a)=c}_1 \wedge \left(\underbrace{f(g(a)) \neq f(c)}_{\bar{2}} \vee \underbrace{g(a)=d}_3 \right) \wedge \underbrace{c \neq d}_{\bar{4}}$$

$$\begin{array}{llll} \emptyset & \parallel & 1, \bar{2} \vee 3, \bar{4} & \Rightarrow \text{(UnitPropagate)} \\ 1 & \parallel & 1, \bar{2} \vee 3, \bar{4} & \Rightarrow \text{(T-Propagate)} \\ 1\ 2 & \parallel & 1, \bar{2} \vee 3, \bar{4} & \Rightarrow \text{(UnitPropagate)} \\ 1\ 2\ 3 & \parallel & 1, \bar{2} \vee 3, \bar{4} & \Rightarrow \text{(T-Propagate)} \\ 1\ 2\ 3\ 4 & \parallel & 1, \bar{2} \vee 3, \bar{4} & \Rightarrow \text{(Fail)} \end{array}$$

Example

Consider again **EU**F and the formula:

$$\underbrace{g(a)=c}_1 \wedge \left(\underbrace{f(g(a)) \neq f(c)}_{\bar{2}} \vee \underbrace{g(a)=d}_3 \right) \wedge \underbrace{c \neq d}_{\bar{4}}$$

$$\begin{array}{llll} \emptyset & \parallel & 1, \bar{2} \vee 3, \bar{4} & \Rightarrow \text{(UnitPropagate)} \\ 1 & \parallel & 1, \bar{2} \vee 3, \bar{4} & \Rightarrow \text{(T-Propagate)} \\ 1\ 2 & \parallel & 1, \bar{2} \vee 3, \bar{4} & \Rightarrow \text{(UnitPropagate)} \\ 1\ 2\ 3 & \parallel & 1, \bar{2} \vee 3, \bar{4} & \Rightarrow \text{(T-Propagate)} \\ 1\ 2\ 3\ 4 & \parallel & 1, \bar{2} \vee 3, \bar{4} & \Rightarrow \text{(Fail)} \\ & & \text{fail} & \end{array}$$

Example

Consider again **EU**F and the formula:

$$\underbrace{g(a)=c}_1 \wedge \left(\underbrace{f(g(a)) \neq f(c)}_{\bar{2}} \vee \underbrace{g(a)=d}_3 \right) \wedge \underbrace{c \neq d}_{\bar{4}}$$

$$\begin{array}{llll} \emptyset & \parallel & 1, \bar{2} \vee 3, \bar{4} & \Rightarrow \text{(UnitPropagate)} \\ 1 & \parallel & 1, \bar{2} \vee 3, \bar{4} & \Rightarrow \text{(T-Propagate)} \\ 1\ 2 & \parallel & 1, \bar{2} \vee 3, \bar{4} & \Rightarrow \text{(UnitPropagate)} \\ 1\ 2\ 3 & \parallel & 1, \bar{2} \vee 3, \bar{4} & \Rightarrow \text{(T-Propagate)} \\ 1\ 2\ 3\ 4 & \parallel & 1, \bar{2} \vee 3, \bar{4} & \Rightarrow \text{(Fail)} \\ & & \text{fail} & \end{array}$$

No search!

Overall algorithm

High-level view gives the same algorithm as in a CDCL SAT solver:

```
while(true){  
    while (propagate_gives_conflict()){  
        if (decision_level==0) return UNSAT;  
        else analyze_conflict();  
    }  
    restart_if_applicable();  
    remove_lemmas_if_applicable();  
    if (!decide()) returns SAT; // All vars assigned  
}
```

Differences are in:

- `propagate_gives_conflict`
- `analyze_conflict`

DPLL(T) - Propagation

propagate_gives_conflict() returns Bool

```
// unit propagate
```

```
if ( unit_prop_gives_conflict() ) then return true
```

```
return false
```

DPLL(T) - Propagation

propagate_gives_conflict() returns Bool

do {

 // unit propagate

if (unit_prop_gives_conflict()) **then return** true

 // check T-consistency of the model

if (solver.is_model_inconsistent()) **then return** true

 // theory propagate

 solver.theory_propagate()

} while (doneSomeTheoryPropagation)

return false

DPLL(T) - Propagation

- Three operations:
 - ◆ Unit propagation (SAT solver)
 - ◆ Consistency checks (T -solver)
 - ◆ Theory propagation (T -solver)
- Cheap operations are computed first
- If theory is expensive, calls to T -solver are sometimes skipped
 - ◆ Only strictly necessary to call T -consistency at the leaves (i.e. when we have a full propositional model)
 - ◆ T -propagation is not necessary for correctness

DPLL(T) - Conflict Analysis

Remember conflict analysis in SAT solvers:

$C :=$ conflicting clause

while C contains more than one lit of last DL

$l :=$ last literal assigned in C

$C := \text{Resolution}(C, \text{reason}(l))$

end while

// let $C = C' \vee l$ where l is the only lit of last DL

backjump(maxDL(C'))

add l to the model with reason C

learn(C)

DPLL(T) - Conflict Analysis

Conflict analysis in DPLL(T):

```
if boolean conflict then  $C :=$  conflicting clause  
else  $C := \neg(\text{solver.explain\_inconsistency}())$ 
```

```
while  $C$  contains more than one lit of last DL
```

```
     $l :=$  last literal assigned in  $C$ 
```

```
     $C :=$  Resolution( $C$ , reason( $l$ ))
```

```
end while
```

```
// let  $C = C' \vee l$  where  $l$  is the only lit of last DL
```

```
backjump(maxDL( $C'$ ))
```

```
add  $l$  to the model with reason  $C$ 
```

```
learn( $C$ )
```

DPLL(T) - Conflict Analysis

What does `explain_inconsistency` return?

- An **explanation** of the inconsistency:
A (small) conjunction of literals $l_1 \wedge \dots \wedge l_n$ such that:
 - ◆ It is T -inconsistent

What is now `reason(l)`?

- If l was unit propagated: clause that propagated it
- If l was T -propagated:
 - ◆ An **explanation** of the propagation:
A (small) clause $\neg l_1 \vee \dots \vee \neg l_n \vee l$ such that:
 - $l_1 \wedge \dots \wedge l_n \models_T l$
 - l_1, \dots, l_n were in the model when l was T -propagated

DPLL(T) - Conflict Analysis

Let M be $c=b$ and let F contain

$$a=b \vee g(a) \neq g(b), \quad h(a)=h(c) \vee p, \quad g(a)=g(b) \vee \neg p$$

Take the following sequence:

1. **Decide** $h(a) \neq h(c)$
2. **T-Propagate** $a \neq b$ (due to $h(a) \neq h(c)$ and $c=b$)
3. **UnitPropagate** $g(a) \neq g(b)$
4. **UnitPropagate** p
5. **Conflicting clause** $g(a)=g(b) \vee \neg p$

Explain($a \neq b$) is $\{h(a) \neq h(c), c=b\}$



$$\frac{h(a)=h(c) \vee c \neq b \vee a \neq b}{h(a)=h(c) \vee c \neq b} \quad \frac{\frac{a=b \vee g(a) \neq g(b)}{h(a)=h(c) \vee a=b} \quad \frac{h(a)=h(c) \vee p \quad g(a)=g(b) \vee \neg p}{h(a)=h(c) \vee g(a)=g(b)}}$$

DPLL(T) – T -Solver API

What does DPLL(T) need from T -Solver?

- T -consistency check of a set of literals M , with:
 - ◆ Explain of T -inconsistency:
find small T -inconsistent subset of M
 - ◆ **Incrementality**: if l is added to M ,
check for $M \cup l$ faster than reprocessing $M \cup l$ from scratch.
- Theory propagation: find input T -consequences of M , with:
 - ◆ Explain T -Propagate of l :
find (small) subset of M that T -entails l .
- Backtrack n : undo last n literals added

Bibliography - Further reading

- R. Nieuwenhuis, A. Oliveras, C. Tinelli. *Solving SAT and SAT Modulo Theories: From an abstract Davis–Putnam–Logemann–Loveland procedure to DPLL(T)*. J. ACM 53(6): 937-977 (2006)
- C. W. Barrett, R. Sebastiani, S. A. Seshia, C. Tinelli. *Satisfiability Modulo Theories*. Handbook of Satisfiability 2009: 825-885
- O. Ohrimenko, P. Stuckey, M. Codish. *Propagation = Lazy Clause Generation*. CP 2007.
- R. Sebastiani. *Lazy Satisfiability Modulo Theories*. JSAT 3(3-4): 141-224 (2007).