Combinatorial Problem Solving (CPS)

2016-17 Spring Term. Final Exam: 2 hours

Publication of grades: 20/06

Revision of exams: 23/06 (office 113, Ω building, under request by e-mail: erodri@cs.upc.edu)

- 1. (3 pts.) Let x, y be variables with finite domains $D_x, D_y \subseteq \mathbb{Z}$. Let $C_1(x, y)$ and $C_2(x, y)$ be two constraints.
 - (a) (1.5 pts.) If at least one of C_1 , C_2 is arc-consistent, is it true that the constraint C_3 defined as $C_3(x,y) \equiv C_1(x,y) \vee C_2(x,y)$ is arc-consistent?

If the answer is positive, prove so. If the answer is negative, give a counterexample.

True. Without loss of generality, let us assume that C_1 is arc consistent. Let us prove that for any $a \in D_x$ there exists $b \in D_y$ such that $C_3(a,b)$ is true. Indeed: since C_1 is arc-consistent, there exists $b \in D_y$ such that $C_1(a,b)$ is true, and therefore $C_3(a,b) \equiv C_1(a,b) \vee C_2(a,b)$ is true. The same argument can be applied to prove that that for any $a \in D_y$ there exists $b \in D_x$ such that $C_3(b,a)$ is true. Hence, C_3 is arc-consistent.

(b) (1.5 pts.) If C_1 and C_2 are both arc-consistent, is it true that the constraint C_4 defined as $C_4(x,y) \equiv C_1(x,y) \wedge C_2(x,y)$ is arc-consistent?

If the answer is positive, prove so. If the answer is negative, give a counterexample.

False. Let us consider domains $D_x = \{0, 1\}$ and $D_y = \{0, 1\}$, and constraints $C_1(x, y) \equiv x = y$ and $C_2(x, y) \equiv x \neq y$.

We have that:

- i. C_1 is arc-consistent: value 0 for x (for y) has support 0 in D_y (in D_x); and value 1 for x (for y) has support 1 in D_y (in D_x).
- ii. C_2 is arc-consistent: value 0 for x (for y) has support 1 in D_y (in D_x); and value 1 for x (for y) has support 0 in D_y (in D_x).
- iii. C_4 is not arc-consistent, since no pair of values can satisfy it.
- 2. (3 pts.) Let P_0 be a (minimization) linear program over 0-1 variables $x=(x_1,...,x_n)$ with cost function c^Tx . Consider the following simplification of the branch-and-bound procedure for finding the minimum cost of P_0 :

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\begin{array}{ll} 1 & S := \{P_0\} \\ 2 & UB := \infty \\ 3 & \mathbf{while} \; (S \neq \emptyset) \; \{ \\ 4 & P := choose\_from(S); \\ 5 & S := S - \{P\} \\ 6 & \beta := basic\_solution\_of\_optimal\_basis\_of (LP(P)) \\ 7 & \mathbf{if} \; (\beta \neq \bot \land c^T\beta < UB) \; \{ \\ 8 & \mathbf{if} \; (\forall x_i \; \beta(x_i) \in \{0,1\}) \\ 9 & UB := c^T\beta \\ 10 & \mathbf{else} \; \{ \\ 11 & x_j := choose\_from(\{\; x_i \mid 0 < \beta(x_i) < 1 \; \}) \\ 12 & S := S \cup \{P \land x_j = 0\} \; \cup \; \{P \land x_j = 1\} \\ 13 & \} \; \} \; \} \\ 14 & \mathbf{return} \; UB \end{array}
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where:

- function *choose_from*(·) returns an element of a given set;
- function $LP(\cdot)$ returns the linear programming relaxation of a given 0-1 linear program;
- function basic_solution_of_optimal_basis_of (·) calls the simplex algorithm on a given (real) linear program and returns the basic solution of an optimal basis (⊥ if infeasible or unbounded)
- (a) (0.5 pts.) Can the linear programming relaxation LP(P) at line 6 be an unbounded linear program? Justify your answer.

No, because variables are bounded between 0 and 1. So the cost function is bounded over the feasible solutions of P_0 .

(b) (0.5 pts.) Does the branch-and-bound procedure terminate? Justify your answer.

Yes. The tree of the search space has finite height because whenever a node is branched, one new variable becomes fixed. This, together with the termination of the simplex algorithm, guarantees the termination of the branch-and-bound procedure.

(c) (2 pts.) At any iteration of the loop, the value of variable UB is an upper bound on the minimum cost of P_0 . Explain the changes you would make to the above pseudo-code so that it also maintained a variable LB giving a lower bound on the minimum cost of P_0 . Note: The grade will depend on how accurate the lower bounds are.

When new 0-1 problems are generated at line 12, their linear programming relaxations are immediately solved and stored in S together with their corresponding 0-1 problems. Then LB has to be the minimum of the optimal solutions of the relaxations of the problems in S.

3. (4 pts.) Let us consider $n = p \times q$ Boolean variables

Let $X = \{x_{(i,j)} \mid 0 \le i < p, 0 \le j < q\}$. The product encoding of the At-Most-One constraint

$$\mathrm{AMO}(X) \equiv \sum_{0 \leq i < p, \; 0 \leq j < q} x_{(i,j)} \leq 1$$

is defined as follows. Let us introduce auxiliary variables $R = \{r_0, \dots, r_{p-1}\}$ and $C = \{c_0, \dots, c_{q-1}\}$ and the following set of clauses:

$$\{ \ \neg x_{(i,j)} \lor r_i, \quad \neg x_{(i,j)} \lor c_j \quad | \quad 0 \le i < p, \ 0 \le j < q \ \}$$

together with the clauses resulting from encoding $\mathrm{AMO}(R)$ and $\mathrm{AMO}(C)$ (recursively, or with another encoding for AMO constraints).

(a) (2 pts.) Show that, if the encodings used for AMO(R) and AMO(C) are consistent, then the product encoding is consistent.

Let us assume that two different variables $x_{(i,j)}$ and $x_{(i',j')}$ are set to true. Since they are different, either $i \neq i'$ or $j \neq j'$. Without loss of generality, let us assume that $i \neq i'$. Then $x_{(i,j)}$ propagates r_i thanks to clause $\neg x_{(i,j)} \lor r_i$, and $x_{(i',j')}$ propagates $r_{i'}$ thanks to clause $\neg x_{(i',j')} \lor r_{i'}$. Since the encoding for AMO(R) is consistent, unit propagation leads to a conflict.

(b) (2 pts.) Show that, if the encodings used for AMO(R) and AMO(C) are arc-consistent, then the product encoding is arc-consistent.

Let us assume that variable $x_{(i,j)}$ is set to true. This propagates r_i thanks to clause $\neg x_{(i,j)} \lor r_i$, and c_j thanks to clause $\neg x_{(i,j)} \lor c_j$. Since the encodings for AMO(R) and AMO(R) are arcconsistent, unit propagation propagates $\neg r_{i'}$ for all $i' \neq i$ and $\neg c_{j'}$ for all $j' \neq j$. But this in turn propagates $\neg x_{(i',j')}$ for all $x_{(i',j')}$ different from $x_{(i,j)}$.

This, together with the previous exercise, justifies that if the encodings used for AMO(R) and AMO(C) are arc-consistent, then the product encoding is arc-consistent.