

## § 0.1 Metric Spaces

### §§ 0.1.1 Topology

**Definition 0.1.1** (Metric Space). Let  $X$  be a non-empty set equipped with an application  $d$ , defined as follows

$$\begin{aligned} d : X \times X &\longrightarrow \mathbb{F} \\ (x, y) &\rightarrow d(x, y) \end{aligned} \tag{1}$$

Where  $\mathbb{F}$  is an ordered field.

The couple  $(X, d)$  is said to be a *metric space*, if and only if  $\forall x, y, z \in X$  the application  $d$  satisfies the following properties

1.  $d(x, y) \geq 0$
2.  $d(x, x) = 0$
3.  $d(x, y) = d(y, x)$
4.  $d(x, y) \leq d(x, z) + d(z, y)$

**Definition 0.1.2** (Ball). Let  $(X, d)$  be a metric space. We then define the *open ball of radius  $r$* , centered in  $x$  in  $X$  ( $B_r^X$ ), and the *closed ball of radius  $r$*  centered in  $x$  ( $\overline{B_r^X}$ ) as follows

$$\begin{aligned} B_r^X(x) &:= \{u \in X \mid d(u, x) < r\} \\ \overline{B_r^X}(x) &:= \{u \in X \mid d(u, x) \leq r\} \end{aligned} \tag{2}$$

When there won't be doubts on where the ball is defined, the superscript indicating the set of reference will be omitted.

We're now ready to define the *topology* on a metric space

**Definition 0.1.3** (Open Set). Let  $(X, d)$  be a metric space, and  $A \subseteq X$  a subset.  $A$  is said to be an *open set* if and only if

$$\forall x \in X \exists B_r^X(x) \subset A \tag{3}$$

**Definition 0.1.4** (Complementary Set). Let  $A$  be a generic set, then the set  $A^c$  is defined as follows

$$A^c := \{a \notin A\} \tag{4}$$

This set is said to be the *complementary set* of  $A$ .

It's also obvious that  $A \cap A^c = \{\}$

**Definition 0.1.5** (Closed Set). Alternatively to the notion of open set, we can say that  $E \subseteq X$  is a *closed set*, if and only if

$$\forall x \in E^c \cap X \exists B_r^X(x) \subset E^c \cap X \tag{5}$$

*Remark.* A set isn't necessarily open nor closed!

**Proposition 1.** 1. The set  $B_r^X(x)$  is open

2. The set  $\overline{B_r^X}(x)$  is closed

*Proof.* Let  $A = B_r^X(x)$ . If  $A$  is open, we have therefore, applying the definition of open set, that

$$\forall x \in A \exists \epsilon > 0 : B_\epsilon^X(x) \subset A$$

So

$$\begin{aligned} x_0 \in A &\implies d(x, x_0) < r \\ \therefore \epsilon = r - d(x, x_0) &> 0 \end{aligned}$$

Then, by definition of open ball we have

$$y \in B_\epsilon^X(x) \implies d(x, y) < \epsilon$$

Then, we can say that

$$\begin{aligned} d(y, x_0) &\leq d(y, x) + d(x, x_0) < \epsilon + d(x, x_0) = r \\ \therefore y \in B_\epsilon^X(x) &\implies y \in B_r^X(x_0) \subset A \end{aligned}$$

The demonstration of the second point is exactly the same, whereby we take  $E$  as our closed ball and  $A = E^c$   $\square$

**Proposition 2.** Let  $(X, d)$

1. The sets  $\{\}, X$  are open
2. The sets  $\{\}, X$  are closed
3. If  $\{A_i\}_{i=1}^n$  is a collection of open sets, then  $A = \bigcap_{i=1}^n A_i$  is open
4. If  $\{C_i\}_{i=1}^n$  is a collection of closed sets, then  $C = \bigcup_{i=1}^n C_i$  is closed
5. Let  $I \subset \mathbb{N}$  be an index set, then
  - (a) If  $\{A_\alpha\}_{\alpha \in I}$  is a collection of open sets, then  $B = \bigcup_{\alpha \in I} A_\alpha$  is open
  - (b) If  $\{C_\alpha\}_{\alpha \in I}$  is a collection of closed sets, then  $D = \bigcap_{\alpha \in I} C_\alpha$  is closed

*Proof.* The first two statements are of easy proof. Let  $B_\epsilon^X \subset \{\}$ . This means that  $B_\epsilon^X$  is empty and therefore  $B_\epsilon^X = \{\}$ , which makes it open by definition. Therefore we have that  $\{\}^c = X$ , and  $X$  must be closed, but if we reason a bit, we can say that  $\forall x \in X B_\epsilon^X(x) \subset X$ , which means that  $X$  is open, thus  $X^c = \{\}$  must be closed.

Since we gave a proof for  $\{\}$  and  $X$  being open, we have that these two sets are both open and closed. These two sets are said to be *clopen*.

For the other statements we use the De Morgan laws on set calculus, therefore we have

$$\begin{aligned} x \in \bigcap_{i=1}^n A_i &\implies x \in A_i \\ \therefore \exists \epsilon_i : B_{\epsilon_i}^X(x) &\subset A_i \end{aligned}$$

Taking  $\epsilon = \min_{i \in I} \epsilon_i$  we have

$$B_\epsilon^X(x) \subset B_{\epsilon_i}^X(x) \implies B_\epsilon^X(x) \subset \bigcap_{i=1}^n A_i = A$$

And  $A$  is open

If we let  $C = A^c$  we have that

$$C = A^c = \left( \bigcap_{i=1}^n A_i \right)^c = \bigcup_{i=1}^n A_i^c$$

$\therefore C$  is closed

For the last two we proceed as follows

$$x \in A_\alpha \implies \exists \alpha_0 \in I : x \in A_{\alpha_0}$$

$$\therefore \exists \epsilon > 0 : B_\epsilon^X(x) \subset A_{\alpha_0} \subset \bigcup_{\alpha \in I} A_\alpha = B$$

For the last one, we use the De Morgan laws and the proposition is demonstrated  $\square$

**Definition 0.1.6** (Internal Points, Closure, Border). Let  $(X, d)$  be a metric space and  $A \subset X$  a subset.

We define the following sets from  $A$

1.  $A^\circ = \bigcup_{\alpha \in I} G_\alpha$  is the set of internal points of  $A$ , where  $I$  is an index set and  $G_\alpha \subset A$  are open
2.  $\bar{A} = \bigcap_{\beta \in J} F_\beta$  is the closure of  $A$ , where  $J$  is another index set and  $F_\beta \subset A$  are closed
3.  $\partial A = \bar{A} \setminus A^\circ = \bar{A} \cup (A^\circ)^c$  is the border of  $A$

**Proposition 3.** 1.  $A$  is an open set iff  $A = A^\circ$

2.  $A$  is closed iff  $A = \bar{A}$

3.  $A^\circ = \overline{(A^\circ)^c}^c$

4.  $\bar{A} = [(A^c)^\circ]^c$

5.  $(A \cap B)^\circ = A^\circ \cap B^\circ$

6.  $\overline{A \cap B} = \bar{A} \cap \bar{B}$

*Proof.* Let  $\mathcal{O}(A)$  be a collection of open sets, such that  $\forall G \in \mathcal{O}(A) \implies G \subset A$ , then

$$A = A^\circ \implies A = \bigcup_{G \in \mathcal{O}(A)} G$$

Therefore, being a union of a finite number of open sets,  $A$  is open.

For the same reason as before and the previous proposition, we have that  $\bar{A}$  is closed

For the third proposition, we have

$$(\bar{A}^c)^c = \left( \bigcap_{A^c \subset F} F \right)^c = \bigcup_{A^c \subset F} F^c = \bigcup_{G \in \mathcal{O}(A)} G = A^\circ$$

The others are easily demonstrated throw this process, iteratively  $\square$

**Proposition 4.** Let  $(X, d)$  be a metric space, and  $A \subset X$ ,  $x \in X$

1.  $x \in A \iff \exists \epsilon > 0 : B_\epsilon(x) \subset A$
2.  $x \in \overline{A} \iff \forall \epsilon > 0 B_\epsilon(x) \cap A \neq \{\}$
3.  $x \in \partial A \iff \forall \epsilon > 0 B_\epsilon(x) \cap A \neq \{\} \wedge B_\epsilon(x) \cap \overline{A} \neq \{\}$

*Proof.* [1] Let  $I(A) := \{x \in X \mid \exists \epsilon > 0 : B_\epsilon(x) \subset A\}$ .

$$x \in I(A) \implies \exists \epsilon > 0 : B_\epsilon(x) \subset A, \therefore x \in \bigcup_{G \subset A} G$$

But

$$\begin{aligned} x \in A^\circ &\implies \exists G \subset X \text{ open} : x \in G \implies \exists \epsilon > 0 : B_\epsilon(x) \subset G \subset A \\ \therefore A^\circ &\subset I(A) \ni x, I(A) \subset A \text{ by definition, } \therefore I(A) = A^\circ \end{aligned}$$

[2] For the second proposition, we have

$$\begin{aligned} \overline{A} &= [(A^c)^\circ]^c \implies x \in A \iff x \in (A^c)^\circ \implies \forall \epsilon > 0 B_\epsilon(x) \not\subset A^c \\ \therefore \forall \epsilon > 0 B_\epsilon(x) \cap A &\neq \{\} \end{aligned}$$

[3] For the last one, we have, taking into account the first two proofs

$$\begin{aligned} x \in \partial A &\iff x \in \overline{A} \setminus A^\circ \implies x \in \overline{A} \wedge x \notin A^\circ \\ [1] \wedge [2] &\implies x \in \overline{A} \iff \forall \epsilon > 0 B_\epsilon(x) \cap A \neq \{\} \\ \therefore x \notin A^\circ &\iff \forall \epsilon > 0 B_\epsilon(x) \cap A^c \neq \{\} \end{aligned}$$

□

**Definition 0.1.7** (Isometry). Let  $(X, d), (Y, \rho)$  be two metric spaces and  $f$  an application, defined as follows

$$f : (X, d) \rightarrow (Y, \rho)$$

$f$  is said to be an *isometry* iff

$$\forall x_1, x_2 \in X, \rho(f(x_1), f(x_2)) = d(x_1, x_2)$$

*Remark.* If  $f$  is an isometry, then  $f$  is injective, but it's not necessarily surjective

*Example 0.1.1.* Let  $X = [0, 1]$  and  $Y = [0, 2]$ , therefore

$$\begin{aligned} f : [0, 1] &\rightarrow [0, 2] \\ x &\rightarrow f(x) = x \end{aligned}$$

$f$  is obviously an isometry, since, for  $x, y \in [0, 1]$

$$d(f(x), f(y)) = d(x, y)$$

But it's obviously not surjective.

**Definition 0.1.8** (Diameter of a Set). Let  $A$  be a set and the couple  $(A, d)$  be a metric space. We define the *diameter* of  $A$  as follows

$$\text{diam}(A) = \sup_{x, y \in A} (d(x, y))$$

## § 0.2 Convergence and Compactness

**Definition 0.2.1** (Convergence). Let  $(X, d)$  be a metric space and  $x \in X$ . A sequence  $(x_k)_{k \geq 0}$  in  $X$  is said to converge in  $X$  and it's indicated as  $x_k \rightarrow x \in X$ , iff

$$\forall \epsilon > 0 \exists N > 0 : \forall k \geq N, d(x_k, x) < \epsilon \quad \therefore \lim_{k \rightarrow \infty} x_k = x$$

**Theorem 0.1** (Unicity of the Limit). Let  $(X, d)$  be a metric space and  $(x_k)_{k \geq 0}$  a sequence in  $X$ . If  $x_k \rightarrow x \wedge x_k \rightarrow y$ , then  $x = y$

**Definition 0.2.2** (Adherent point). Let  $(X, d)$  be a metric space and  $A \subset X$ .  $x \in X$  is said to be an *adherent point* of  $A$  if  $\exists (x_k)_{k \geq 0} \in A : x_k \rightarrow x \in X$ . The set of all adherent points of  $A$  is called  $\text{ad}(A)$

**Definition 0.2.3** (Accumulation point). Let  $(X, d)$  be a metric space and  $A \subset X$ .  $x \in X$  is an *accumulation point* of  $A$ , or also *limit point* of  $A$  if  $\exists (x_k)_{k \geq 0} : x_k \neq x \wedge x_k \rightarrow x \in \text{ad}(A)$

**Proposition 5.** Let  $(X, d)$  be a metric space and  $A \subset X$ , then  $\overline{A} = \text{ad}(A)$

*Proof.* Let  $Y = \text{ad}(A)$ , then

$$\begin{aligned} x \in \overline{A} &\implies \forall \epsilon > 0 B_\epsilon(x) \cap A \neq \{\} \\ \therefore \forall n \in \mathbb{N} B_{\frac{1}{n}}(x) \cap A &\neq \{\} \implies \forall n \in \mathbb{N} \exists x_n \in B_{\frac{1}{n}}(x) \end{aligned}$$

But  $d(x, x_n) < n^{-1}$ , therefore  $x \in Y \implies x \in \text{ad}(A)$ , and by definition

$$\begin{aligned} \exists (x_n)_{n \geq 0} : \forall \epsilon > 0 \exists N \in \mathbb{N} : \forall k \geq N d(x_k, x) < \epsilon &\implies x_N \in B_\epsilon(x) \quad \therefore x_N \in A \\ \therefore \forall \epsilon > 0 x_N \in B_\epsilon(x) \cap A \neq \{\} &\implies x \in \overline{A} \implies Y \subset \overline{A}, \therefore Y = \text{ad}(A) = \overline{A} \end{aligned}$$

□

**Proposition 6.** Let  $(X, d)$  be a metric space and  $A \subset X$ . Then  $A$  is closed iff  $\exists (x_k)_{k \geq 0} \in A : x_k \rightarrow x \in \overline{A} \implies \text{ad}(A) \subset A$

**Definition 0.2.4** (Dense Set). Let  $(X, d)$  be a metric space and  $A, B \subset X$ .  $A$  is said to be dense in  $B$  iff  $B \subset \overline{A}$ , therefore  $\forall \epsilon > 0 \exists y \in A : d(x, y) < \epsilon$ . One example for this is  $\mathbb{Q} \subset \mathbb{R}$ , with the usual euclidean distance defined through the modulus.

**Definition 0.2.5.** Let  $(X, d)$  be a metric space and  $(x_k)_{k \geq 0} \in X$ . The sequence  $x_k$  is said to be a *Cauchy sequence* iff

$$\forall \epsilon > 0 \exists N > 0 : \forall k, n \geq N d(x_k, x_n) < \epsilon$$

**Proposition 7.** Let  $(X, d)$  be a metric space and  $(x_k)_{k \geq 0} \in X$  a sequence. Then, if  $x_k \rightarrow x$ ,  $x_k$  is a Cauchy sequence

**Definition 0.2.6** (Complete Space). Let  $(X, d)$  be a metric space.  $(X, d)$  is said to be *complete* iff  $\forall (x_k)_{k \geq 0} \in X$  Cauchy sequences, we have  $x_k \rightarrow x \in X$

**Theorem 0.2** (Completeness). Let  $(X, d)$  be a metric space and  $Y \subset X$ .  $(Y, d)$  is complete iff  $Y = \overline{Y}$  in  $X$

*Proof.* Let  $(Y, d)$  be a complete space, then

$$(x_k) \in Y \text{ Cauchy sequence} \implies \exists y \in Y : x_k \rightarrow y$$

Let  $z \in \text{ad}(A)$  and  $\eta_k$  a subsequence of  $x_k$ , then

$$\exists(\eta_k) \in Y : \eta_k \rightarrow z \implies \exists y \in Y : \eta_k \rightarrow y \therefore z = y \implies \text{ad}(Y) \subset Y$$

Going the opposite way we have that  $\text{ad}(Y) = Y$  and therefore  $Y = \overline{Y}$  □

**Definition 0.2.7** (Compact Space). A metric space  $(X, d)$  is said to be *compact* or *sequentially compact* if

$$\forall(x_k) \in X \ x_k \rightarrow x \in X, \exists(y_k) \text{ Subsequence} : y_k \rightarrow y \in X$$

**Theorem 0.3.** Let  $(X, d)$  be a compact space. Then  $(X, d)$  is also complete

*Proof.*  $(X, d)$  is compact, therefore

$$\forall(x_k) \in X \text{ Cauchy sequence} \implies x_k \rightarrow x \in X$$

Taken  $(x_{n_k})_k \in X$  a subsequence, we have

$$x_k \rightarrow x \implies x_{n_k} \rightarrow x \in X$$

□

**Definition 0.2.8** (Completely Bounded). Let  $(X, d)$  be a metric space.  $X$  is *totally bounded* iff

$$\exists Y \subset X : \forall \epsilon > 0, \forall x \in Y \ X = \bigcup_{i=1}^n B_\epsilon(x)$$

**Definition 0.2.9** (Polygonal Chain). Let  $z, w \in \mathbb{C}$ . We define a *polygonal*  $[z, w]$  as follows

$$[z, w] := \{z, w \in \mathbb{C} \mid z + t(w - z), t \in [0, 1] \subset \mathbb{R}\}$$

A *polygonal chain* will be indicated as follows  $P_{z,w}$  and it's defined as follows

$$P_{z,w} = \bigcup_{k=1}^{n-1} [z_k, z_{k+1}] = [z, z_1, \dots, z_{n-1}, w]$$

It can also be defined analogously for every metric space  $(X, d) \neq (\mathbb{C}, \|\cdot\|)$ , where  $\|\cdot\| : \mathbb{C} \rightarrow \mathbb{R}$  is the usual complex norm  $\|z\| = \sqrt{z\bar{z}} = \sqrt{\text{Re}(z)^2 + \text{Im}(z)^2}$

**Definition 0.2.10** (Connected Space). Let  $(G, d)$  be a metric space,  $G$  is *connected* if

$$\forall z, w \in G \ \exists P_{z,w} \subset G$$

**Definition 0.2.11** (Contraction Mapping). Let  $(X, d)$  be a complete metric space. Let  $T : X \longrightarrow X$ .  $T$  is said to be a *contraction mapping* or *contractor* if

$$\forall x, y \in X \ \exists q \in [0, 1) : d(T(x), T(y)) \leq qd(x, y) \quad (6)$$

Note that a contractor is necessarily continuous.

**Theorem 0.4** (Banach Fixed Point). *Let  $(X, d)$  be a complete metric space, with  $X \neq \{\}$  and equipped with a contractor  $T : X \rightarrow X$ . Then*

$$\exists! x^* \in X : T(x^*) = x^* \quad (7)$$

*Proof.* Take  $x_0 \in X$  and a sequence  $x_n : \mathbb{N} \rightarrow X$ , where

$$x_n = T(x_{n-1}), \quad \forall n \in \mathbb{N}$$

It's obvious that

$$d(x_{n+1}, x_n) = d(T(x_n), T(x_{n-1})) \leq qd(x_n, x_{n-1}) \leq q^n d(x_1, x_0)$$

We need to prove that  $x_n$  is a Cauchy sequence. Let  $m, n \in \mathbb{N} : m > n$ , then

$$d(x_m, x_n) \leq d(x_m, x_{m-1}) + \cdots + d(x_{n+1}, x_n) \leq q^{m-1}d(x_1, x_0) + \cdots + q^n d(x_1, x_0)$$

Regrouping, we have

$$d(x_m, x_n) \leq q^n d(x_1, x_0) \sum_{k=0}^{m-n-1} q^k \leq q^n d(x_1, x_0) \sum_{k=0}^{\infty} q^k = q^n d(x_1, x_0) \left( \frac{1}{1-q} \right)$$

By definition of convergence, we have then

$$\forall \epsilon > 0, \exists N \in \mathbb{N} : \forall n > N \quad d(x_n, x) < \epsilon$$

Then

$$\frac{q^n d(x_1, x_0)}{1-q} < \epsilon \implies q^n < \frac{\epsilon(1-q)}{d(x_1, x_0)}, \quad \forall n > N$$

Therefore, after taking  $m > n > N$ , we have

$$d(x_m, x_n) < \epsilon$$

Therefore  $x_n$  is a Cauchy sequence. Since  $(X, d)$  is a complete metric space, this sequence must have a limit  $x_n \rightarrow x^* \in X$ , but, by definition of convergence and limit, we have that by continuity

$$x^* = \lim_{n \rightarrow \infty} x_n = \lim_{n \rightarrow \infty} T(x_{n-1}) = T\left(\lim_{n \rightarrow \infty} x_{n-1}\right) = T(x^*)$$

This point is unique. Take  $y^* \in X$  such that  $T(y^*) = y^* \neq x^*$ , then

$$0 < d(T(x^*), T(y^*)) = d(x^*, y^*) > qd(x^*, y^*) \quad \nexists$$

Therefore

$$\exists! x^* \in X : T(x^*) = x^*$$

And  $x^*$  is the fixed point of the contractor  $T$

□

## § 0.3 Vector Spaces

**Definition 0.3.1** (Vector Space). A vector space  $\mathcal{V}$  over a field  $\mathbb{F}$  is a set, where  $\mathcal{V} \neq \{\}$  and it satisfies the following properties,  $\forall u, v, w \in \mathcal{V}$  and  $a, b \in \mathbb{F}$

1.  $u + v \in \mathcal{V}$  sum closure
2.  $av \in \mathcal{V}$  scalar closure
3.  $u + v = v + u$
4.  $(u + v) + w = u + (v + w)$
5.  $\exists! 0 \in \mathcal{V} : u + 0 = 0 + u = u$
6.  $\exists! v \in \mathcal{V} : u + v = 0 \implies v = -u$
7.  $\exists! 1 \in \mathbb{F} : 1 \cdot u = u$
8.  $(ab)u = a(bu) = b(au) = abu$
9.  $(a + b)u = au + bu$
10.  $a(u + v) = au + av$

**Definition 0.3.2** (Norm). Let  $\mathcal{V}$  be a vector space over a field  $\mathbb{F}$ , then the *norm* is an application defined as follows

$$\|\cdot\| : \mathcal{V} \longrightarrow \mathbb{F}$$

Where it satisfies the following properties

1.  $\|u\| \geq 0 \ \forall u \in \mathcal{V}$
2.  $\|u\| = 0 \iff u = 0$
3.  $\|cu\| = |c|\|u\| \ \forall u \in \mathcal{V} \ c \in \mathbb{F}$
4.  $\|u + v\| \leq \|u\| + \|v\| \ \forall u, v \in \mathcal{V}$

**Definition 0.3.3** (Normed Vector Space). A *normed vector space* is defined as a couple  $(\mathcal{V}, \|\cdot\|)$ , where  $\mathcal{V}$  is a vector space over a field  $\mathbb{F}$ .

**Proposition 8.** A normed vector space (NVS), is also a metric vector space (MVS) if we define our distance as follows

$$d(u, v) = \|u - v\| \ \forall u, v \in \mathcal{V}$$

**Definition 0.3.4** (Vector Subspace). Let  $\mathcal{V}$  be a vector space and  $\mathcal{U} \subset \mathcal{V}$ .  $\mathcal{U}$  is a *vector subspace* of  $\mathcal{V}$  iff

1.  $u, v \in \mathcal{U} \implies u + v \in \mathcal{U}$
2.  $u \in \mathcal{U}, a \in \mathbb{F} \implies au \in \mathcal{U}$



**Proposition 9.** If  $(\mathcal{V}, \|\cdot\|)$  is a normed vector space and  $\mathcal{W} \subset \mathcal{V}$  is a subspace of  $\mathcal{V}$ , then  $(\mathcal{W}, \|\cdot\|)$  is a normed vector space

**Definition 0.3.5** (p-norm). Let  $(\mathcal{V}, \|\cdot\|_p)$  be a normed vector space. The norm  $\|\cdot\|_p$  is said to be a *p-norm* if it's defined as follows

$$\|v\|_p := \left( \sum_{i=1}^{\dim(\mathcal{V})} (v_i)^p \right)^{\frac{1}{p}}, \quad \forall v \in \mathcal{V}, \quad \forall p \in \mathbb{N}^* := \mathbb{N} \cup \{\pm\infty\} \quad (8)$$

Setting  $p = \infty$  we have that

$$\|v\|_\infty = \max_{i \leq \dim(\mathcal{V})} |v_i| \quad (9)$$

**Definition 0.3.6** (Dual Space). Let  $\mathcal{V}$  be a vector space over the field  $\mathbb{F}$ , we define a *linear functional* as an application  $\varphi : \mathcal{V} \rightarrow \mathbb{F}$  such that  $\forall u, v \in \mathcal{V}$  and  $c \in \mathbb{F}$

$$\begin{aligned} \varphi(u + v) &= \varphi(u) + \varphi(v) \\ \varphi(\lambda u) &= \lambda \varphi(u) \end{aligned} \quad (10)$$

Defining the sum of two linear functionals as  $(\varphi_1 + \varphi_2)(v) = \varphi_1(v) + \varphi_2(v)$  we immediately see that the set of all linear functionals forms a vector space over  $\mathcal{V}$ , which will be called the *dual space*  $\mathcal{V}^*$ .

### §§ 0.3.1 Hölder and Minkowski Inequalities

Having defined p-norms, we can prove two inequalities that work with these norms, the *Minkowski inequality* and the *Hölder Inequality*

**Theorem 0.5** (Hölder Inequality). Let  $p, q \in \mathbb{N}^*$ , where

$$\frac{1}{p} + \frac{1}{q} = 1$$

Then

$$\forall x, y \in \mathbb{R}^n \quad \|x\|_p \|y\|_q \geq \sum_{k=1}^n |x_k y_k| \quad (11)$$

*Proof.* Taking  $p = 1$ , we have  $q = \infty$ , and the demonstration is obvious

$$\|x\|_1 \|y\|_\infty = \|x\|_1 \|y\|_\infty = \max_{k \leq n} |y_k| \sum_{k=1}^n |x_k| \geq \sum_{k=1}^n |x_k y_k|$$

Else, if  $p > 1$ , we have that

$$ab \leq \frac{a^p}{p} + \frac{b^q}{q} \quad \forall a, b \geq 0$$

Let

$$s = \frac{x}{\|x\|_p}, \quad t = \frac{y}{\|y\|_q}$$

We have

$$\sum_{k=1}^n \|s\|^p = \frac{1}{\|x\|_p^p} \sum_{k=1}^n |x_k|^p = 1 = \sum_{k=1}^n |t|^q = \frac{1}{\|y\|_q^q} \sum_{k=1}^n |y|^p$$

Therefore

$$\sum_{k=1}^n |s_k t_k| \leq \frac{1}{p} \sum_{k=1}^n |s_k|^p + \frac{1}{q} \sum_{k=1}^n |t_k|^q$$

Substituting again the definitions of  $s, t$  we have

$$\sum_{i=1}^n |y_k x_k| = \|x\|_p \|y\|_q \sum_{k=1}^n |s_k t_k| \leq \|x\|_p \|y\|_q$$

□

**Theorem 0.6** (Minkowski Inequality). *Let  $p \geq 1$ , therefore  $\forall x, y \in \mathbb{R}^n$  we have*

$$\|x + y\|_p \leq \|x\|_p + \|y\|_p \quad (12)$$

*Proof.* We begin by writing explicitly the p-norm

$$\|x + y\|_p^p = \sum_{k=1}^n (|x_k| + |y_k|)^p = \sum_{k=1}^n (|x_k| + |y_k|) (|x_k| + |y_k|)^{p-1}$$

Letting  $u_k = (|x_k| + |y_k|)^{p-1}$  we have, after imposing the condition on  $q$  of the p-norm as  $q(p+1) = p$  and using that the sum is Abelian, we have

$$\begin{cases} \sum_{k=1}^n |x_k| u_k \leq \|x\|_p \|u\|_q = \|x\|_p \left( \sum_{k=1}^n (|x_k| + |y_k|)^p \right)^{\frac{1}{q}} \\ \sum_{k=1}^n |y_k| u_k \leq \|y\|_p \|u\|_q = \|y\|_p \left( \sum_{k=1}^n (|x_k| + |y_k|)^p \right)^{\frac{1}{q}} \end{cases}$$

Therefore, summing and imposing that  $1 - q^{-1} = p$  we have that

$$\|x + y\|_p \leq \|x\|_p + \|y\|_q$$

□