

home/prensila_ros_ws
/src/mia_hand_ros_pkgs
/mia_hand_description/include
/mia_hand_description/mia_thumb
_opp_passivejoints.h

```
graph BT; A["home/prensila_ros_ws  
/src/mia_hand_ros_pkgs  
/mia_hand_description/src  
/mia_thumb_opp_passivejoints.cpp"] --> C["home/prensila_ros_ws  
/src/mia_hand_ros_pkgs  
/mia_hand_description/include  
/mia_hand_description/mia_thumb_opp_passivejoints.h"]; B["home/prensila_ros_ws  
/src/mia_hand_ros_pkgs  
/mia_hand_description/src  
/remap_mia_joint_states.cpp"] --> C;
```

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/src/mia_hand_ros_pkgs
/mia_hand_description/src
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home/prensila_ros_ws
/src/mia_hand_ros_pkgs
/mia_hand_description/src
/remap_mia_joint_states.cpp