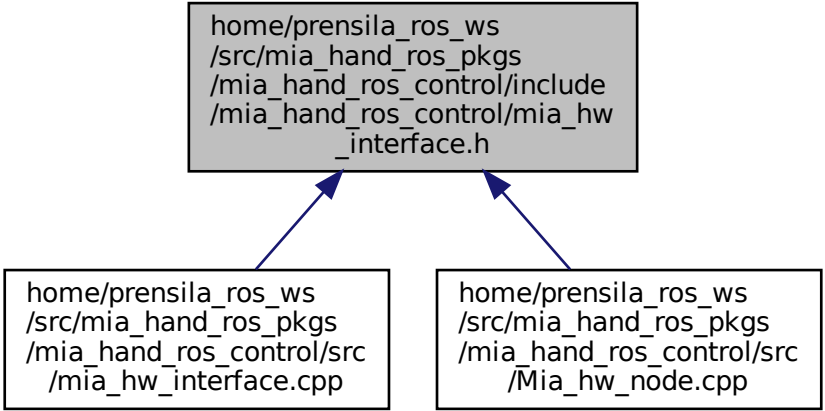


home/prensila\_ros\_ws  
/src/mia\_hand\_ros\_pkgs  
/mia\_hand\_ros\_control/include  
/mia\_hand\_ros\_control/mia\_hw  
\_interface.h



```
graph BT; A["home/prensila_ros_ws  
/src/mia_hand_ros_pkgs  
/mia_hand_ros_control/src  
/mia_hw_interface.cpp"] --> C["home/prensila_ros_ws  
/src/mia_hand_ros_pkgs  
/mia_hand_ros_control/include  
/mia_hand_ros_control/mia_hw  
_interface.h"]; B["home/prensila_ros_ws  
/src/mia_hand_ros_pkgs  
/mia_hand_ros_control/src  
/Mia_hw_node.cpp"] --> C;
```

home/prensila\_ros\_ws  
/src/mia\_hand\_ros\_pkgs  
/mia\_hand\_ros\_control/src  
/mia\_hw\_interface.cpp

home/prensila\_ros\_ws  
/src/mia\_hand\_ros\_pkgs  
/mia\_hand\_ros\_control/src  
/Mia\_hw\_node.cpp