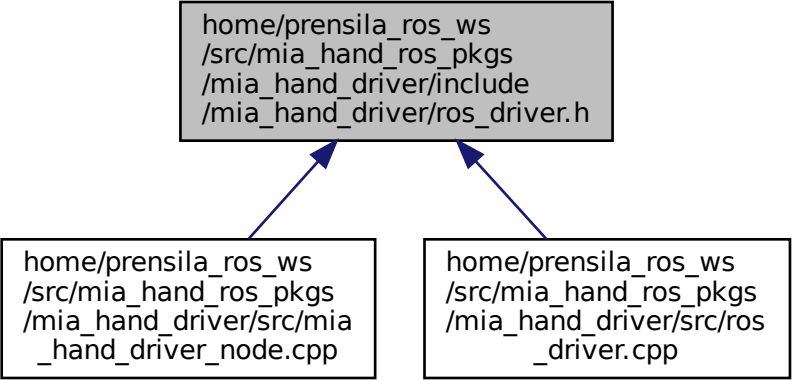


home/prensila\_ros\_ws  
/src/mia\_hand\_ros\_pkgs  
/mia\_hand\_driver/include  
/mia\_hand\_driver/ros\_driver.h



```
graph BT; A["home/prensila_ros_ws<br>/src/mia_hand_ros_pkgs<br>/mia_hand_driver/src/mia<br>_hand_driver_node.cpp"] --> C["home/prensila_ros_ws<br>/src/mia_hand_ros_pkgs<br>/mia_hand_driver/include<br>/mia_hand_driver/ros_driver.h"]; B["home/prensila_ros_ws<br>/src/mia_hand_ros_pkgs<br>/mia_hand_driver/src/ros<br>_driver.cpp"] --> C; style C fill:#ccc
```

home/prensila\_ros\_ws  
/src/mia\_hand\_ros\_pkgs  
/mia\_hand\_driver/src/mia  
\_hand\_driver\_node.cpp

home/prensila\_ros\_ws  
/src/mia\_hand\_ros\_pkgs  
/mia\_hand\_driver/src/ros  
\_driver.cpp