

Lab 6 Report: Dylan Money

I started connecting to the robot and trying out the teleoperated control. I looked through the different modes and noticed that mode 5 makes it sit, mode 6 makes it stand and mode 2 makes it walk. I downloaded the code and saw there was already code to make the robot walk forward for a short duration. I made other commands for the robot to move backwards, sideways, change modes and rotate. I had all these commands set to time intervals and executed.