

# Lab 5 Report: Dylan Money

I started by making a map of the environment. I launched Slam and moved the robot around to reveal the whole area. After which I downloaded the pgm and yaml files. Then I needed to work on the planning. I went into rviz and tried the 2D Nav Goal feature. After which it was time for me to write my own code to move the robot to the goal. I took the coordinates out of rviz and used those in my code to move the robot to it's goal.