# Lab 7 Report: Dylan Money

In this assignment we were focused on writing code to move the robot dog. The first objective was to move the robot in a circle controlling the mode, and velocity. I was able to do this and demo it to my TA. Then we need to demonstrate control over the robot's LEDs and Audio Playback features. Finally we needed to control the robot through ROS. I created a circle walk code that would run the robot using the ROS publishing feature.