

# Math 110 HW5

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09/30/2023

## Problem 1.

Let  $V := \mathbb{C}^3$ . Give an example of a map  $T \in \mathcal{L}(V, V)$  such that  $V = \text{null}T \oplus \text{range}T$ , with both  $\text{null}T$  and  $\text{range}T$  non-zero, or prove that none such exists.

*Solution.* Let  $T : (x, y, z) \mapsto (x, 0, 0)$  for  $x, y, z \in \mathbb{C}$ . Then the range of  $T$  is  $\{(x, 0, 0) : x \in \mathbb{C}\}$ , and the null space of  $T$  is  $\{(0, y, z) : y, z \in \mathbb{C}\}$ . It is obvious that  $\text{null}T + \text{range}T = V$  because every  $v \in V$  can be written as a sum of a vector in the null space and a vector in the range. Also,  $\text{null}T \cap \text{range}T = \{(0, 0, 0)\}$ . Therefore, it is also a direct sum.  $\square$

**Problem 2.**

Given an example of a map  $T \in \mathcal{L}(\mathbb{R}^6, \mathbb{R}^2)$  such that

$$\text{null}T = \{(x_1, x_2, x_3, x_4, x_5, x_6) : x_1 = -x_2, \ x_3 + x_5 = 0, \ x_1 - x_4 - x_5 = 0\}$$

or prove that none such exists.

*Solution.* We claim that such a map does not exist. Assume for the sake of contradiction that such a map  $T$  exists.

Let's rewrite the null space of  $T$  as

$$\text{null}T = \{(x_1, -x_1, -x_5, x_1 - x_5, x_5, x_6) : x_1, x_5, x_6 \in \mathbb{R}\}.$$

In other words,  $\text{null}T$  is the span of the vectors  $(1, -1, 0, 1, 0, 0)$ ,  $(0, 0, -1, -1, 1, 0)$ , and  $(0, 0, 0, 0, 0, 1)$ . We can check whether these three vectors are linearly independent to find the exact dimension of  $\text{null}T$  but it is unnecessary for this problem.

Since  $\text{null}T$  is defined by a span of three vectors, the maximum dimension of  $\text{null}T$  is 3. Then, by the rank-nullity theorem, the dimension of the range of  $T$  is at least  $6 - 3 = 3$ . However, the range of  $T$  is a subspace of  $\mathbb{R}^2$ , so the dimension of the range of  $T$  is at most 2. This is a contradiction. Therefore, such a map  $T$  does not exist.  $\square$

### Problem 3.

Suppose  $T : \mathcal{P}_3(\mathbb{R}) \rightarrow \mathcal{P}_2(\mathbb{R})$  is defined by the formula  $(Tf)(x) = 4xf''(x) - f'(x)$ . Check that  $T \in \mathcal{L}(\mathcal{P}_3(\mathbb{R}), \mathcal{P}_2(\mathbb{R}))$  and find a basis for the null space and a basis for the range of  $T$ .

*Solution.* To check whether  $T$  is a linear map, we need to check whether  $T$  follows additivity and homogeneity.

**Additivity:** Let  $f, g \in \mathcal{P}_3(\mathbb{R})$ . Then

$$\begin{aligned} T(f+g)(x) &= 4x(f+g)''(x) - (f+g)'(x) \\ &= 4x(f''+g'')(x) - (f'+g')(x) \\ &= 4xf''(x) + 4xg''(x) - f'(x) - g'(x) \\ &= T(f)(x) + T(g)(x). \end{aligned}$$

**Homogeneity:** Let  $f \in \mathcal{P}_3(\mathbb{R})$  and  $c \in \mathbb{R}$ . Then

$$\begin{aligned} T(cf)(x) &= 4x(cf)''(x) - (cf)'(x) \\ &= 4x(c(f''))'(x) - cf'(x) \\ &= 4cx(f'')'(x) - cf'(x) \\ &= c(4xf''(x) - f'(x)) \\ &= cT(f)(x). \end{aligned}$$

**Range:** Let  $v \in \mathcal{P}_3(\mathbb{R})$ , which can be written as  $ax^3 + bx^2 + cx + d$  for  $a, b, c, d \in \mathbb{R}$ . Then, after applying  $T$  to  $v$ , we get

$$\begin{aligned} T(v)(x) &= 4xv''(x) - v'(x) \\ &= 4x(6ax + 2b) - (3ax^2 + 2bx + c) \\ &= 24ax^2 + 8bx - 3ax^2 - 2bx - c \\ &= 21ax^2 + 6bx - c, \end{aligned}$$

which is a linear combination of  $x^2$ ,  $x$ , and  $1$ . Therefore, the range of  $T$  is  $\text{span}\{x^2, x, 1\}$ .

**Null Space:** Let  $v \in \mathcal{P}_3(\mathbb{R})$ ,  $ax^3 + bx^2 + cx + d$ , such that  $T(v)(x) = 0$ . From what we have derived for  $\text{range } T$ , it means for all  $x$

$$21ax^2 + 6bx - c = 0.$$

This is only possible when  $21a = 6b = c = 0$  because  $x^2, x, 1$  are linearly independent, in fact basis. Therefore, all vectors in the null space of  $T$  are of the form  $ax^3 + bx^2 + cx + d$  where  $a = b = c = 0$ . In other words, the null space of  $T$  is  $\text{span}\{1\}$ , or equivalently  $\mathbb{R}$ . Hence, the basis is  $\{1\}$ .  $\square$

**Problem 4.**

Let  $T : f(x) \mapsto (x-1)^2 f'''(x) - 3(x-1)f''(x) + f'(x)$ . Write down its matrix representation:

- (a) as a map in  $\mathcal{L}(\mathcal{P}_3, \mathcal{P}_2)$  using the standard monomial bases both for the domain and codomain;
- (b) as a map in  $\mathcal{L}(\mathcal{P}_3, \mathcal{P}_3)$  using the standard monomial basis both for the domain and codomain;
- (c) as a map in  $\mathcal{L}(\mathcal{P}_3, \mathcal{P}_3)$  using the shifted monomial basis  $1, x-1, (x-1)^2, (x-1)^3$  for the domain and for the codomain.

*Solution.*

(a)

$$\begin{aligned}
 T(x^3) &= (x-1)^2(6) - 3(x-1)(6x) + 3x^2 \\
 &= 6x^2 - 12x + 6 - 18x^2 + 18x + 3x^2 \\
 &= -9x^2 + 6x + 6 \\
 T(x^2) &= -3(x-1)(2) + 2x \\
 &= -6x + 6 + 2x \\
 &= -4x + 6 \\
 T(x) &= 1 \\
 T(1) &= 0.
 \end{aligned}$$

Hence, the matrix representation is

$$\begin{bmatrix} -9 & 0 & 0 & 0 \\ 6 & -4 & 0 & 0 \\ 6 & 6 & 1 & 0 \end{bmatrix}.$$

- (b) The matrix representation is simply prepending an empty row at the top of the matrix from (a):

$$\begin{bmatrix} 0 & 0 & 0 & 0 \\ -9 & 0 & 0 & 0 \\ 6 & -4 & 0 & 0 \\ 6 & 6 & 1 & 0 \end{bmatrix}.$$

(c)

$$\begin{aligned}
 T((x-1)^3) &= (x-1)^2(6) - 3(x-1)(6(x-1)) + 3(x-1)^2 \\
 &= 6(x-1)^2 - 18(x-1)^2 + 18(x-1)^2 \\
 &= 6(x-1)^2 \\
 T((x-1)^2) &= -3(x-1)(2) + 2(x-1) \\
 &= -6(x-1) + 2(x-1) \\
 &= -4(x-1) \\
 T((x-1)) &= 1 \\
 T(1) &= 0.
 \end{aligned}$$

Hence, the matrix representation is

$$\begin{bmatrix} 0 & 0 & 0 & 0 \\ 6 & 0 & 0 & 0 \\ 0 & -4 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}.$$

□

### Problem 5.

Suppose  $V$  and  $W$  are finite-dimensional vector spaces. Let  $v$  be a fixed vector in  $V$ , and consider

$$E_v := \{T \in \mathcal{L}(V, W) : Tv = 0\}.$$

(a) Show that  $E_v$  is a subspace of  $\mathcal{L}(V, W)$ .

(b) Suppose  $v \neq 0$ . What is  $\dim E_v$ ?

*Solution.*

(a) Firstly,  $E_v$  is obviously a subset of  $\mathcal{L}(V, W)$ .

**Additive identity:** The zero map from  $V$  to  $W$  is obviously in  $E_v$  because it maps every vector, including  $v$ , to 0. Hence, the additive identity, which is the zero map, is in  $E_v$ .

**Closed under addition:** Let  $T_1, T_2 \in E_v$ . Then

$$\begin{aligned} (T_1 + T_2)v &= T_1v + T_2v \\ &= 0 + 0 \\ &= 0. \end{aligned} \tag{1}$$

(1) is possible because  $T_1, T_2$  are in  $\mathcal{L}(V, W)$ . Therefore,  $T_1 + T_2 \in E_v$ .

**Closed under scalar multiplication:** Let  $T \in E_v$  and  $c \in \mathbb{R}$ . Then

$$\begin{aligned} (cT)v &= c(Tv) \\ &= c0 \\ &= 0. \end{aligned} \tag{2}$$

(2) is possible because  $T$  is in  $\mathcal{L}(V, W)$ . Therefore,  $cT \in E_v$ .

(b) We can construct a basis of  $V$  that includes  $v$ , denoted as  $(v, v_2, \dots, v_n)$ . Then consider arbitrary  $T \in \mathcal{L}(V, W)$  and  $z \in V$ ,

$$\begin{aligned} T(z) &= T(c_1v + c_2v_2 + \dots + c_nv_n) \\ &= c_1T(v) + c_2T(v_2) + \dots + c_nT(v_n) \\ &= c_2T(v_2) + \dots + c_nT(v_n) \\ &= T(c_2v_2 + \dots + c_nv_n). \end{aligned}$$

We can see that  $T$  is completely determined by its action on  $v_2, \dots, v_n$ . Therefore, we can define a map  $\Phi : E_v \rightarrow \mathcal{L}(V', W)$ ,  $V' = \text{span}\{v_2, \dots, v_n\}$  by restricting the domain of  $T$  to  $V'$ . This map is well-defined as we saw from the above derivation. We will show that  $\Phi$  is an isomorphism.

**Linearity of  $\Phi$ :**

(i) Let  $T_1, T_2 \in \mathcal{L}(V, W)$  and  $z \in V'$ . Then

$$\begin{aligned} \Phi(T_1 + T_2)(z) &= (T_1 + T_2)(z) \\ &= T_1(z) + T_2(z) \\ &= \Phi(T_1)(z) + \Phi(T_2)(z). \end{aligned}$$

(ii) Let  $T \in \mathcal{L}(V, W)$ ,  $c \in \mathbb{R}$ , and  $z \in V'$ . Then

$$\begin{aligned}\Phi(cT)(z) &= (cT)(z) \\ &= cT(z) \\ &= c\Phi(T)(z).\end{aligned}$$

**Injectivity of  $\Phi$ :** Let  $\Phi(T) = T' \in \mathcal{L}(V', W)$  be the zero map. Then  $T'$  maps every vector of  $V'$ , including the basis to 0. Then,  $T$  must map every  $v_i$  for  $i \in [2, n]$ , also the fixed  $v$  obviously, to 0 because  $T$  have the same actions as  $T'$  on  $V'$ . Hence,  $T$  maps every basis in  $V$  to zero, consequently every vectors in  $V$  to zero. Therefore,  $T$  is the zero map and  $\Phi$  is injective.

**Surjectivity of  $\Phi$ :** We know  $\Phi$  has to be surjective because of how we defined  $\Phi$ . Every  $T' \in \mathcal{L}(V', W)$  has a corresponding  $T \in \mathcal{L}(V, W)$  that perform the same action on  $V'$  as  $T'$  does. Therefore,  $\Phi$  is surjective.

**$\Phi$  is isomorphism:** We have shown that  $\Phi$  is linear, injective, and surjective. Therefore,  $\Phi$  is an isomorphism between  $E_v$  and  $\mathcal{L}(V', W)$ . Therefore,  $\dim E_v = \dim \mathcal{L}(V', W) = \dim W \times \dim V' = \dim W \times (\dim V - 1)$

□