

COGS 182 Project 2 | Schedule Optimization

```
In [26]: import numpy as np
import matplotlib.pyplot as plt
import sys
from mpl_toolkits import mplot3d
import seaborn as sns
from tqdm.auto import tqdm
```

List of Possible Topics & Actions (Hour Allocations to Each Topic) & Resultant States

```
In [27]: possible_topics=[ 'topology',
                           'Japanese',
                           'webtooning',
                           'physics',
                           'video-editing',
                           'graphic design',
                           'animation',
                           'psych/linguistics',
                           'R/statistical packages',
                           'front-end coding']

#0-12 = allot hrs, 7 = commit to schedule
possible_actions = [0,1,3,5,7]
```

```
In [28]: r_times = []
for remaining_time in np.arange(25):
    for action in [0,1,3,5]:
        for org_hrs in [0,1,2,3,4]:
            for lab_hrs in [0, 1,2]:
                r_time = remaining_time - action - org_hrs - lab_hrs
                r_times.append(r_time)

possible_remaining_times = sorted(np.unique(r_times))

terminal_states = []
for r_time in possible_remaining_times:
    terminal_state = [r_time, 0]
    terminal_states.append(terminal_state)

possible_states = [0]
for r_time in possible_remaining_times:
    for len_schedule in np.arange(len(possible_topics) +1):
        for topic in possible_topics:
            state = [r_time, len_schedule, topic]
            if state[0] > 0:
                possible_states.append(state)

len(terminal_states),len(possible_states)
```

Out[28]: (36, 2641)

```
In [29]: pos_states = [0]
for state_indx, state in enumerate(possible_states[1:]):
    r_time, len_schd, topic = state
    no_topic_state = [r_time, len_schd]
    if no_topic_state not in pos_states:
        pos_states.append(no_topic_state)
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In [ ]:
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In [ ]:
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Factors (i.e. schedule fulfillment, coherence) to take into account when calculating the rewards

```
In [30]: #mutually reinforcing subjects (not really accurate to real life, but it suffices)
related_topics = {'topology': ['physics', 'R/statistical packages', 'graphic design'],
                  'Japanese': ['linguistics', 'animation', 'webtooning'],
                  'webtooning': ['animation', 'Japanese', 'graphic design'],
                  'physics': ['topology', 'chemistry', 'R/statistical packages'],
                  'video-editing': ['animation', 'content creation', 'webtooning'],
                  'graphic design': ['webtooning', 'front-end coding'],
                  'animation': ['webtooning', 'video-editing', 'graphic design', 'content creation'],
                  'psych/linguistics': ['Japanese', 'R/statistical packages'],
                  'R/statistical packages': ['educational psychology', 'physics'],
                  'front-end coding': ['graphic design', 'animation', 'content creation']}

# personal ratings of [frustration/learning curve, intrigue, applicability] by topic
fulfillment_factors = {'topology': [1, 1, 0.6],
                       'Japanese': [0.7, 1, 1],
                       'webtooning': [0.5, 0.5, 0.4],
                       'physics': [1, 0.9, .6],
                       'video-editing': [0.8, 0.4, 1],
                       'graphic design': [0.5, 0.3, 0.6],
                       'animation': [1, 0.9, 0.7],
                       'psych/linguistics': [0.6, 0.7, 0.7],
                       'R/statistical packages': [0.5, 0.4, 1],
                       'front-end coding': [0.6, 0.7, 1]}

fulfillment_scores = {}
for topic in fulfillment_factors:
    frustration, intrigue, applicability = fulfillment_factors[topic]

    #fulfillment factors scale positive rewards
    fulfillment_score = (-0.25*frustration + 0.5*intrigue + 0.25*applicability)
    fulfillment_scores[topic] = fulfillment_score
```

Step function, take in remaining time (in a day), the schedule, the topic of consideration, and the action

- NOTE: for feasibility sake, the observed state is actually only the LENGTH of the current schedule, but the entire schedule is passed for the environment to do calculations

```
In [31]: # state keeps track of remaining free time in a day, the length of the schedule, and the current topic
        # Length of schedule instead of actual schedule, since that's too many different states...

def step(remaining_time, schedule, topic, action):

    state = [remaining_time, len(schedule)]
    state_indx = pos_states.index(state)

    if action != 7:
        if action != 0:
            remaining_time -= action
            schedule[topic] = action #then allot hours according to a policy?

        topic = np.random.choice(possible_topics)
        new_state = [remaining_time, len(schedule)]
        reward = 0

        if remaining_time < 6:
            # print("\033[1;31m KAROSHI \033[0m YOU DIED OF OVERWORK")
            # sys.stdout.flush()
            reward = -1
            new_state = 0

        return new_state, reward, schedule, topic

# ENVIRONMENT GOES when commit to schedule
elif action == 7:
    new_state, reward, schedule, remaining_time = env(remaining_time, schedule)

    return new_state, reward, schedule, remaining_time
```

When the environment goes,

it takes the remaining time and schedule, adds on random hours from existing commitments, calculates if the remaining time in a day allows for sleep, calculates the schedule fulfillment and modulates the fulfillment with bonuses for schedule coherence and having enough to sleep. The terminal state is returned [remaining_time, 0].

```
In [32]: def env(remaining_time, schedule):

    existing_commitments = {'Orgs': np.random.choice(np.arange(1,5)), 'LabStuff': np.random.choice(np.arange(1,3))}
    # factor in existing commitments
    remaining_time -= (existing_commitments['Orgs'] + existing_commitments['LabStuff'])

    # KAROSHI AGAIN if forget about current commitments
    if remaining_time < 6:
        reward = -1

    #penalty for undercommitment (Listlessness)
    elif remaining_time > 18:
        reward = -0.5

    else:
        total_fulfillment = 0

        # get average of fulfillments of all commitments in schedule
        for topic in schedule:
            if topic in ["Orgs", "LabStuff"]:
                continue
            else:
                total_fulfillment += fulfillment_scores[topic]
        total_fulfillment = np.mean(total_fulfillment)

        # factor in related subjects into fulfillment score (mutually reinforcing)
        # if too many subjects at once, coherence turns into distraction factor, negative rate
        coherence = 1
        if len(schedule) >= 3:
            for topic in schedule:
                for possible_topic in possible_topics:
                    if topic == possible_topic:
                        for related_topic in related_topics[topic]:
                            if related_topic in schedule:
                                coherence += 0.05
        elif len(schedule) > 5: #too many topics
            coherence = -0.5

        # sleep and free time bonus (a rate)
        if remaining_time >= 8 and remaining_time <= 10:
            bonus = 1.1 # 10% bonus fulfillment
        else:
            bonus = 1 # no bonus

        # reward to return as a function of bonus, topic-based fulfillment and coherence of schedule
        reward = (total_fulfillment)* ((bonus + coherence)/ 2)

        schedule['Orgs'] = existing_commitments['Orgs']
        schedule['LabStuff'] = existing_commitments['LabStuff']

        new_state = 0

    return new_state, reward, schedule, remaining_time
```

In []:

Check that environment dynamics $p(s', r|s, a)$ work

Test environment dynamics using select inputs

Input 1: step(remaining_time=1, schedule={'topology':2}, topic = "Japanese", action= 3)

- Certain karoshi, because action > remaining_time
- If action is not 7 ('commit'), the returned schedule should NOT contain "Orgs" or "LabStuff," since these are added when the environment goes.

```
In [33]: # certain karoshi - allotting more hours to a topic than you have time in a day
print("Certain Karoshi (action > remaining_time or remaining_time + 6):")

new_state1, reward1, schedule1, topic1 = step(remaining_time=1,
                                             schedule={'topology':2},
                                             topic = "Japanese",
                                             action= 3)

print(new_state1, reward1, schedule1, topic1)
```

```
Certain Karoshi (action > remaining_time or remaining_time + 6):
0 -1 {'topology': 2, 'Japanese': 3} topology
```

Input 2: step(remaining_time=10, schedule={}, topic = "Japanese", action= 7)

- When the action is 7, the env goes, returning a schedule with "Orgs" and "LabStuff" and the terminal state, (remaining_time, 0])
- Uncertain Karoshi: Since the input schedule is empty but the hours allocated to "Orgs" and "LabStuff" range between 0 and 8 hours total, should see karoshi some of the time, i.e. if (Orgs + LabStuff - remaining_time) does not leave enough time for sleep (6 hours).

In []:

```
In [34]: print("\nUncertain Karoshi:")
# uncertain karoshi > if action is 7, then the environment should return the terminal state and remaining_time
# should decrease, due to Orgs and Labstuff hours
is_karoshi = 0
for call in np.arange(10):
    new_state2, reward2, schedule2, remaining_time2 = step(remaining_time=9,
                                                           schedule={},
                                                           topic = "Japanese",
                                                           action= 7)

    call = [remaining_time2, reward2, schedule2]
    if reward2 == -1:
        is_karoshi += 1
    print(call)
print("Observed Karoshi Rate:", (is_karoshi / 10) *100, "%")
```

```
Uncertain Karoshi:
[6, 0.0, {'Orgs': 2, 'LabStuff': 1}]
[3, -1, {'Orgs': 4, 'LabStuff': 2}]
[6, 0.0, {'Orgs': 2, 'LabStuff': 1}]
[6, 0.0, {'Orgs': 1, 'LabStuff': 2}]
[4, -1, {'Orgs': 4, 'LabStuff': 1}]
[4, -1, {'Orgs': 3, 'LabStuff': 2}]
[4, -1, {'Orgs': 3, 'LabStuff': 2}]
[5, -1, {'Orgs': 2, 'LabStuff': 2}]
[3, -1, {'Orgs': 4, 'LabStuff': 2}]
[3, -1, {'Orgs': 4, 'LabStuff': 2}]
Observed Karoshi Rate: 70.0 %
```

```
In [35]: is_karoshi = 0
for call in np.arange(10000):
    new_state2, reward2, schedule2, remaining_time2 = step(remaining_time=9,
                                                           schedule={},
                                                           topic = "Japanese",
                                                           action= 7)

    call = [remaining_time2, reward2, schedule2]
    if reward2 == -1:
        is_karoshi += 1
#     print(call)
print("Observed Karoshi Rate:", (is_karoshi / 10000) *100, "%")
```

```
Observed Karoshi Rate: 62.480000000000004 %
```

Input 3: step(remaining_time=24, schedule={'animation': 3, 'Japanese': 3}, topic = "Japanese", action= 7)

- & Input 4: step(remaining_time=24, schedule={'animation': 3, 'physics': 3}, topic = "Japanese", action= 7)
 - Rewards of coherent schedules (Input3) should be higher than noncoherent schedules (Input4)
 - UNLESS accounting for coheren schedules that UNDERCOMMIT

In []:

```
In [36]: # rewards of coherent schedule should be higher than reward of noncoherent schedule
# unless it's org hours allow for more productivity
coherent_more = 0
for call in np.arange(10000):
    new_state3, reward3, schedule3, remaining_time3 = step(remaining_time=24,
                                                            schedule={'animation': 3, 'Japanese': 3},
                                                            topic = "Japanese",
                                                            action= 7)

    call3 = [remaining_time3, reward3, schedule3]

    new_state4, reward4, schedule4, remaining_time4 = step(remaining_time=24,
                                                            schedule={'animation': 3, 'physics': 3},
                                                            topic = "Japanese",
                                                            action= 7)

    call4 = [remaining_time4, reward4, schedule4]
    if reward3 >= reward4:
        coherent_more += 1

print("Coherent Reward >= Noncoherent Reward is True", coherent_more / len(np.arange(10000)) *100, "% of the time, because of undercommitment penalties.")
```

Coherent Reward >= Noncoherent Reward is True 88.75999999999999 % of the time, because of undercommitment penalties.

Input 5: step(remaining_time=24, schedule={'animation': 3, 'physics': 3}, topic = "animation", action= 1)

- Resampling the same topic should NOT change the length of the schedule but should override the hour allocation

```
In [37]: new_state5, reward5, schedule5, topic5 = step(remaining_time=24,
                                                        schedule={'animation': 3, 'physics': 3},
                                                        topic = "animation",
                                                        action= 1)

print("Resampling a topic overwrites hour allocation/action:\n", new_state5, reward5, schedule5, topic5)
```

Resampling a topic overwrites hour allocation/action:
[23, 2] 0 {'animation': 1, 'physics': 3} physics

Test with random actions and topics

```
In [42]: rewards = []
next_states = []
actions = []
schedule_lens = []
remaining_times = []

for episode in np.arange(10):
    print("-----")
    print("\033[1;43m  EPISODE {} \033[0m".format(episode))
    # print("-----")
    remaining_time = 24
    schedule = {}
    topic = np.random.choice(possible_topics)
    action = np.random.choice([0,1,3,5])

    ep_actions = []
    ep_sch_lens = []
    while True:
        if action != 7:
            next_state, reward, schedule, topic = step(remaining_time, schedule, topic, action)
            next_states.append(next_state)
        elif action == 7:
            next_state, reward, schedule, remaining_time = step(remaining_time, schedule, topic, action)
            next_states.append(next_state)

        if next_state == 0:

            actions.append(ep_actions)
            schedule_lens.append(len_schedule)
            remaining_times.append(remaining_time)
            break

        remaining_time, len_schedule = next_state

        action = np.random.choice(possible_actions)
        ep_actions.append(action)
        print('New STATE:', next_state)
        print("New ACTION:", action)
    print("Schedule:", schedule)
    print('Remaining Time:', remaining_time, "hrs")
    print("Reward:", reward)
    rewards.append(reward)
    sys.stdout.flush()
```

EPISODE 0

New STATE: [24, 0]
New ACTION: 0
New STATE: [24, 0]
New ACTION: 7
Schedule: {'Orgs': 2, 'LabStuff': 1}
Remaining Time: 21 hrs
Reward: -0.5

EPISODE 1

New STATE: [23, 1]
New ACTION: 7
Schedule: {'front-end coding': 1, 'Orgs': 4, 'LabStuff': 2}
Remaining Time: 17 hrs
Reward: 0.44999999999999996

EPISODE 2

New STATE: [23, 1]
New ACTION: 3
New STATE: [20, 2]
New ACTION: 3
New STATE: [17, 3]
New ACTION: 7
Schedule: {'psych/linguistics': 1, 'graphic design': 3, 'animation': 3, 'Orgs': 4, 'LabStuff': 1}
Remaining Time: 12 hrs
Reward: 0.948125

EPISODE 3

New STATE: [19, 1]
New ACTION: 1
New STATE: [18, 2]
New ACTION: 7
Schedule: {'psych/linguistics': 5, 'animation': 1, 'Orgs': 4, 'LabStuff': 1}
Remaining Time: 13 hrs
Reward: 0.75

EPISODE 4

New STATE: [21, 1]
New ACTION: 7
Schedule: {'graphic design': 3, 'Orgs': 1, 'LabStuff': 1}
Remaining Time: 19 hrs
Reward: -0.5

EPISODE 5

New STATE: [23, 1]
New ACTION: 7
Schedule: {'physics': 1, 'Orgs': 1, 'LabStuff': 2}
Remaining Time: 20 hrs
Reward: -0.5

EPISODE 6

New STATE: [19, 1]
New ACTION: 0
New STATE: [19, 1]
New ACTION: 1
New STATE: [18, 2]
New ACTION: 3
New STATE: [15, 3]
New ACTION: 7
Schedule: {'graphic design': 5, 'animation': 1, 'R/statistical packages': 3, 'Orgs': 3, 'LabStuff': 2}
Remaining Time: 10 hrs
Reward: 0.9406250000000002

EPISODE 7

New STATE: [23, 1]
New ACTION: 0
New STATE: [23, 1]
New ACTION: 7
Schedule: {'R/statistical packages': 1, 'Orgs': 3, 'LabStuff': 2}
Remaining Time: 18 hrs
Reward: 0.325

EPISODE 8

New STATE: [24, 0]
New ACTION: 3
New STATE: [21, 1]
New ACTION: 5
New STATE: [16, 2]
New ACTION: 3
New STATE: [13, 2]
New ACTION: 5
New STATE: [8, 3]
New ACTION: 0
New STATE: [8, 3]
New ACTION: 0
New STATE: [8, 3]
New ACTION: 7

```
Schedule: {'Japanese': 3, 'physics': 3, 'topology': 5, 'Orgs': 2, 'LabStuff': 1}
Remaining Time: 5 hrs
Reward: -1
-----
EPISODE 9
New STATE: [19, 1]
New ACTION: 7
Schedule: {'video-editing': 5, 'Orgs': 2, 'LabStuff': 2}
Remaining Time: 15 hrs
Reward: 0.25
```

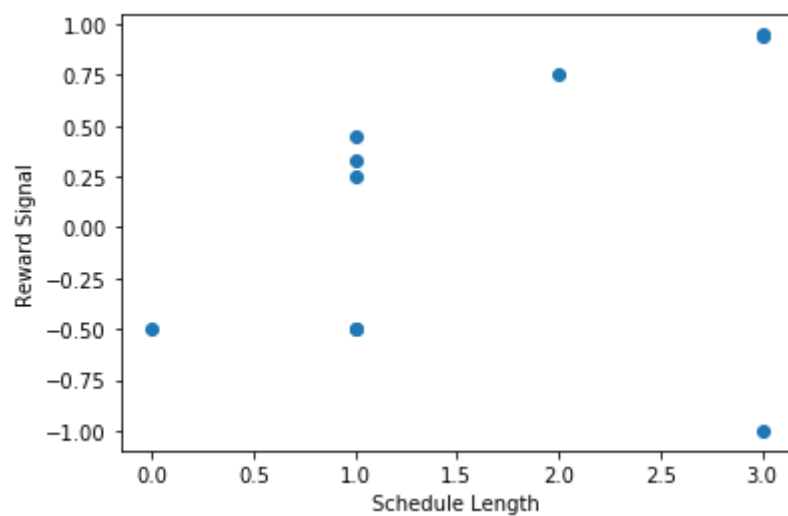
```
In [43]: print("rewards:", rewards)
print("actions:", actions)
print("schedule lengths:", schedule_lens)
```

```
rewards: [-0.5, 0.44999999999999996, 0.948125, 0.75, -0.5, -0.5, 0.9406250000000002, 0.325, -1, 0.25]
actions: [[0, 7], [7], [3, 3, 7], [1, 7], [7], [7], [0, 1, 3, 7], [0, 7], [3, 5, 3, 5, 0, 0, 7], [7]]
schedule lengths: [0, 1, 3, 2, 1, 1, 3, 1, 3, 1]
```

Plot Schedule Length vs. Reward

- the longer the schedule, the more likely karoshi happens, so reward should go down as length of schedule increases
- length of schedule doesn't necessarily mean lots of hours are allocated per reward, so karoshi might not happen, BUT longer schedules increase chances of incoherence, so reward also diminished

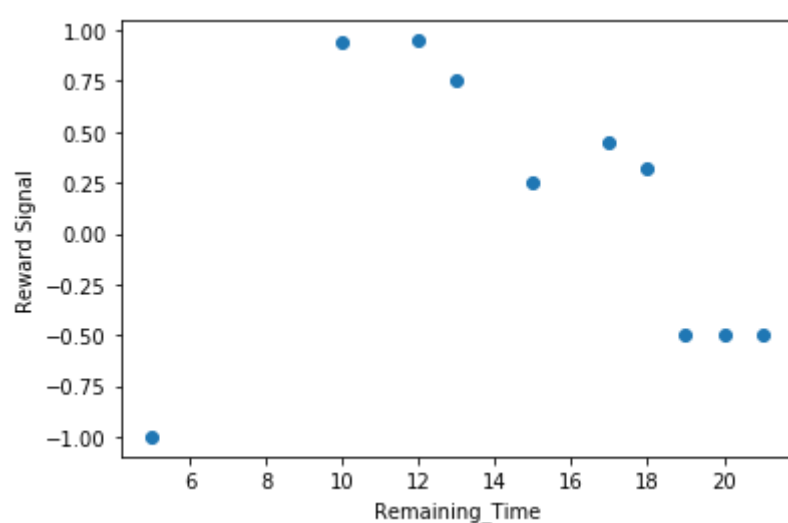
```
In [44]: plt.plot(schedule_lens, rewards, "o")
plt.xlabel("Schedule Length")
plt.ylabel("Reward Signal")
plt.show()
```



Plot Remaining Times vs. Reward

- When remaining time is under 6-8, the reward should rapidly decrease, since karoshi happens due to lack of sleep/ bonuses are not rewarded for being sleep-deprived.
- When remaining time is 24, meaning the schedule is empty, undercommitment is not penalized but also not rewarded, leaving the agent with a reward of 0.
- The sweet spot is to have around 8-15 hours of remaining time, which accounts for sleep and free time. Having more free time than that makes the agent unlikely to be able to accrue schedule-fulfillment points.
-

```
In [45]: plt.plot(remaining_times, rewards, "o")
plt.xlabel("Remaining Time")
plt.ylabel("Reward Signal")
plt.show()
```



In []: