

# Project Name: End-To-End ML with Deployment AIBasketball Prediction – Faster RCNN – Classification

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```

11
12 app = Flask(__name__)
13 UPLOAD_FOLDER = './static/uploads'
14 app.config['UPLOAD_FOLDER'] = UPLOAD_FOLDER
15 #useless key, in order to use session
16 app.secret_key = "super secret key"
17
18 @app.route("/")
19 def index():
20     return render_template("index.html")
21
22 @app.route('/detection_json', methods=['GET', 'POST'])
23 def detection_json():
24     if request.method == 'POST':
25         response = []
26         f = request.files['image']
27         # create a secure filename
28         filename = secure_filename(f.filename)
29         print("filename", filename)
30         # save file to /static/uploads
31         filepath = os.path.join(app.config['UPLOAD_FOLDER'], filename)
32         print("filepath", filepath)
33         f.save(filepath)
34         detectionAPI(response, filepath)
35         print(response)
36         try:
37             return jsonify(response), 200
38         except FileNotFoundError:
39             abort(404)
40
41
42 @app.route('/sample_detection', methods=['GET', 'POST'])
43 def upload_sample_image():
44     if request.method == 'POST':
45         response = []
46         filename = "sample_image.jpg"
47         print("filename", filename)
48         filepath = "./static/uploads/sample_image.jpg"
49         print("filepath", filepath)
50         get_image(filepath, filename, response)
51         return render_template("shot_detection.html", display_detection=filename, fname=filename, response=response)
52
53 @app.route('/basketball_detection', methods=['GET', 'POST'])
54 def upload_image():
55     if request.method == 'POST':
56         response = []
57         f = request.files['image']
58         # create a secure filename
59         filename = secure_filename(f.filename)
60         print("filename", filename)
61         # save file to /static/uploads
62         filepath = os.path.join(app.config['UPLOAD_FOLDER'], filename)
63         print("filepath", filepath)
64         f.save(filepath)
65         get_image(filepath, filename, response)
66         return render_template("shot_detection.html", display_detection=filename, fname=filename, response=response)
67
68 @app.route('/sample_analysis', methods=['GET', 'POST'])
69 def upload_video():
70     global shooting_result
71     shooting_result['attempts'] = 0
72     shooting_result['made'] = 0
73     shooting_result['miss'] = 0
74     if (os.path.exists("./static/detections/trajectory_fitting.jpg")):
75         os.remove("./static/detections/trajectory_fitting.jpg")
76     if request.method == 'POST':
77         filename = "sample_video.mp4"
78         print("filename", filename)
79         filepath = "./static/uploads/sample_video.mp4"
80         print("filepath", filepath)
81         session['video_path'] = filepath
82         return render_template("shooting_analysis.html")
83

```

```

84 @app.route('/shooting_analysis', methods=['GET', 'POST'])
85 def upload_sample_video():
86     global shooting_result
87     shooting_result['attempts'] = 0
88     shooting_result['made'] = 0
89     shooting_result['miss'] = 0
90     if (os.path.exists("./static/detections/trajectory_fitting.jpg")):
91         os.remove("./static/detections/trajectory_fitting.jpg")
92     if request.method == 'POST':
93         f = request.files['video']
94         # create a secure filename
95         filename = secure_filename(f.filename)
96         print("filename", filename)
97         # save file to /static/uploads
98         filepath = os.path.join(app.config['UPLOAD_FOLDER'], filename)
99         print("filepath", filepath)
100        f.save(filepath)
101        session['video_path'] = filepath
102        return render_template("shooting_analysis.html")
103
104 @app.route('/video_feed')
105 def video_feed():
106     video_path = session.get('video_path', None)
107     stream = getVideoStream(video_path)
108     return Response(stream,
109                     mimetype='multipart/x-mixed-replace; boundary=frame')
110
111 @app.route("/result", methods=['GET', 'POST'])
112 def result():
113     return render_template("result.html", shooting_result=shooting_result)
114
115 #disable caching
116 @app.after_request
117 def after_request(response):
118     response.headers["Cache-Control"] = "no-cache, no-store, must-revalidate, public, max-age=0"
119     response.headers["Expires"] = 0
120     response.headers["Pragma"] = "no-cache"
121     return response
122
123 if __name__ == '__main__':
124     app.run(debug=True, use_reloader=True)

```

## Live Web App Demo Link

Deployment on Heroku: <https://dlaib.herokuapp.com/>

## Abstract

The purpose of this report will be to use the pre-trained models to analyse basketball shots and shooting pose depending on details provided by user. This can be used to gain insight into how and why shot is such at a given time. This can also be used as a model to gain a marketing advantage, by advertisement targeting those who have interest in sports or e-gaming industry. Shot Prediction is a classification problem, where using the various parameters or inputs from user model will supply result. This is an artificial intelligence application built on the concept of object detection. Analyze basketball shots by digging into the data collected from object detection.

This is diving into Analyses of Shot Detection through Machine Learning Concept.

End to End Project means that it is step by step process, starts with data collection, EDA, Data Preparation which includes cleaning and transforming then selecting, data resizing, data rescaling training and saving DL Models, Cross-validation and Hyper-Parameter Tuning and developing web service then Deployment for end users to use it anytime and anywhere.

This repository contains the code for Shot Detection using python's various libraries.

It used numpy, matplotlib, tensorflow, opencv, os, sys, time and flask libraries.

These libraries help to perform individually one particular functionality.

Numpy is used for working with arrays. It stands for Numerical Python.

Matplotlib is a plotting library.

TensorFlow is an open-source software library for high performance numerical computation.

Flask is classified as a microframework because it does not require particular tools or libraries.

This is an artificial intelligence application built on the concept of object detection. Analyze basketball shots by digging into the data collected from object detection. We can get the result by simply uploading files to the web App, or submitting a POST request to the API.

The purpose of creating this repository is to gain insights into Complete DL Project.

These python libraries raised knowledge in discovering these libraries with practical use of it.

It leads to growth in my DL repository.

These above screenshots and video in Video\_File Folder will help you to understand flow of output.

## Motivation

The reason behind building this project is, because I like to play sports in my free time as we all know it has many benefits along with that it refreshes our mind. At the same time this deep learning concepts are more interesting to apply. So, I created AIBasketball Detection Project to gain insights from IT perspective to know working of the model. Hence, I continue to spread tech wings in IT Heaven.

## The Data

All the data for the shooting pose analysis is calculated by implementing OpenPose. Please note that this is an implementation only for non-commercial research use only.

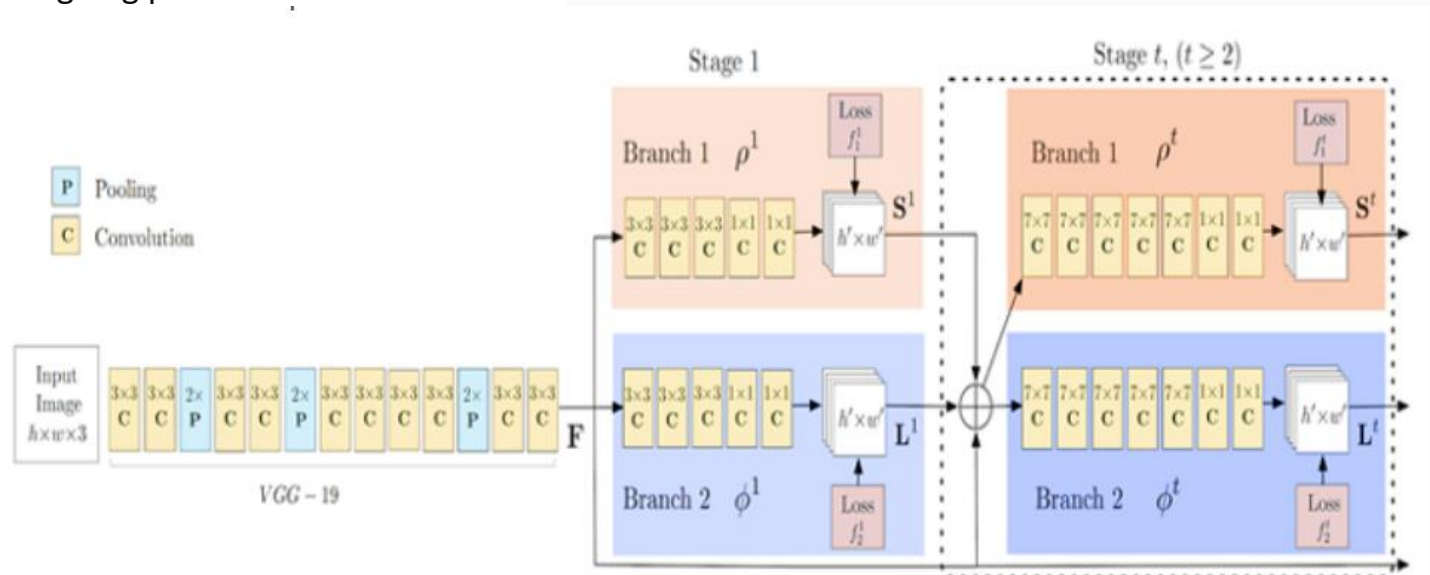
## Modelling

- Math behind the metrics

OpenPose:

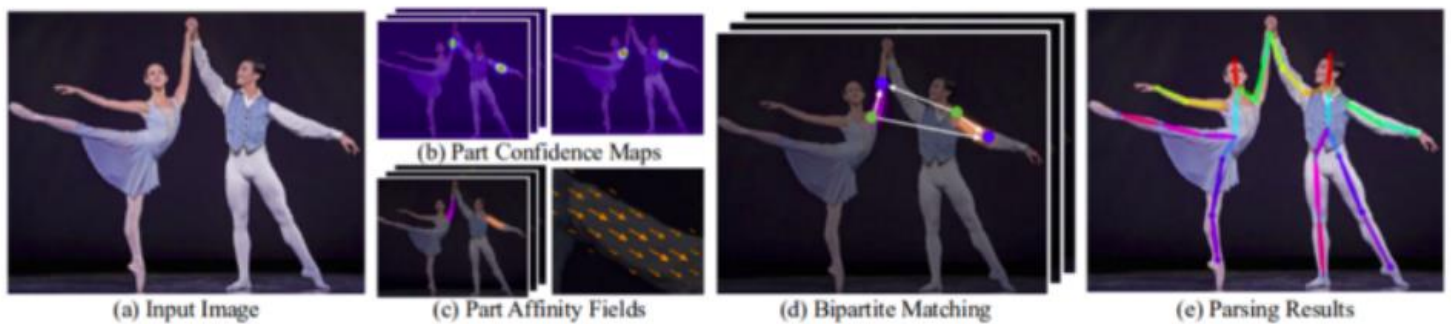
A Human Pose Skeleton represents the orientation of a person in a graphical format. Essentially, it is a set of coordinates that can be connected to describe the pose of the person. Each coordinate in the skeleton is known as a part (or a joint, or a keypoint). A valid connection between two parts is known as a pair (or a limb). Note that, not all part combinations give rise to valid pairs.

OpenPose first detects parts (key points) belonging to every person in the image, followed by assigning parts to distinct individuals.



Flowchart of the OpenPose architecture. (Source)

The OpenPose network first extracts features from an image using the first few layers (VGG-19 in the above flowchart). The features are then fed into two parallel branches of convolutional layers. The first branch predicts a set of 18 confidence maps, with each map representing a particular part of the human pose skeleton. The second branch predicts a set of 38 Part Affinity Fields (PAFs) which represents the degree of association between parts.

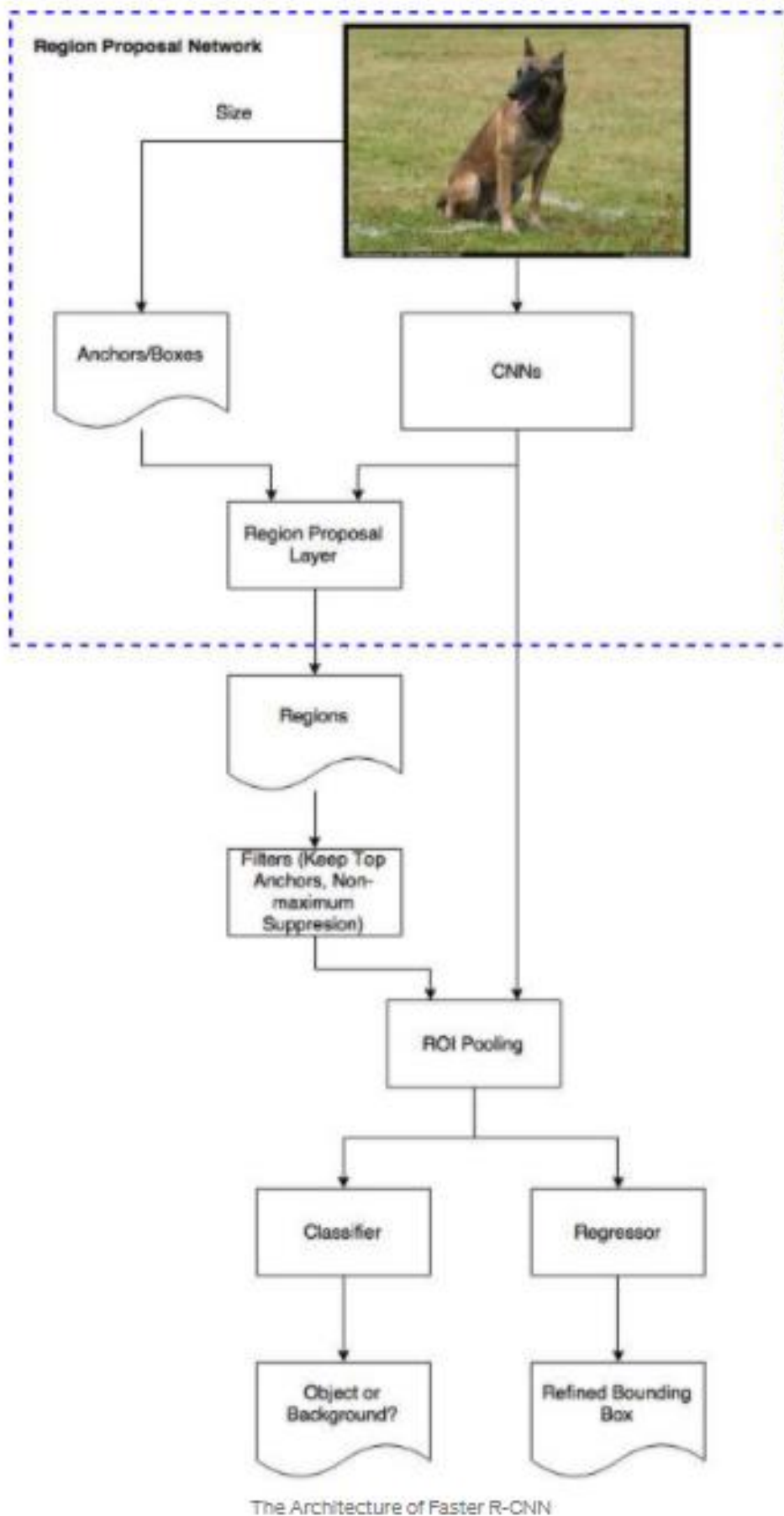


Steps involved in human pose estimation using OpenPose. ([Source](#))

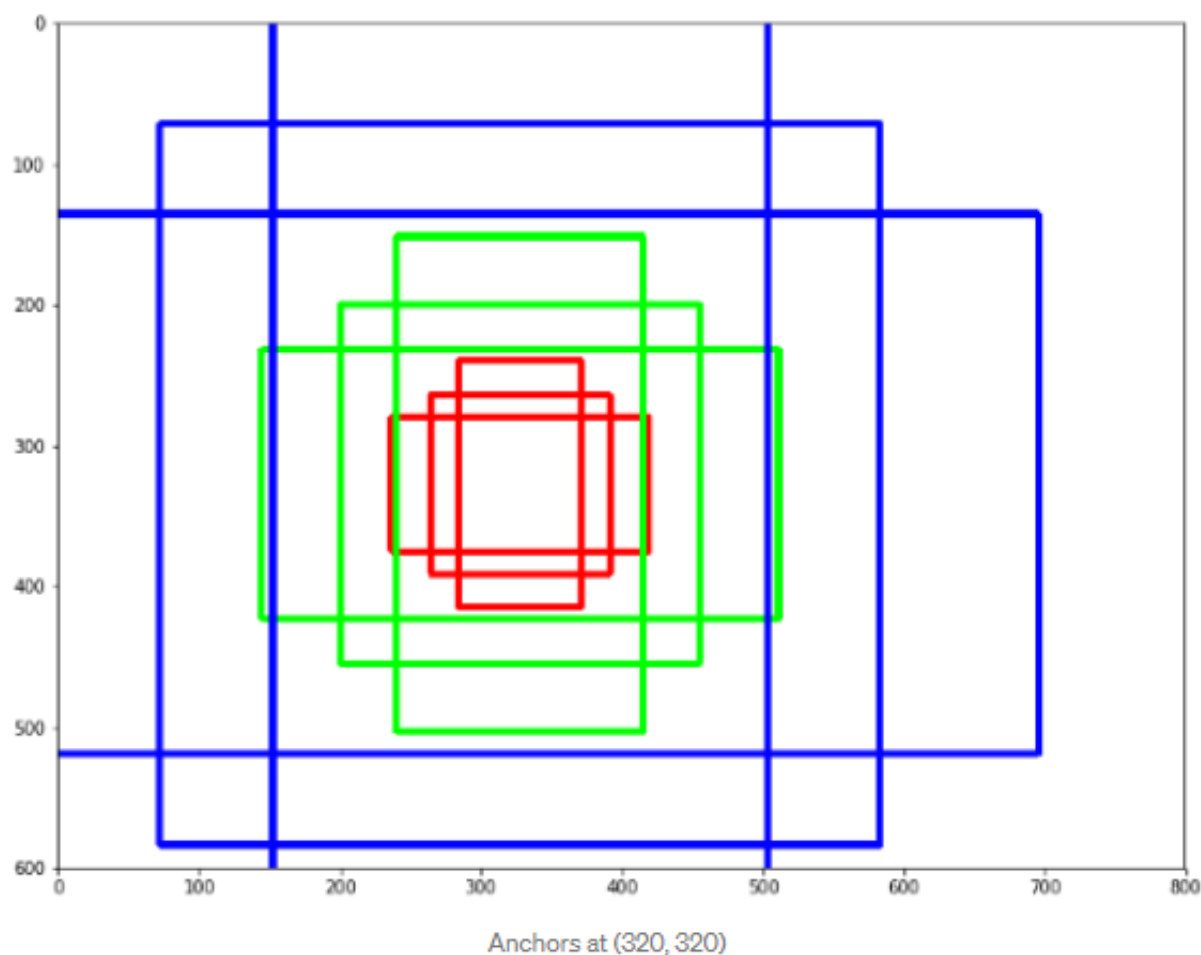
Successive stages are used to refine the predictions made by each branch. Using the part confidence maps, bipartite graphs are formed between pairs of parts (as shown in the above image). Using the PAF values, weaker links in the bipartite graphs are pruned. Through the above steps, human pose skeletons can be estimated and assigned to every person in the image.

#### Faster RCNN:

Faster R-CNN has two networks: region proposal network (RPN) for generating region proposals and a network using these proposals to detect objects. The main difference here with Fast R-CNN is that the later uses selective search to generate region proposals. The time cost of generating region proposals is much smaller in RPN than selective search, when RPN shares the most computation with the object detection network. Briefly, RPN ranks region boxes (called anchors) and proposes the ones most likely containing objects. The architecture is as follows.



Anchors play an important role in Faster R-CNN. An anchor is a box. In the default configuration of Faster R-CNN, there are 9 anchors at a position of an image. The following graph shows 9 anchors at the position (320, 320) of an image with size (600, 800).



Let's look closer:

1. Three colors represent three scales or sizes: 128x128, 256x256, 512x512.
2. Let's single out the red boxes/anchors. The three boxes have height width ratios 1:1, 1:2 and 2:1 respectively.

If we choose one position at every stride of 16, there will be 1989 (39x51) positions. This leads to 17901 (1989 x 9) boxes to consider. The sheer size is hardly smaller than the combination of sliding window and pyramid. Or you can reason this is why it has a coverage as good as other state of the art methods. The bright side here is that we can use region proposal network, the method in Fast RCNN, to significantly reduce number.

If you follow the process of labelling anchors, you can also pick out the anchors based on the similar criteria for the regressor to refine. One point here is that anchors labelled as background shouldn't include in the regression, as we don't have ground-truth boxes for them. The depth of feature map is 32 (9 anchors x 4 positions).

The paper uses smooth-L1 loss on the position (x, y) of top-left the box, and the logarithm of the heights and widths, which is as the same as in Fast R-CNN.

$$L_{\text{loc}}(t^u, v) = \sum_{i \in \{x, y, w, h\}} \text{smooth}_{L_1}(t_i^u - v_i), \quad (2)$$

in which

$$\text{smooth}_{L_1}(x) = \begin{cases} 0.5x^2 & \text{if } |x| < 1 \\ |x| - 0.5 & \text{otherwise,} \end{cases} \quad (3)$$

Loss Function of the Regressor



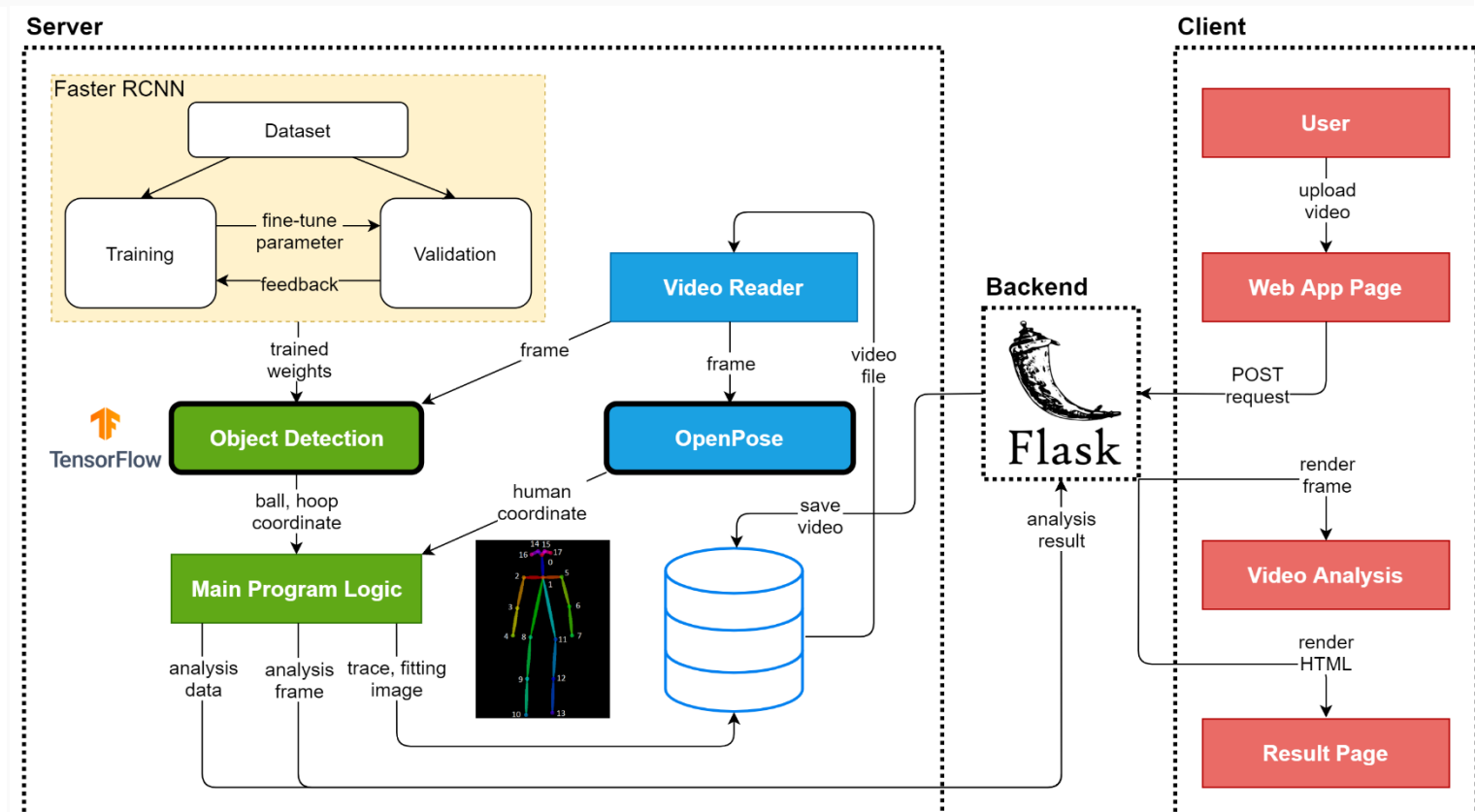
The overall loss of the RPN is a combination of the classification loss and the regression loss.

<https://www.geeksforgeeks.org/openpose-human-pose-estimation-method/>

## - The Model Analysis

The difference between object detection algorithms and classification algorithms is that in detection algorithms, we try to draw a bounding box around the object of interest to locate it within the image. Also, you might not necessarily draw just one bounding box in an object detection case, there could be many bounding boxes representing different objects of interest within the image and you would not know how many beforehand. The reason “Fast R-CNN” is faster than R-CNN is because you don't have to feed 2000 region proposals to the convolutional neural network every time. Instead, the convolution operation is done only once per image and a feature map is generated from it. Faster RCNN is an object detection architecture presented by Ross Girshick, Shaoqing Ren, Kaiming He and Jian Sun in 2015, and is one of the famous object detection architectures that uses convolution neural networks. Faster R-CNN is a single-stage model that is trained end-to-end. It uses a novel region proposal network (RPN) for generating region proposals, which save time compared to traditional algorithms like Selective Search. It uses the ROI Pooling layer to extract a fixed-length feature vector from each region proposal. OpenPose is the first real-time multi-person system to jointly detect human body, hand, facial, and foot key-points (in total 135 key-points) on single images.

## Project Architecture Process Through Visualization



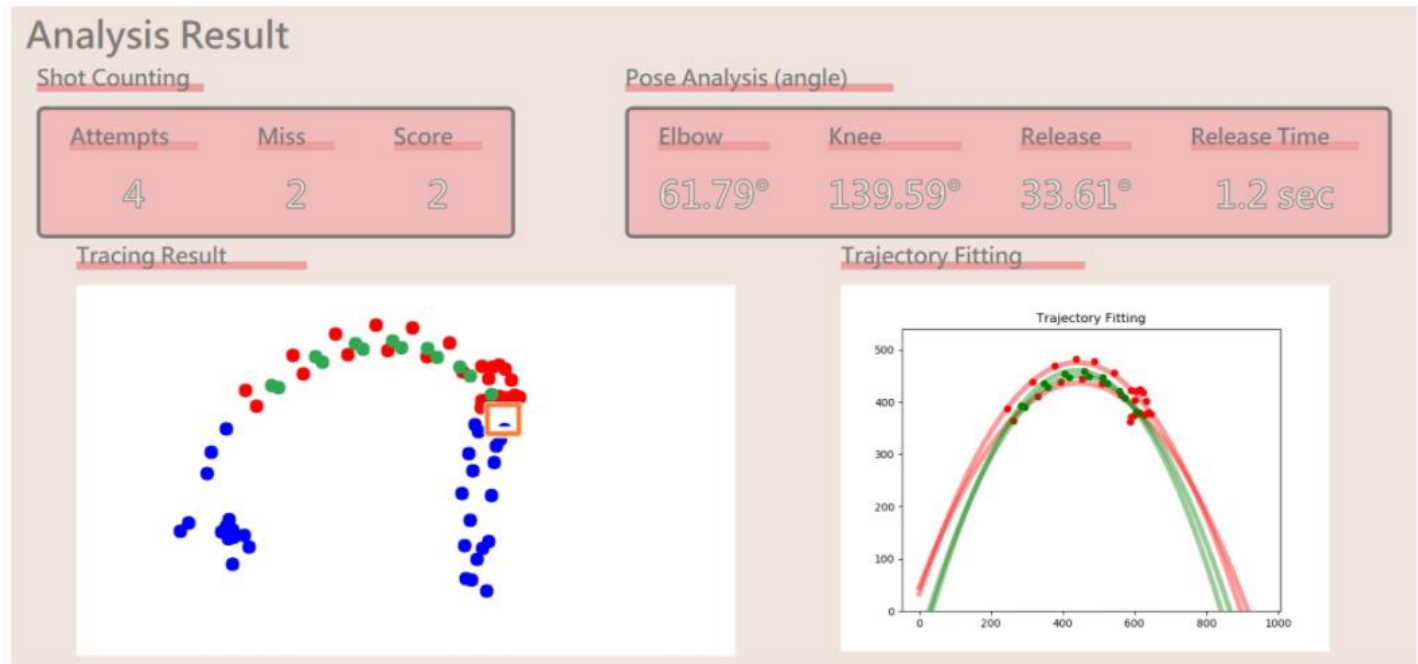


## Project Features

This project has three main features, shot analysis, shot detection, detection API.

Shot and Pose analysis:

*Shot counting*

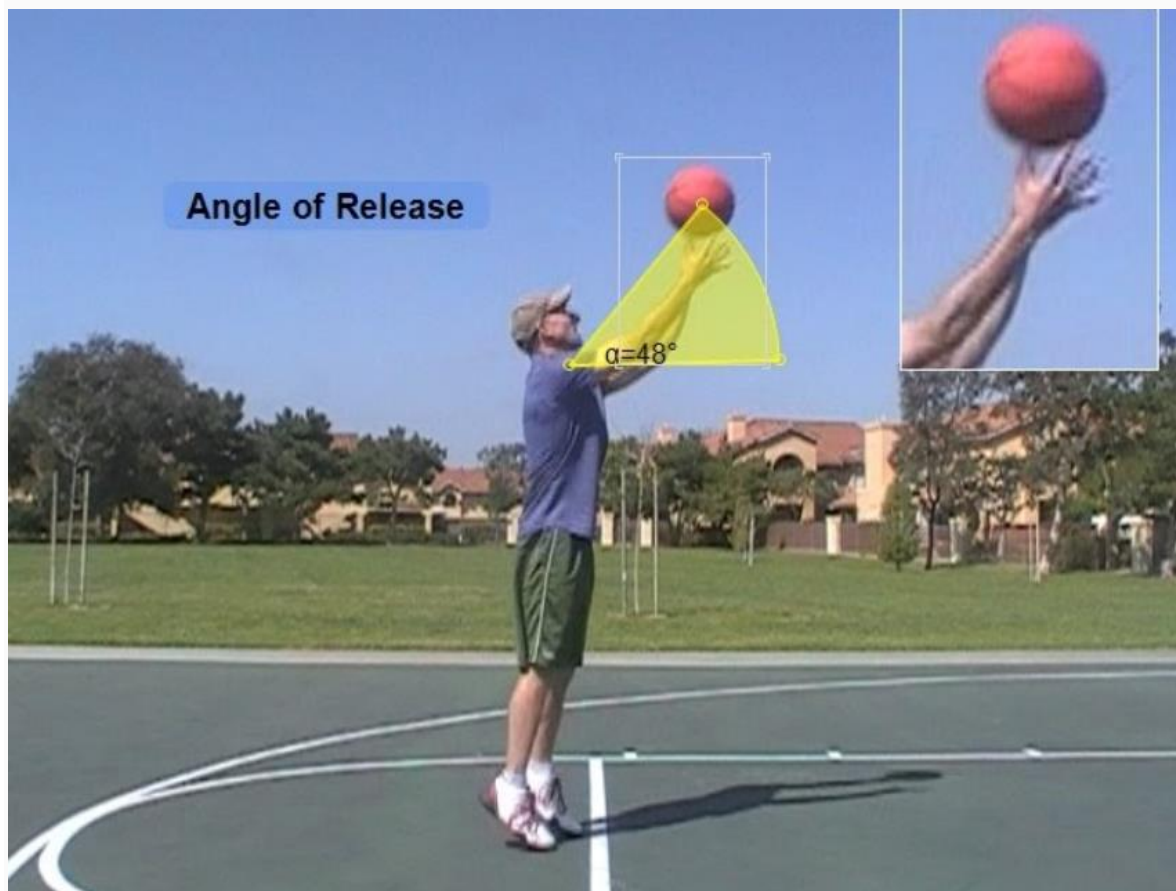


Counting shooting attempts and missing, scoring shots from the input video. Detection keypoints in different colors have different meanings listed below:

- **Blue:** Detected basketball in normal status
- **Purple:** Undetermined shot
- **Green:** Shot went in
- **Red:** Miss



Implementing OpenPose to calculate the angle of elbow and knee during shooting.



Release angle and release time are calculated by all the data collected from shot analysis and pose analysis. Please note that there will be a relatively big error for the release time since it was calculated as the total time when the ball is in hand.

Shot detection:

Shot detection

Original



Class	Confidence	Coordinate
Hoop	0.999992	(1245, 392)

Detection



Class	Confidence	Coordinate
Basketball	0.999928	(685, 240)

Detection will be shown on the image. The confidence and the coordinate of the detection will be listed below.

Detection API:

none form-data x-www-form-urlencoded raw binary GraphQL

KEY	VALUE
<input checked="" type="checkbox"/> image	ball3.jpg X
Key	Value

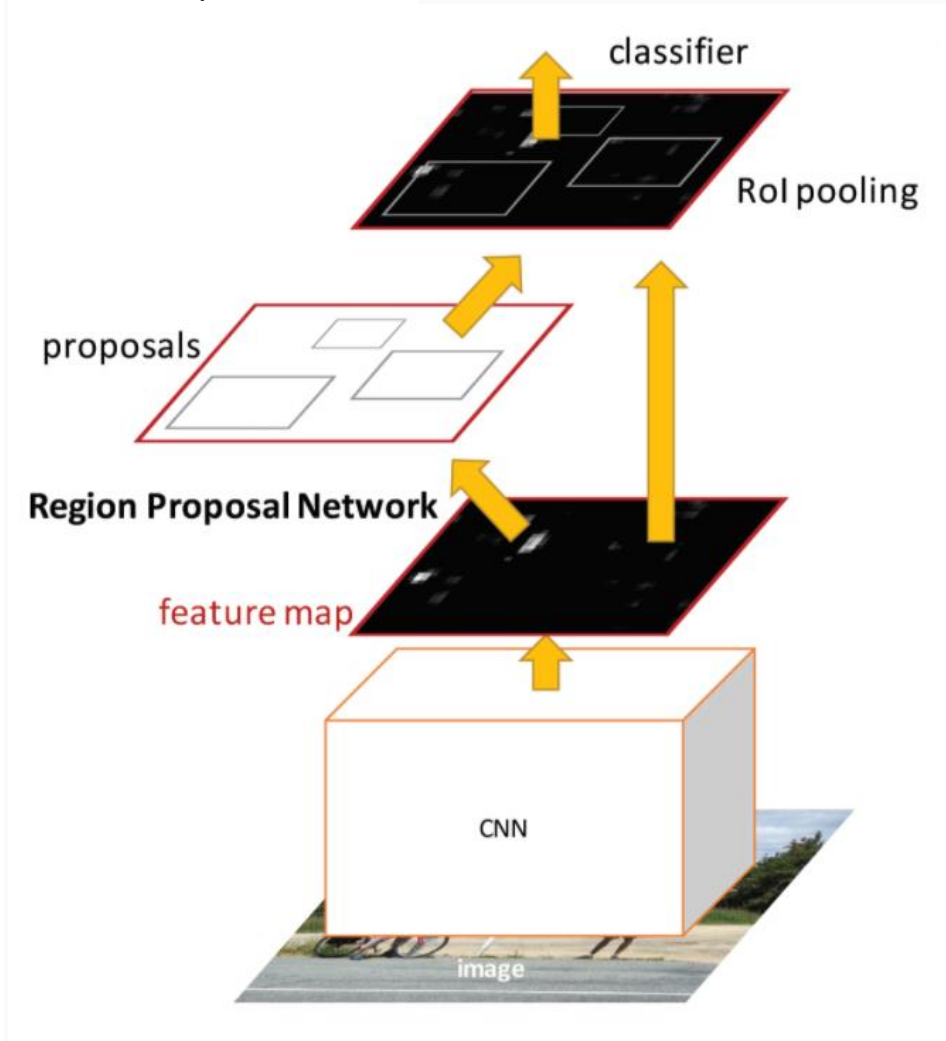
Body Cookies Headers (9) Test Results

Pretty Raw Preview Visualize JSON

```
1 {
2   {
3     "class": "Hoop",
4     "detection_detail": {
5       "box_boundary": {
6         "x_max": 1294,
7         "x_min": 1198,
8         "y_max": 433,
9         "y_min": 349
10      },
11      "center_coordinate": {
12        "x": 1246,
13        "y": 391
14      },
15      "confidence": 0.9999831914901733
16    }
17  },
18  {
19    "class": "Basketball",
20    "detection_detail": {
21      "box_boundary": {
22        "x_max": 972,
23        "x_min": 920,
24        "y_max": 195,
25        "y_min": 139
26      },
27      "center_coordinate": {
28        "x": 946,
29        "y": 167
30      },
31      "confidence": 0.999194324016571
32    }
33  }
34 }
```

## Detection Model

The object detection model is trained with the Faster R-CNN model architecture, which includes pretrained weight on COCO dataset. Taking the configuration from the model architecture and train it on my own dataset.



## Creation of App

Here, I am creating Flask App. Input image or video is taken from the user. Then it calls respective py file with its method calculation in it. Then render respective .html page for solution.

## Technical Aspect

Numpy used for working with arrays. It also has functions for working in domain of linear algebra, fourier transform, and matrices. It contains a multi-dimensional array and matrix data structures. It can be utilised to perform a number of mathematical operations on arrays.

Matplotlib is used for EDA. Visualization of graphs helps to understand data in better way than numbers in table format. Matplotlib is mainly deployed for basic plotting. It consists of bars, pies, lines, scatter plots and so on. Inline command display visualization inline within frontends like in Jupyter Notebook, directly below the code cell that produced it.

Flask is a web framework. This means flask provides you with tools, libraries and technologies that allow you to build a web application. This web application can be some web pages, a blog, a wiki or go as big as a web-based calendar application or a commercial website.

OpenCV is a cross-platform library using which we can develop real-time computer vision applications. It mainly focuses on image processing, video capture and analysis including features like face detection and object detection.

TensorFlow is a Python library for fast numerical computing. It allows developers to create large-scale neural networks with many layers. TensorFlow is mainly used for: Classification, Perception, Understanding, Discovering, Prediction and Creation. It has a unique approach that allows monitoring the training progress of our models and tracking several metrics.

SciPy is an open-source Python library which is used to solve scientific and mathematical problems. It is built on the NumPy extension and allows the user to manipulate and visualize data with a wide range of high-level commands.

The OS module in Python is a part of the standard library of the programming language. When imported, it lets the user interact with the native OS Python is currently running on. In simple terms, it provides an easy way for the user to interact with several os functions that come in handy in day-to-day programming.

The python sys module provides functions and variables which are used to manipulate different parts of the Python Runtime Environment. It lets us access system-specific parameters and functions. The first advantage the sys module offers to us is its independence from the host machine Operating System. This means that this module can work the same even if it is working on Windows or Macintosh or Linux or any given OS.

The Python time module provides many ways of representing time in code. provides functionality other than representing time, like waiting during code execution and measuring the efficiency of your code.

## Installation

---

Using intel core i5 9<sup>th</sup> generation with NVIDIA GFORCE GTX1650.

Windows 10 Environment Used.

Already Installed Anaconda Navigator for Python 3.x

The Code is written in Python 3.8.

If you don't have Python installed then please install Anaconda Navigator from its official site.

If you are using a lower version of Python you can upgrade using the pip package, ensuring you have the latest version of pip, *python -m pip install --upgrade pip and press Enter.*

## Run/How to Use/Steps

---

Keep your internet connection on while running or accessing files and throughout too.

Follow this when you want to perform from scratch.

Open Anaconda Prompt, Perform the following steps:

```
cd <PATH>
```

```
pip install numpy
```

```
pip install tensorflow==1.15.2
```



pip install matplotlib

pip install opencv-python

pip install flask

Note: If it shows error as 'No Module Found' , then install relevant module.

You can also create requirement.txt file as, pip freeze > requirements.txt

Create Virtual Environment:

conda create -n aib python=3.6

y

conda activate aib

cd <PATH-TO-FOLDER>

run .py or .ipynb files.

Paste URL to browser to check whether working locally or not.

Follow this when you want to just perform on local machine.

Download ZIP File.

Right-Click on ZIP file in download section and select Extract file option, which will unzip file.

Move unzip folder to desired folder/location be it D drive or desktop etc.

Open Anaconda Prompt, write cd <PATH> and press Enter.

eg: cd C:\Users\Monica\Desktop\Projects\Python Projects 1\

23)End\_To\_End\_Projects\Project\_10\_DL\_FileUse\_End\_To\_End\_AIBasketball

conda create -n aib python=3.6

y

conda activate aib

In Anconda Prompt, pip install -r requirements.txt to install all packages.

In Anconda Prompt, write python app.py and press Enter.

Paste the URL '<http://127.0.0.1:5000/>' to browser to check whether working locally or not.

Please be careful with spellings or numbers while typing filename and easier is just copy filename and then run it to avoid any silly errors.

Note: cd <PATH>

[Go to Folder where file is. Select the path from top and right-click and select copy option and paste it next to cd one space <path> and press enter, then you can access all files of that folder]

[cd means change directory]

## Directory Tree/Structure of Project

---

Folder: AI\_Basketball > AIB

requirements.txt

Procfile

app.py

Aptfile

AI\_Basketball > AIB > templates

index.html

layout.html

result.html

shooting\_analysis.html  
shot\_detection.html

AI\_Basketball > AIB > static  
AI\_Basketball > AIB > static > css  
main.css  
AI\_Basketball > AIB > static > detections  
.jpg

AI\_Basketball > AIB > static > img  
.png

AI\_Basketball > AIB > static > uploads  
.mp4 and .jpg

AI\_Basketball > AIB > src

app\_helper.py

config.py

utils.py

AI\_Basketball > AIB > OpenPose

AI\_Basketball > AIB > OpenPose > models

Coco, body\_25 and mpi folder

.bat and .sh file

AI\_Basketball > AIB > OpenPose > openpose  
\_\_init\_\_.py

AI\_Basketball > AIB > openPose > Release

.dll and .exe files

AI\_Basketball > AIB > inference\_graph

frozen\_inference\_graph.pb



```

Project_DL_AIBasketball/
├── inference_graph/
│   └── frozen_inference_graph.pb
├── OpenPose/
│   ├── models/
│   │   ├── cameraParameters/
│   │   │   └── flir/
│   │   │       └── 17012332.xml.example
│   │   ├── pose/
│   │   │   ├── body_25/
│   │   │   │   ├── pose_deploy.prototxt
│   │   │   │   └── pose_iter_584000.caffemodel
│   │   │   ├── coco/
│   │   │   │   ├── pose_deploy_linevec.prototxt
│   │   │   │   └── mpi/
│   │   │   │       ├── pose_deploy_linevec.prototxt
│   │   │   │       └── pose_deploy_linevec_faster_4_stages.prototxt
│   │   ├── getModels.bat
│   │   └── getModels.sh
│   ├── openpose/
│   │   ├── __init__.py
│   │   └── pyopenpose.cpython-36m-x86_64-linux-gnu.so
│   └── Release/
├── src/
│   ├── app_helper.py
│   ├── config.py
│   └── utils.py
├── static/
│   ├── css/
│   ├── detections/
│   ├── img/
│   └── uploads/
├── templates/
│   ├── index.html
│   ├── layout.html
│   ├── result.html
│   ├── shooting_analysis.html
│   └── shot_detection.html
├── Procfile
├── requirements.txt
├── Aptfile
├── .travis.yml
└── app.py

```

## To Do/Future Scope

Can also deploy on AWS and Google Cloud.

## Technologies Used/System Requirements/Tech Stack



NumPy

matplotlib



OpenCV



HEROKU



Flask  
web development,  
one drop at a time



SciPy



## Download the Material

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You can Download Entire Project from here: [https://github.com/monicadesAI-tech/Project\\_81](https://github.com/monicadesAI-tech/Project_81)

You can Download App\_File from here: [https://github.com/monicadesAI-tech/Project\\_81/blob/main/app.py](https://github.com/monicadesAI-tech/Project_81/blob/main/app.py)

You can see Detailed Project at Website here: <https://github.com/monicadesAI-tech.github.io/aibasketball.html>

Download dependencies from here: [https://github.com/monicadesAI-tech/Project\\_81/blob/main/requirements.txt](https://github.com/monicadesAI-tech/Project_81/blob/main/requirements.txt)

Download images to test app from here: [https://github.com/monicadesAI-tech/Project\\_81/tree/main/Test%20App%20Images%20%26%20Videos](https://github.com/monicadesAI-tech/Project_81/tree/main/Test%20App%20Images%20%26%20Videos)

## Credits

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Chonyy

## Paper Citation

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<https://dl.acm.org/doi/10.5555/2969239.2969250>

<https://ieeexplore.ieee.org/document/8496641>

<https://arxiv.org/pdf/1812.08008.pdf>

Note: [https://colab.research.google.com/github/hardik0/AI-basketball-analysis-on-google-colab/blob/master/AI\\_basketball\\_analysis\\_google\\_colab.ipynb](https://colab.research.google.com/github/hardik0/AI-basketball-analysis-on-google-colab/blob/master/AI_basketball_analysis_google_colab.ipynb)

Note: Heroku

This project is also hosted on Heroku. However, the heavy computation of TensorFlow may cause Timeout error and crash the app (especially for video analysis). Therefore, hosting the project on your local machine is more preferable. Please note that the shooting pose analysis won't be running on the Heroku hosted website, since a CUDA device is required to run OpenPose.