

# Indian Institute of Technology, Madras



## Deep Learning

Course: CS7015

Department of Computer Science and  
Engineering

**DLM**

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# Restricted Boltzmann machines

## Question Answers:

1. Plot of the learned representations in a 2-dimensional space for different values of  $n$ .

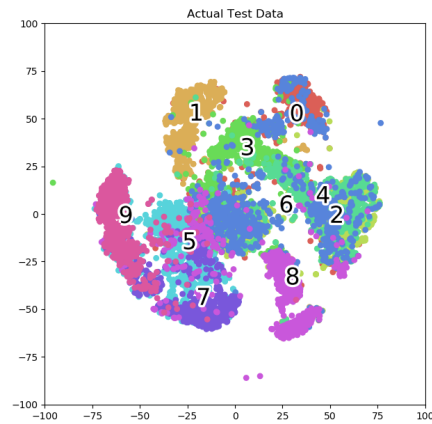
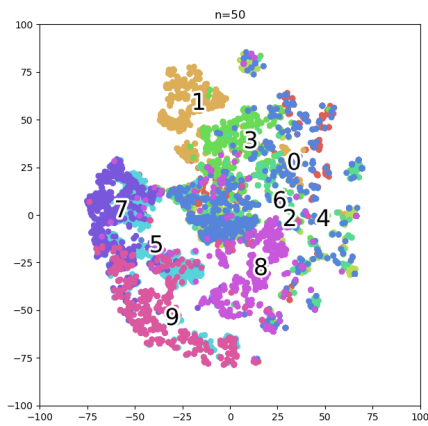
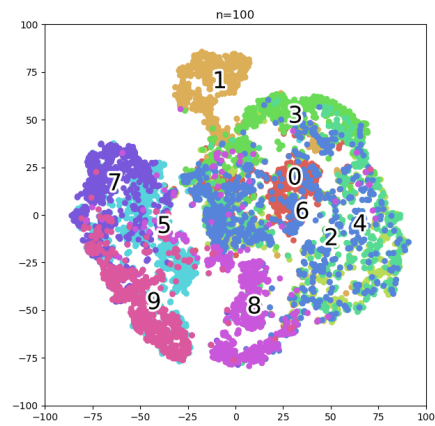


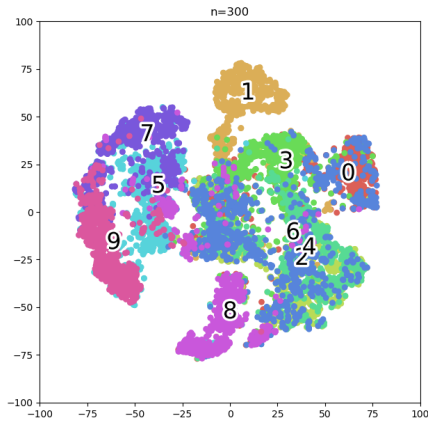
Figure 0.1: Actual Test Data



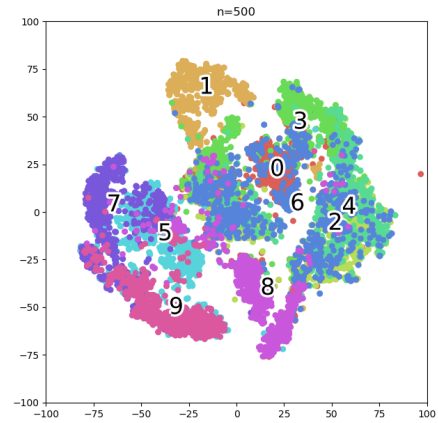
(a) Representation for  $n=50$



(b) Representation for  $n=100$



(a) Representation for  $n=300$



(b) Representation for  $n=500$

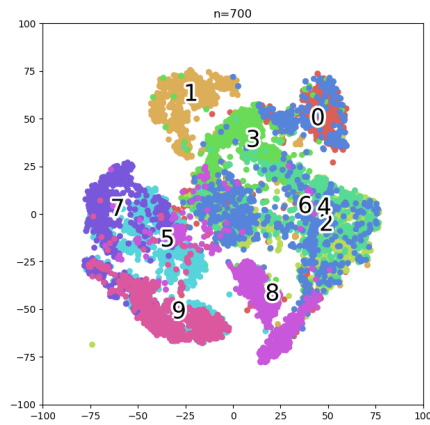


Figure 0.4: Representation for  $n=700$

### Other Parameters:

Learning rate: .001

k: 1

Epochs: 10

2. In every step of stochastic gradient descent (SGD) you will be running the Gibbs Chain for  $k$  steps. Study the effect of using different values of  $k$ .

Loss decreases faster as  $k$  increases

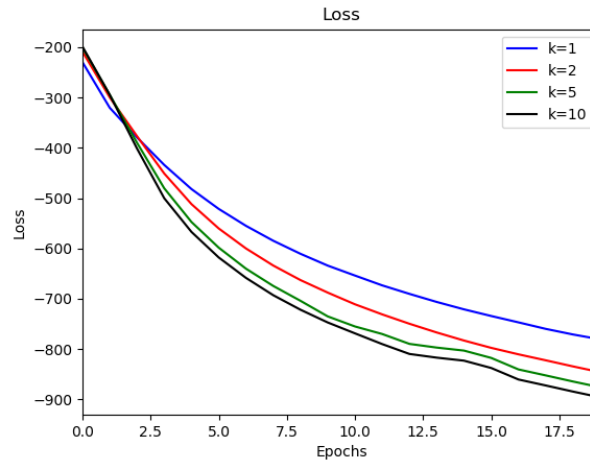
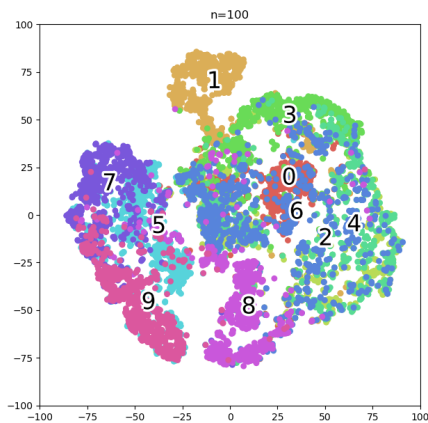
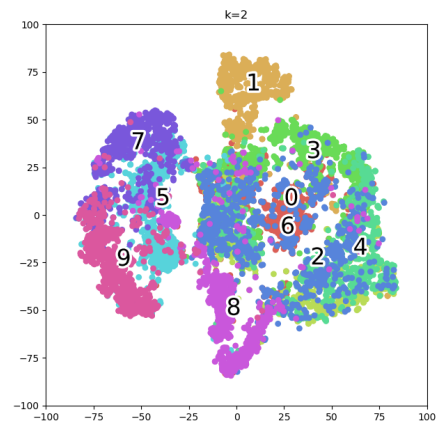


Figure 0.5: Loss for  $n=700$

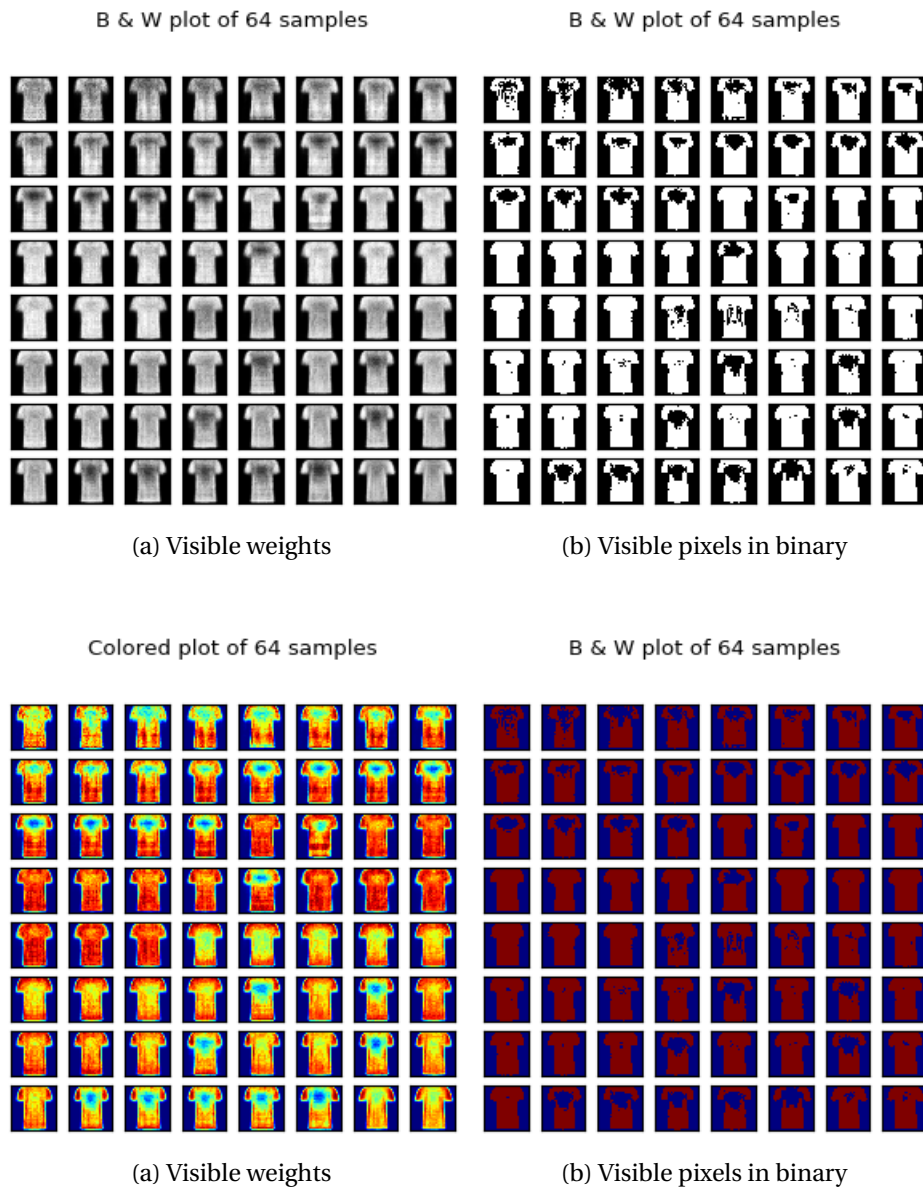


(a) Representation for  $k=1$



(b) Representation for  $k=2$

3. Suppose CD takes  $m$  iterations of SGD to converge. Plot the samples generated by Gibbs chain after every  $\frac{m}{64}$  steps of SGD.



Number of updates  $m$  is 480,000

Stochastic Gradient Descent has been used

Plots are drawn at every  $m/64^{th}$  step for a chosen data point

Plots are also drawn in BnW for better visualization

4. Instead of CD use Gibbs Sampling. How many steps do you need to run the chain for before you start seeing samples from  $P(V, H)$ ? Does this number change as SGD reaches convergence?

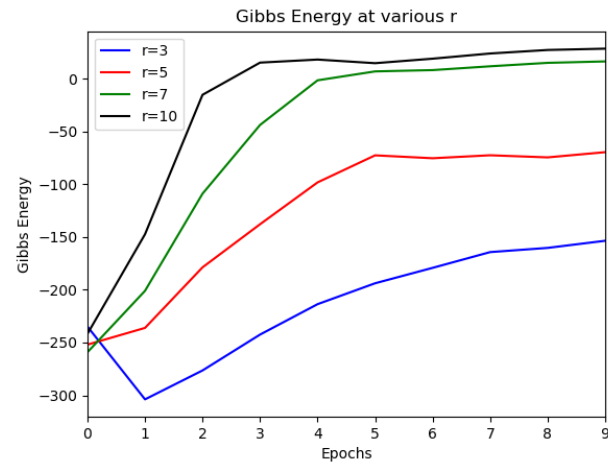


Figure 0.9: Gibb's Energy at  $K=5$  and  $r=5,7,10$

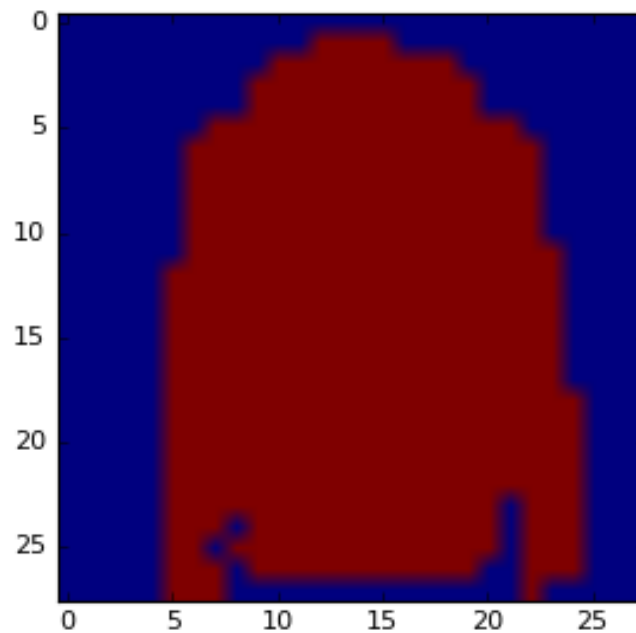
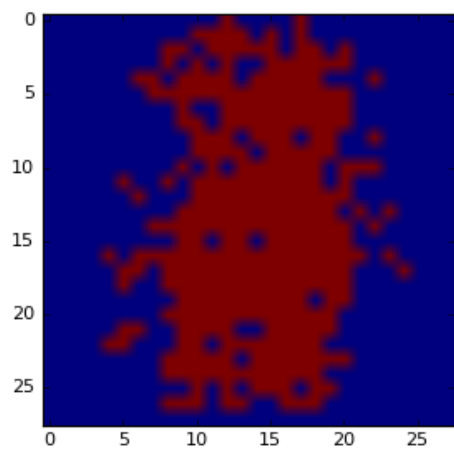
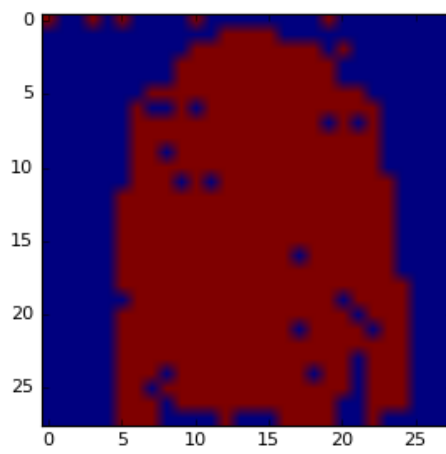


Figure 0.10: Original Image



(a)  $r=10$



(b) 25

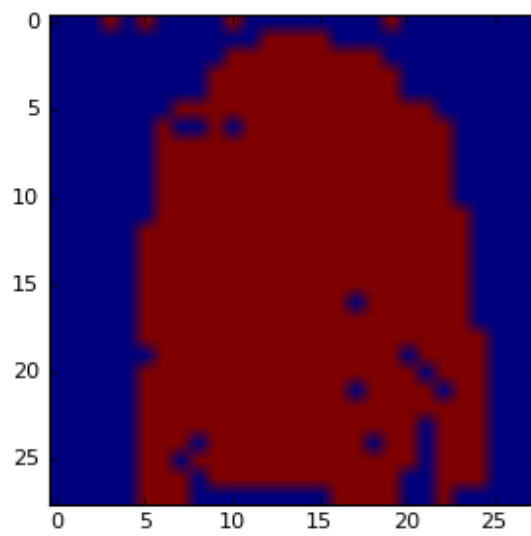


Figure 0.12: Original Image